



ERASMUS RESEARCH
INSTITUTE OF MANAGEMENT

Variable trip times for cyclic railway timetabling

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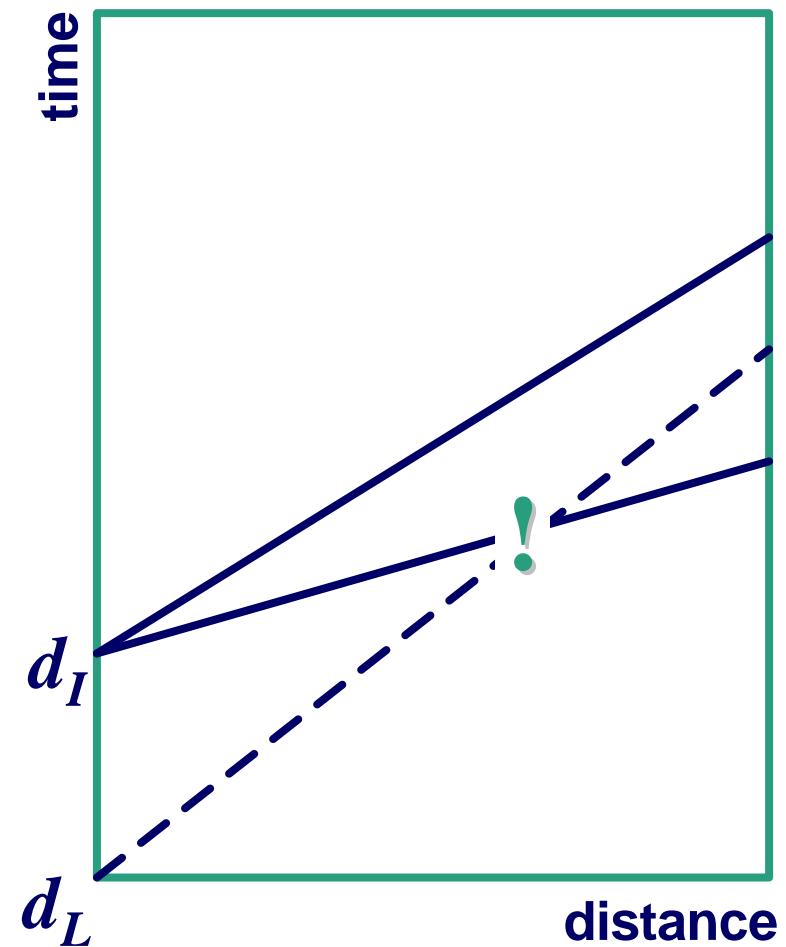
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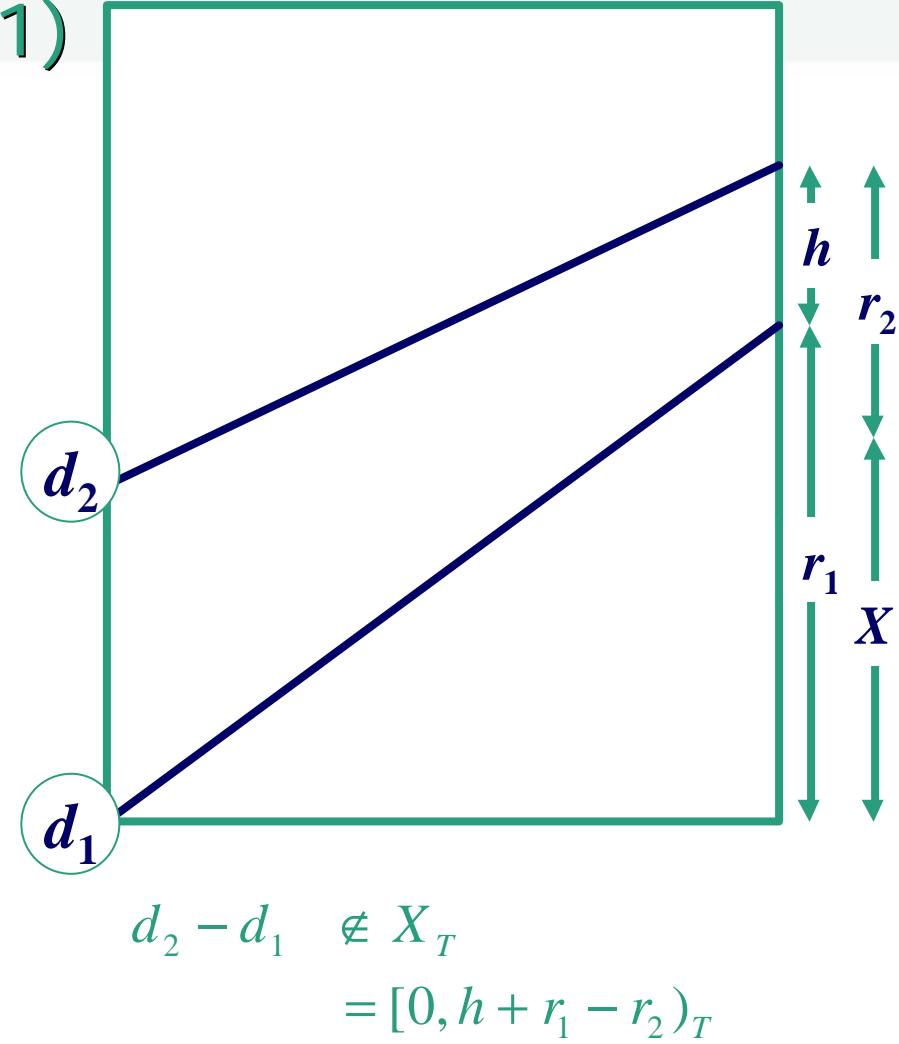
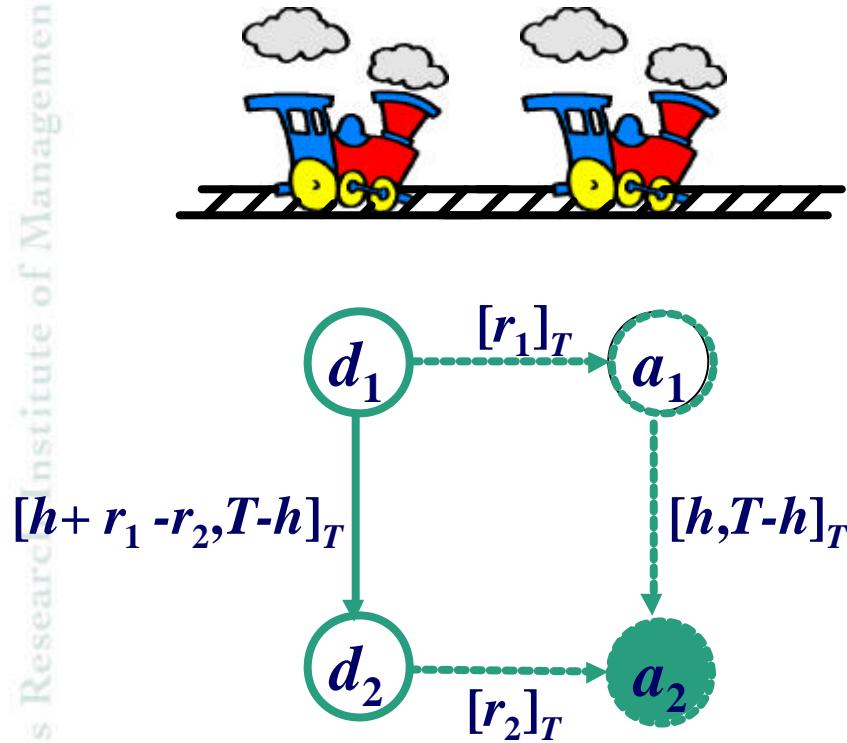
Why study variable trip times?

- Basic model: fixed trip times
- Larger solution space
- Possibly better solutions
- Used in practice!



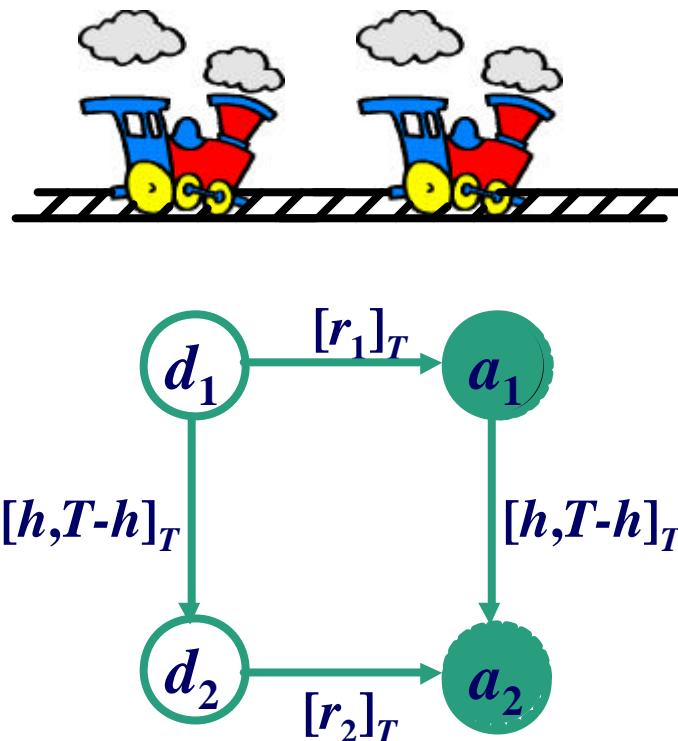


Fixed trip times(1)





Fixed trip times(2)



Theorem (Lindner)

Suppose

$$d_2 - d_1 + T p_d \in [h, T - h]$$

$$a_2 - a_1 + T p_a \in [h, T - h]$$

Trains 1 and 2 do not overtake each other if and only if

$$p_d = p_a$$



Problems with variable trip time

- Trip times straightforward

$$a_i - d_i \in [r_i, R_i]$$

- Safety constraints

$$d_2 - d_1 \notin X_T = [-h, h + \mathbf{r}_1 - \mathbf{r}_2]_T$$

...but $\mathbf{r}_1, \mathbf{r}_2 = ?$

- Lindner's result requires JPESP (Joined constraints) for expressing $p_d = p_a$



Variable trip times

Theorem

The constraints

$$d_2 - d_1 \notin (-h, h)_T$$

$$a_2 - a_1 \notin (-h, h)_T$$

are necessary to guarantee

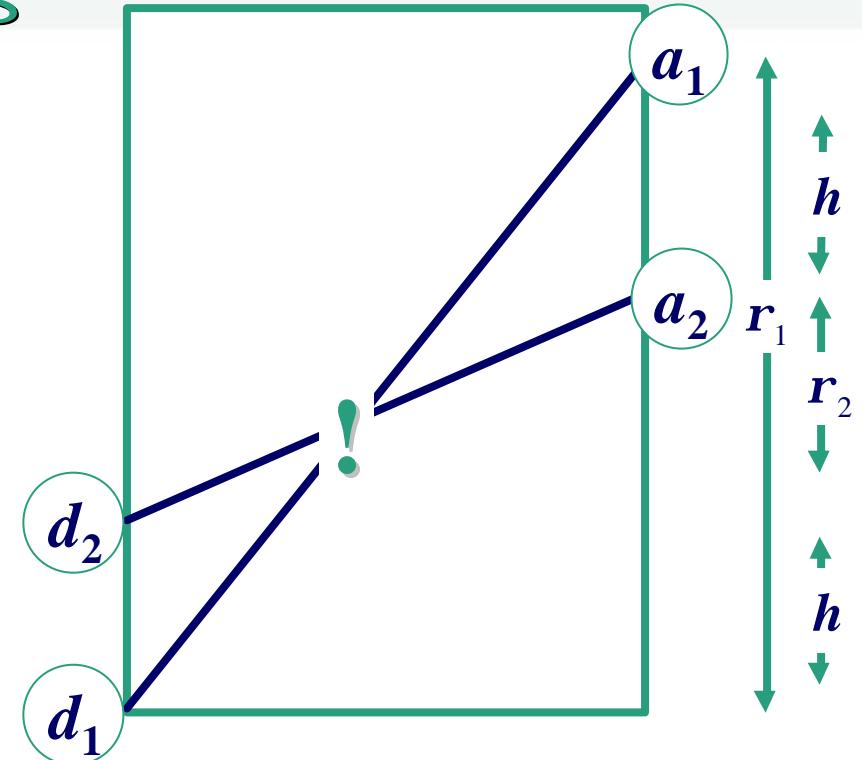
- non-overtaking of 1 and 2
- respecting headways

If

$$R_1 - r_2 < 2h$$

$$R_2 - r_1 < 2h$$

then also sufficient.



$$r_1 > r_2 + 2h$$

$$\Rightarrow \max\{r_1 - r_2\} < 2h$$

$$\Rightarrow R_1 - r_2 < 2h$$



Disjoint trip time windows

Assume $r_1 > R_2$

Theorem

$$d_2 - d_1 \notin (-h, h + r_1 - R_2)_T$$

$$a_1 - a_2 \notin (-h, h + r_1 - R_2)_T$$

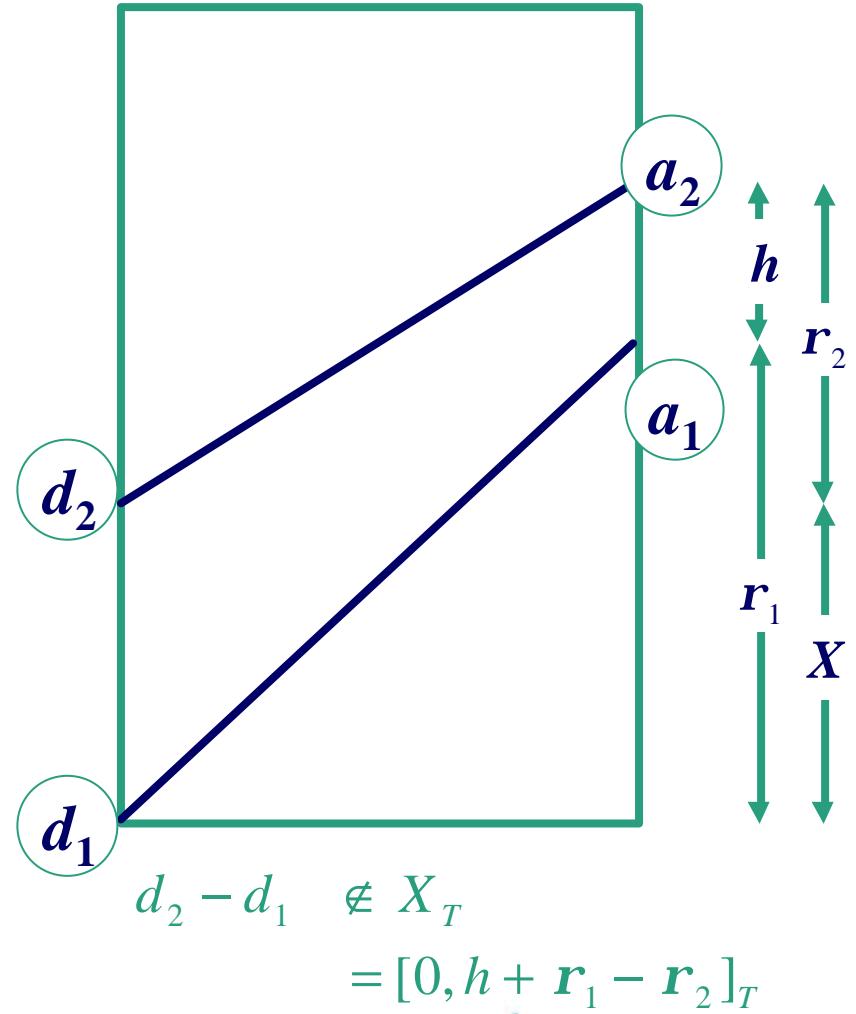
are necessary to guarantee

- non-overtaking of 1 and 2
- respecting headways

If

$$\begin{aligned} (R_1 - r_1) + (R_2 - r_2) \\ < 2h + (r_1 - R_2) \end{aligned}$$

then also sufficient.





Conclusion & Practical experience

- Similar result for opposite trains on single track
- General case: trip window at most 5 wide
- Disjoint case: more space
- Uses PESP constraints only
- Works well in practice
 - First without variable trip times
 - If not feasible, use variable trip times



Computational experiments for the Netherlands' Intercity network

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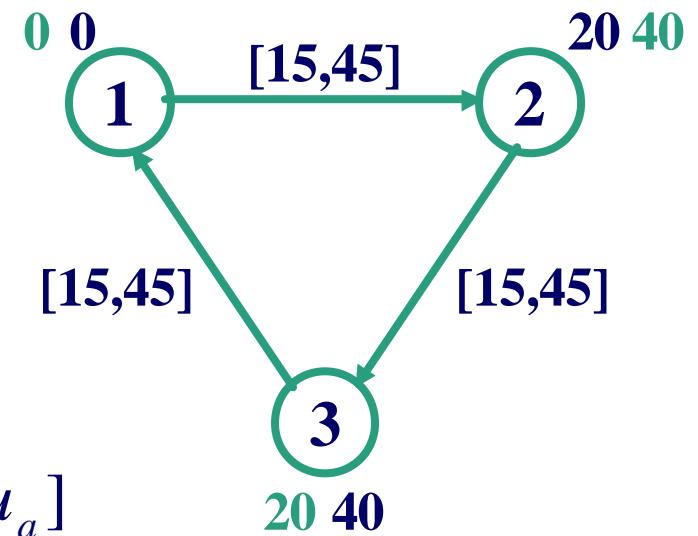


Model - cycles

- Consider a cycle:

- Cycle directions $c = c^+ \cup c^-$
- Decision variables $d_a \in [l_a, u_a]$
- Integer variable q_c
- For every cycle $c \in C$:

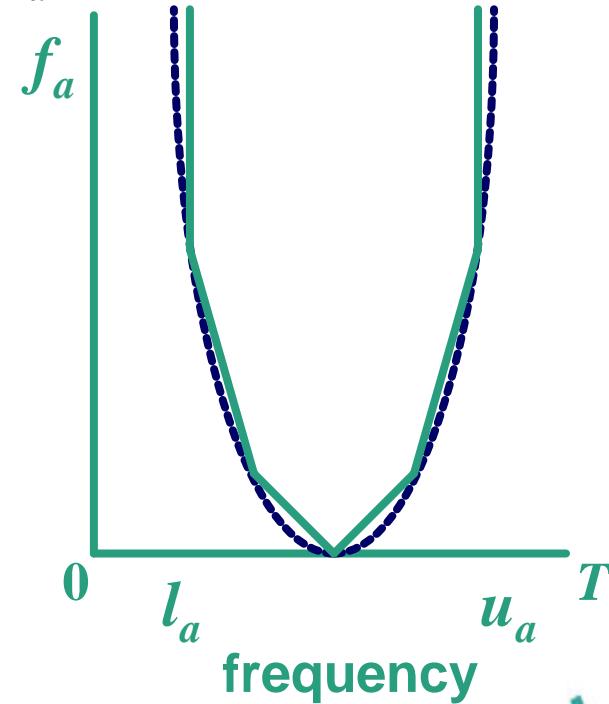
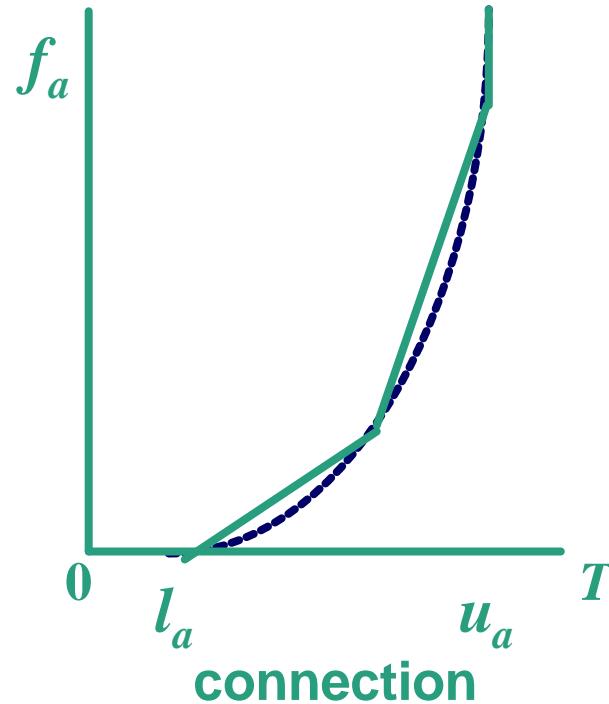
$$\sum_{a \in c^+} d_a - \sum_{a \in c^-} d_a = T q_c$$





Objective function: d_a -variables

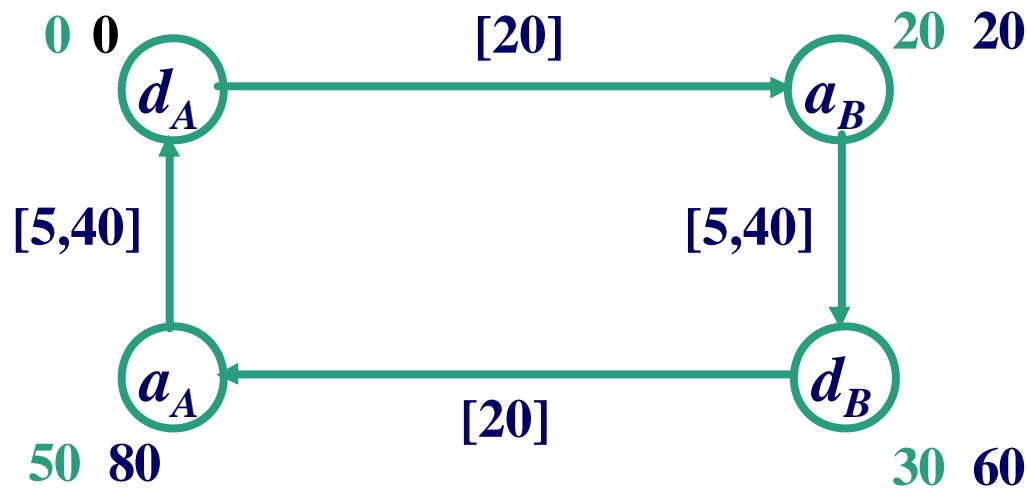
- Minimize $\sum_{a \in A_{obj}} f_a(d_a)$
- Shape of functions f_a :





Alternative objective function - rolling stock

- Minimize number of rolling stock compositions
- Consider train cycle:

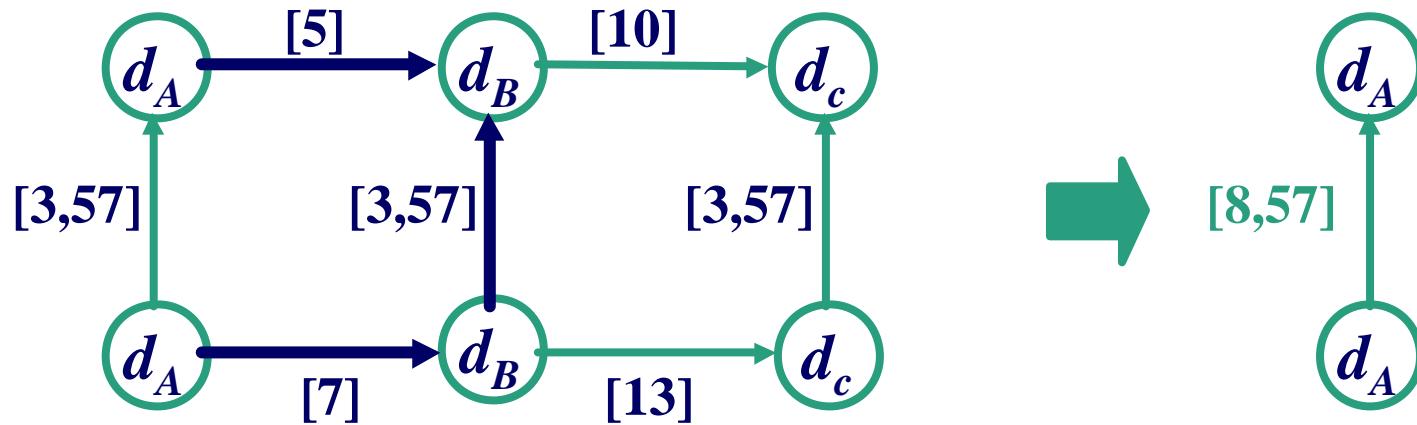


- Minimize $\sum_{c \in C_t} q_c$, $C_t \subseteq C$ set of train cycles



Preprocessing

- Contract nodes with degree 1 or 2
- Shrink subsequent safety constraints:



- Substitute remaining equality constraints



Calculating a cycle basis

- Find a MST with respect to $w_a = u_a - l_a$
- Widest arcs each in only one cycle
- Bounds on the q_c -variables:

$$\sum_{a \in c} l_a \leq \sum_{a \in c} d_a = T q_c \leq \sum_{a \in c} u_a$$

↓

$$\left\lceil \frac{1}{T} \sum_{a \in c} l_a \right\rceil \leq q_c \leq \left\lfloor \frac{1}{T} \sum_{a \in c} u_a \right\rfloor$$



Characteristics IC-97

- Train lines 25
- Stations 50
- Original size $n=1475, m=3342$
- After pre-processing $n= 207, m= 525$
- # connections 34
- # stops 162
- # safety 300

- MIP solver CPLEX 6.5
- Sun Enterprise/250, two 400MHz UltraSPARC processors, 1 Gb mem.



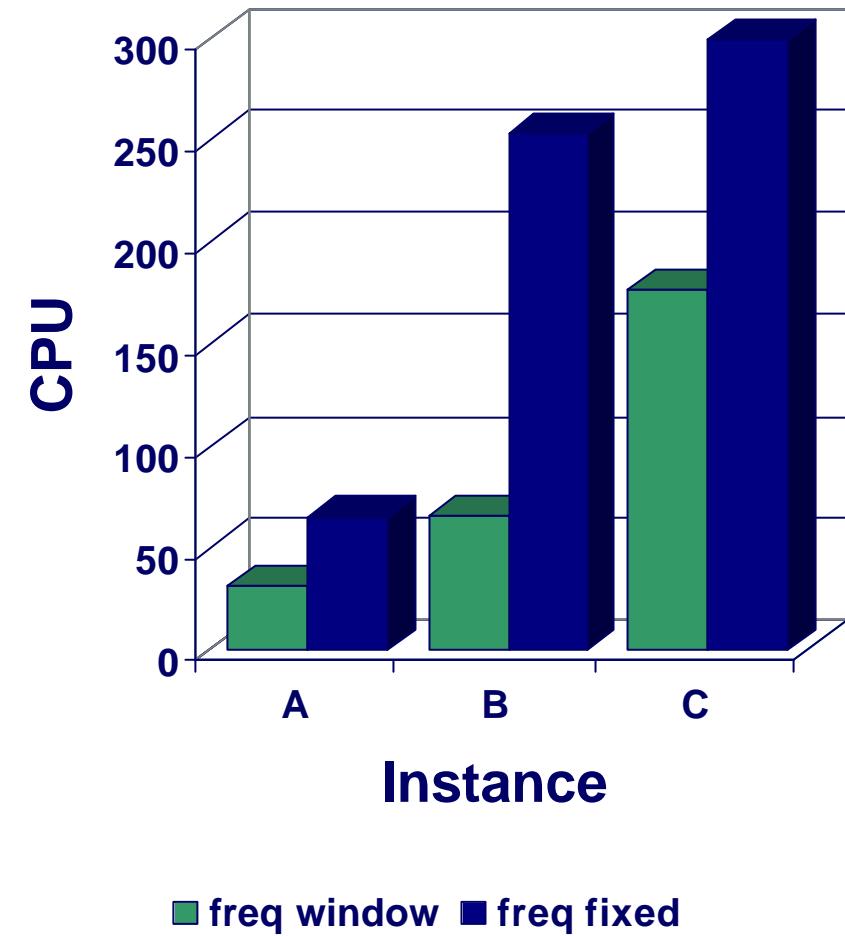
Minimizing waiting time

- Minimize $\sum_{a \in A_{conn} \cup A_{stop}} f_a(d_a)$

- Variants:

Instance	D_{conn}	D_{stop}
A	3	2
B	5	3
C	8	5

frequency	$[l_a, u_a]$	z_{opt}
window	[28,32]	114
fixed	[30]	154

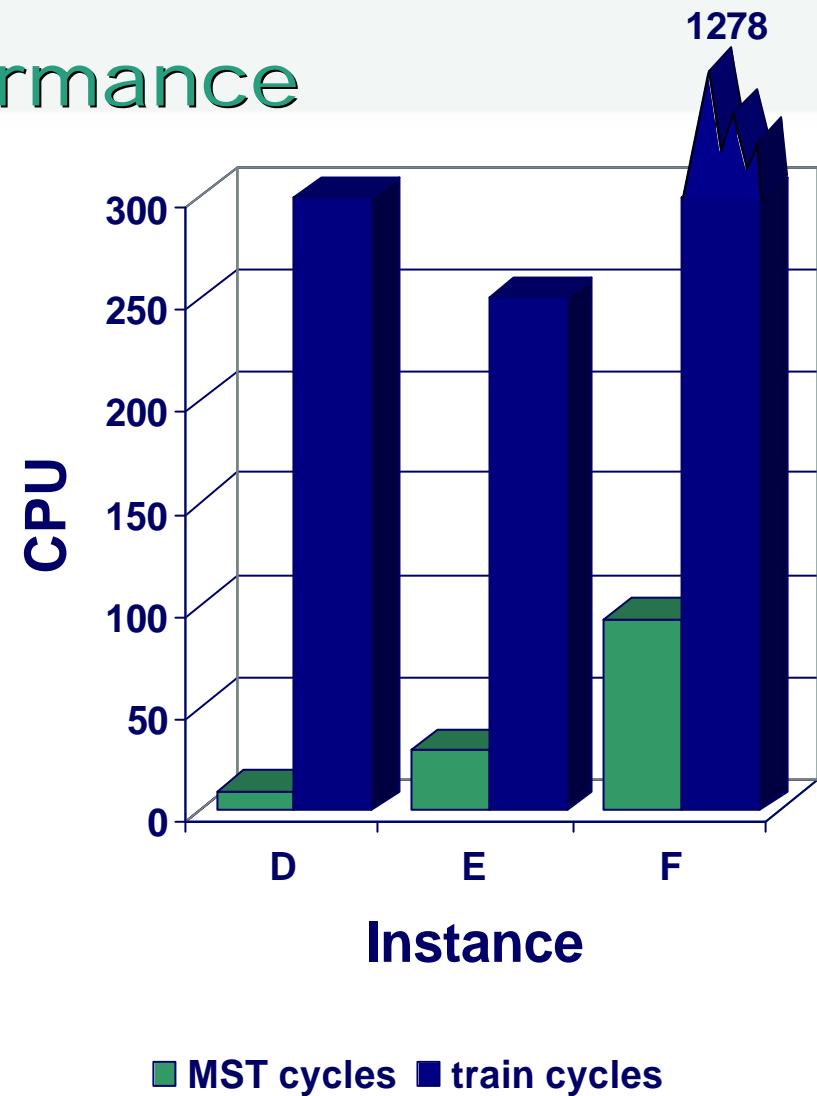




Cycle basis performance

- Cycle bases
 - MST
 - Train cycles
- Variants:

Instance	l_{turn}	u_{turn}	z_{opt}
D	10	40	764
E	5	40	247
F	5	59	154





Minimizing rolling stock & waiting time

- Minimize $\sum_{a \in A_{conn} \cup A_{stop}} f_a(d_a) + K \sum_{c \in C_t} q_c$
- Train cycle basis
- Variants:

Instance	z_{opt}
D	62.765
E	57.247
F	55.171

