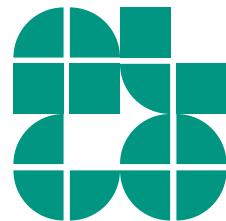


Algorithms for Graph Visualization

Flow Methods: Compaction and Upward Planarity

INSTITUT FÜR THEORETISCHE INFORMATIK · FAKULTÄT FÜR INFORMATIK

Tamara Mchedlidze
23.01.2017



(Planar) Orthogonal Layout

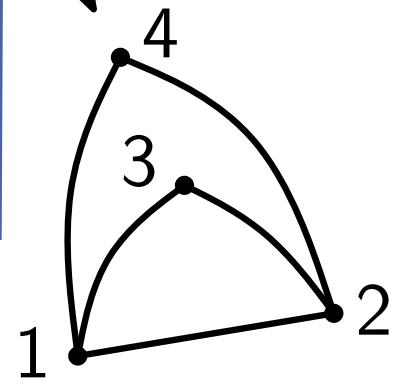
Three-step approach: *Topology – Shape – Metrics*

[Tamassia SIAM J. Comput. 1987]

$$V = \{v_1, v_2, v_3, v_4\}$$

$$E = \{v_1v_2, v_1v_3, v_1v_4, v_2v_3, v_2v_4\}$$

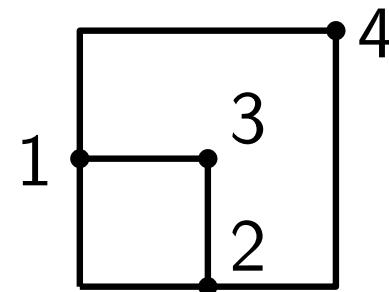
Reduce Crossings



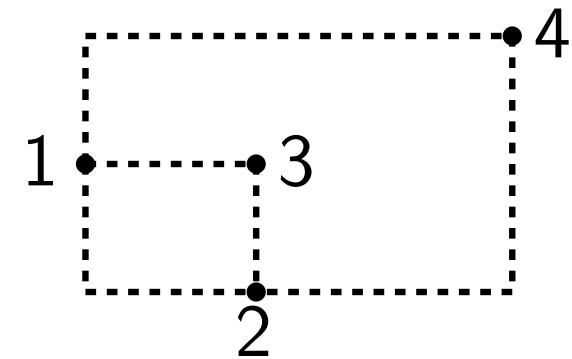
combinatorial
embedding/
planarization

Bend Minimization

orthogonal
representation



planar
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Area-
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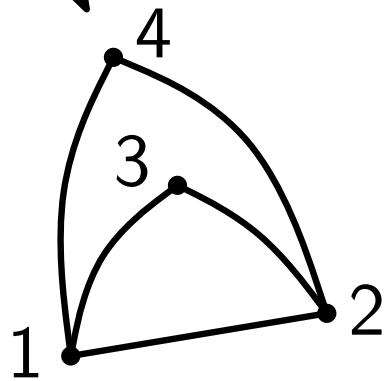
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combinatorial
embedding/
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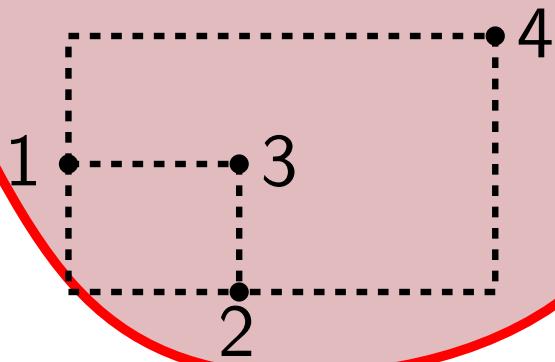
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Problem Compaction

Given:

- planar graph $G = (V, E)$ with maximum degree 4
- orthogonal representation $H(G)$

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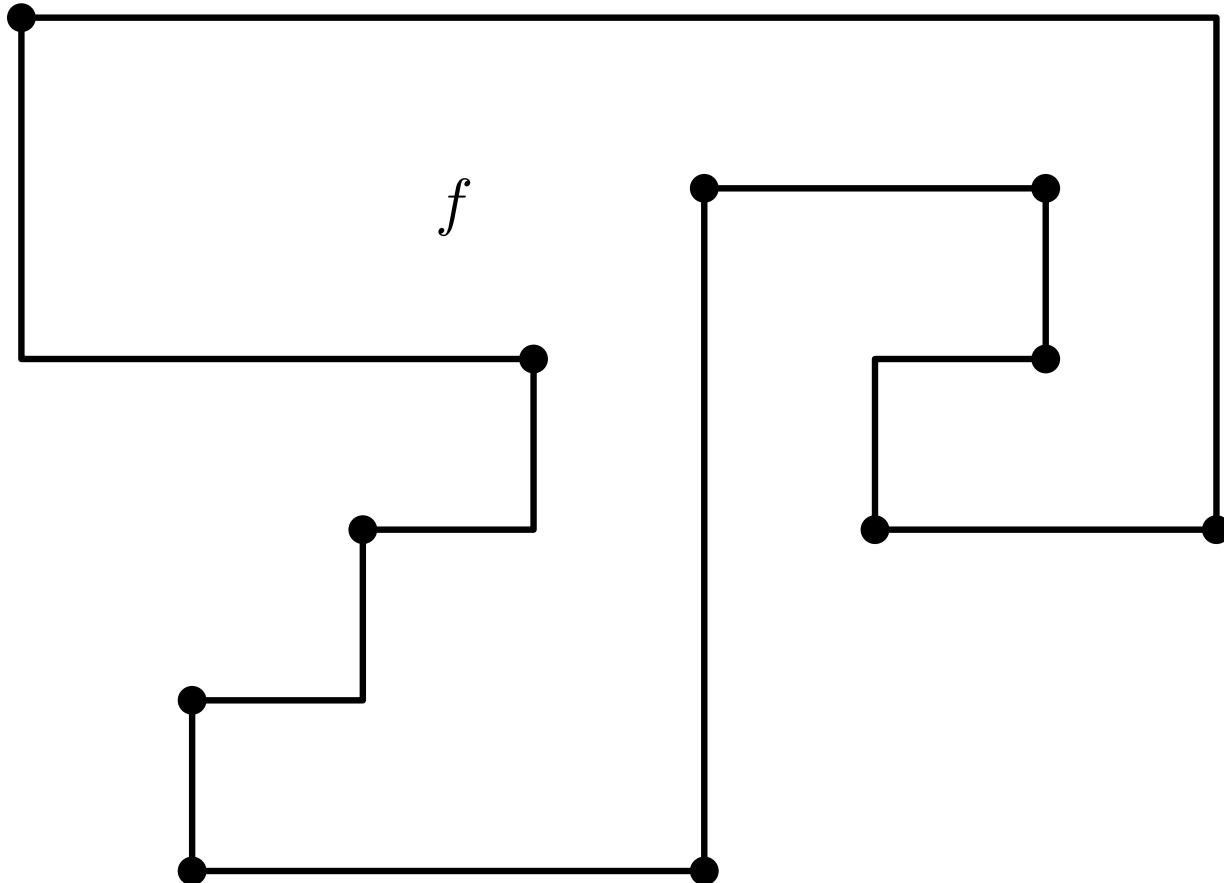
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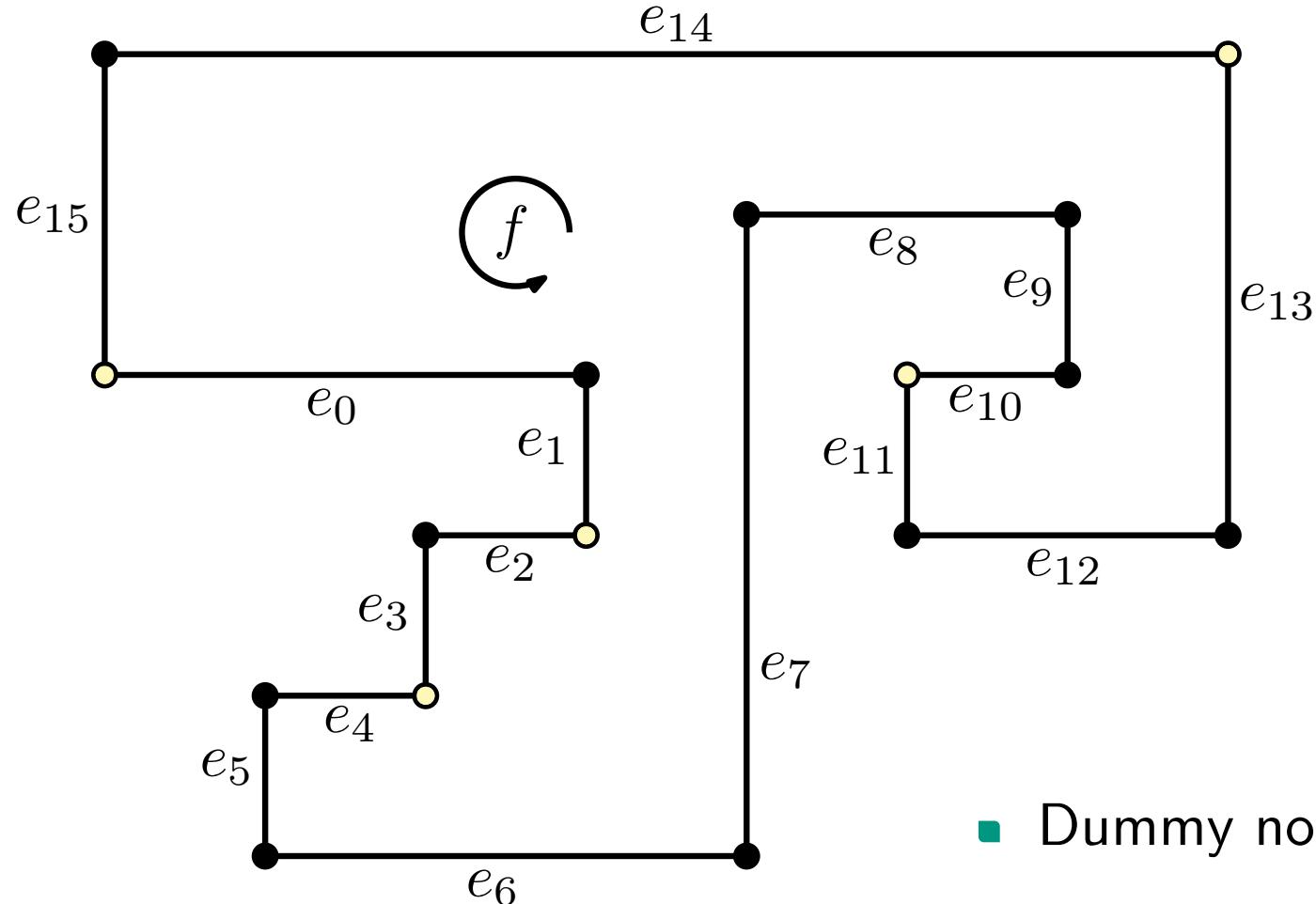
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What is the faces are not rectangles?

Refinement of (G, H) – Inner Face

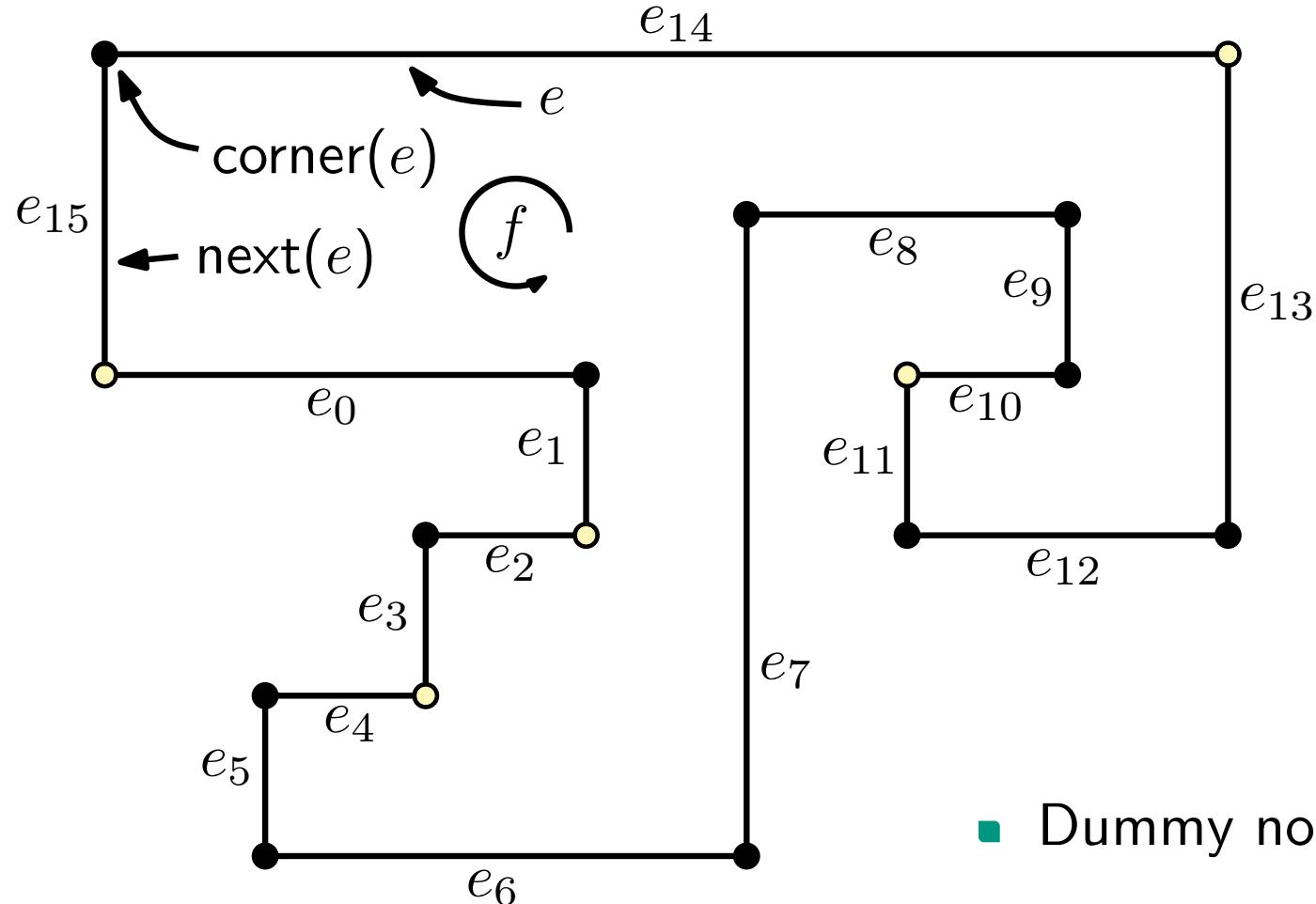


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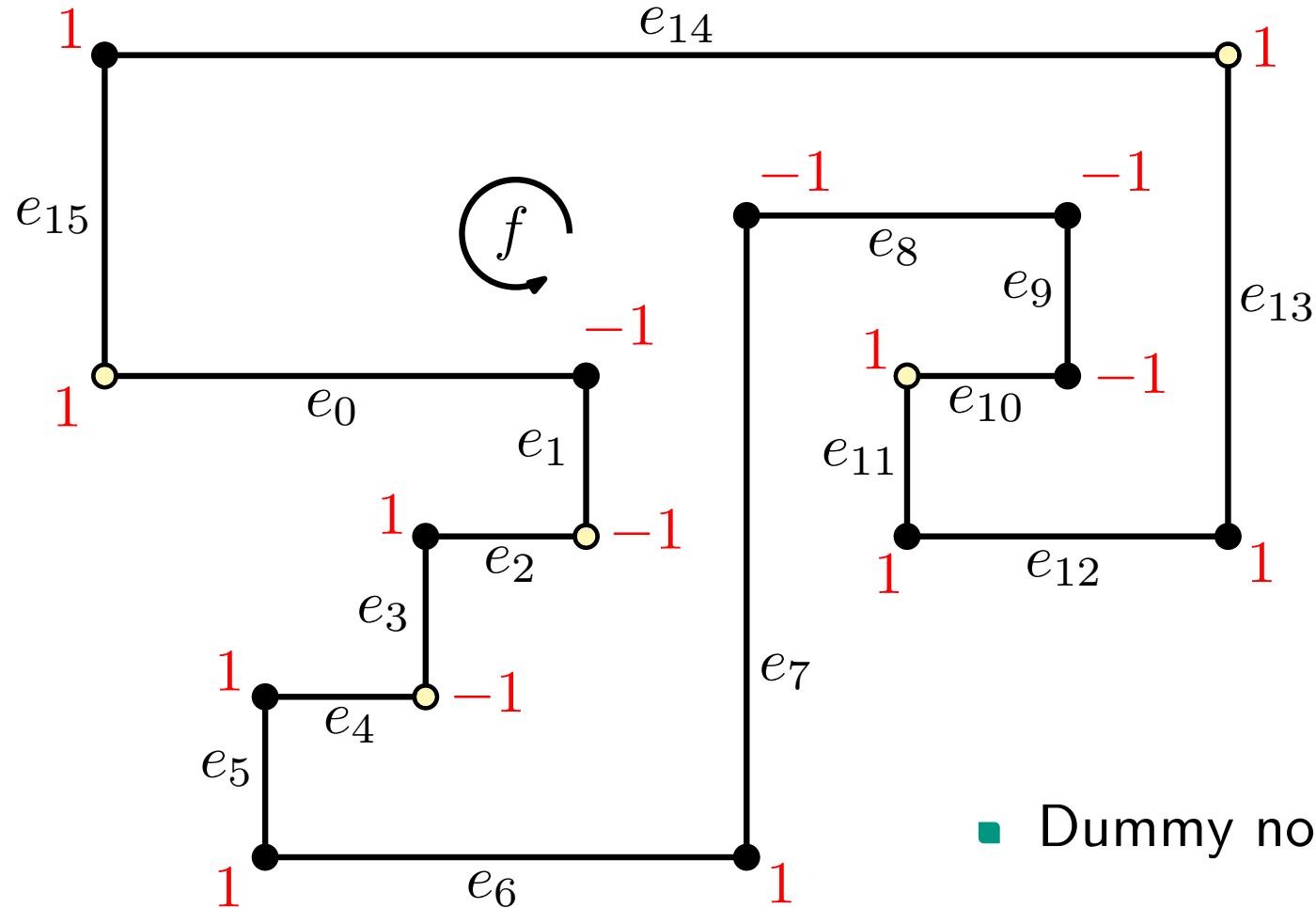
- Dummy nodes for bends

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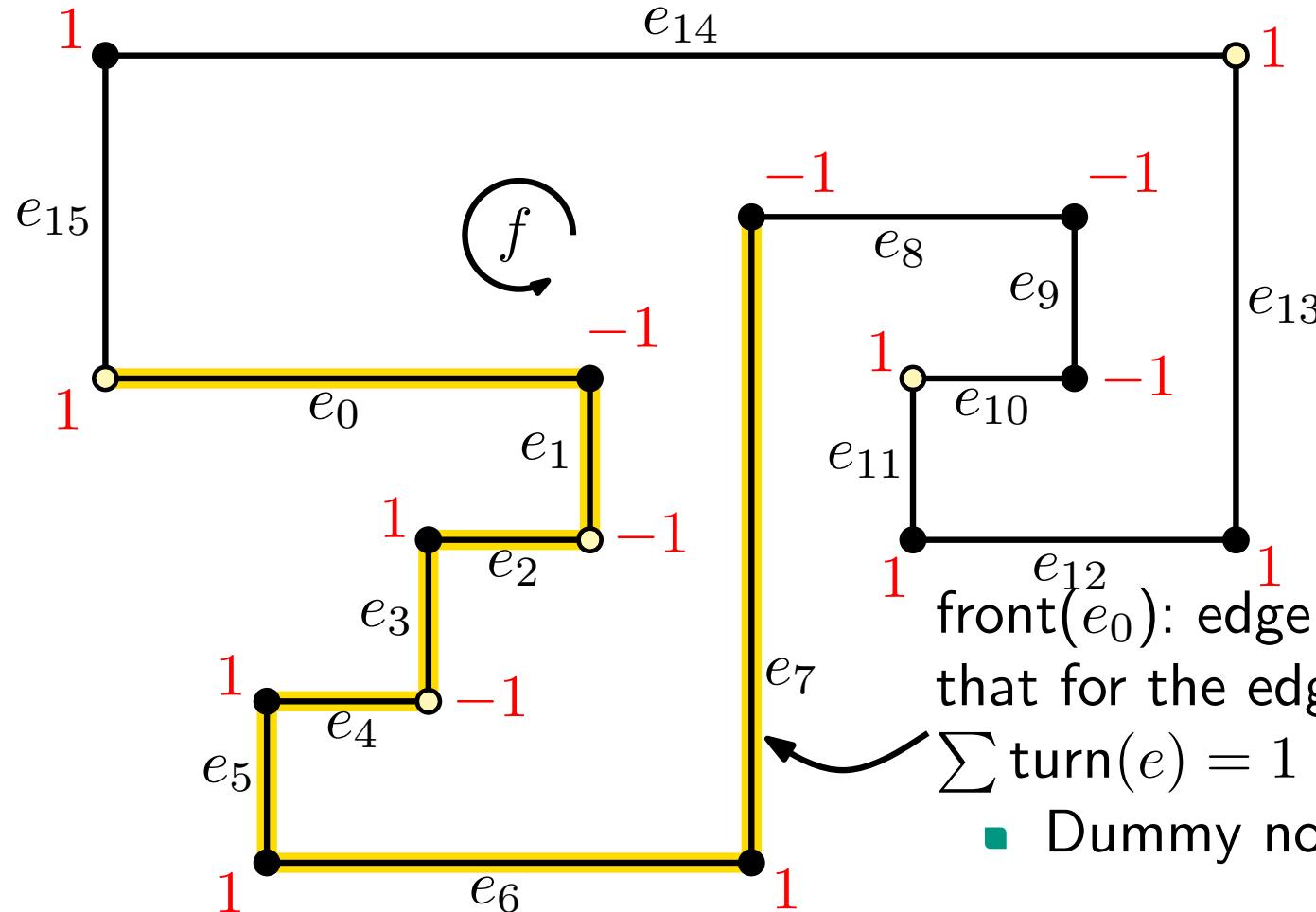
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Refinement of (G, H) – Inner Face



- Dummy nodes for bends
- $\text{turn}(e) = \begin{cases} 1 & \text{left bend} \\ 0 & \text{no bend} \\ -1 & \text{right bend} \end{cases}$

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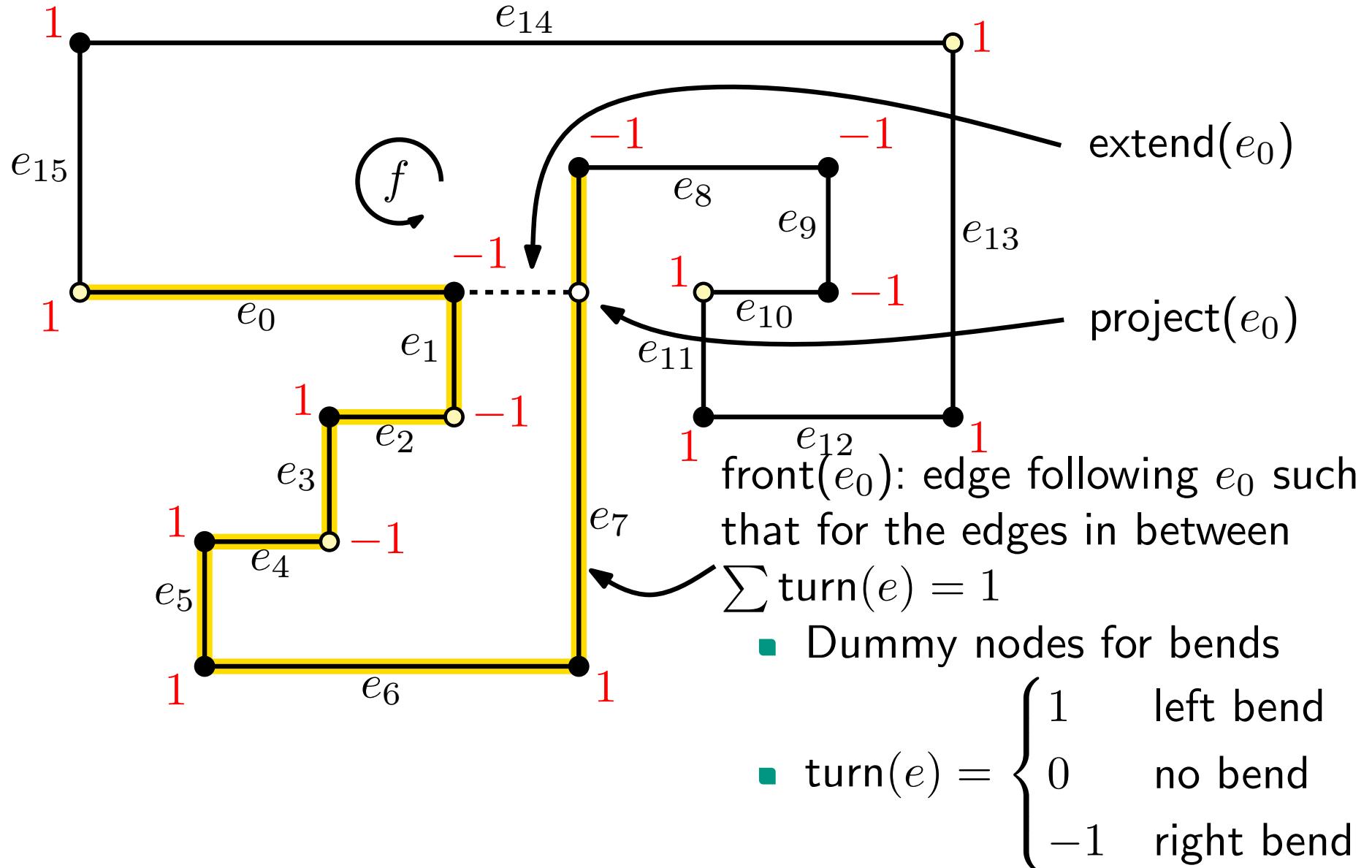
$\text{front}(e_0)$: edge following e_0 such that for the edges in between

$$\sum \text{turn}(e) = 1$$

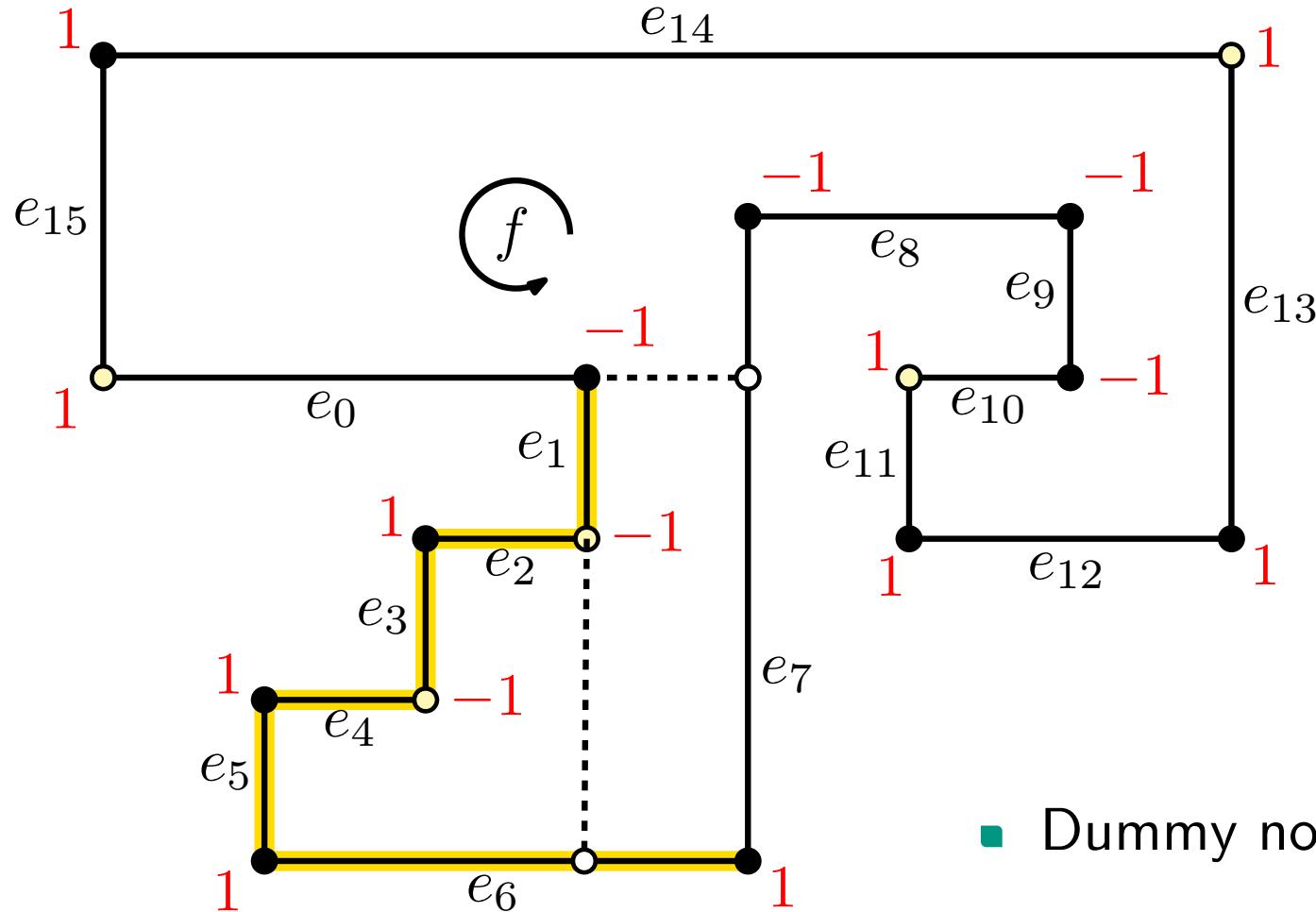
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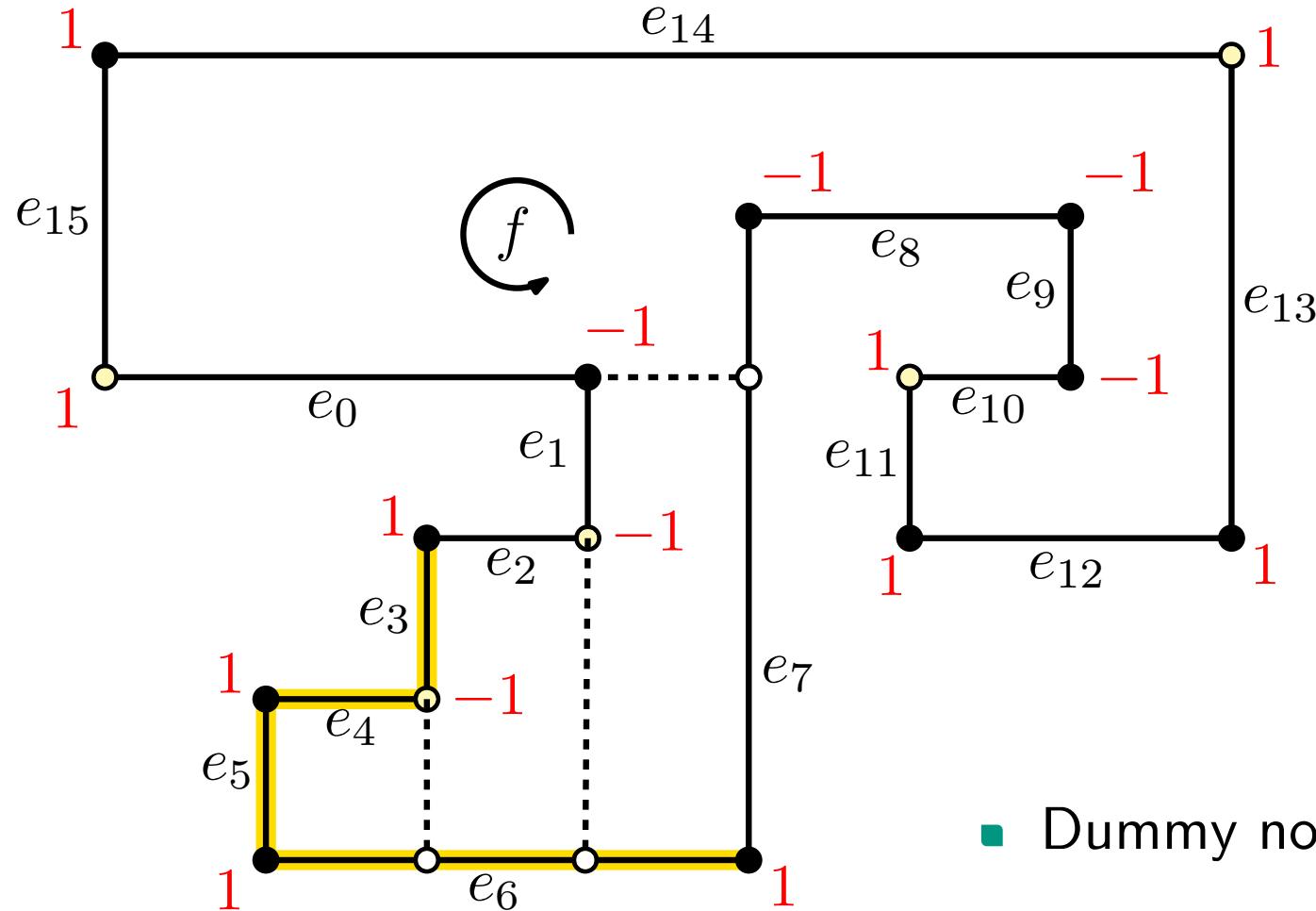


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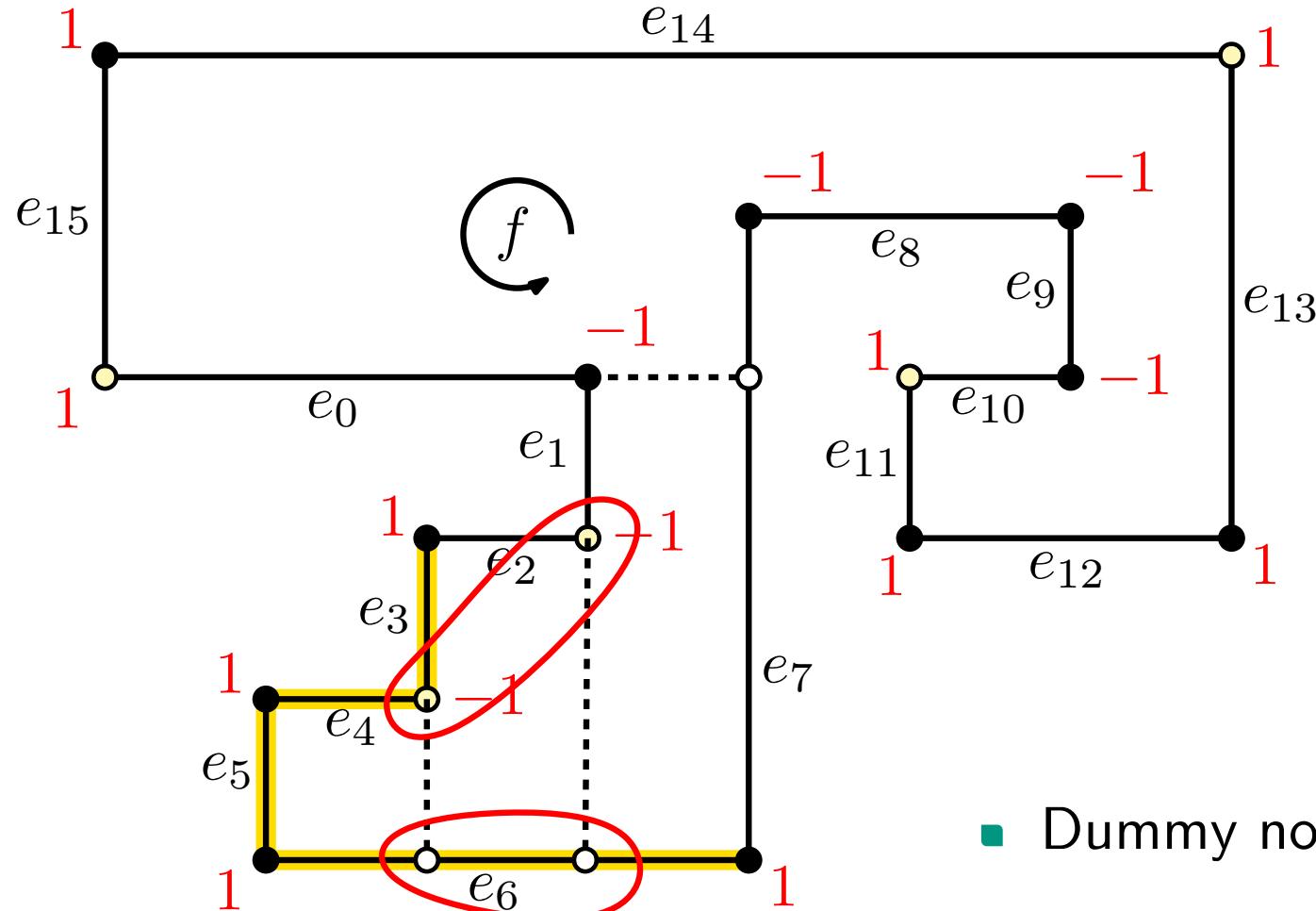
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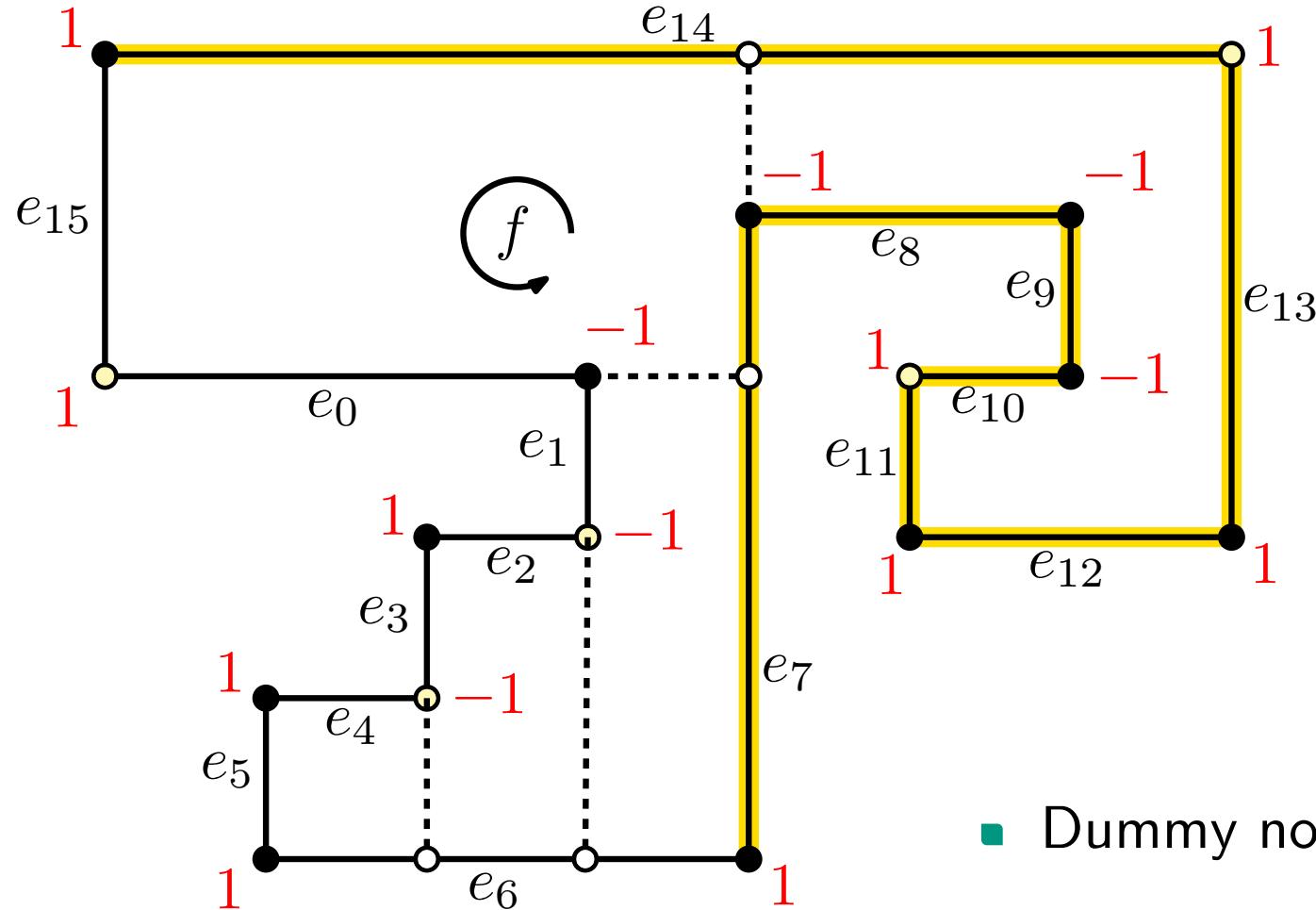
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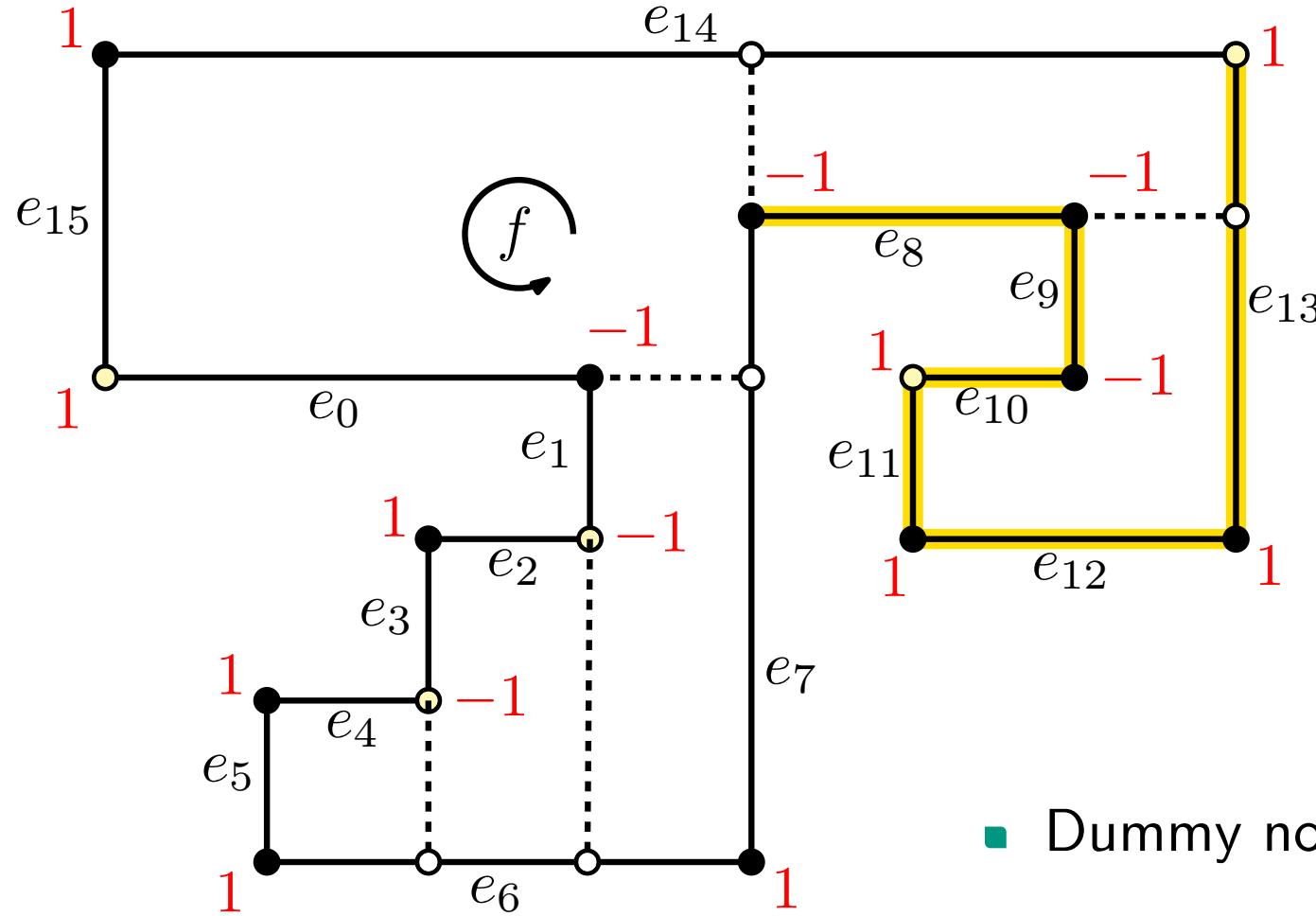
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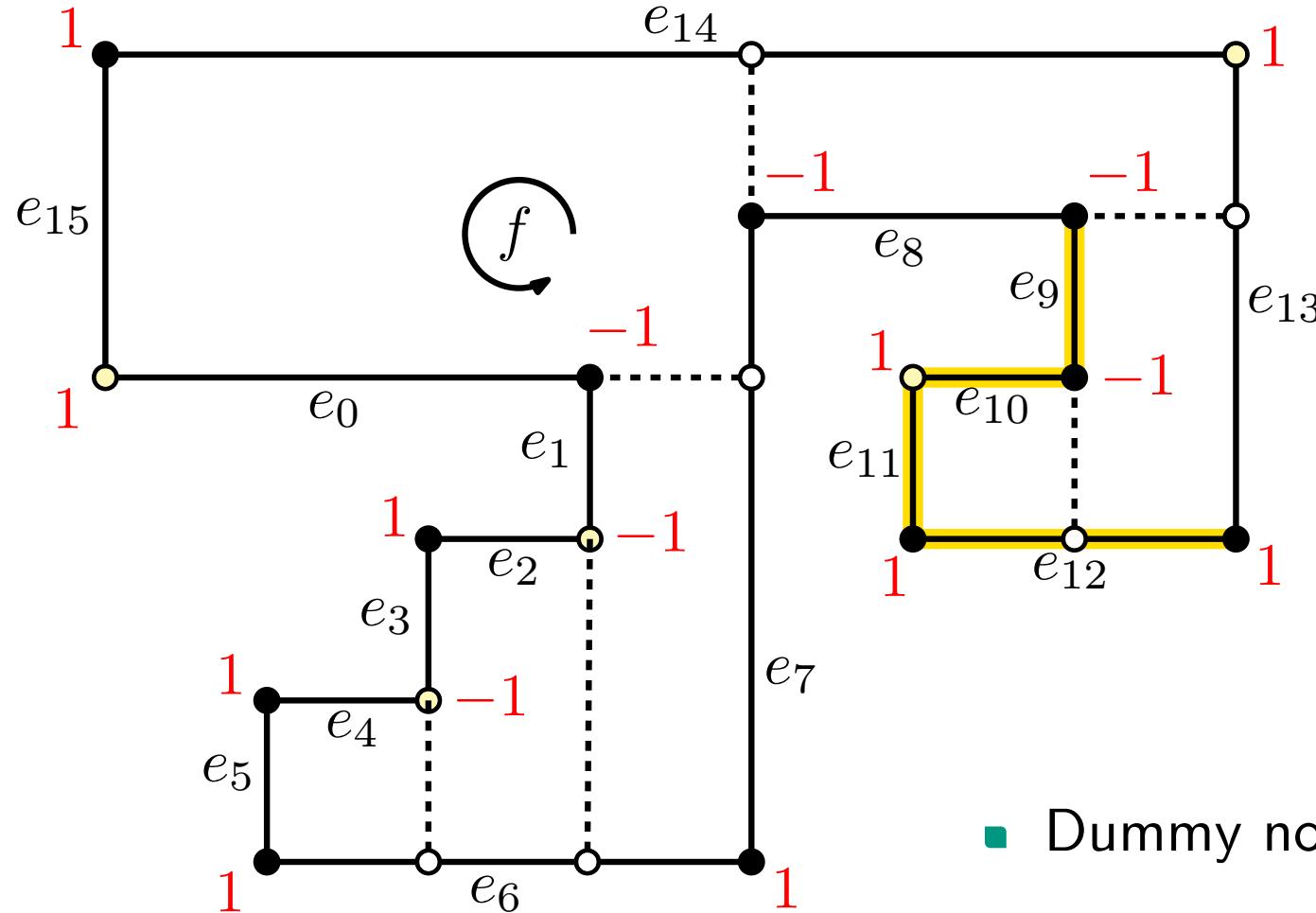
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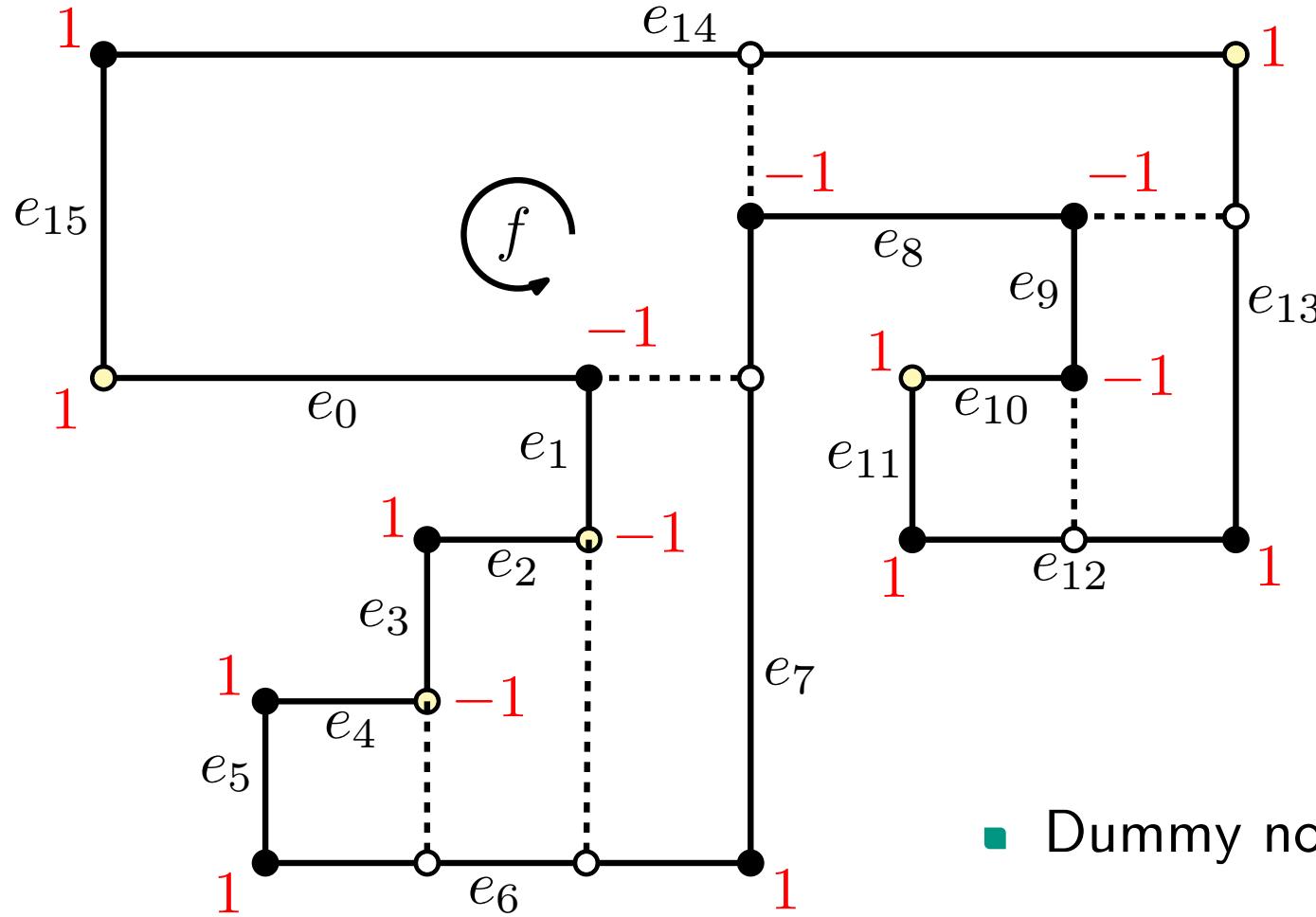
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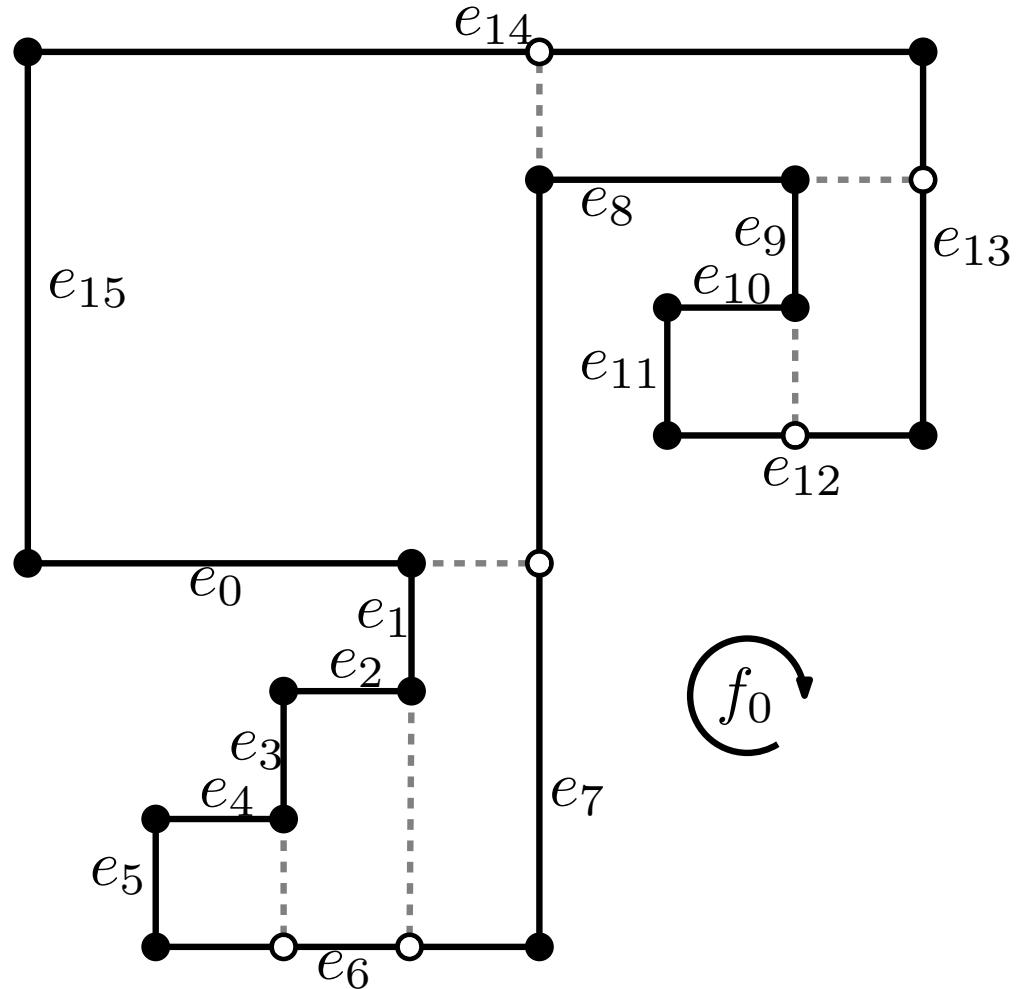
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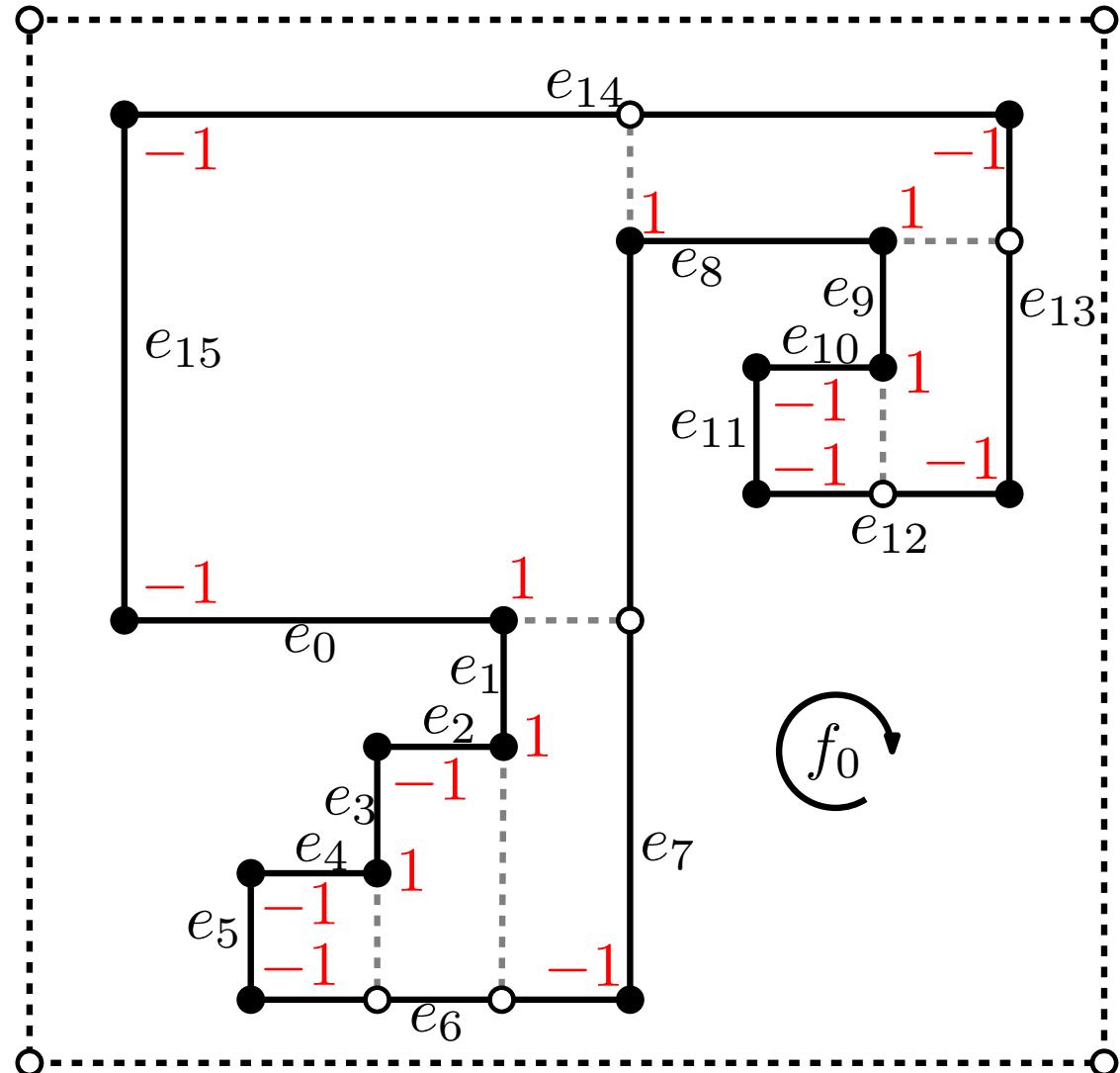


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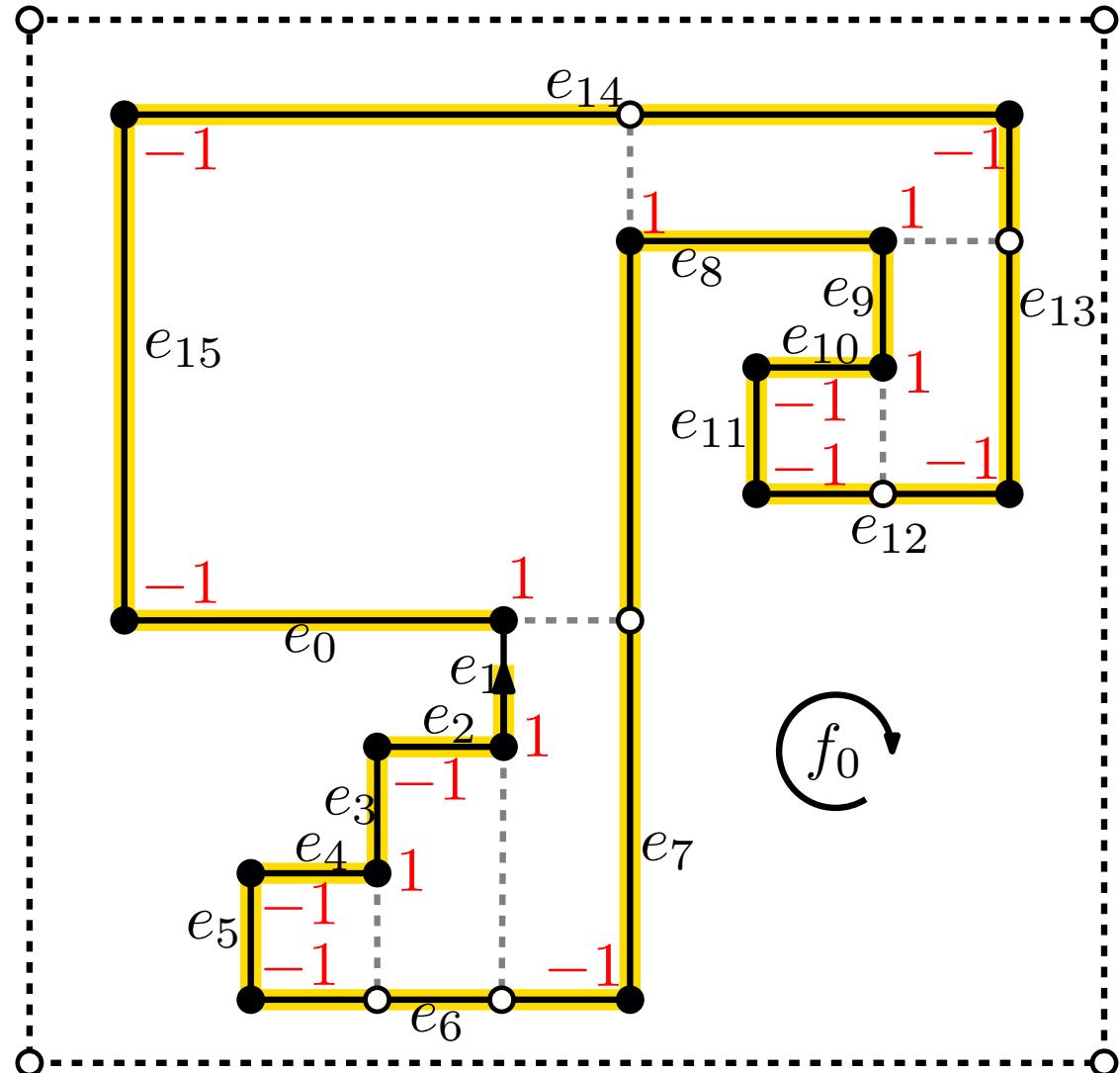
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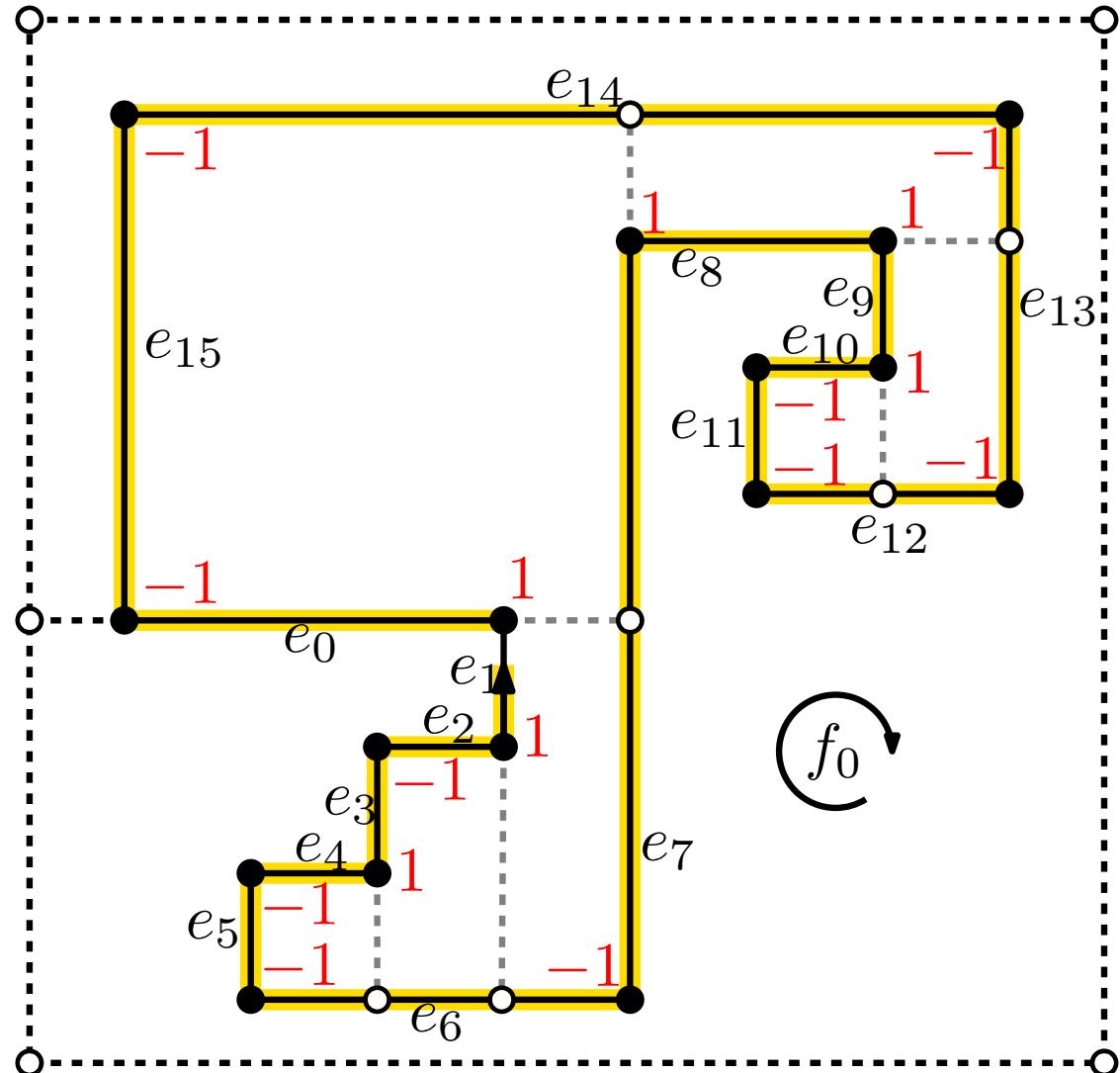
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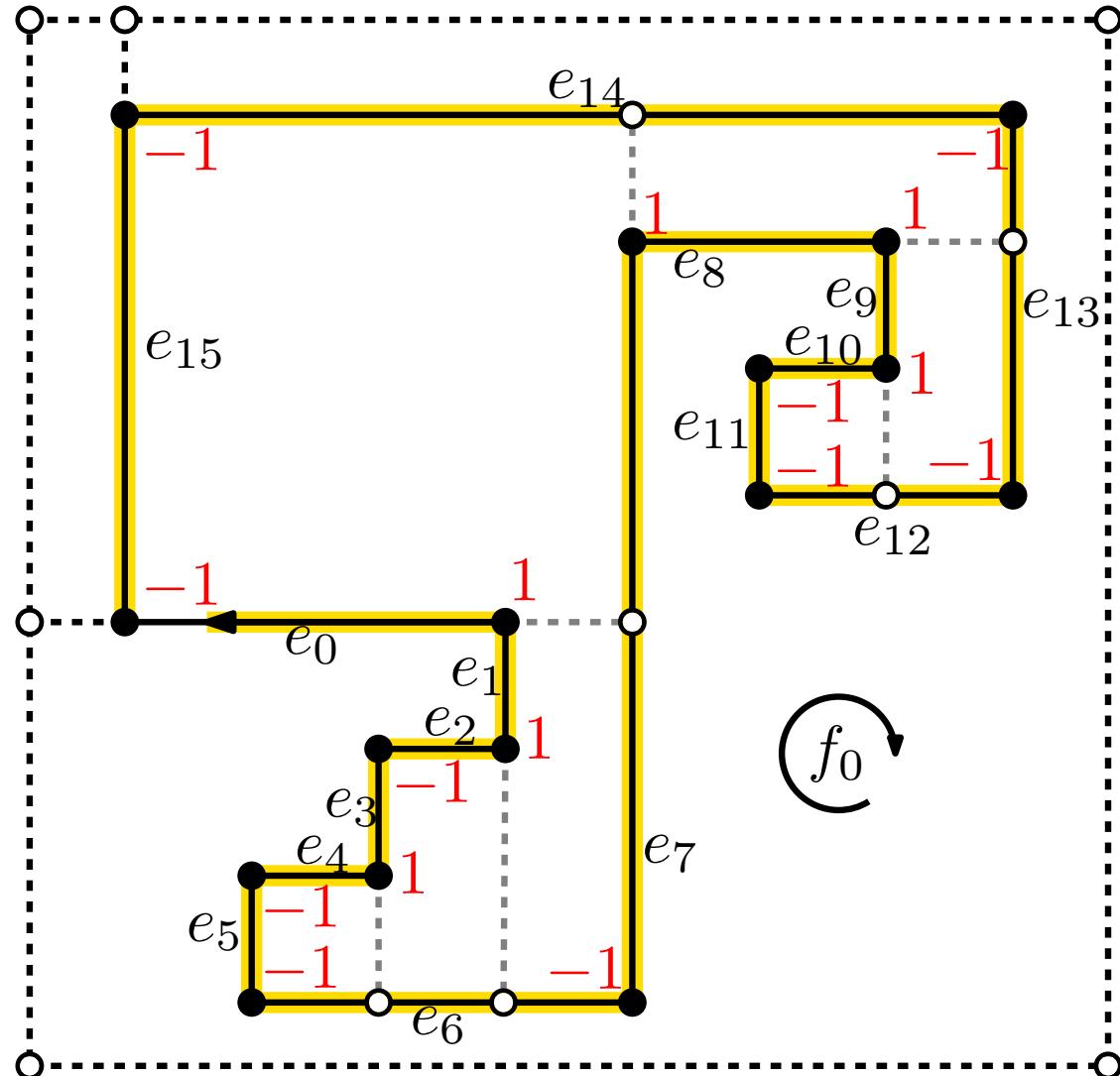
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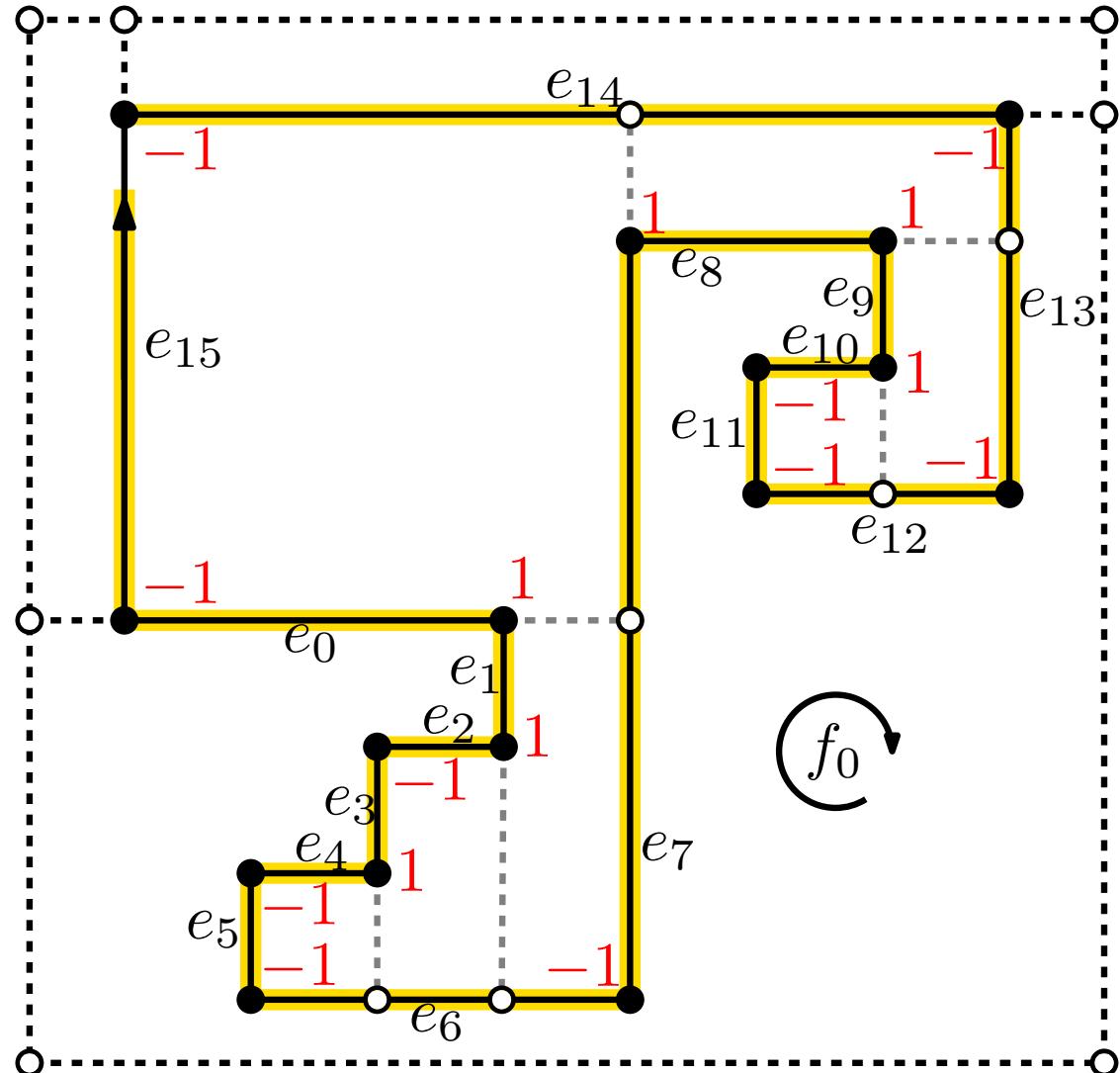
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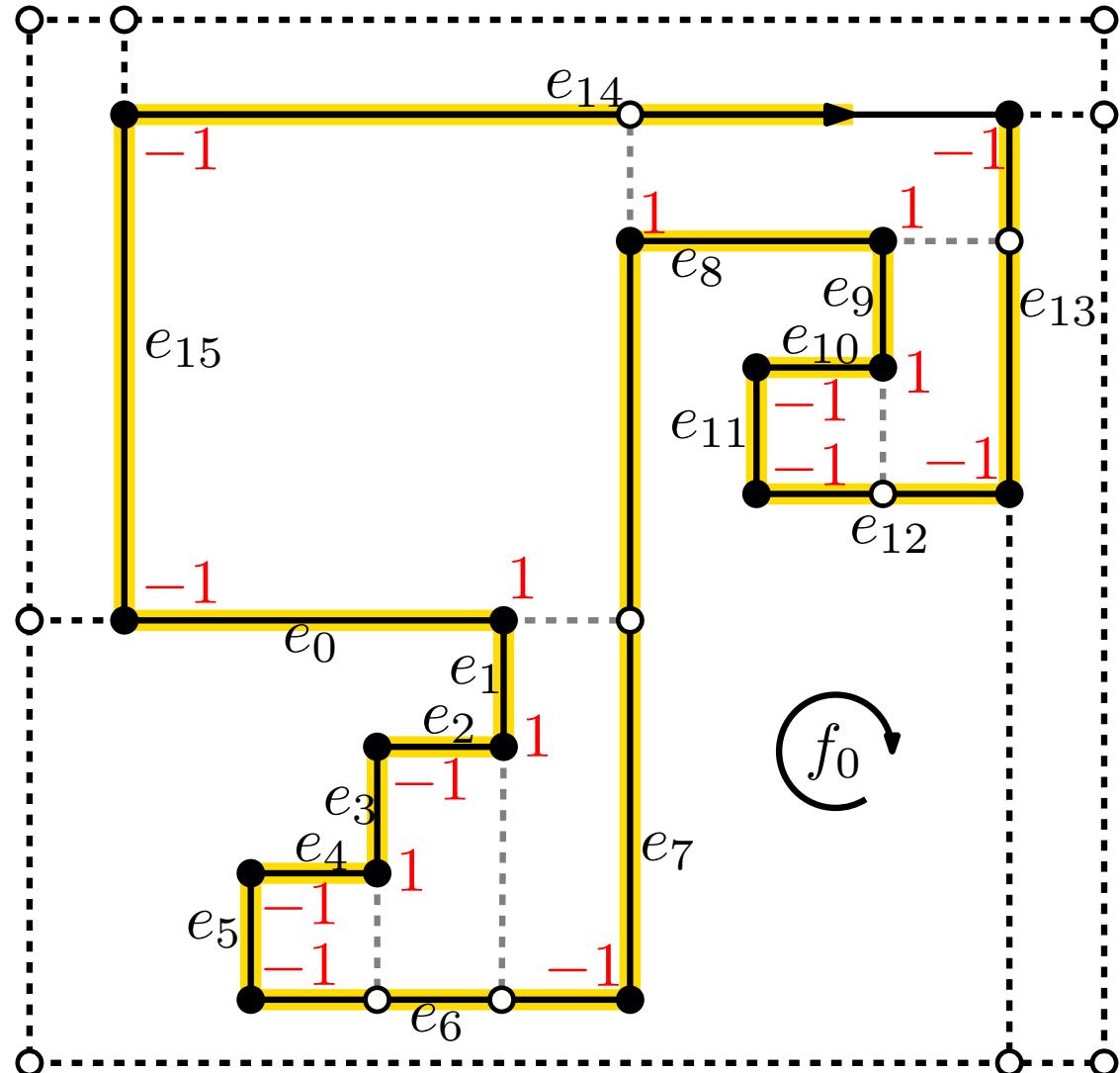
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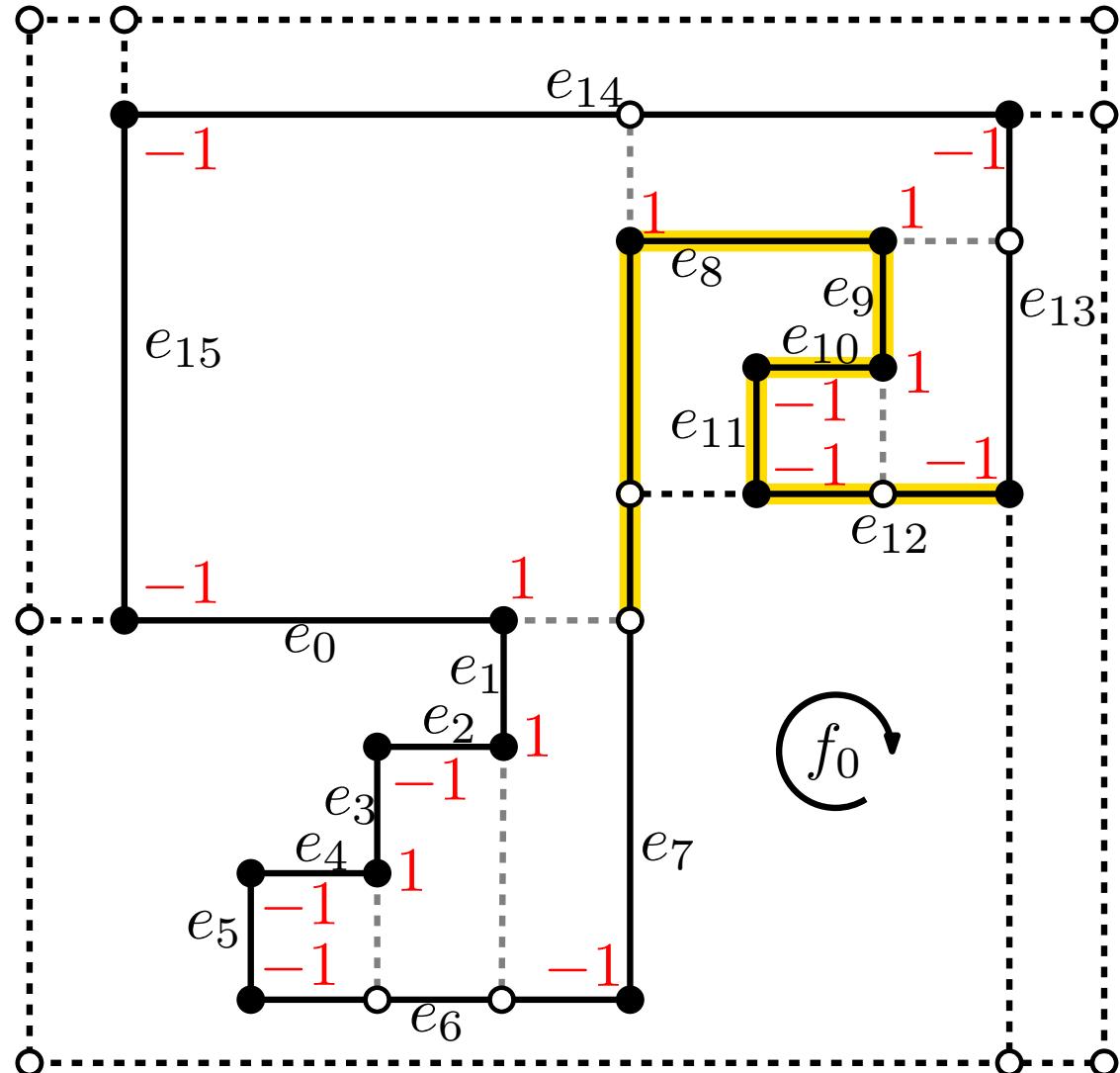
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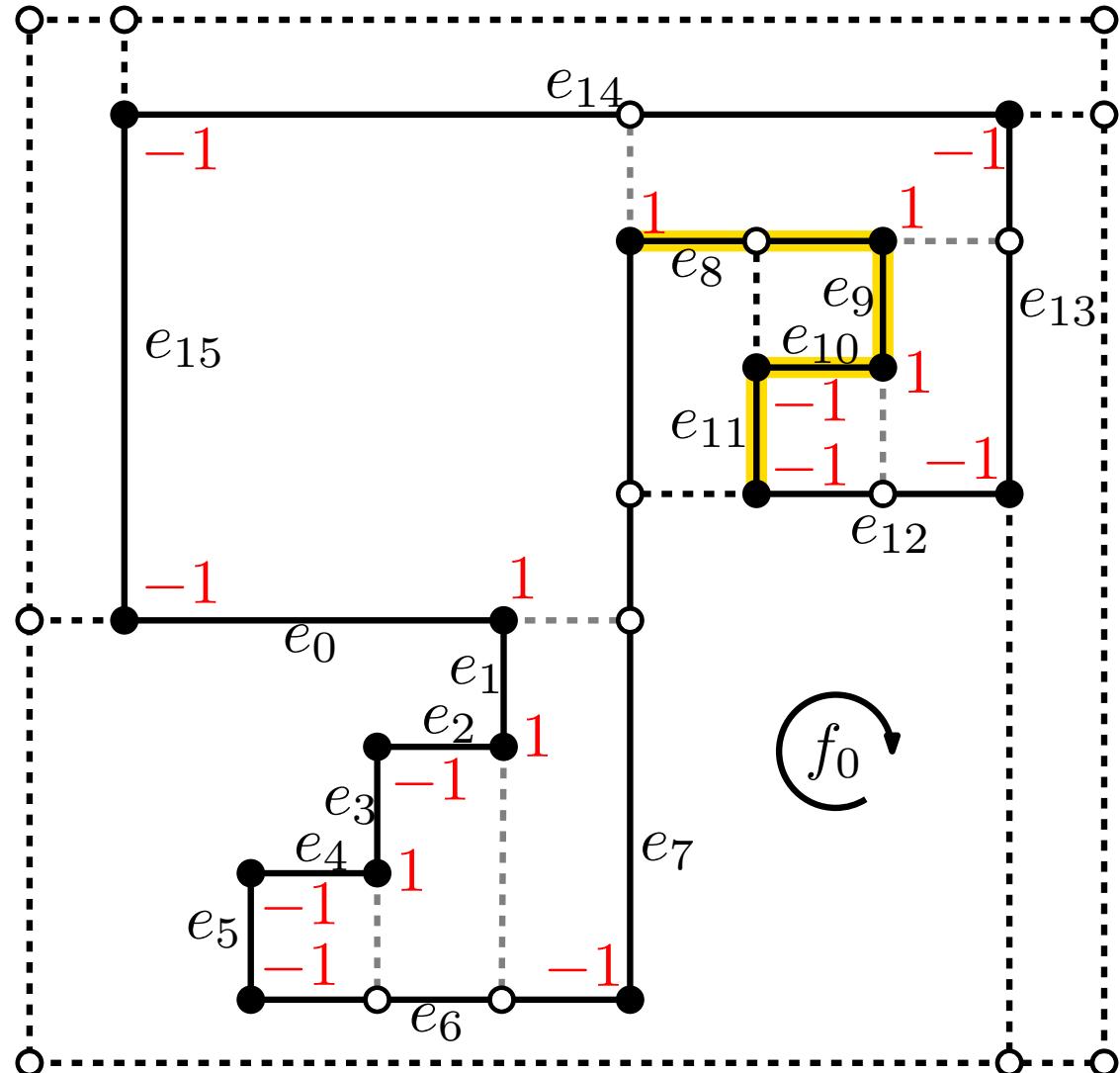
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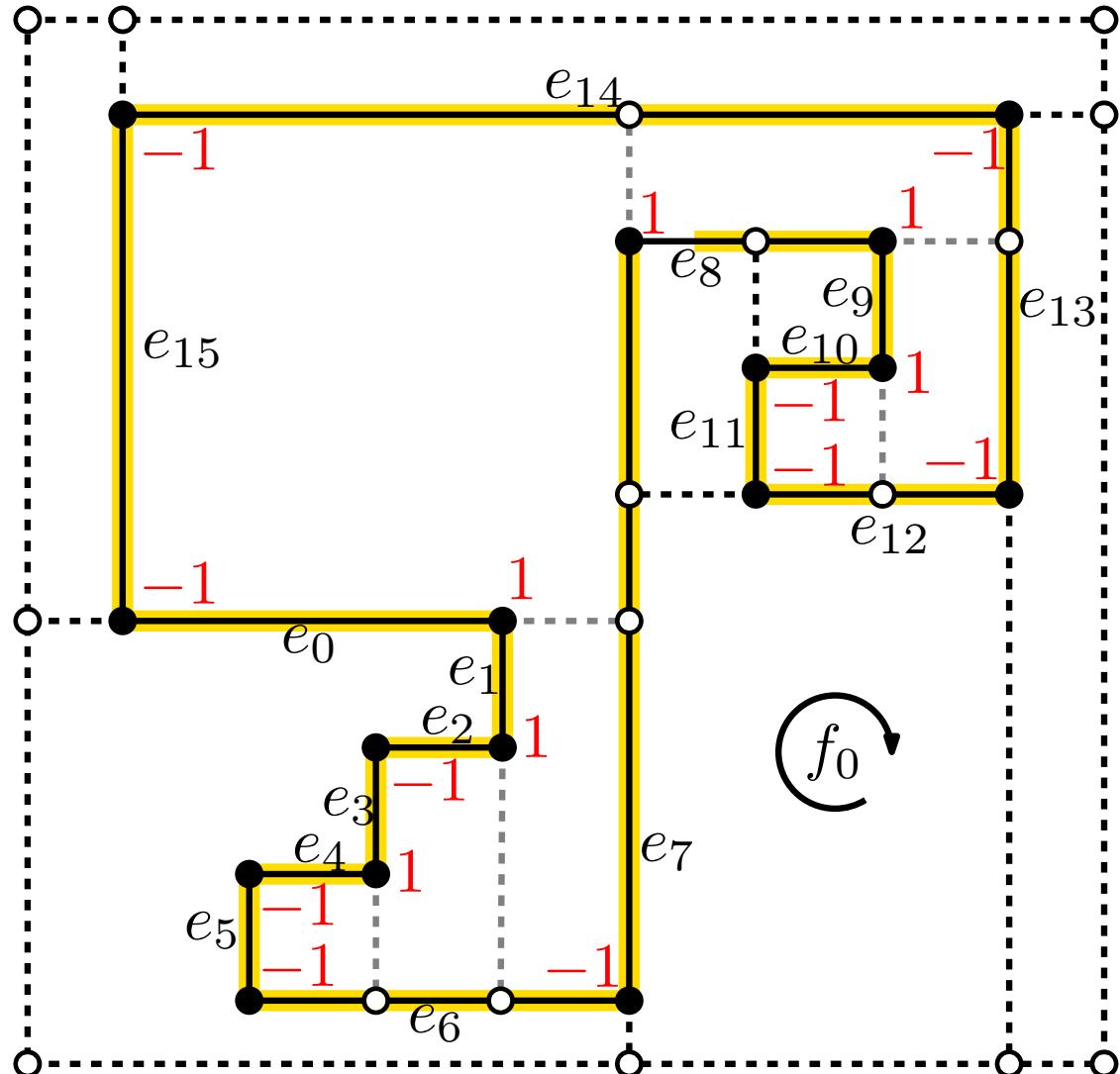
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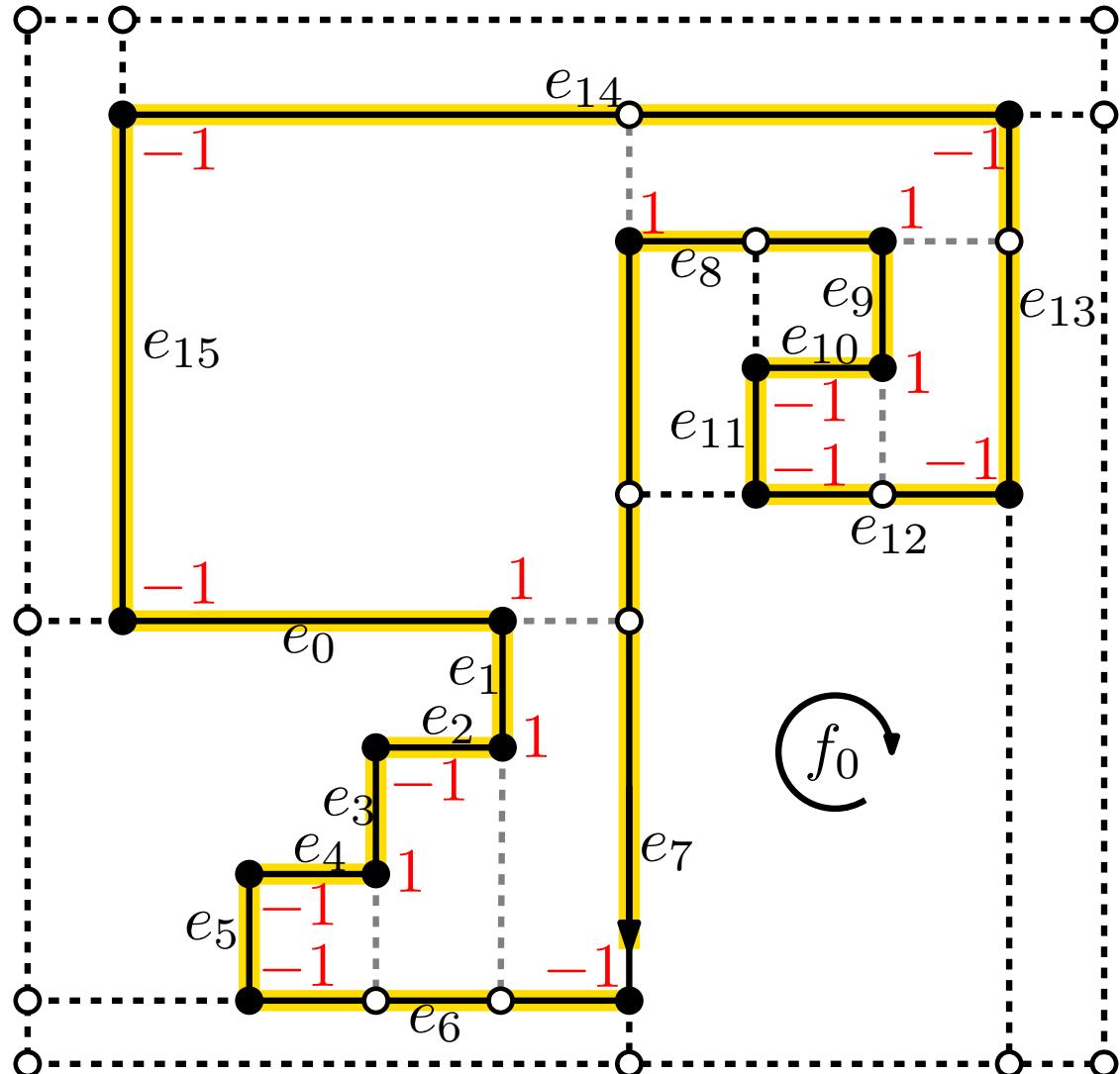
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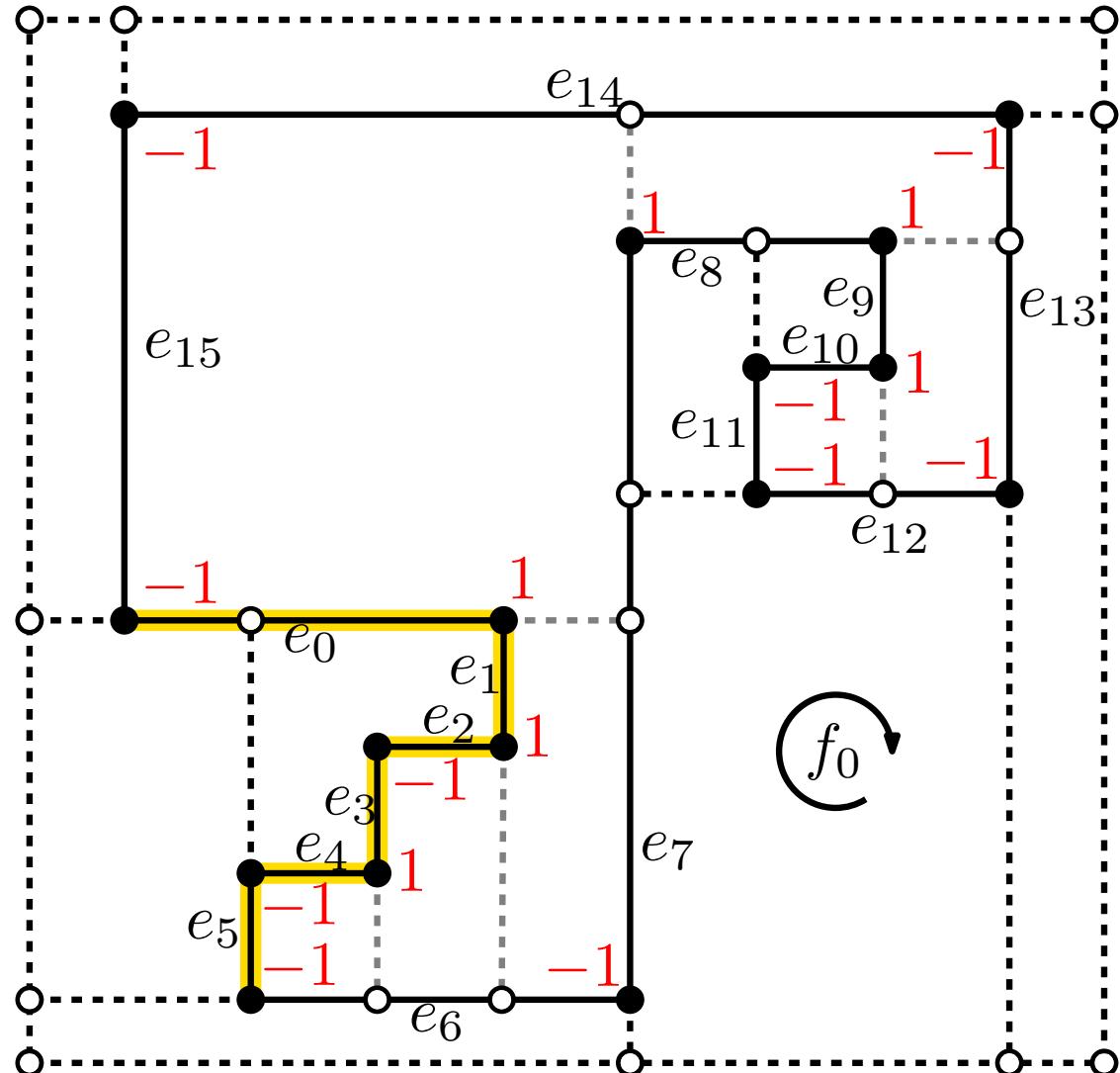
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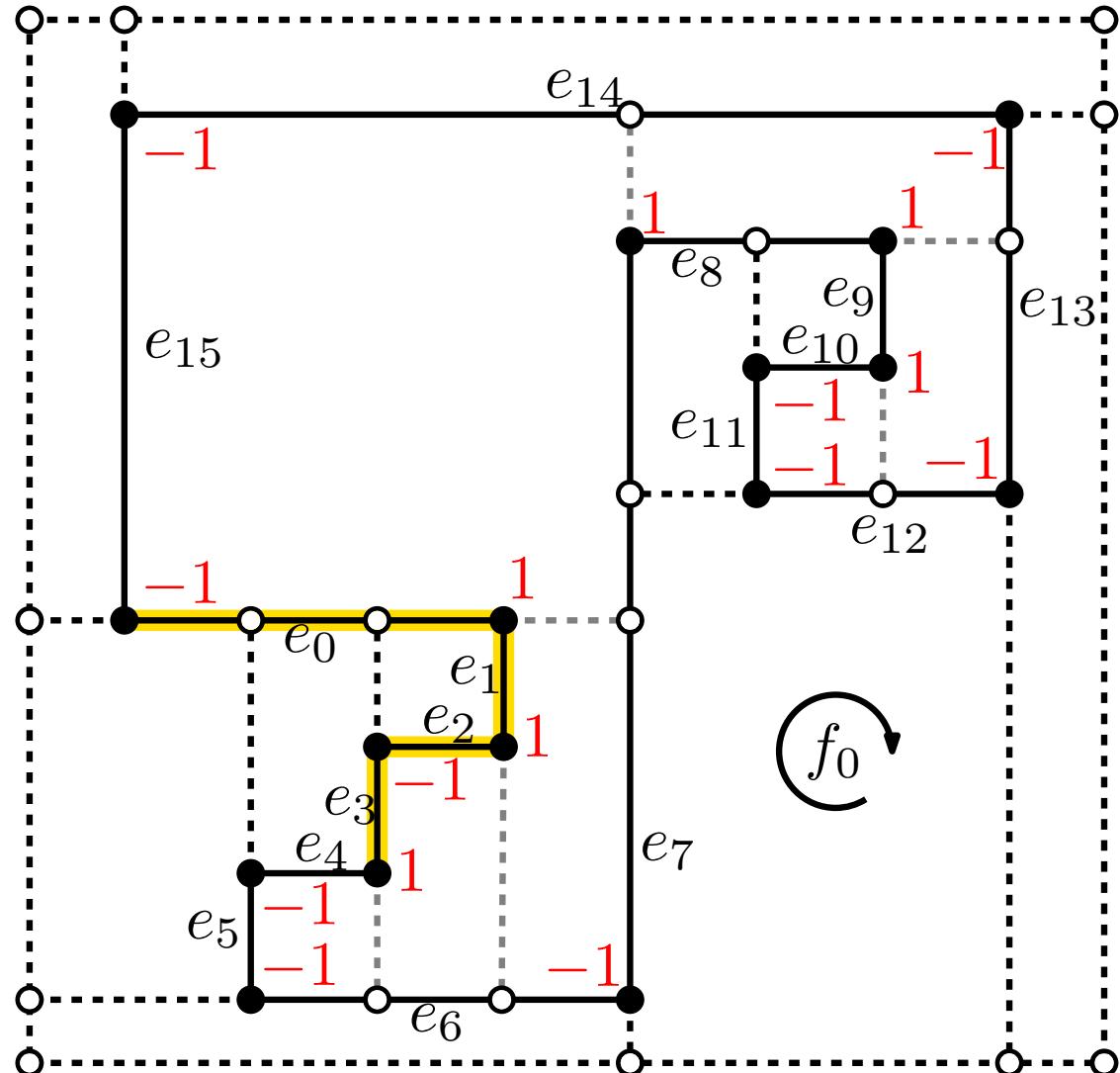
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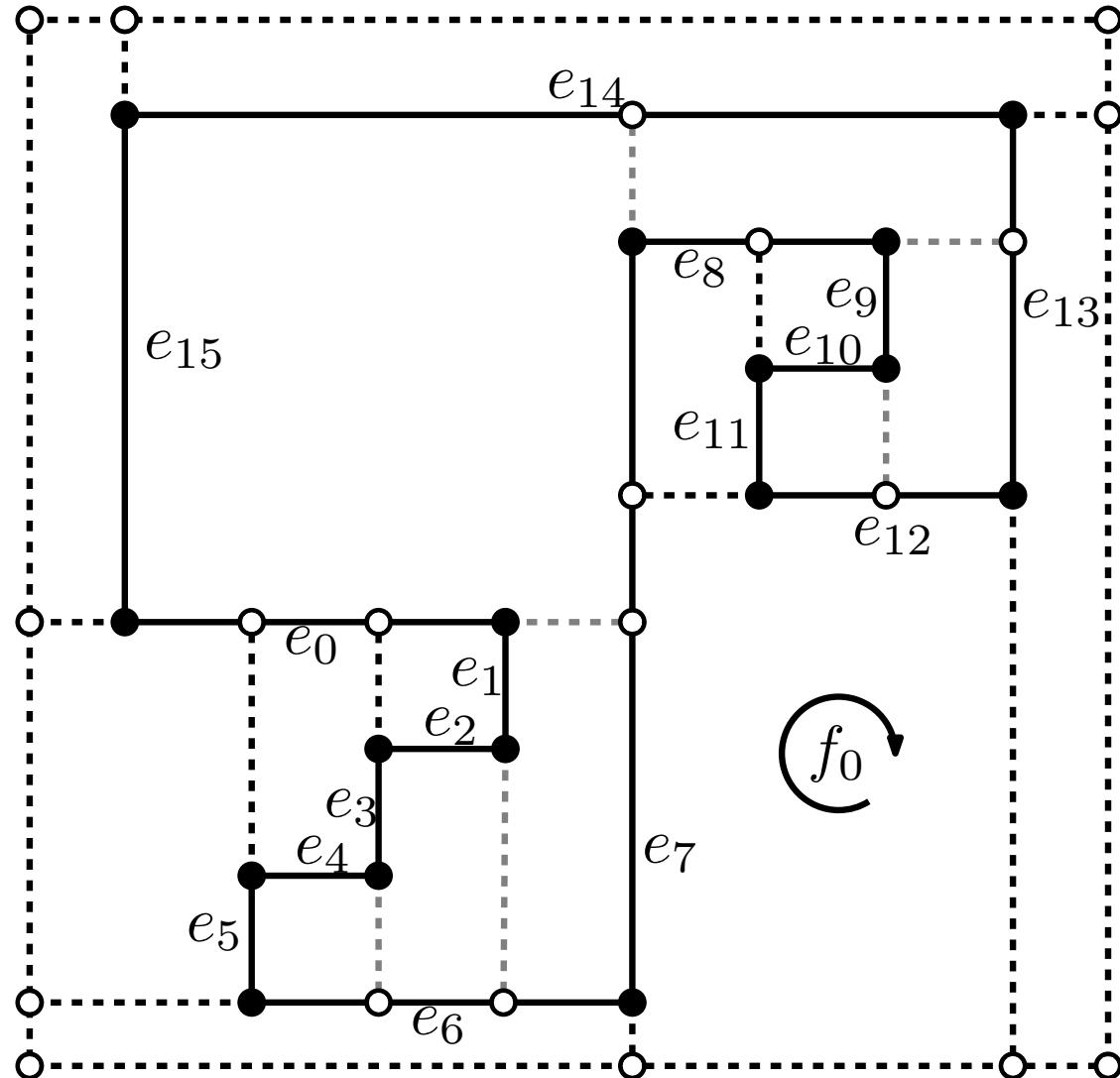
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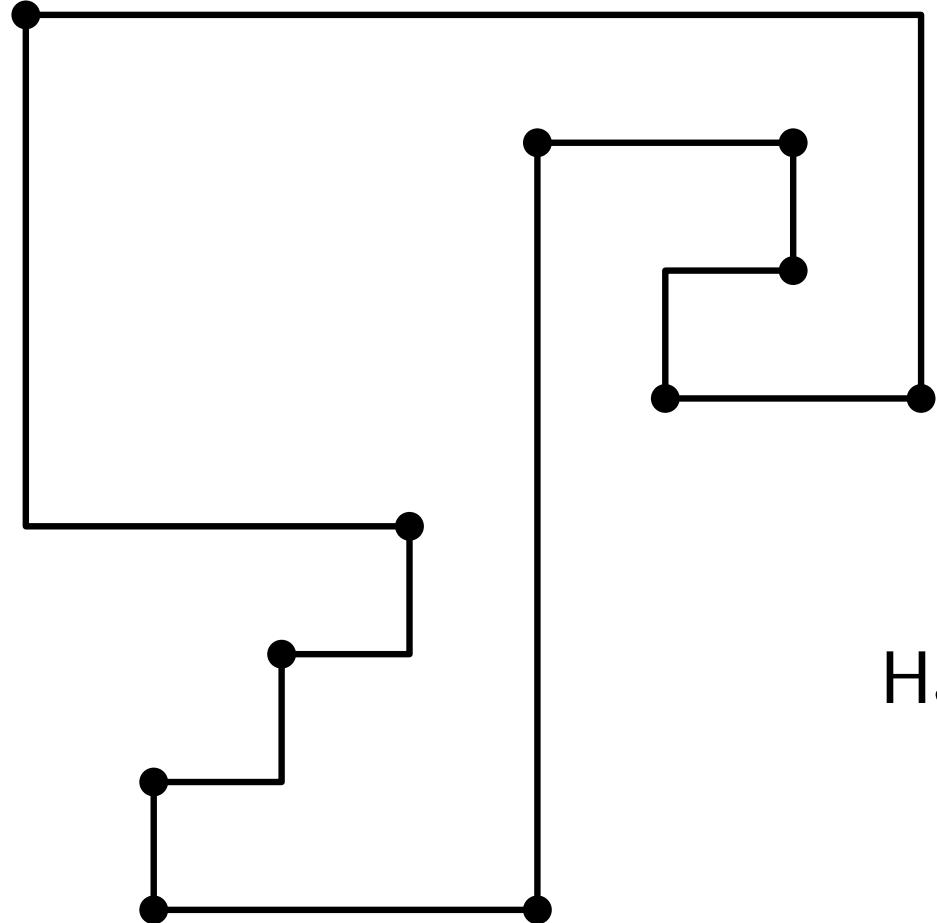
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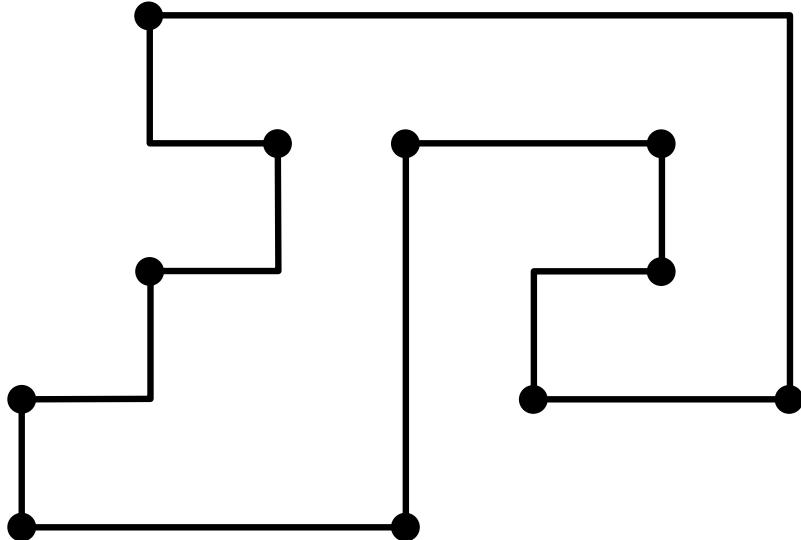
all faces are rectangles \rightarrow apply flow network

Refinement of (G, H) – Outer Face



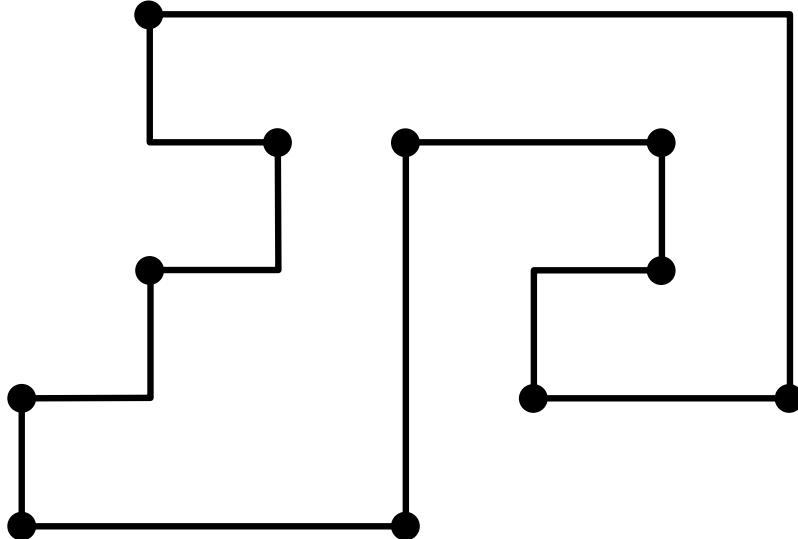
Has minimum area?

Refinement of (G, H) – Outer Face



Has minimum area?
NO!

Refinement of (G, H) – Outer Face



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Area Minimization with a given orthogonal representation is an
NP-hard problem!

Summary

- An orthogonal representation with minimum number of bends can be found in $O(n^{3/2})$ time
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- for non-planar graphs the area minimization is hard to approximate [Bannister, Eppstein, Simons JGAA 2012]

Upward Planar Drawings

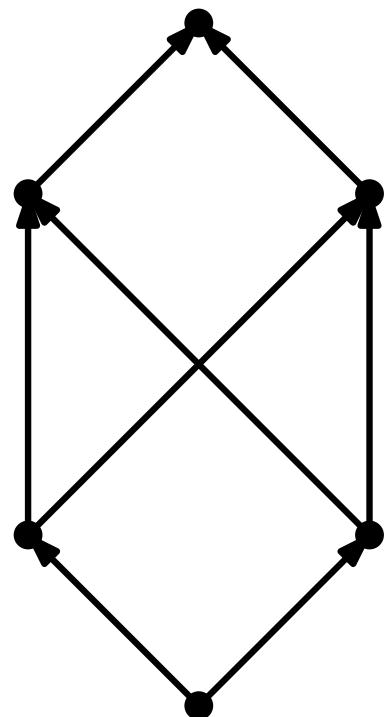
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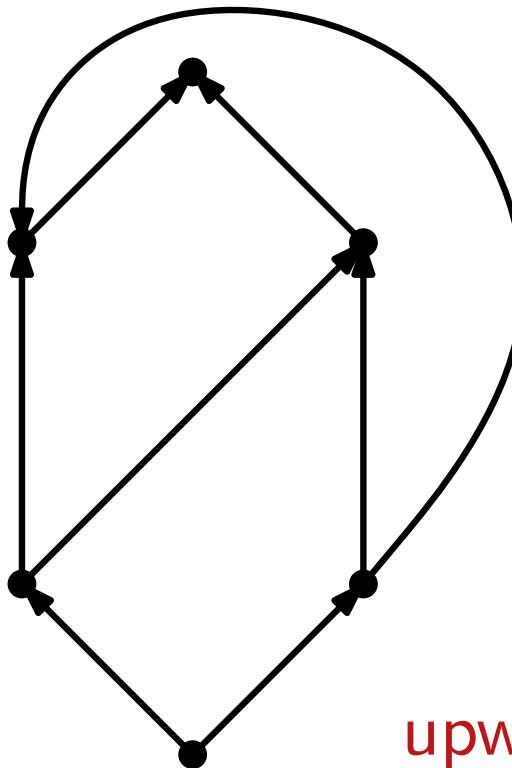
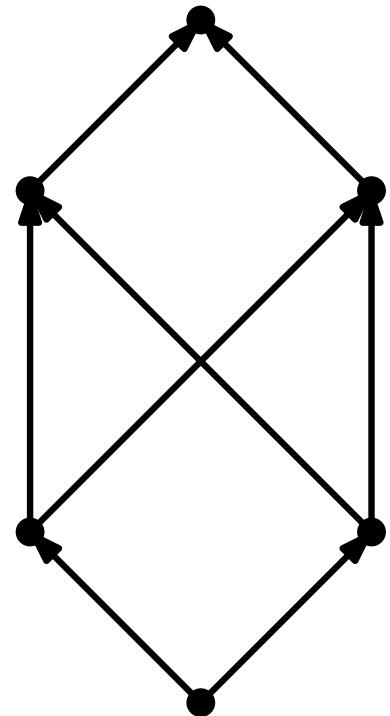
Example:



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Example:



planar!

upward planar? – NO!

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Thm 4: For a directed graph $D = (V, A)$ the following statements are equivalent:

1. D is upward planar
2. D admits an upward planar straight-line drawing
3. D is the spanning subgraph of a planar *st*-digraph

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- (3) \Rightarrow (2) triangulation and construction of straight-line drawing (blackboard)

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st-digraph: (i) single source s and sink t , (ii) edge $(s, t) \in E$

Proof:

- (2) \Rightarrow (1) obvious
- (1) \Leftrightarrow (3) simple augmentation of a layout (blackboard)
- (3) \Rightarrow (2) triangulation and construction of straight-line drawing (blackboard)

- Step (3) \Rightarrow (2) implies a $O(n)$ algorithm to construct a planar straight-line drawing of an *st*-digraph.

Characterization

Thm 4: For a directed graph $D = (V, A)$ the following statements are equivalent:

1. D is upward planar
2. D admits an upward planar straight-line drawing
3. D is the spanning subgraph of a planar *st*-digraph

[Di Battista, Tamassia TCS 1988]

st-digraph: (i) single source s and sink t , (ii) edge $(s, t) \in E$

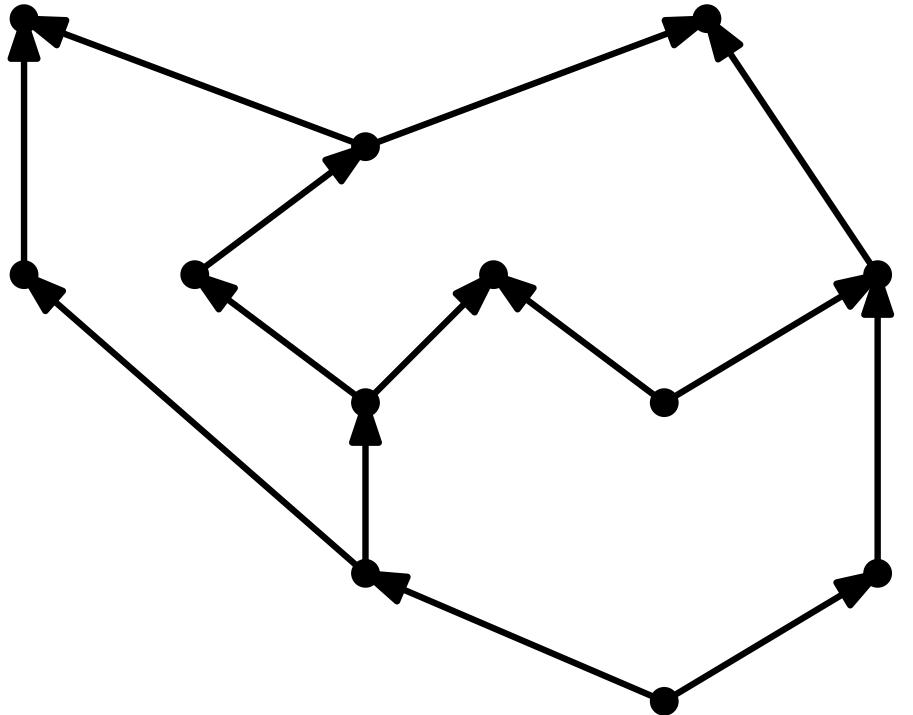
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- May have exponential area. There are examples where this is unavoidable (see Lecture 3).

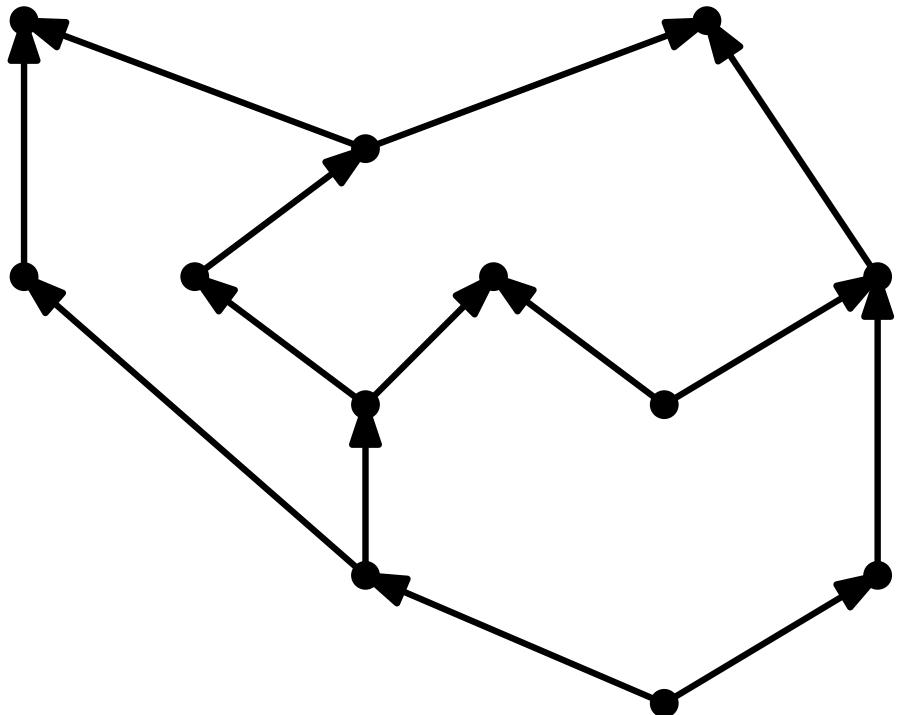
Fixed Outer Face: Angles

Problem: Consider a directed acyclic graph $D = (V, A)$ with embedding \mathcal{F}, f_0 . Test whether D, \mathcal{F}, f_0 is upward planar and construct corresponding drawing.

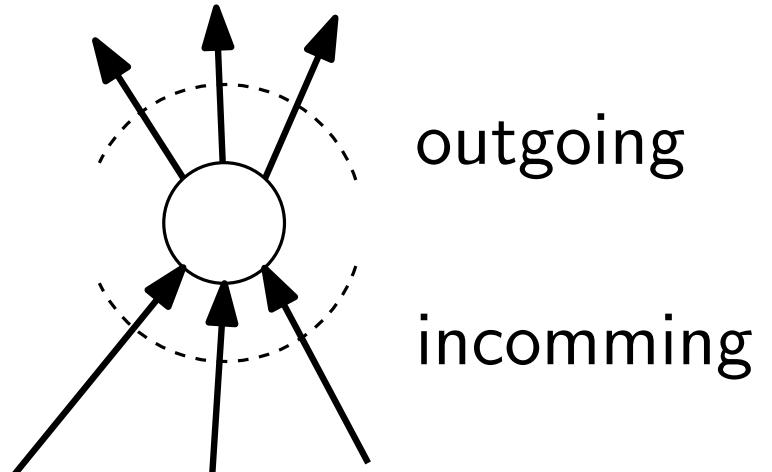


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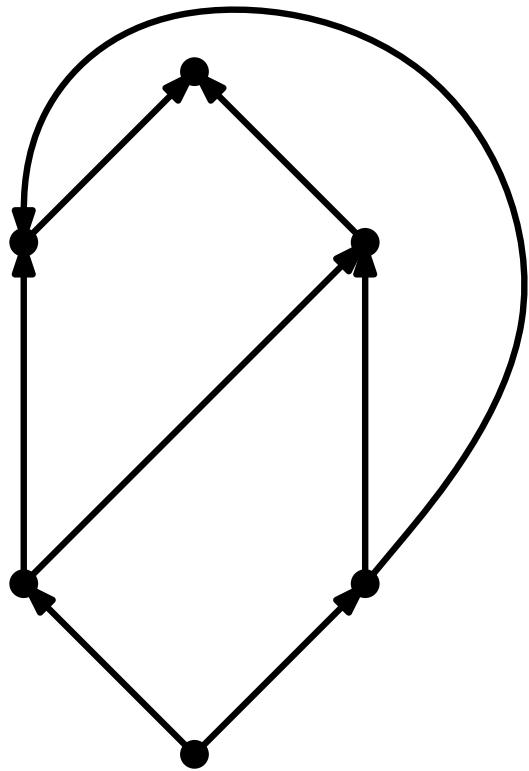


Embedding is **bimodal**
if for each node:



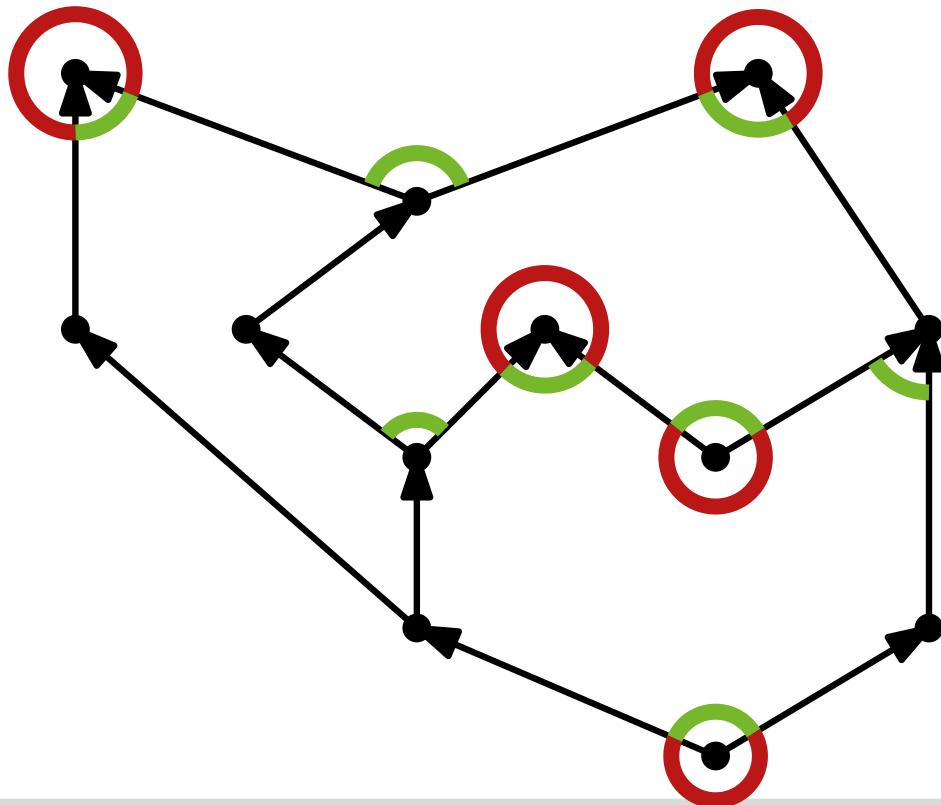
Fixed Outer Face: Observations

- Bimodality is necessary but not sufficient



Fixed Outer Face: Observations

- Bimodality is necessary but not sufficient
- measure angles between two incomming/outgoing edges
Angle α is **large** when $\alpha > \pi$, **small** otherwise
 $L(v) := \#$ large angles at node v
 $L(f) := \#$ large angles in face f
 $S(v)$ resp. $S(f)$: $\#$ **small** angles



Fixed Outer Face: Observations

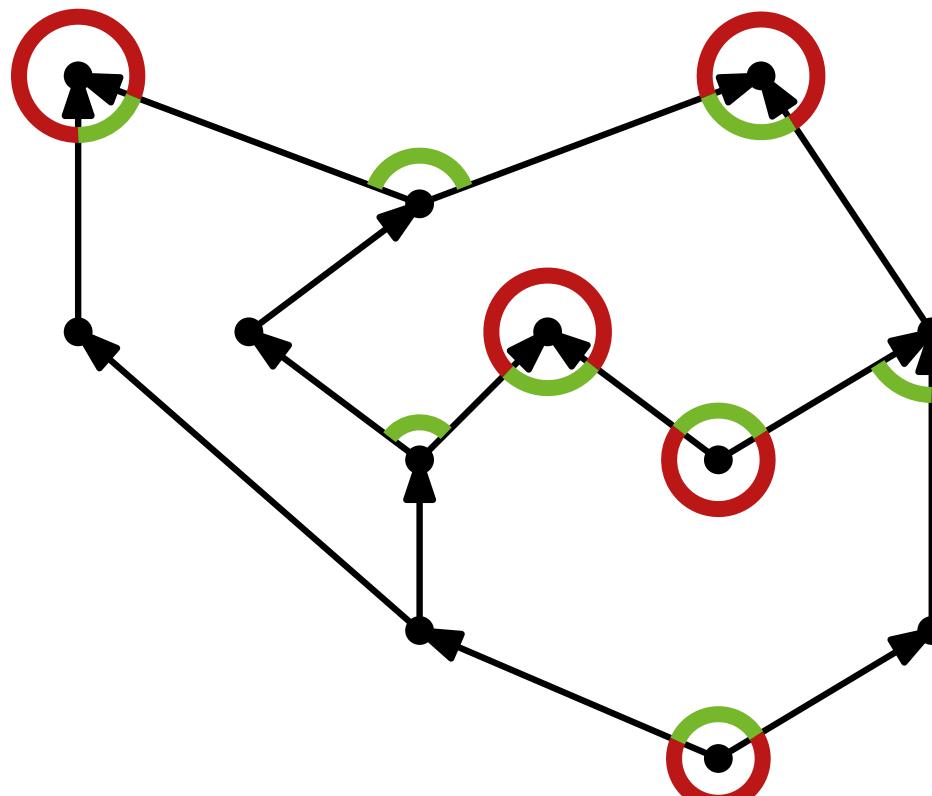
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Lemma 1: In any upward layout of D holds:

$$(1) \forall v \in V : L(v) = \begin{cases} 0 & v \text{ non source/sink} \\ 1 & v \text{ source/sink} \end{cases}$$

$$(2) \forall f \in \mathcal{F} : L(f) - S(f) = \begin{cases} -2 & f \neq f_0 \\ 2 & f = f_0 \end{cases}$$

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Fixed Outer Face: Observations

- $A(f) := \# \text{ sources in face } f$ (equal to the number of sinks)
It holds that: $L(f) + S(f) = 2A(f)$ for all faces.
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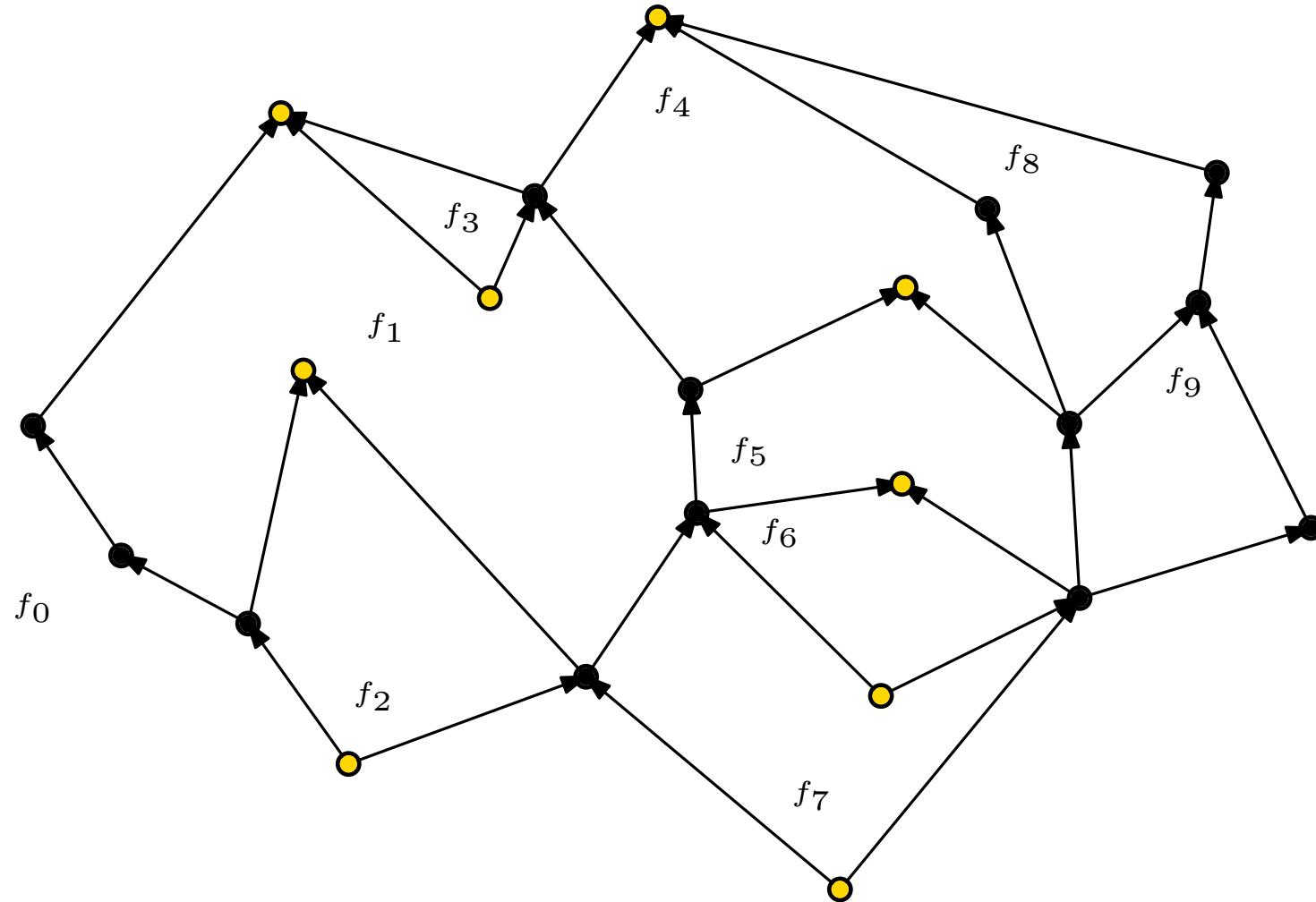
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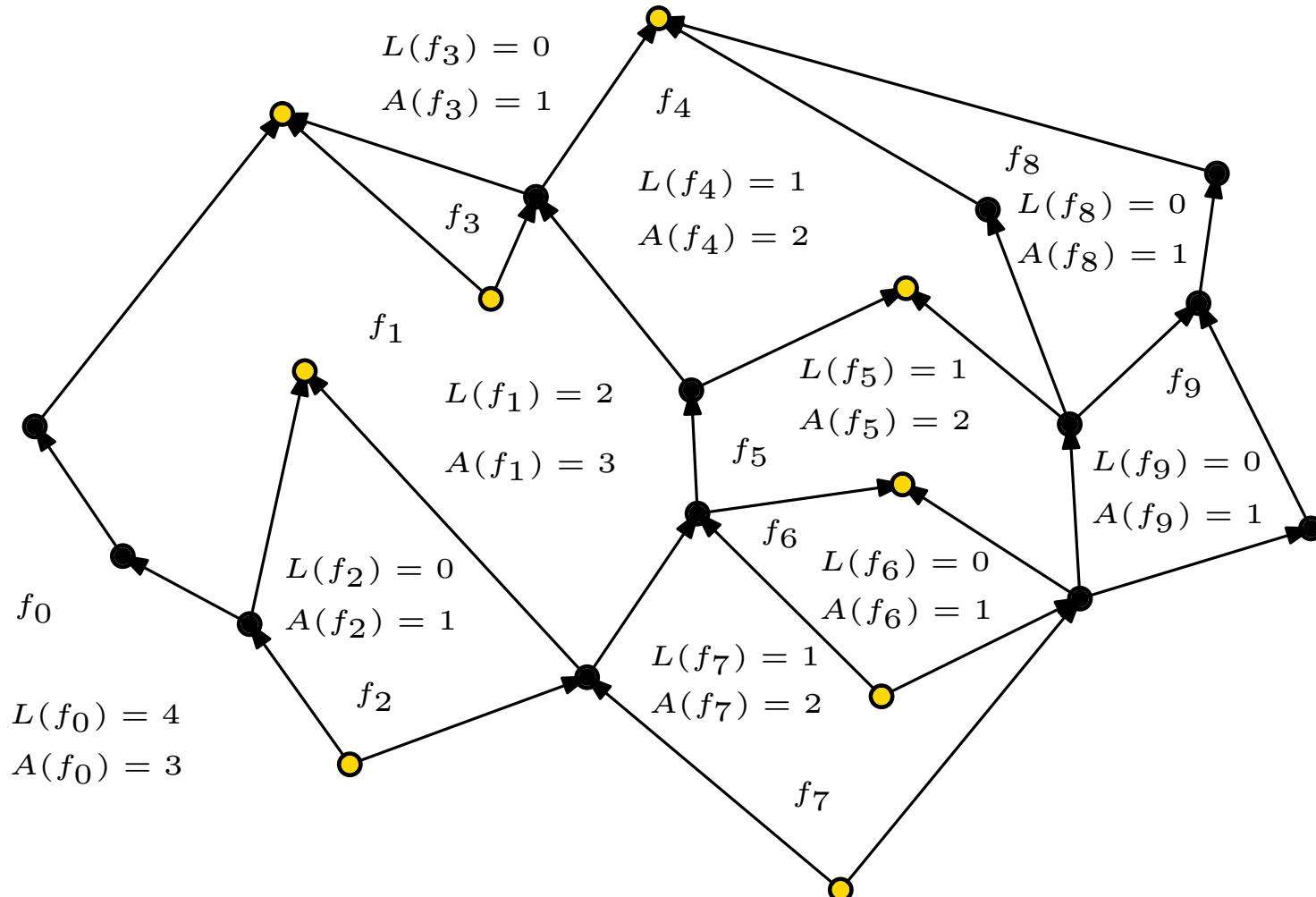
- Define assignment $\Phi : S \cup T \rightarrow \mathcal{F}$
(S set of sources, T sinks), where
 $\Phi : v \mapsto$ incident face, where v forms large angle

- Φ is called **consistent**, if: $|\Phi^{-1}(f)| = \begin{cases} A(f) - 1 & f \neq f_0 \\ A(f) + 1 & f = f_0 \end{cases}$

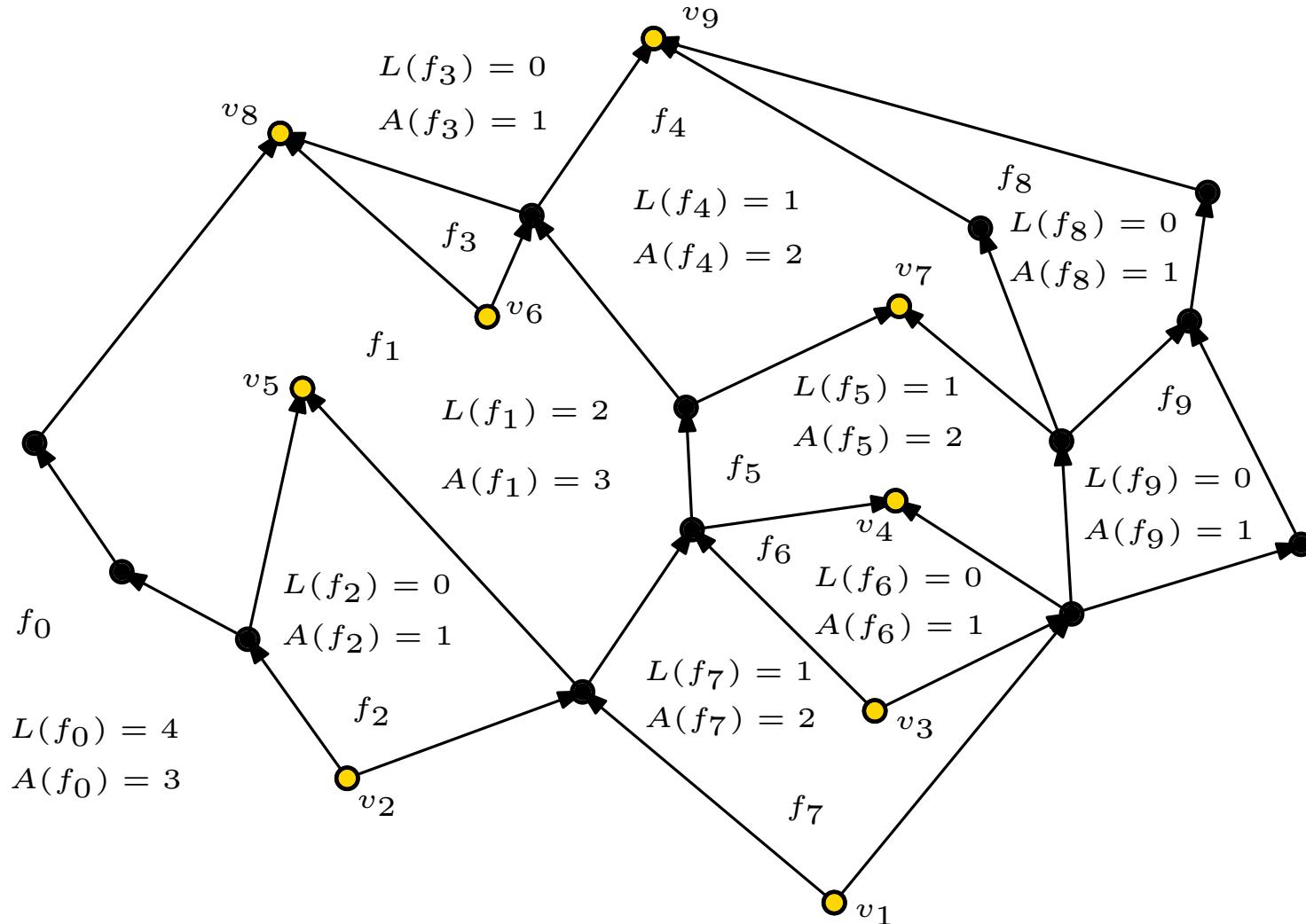
Example: Vertex-Face Assignment



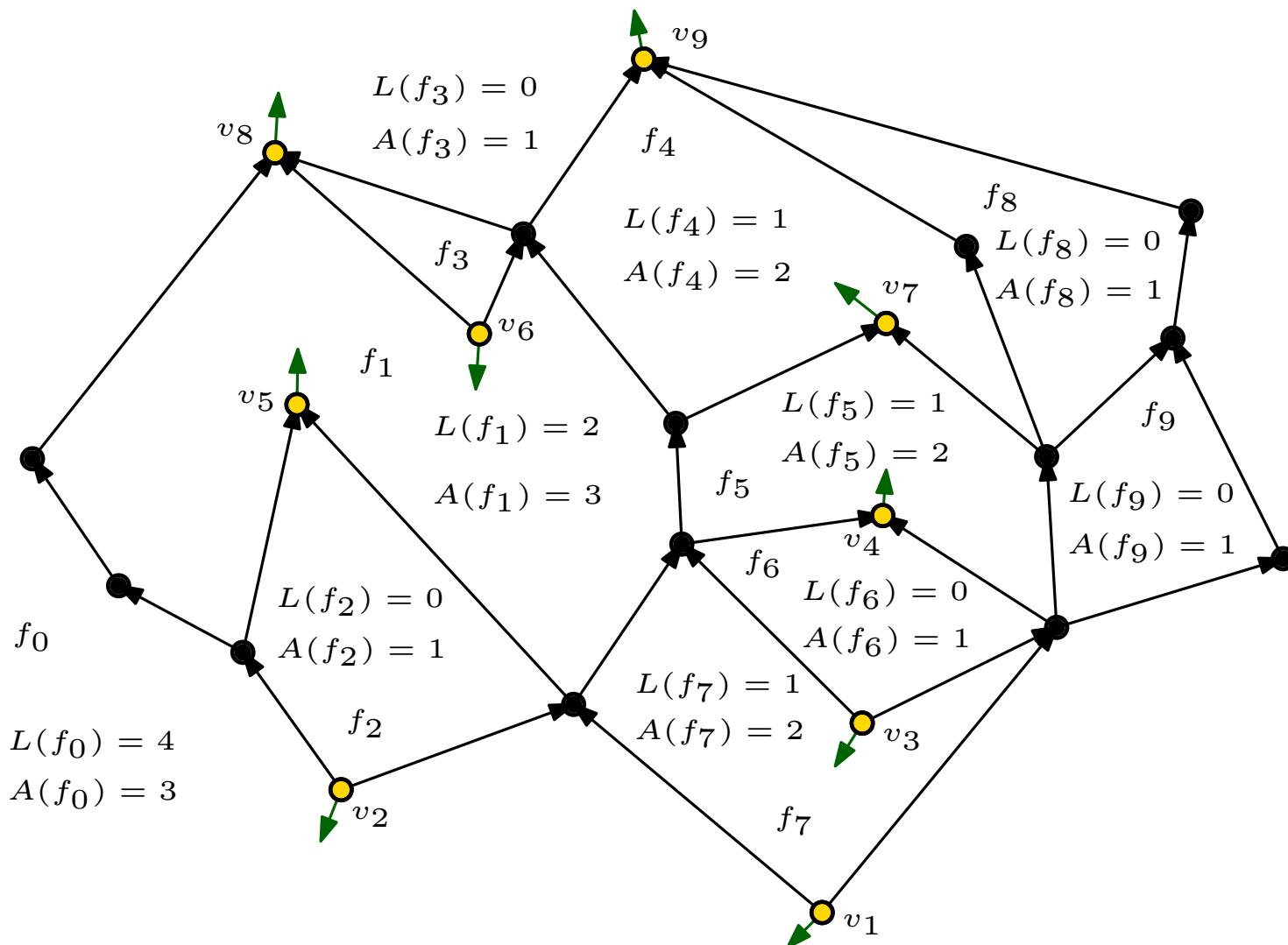
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Example: Vertex-Face Assignment



$\Phi(v_1) = f_0$
 $\Phi(v_2) = f_0$
 $\Phi(v_3) = f_7$
 $\Phi(v_4) = f_5$
 $\Phi(v_5) = f_1$
 $\Phi(v_6) = f_1$
 $\Phi(v_7) = f_4$
 $\Phi(v_8) = f_0$
 $\Phi(v_9) = f_0$

Characterization

Thm 5: For a directed acyclic graph $D = (V, A)$ with combinatorial embedding \mathcal{F}, f_0 it holds:
 D is upward planar $\Leftrightarrow D$ bimodal and \exists consistent Φ

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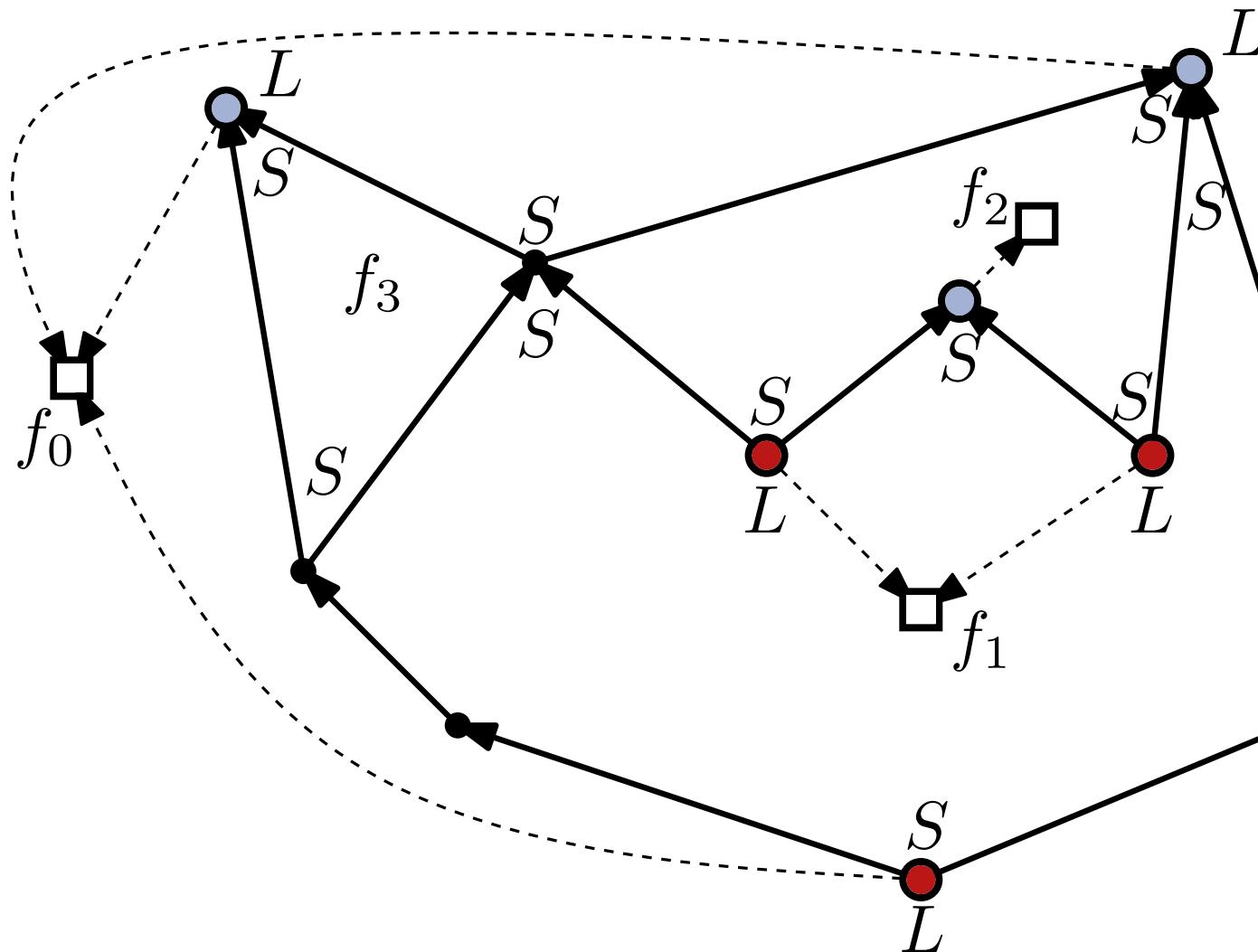
\Rightarrow already clear

\Leftarrow construct an st -digraph that contains D as spanning subgraph:

- insert edges in faces until they have single source and sink
- proof acyclicity, planarity and bimodality

Proof of Theorem 5

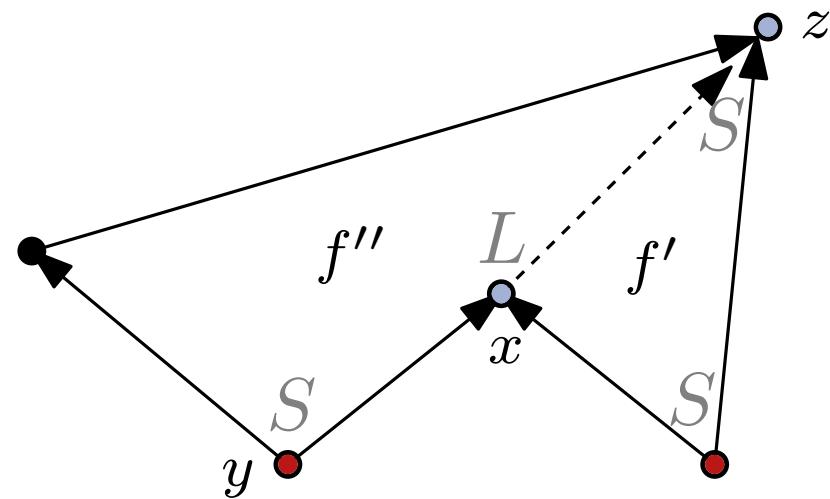
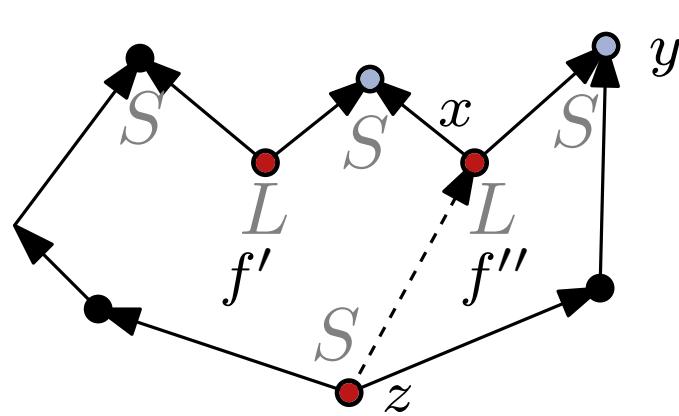
Assign labels s_L, t_L, s_S, t_S to each source/sink of each face f .
Sequence σ_f .



$$\begin{aligned}\sigma_{f_1} &:= (S, S, L, S, L, S) \\ \sigma_{f_2} &:= (L, S, S, S) \\ \sigma_{f_3} &:= (S, S) \\ \sigma_{f_0} &:= (L, L, S, L)\end{aligned}$$

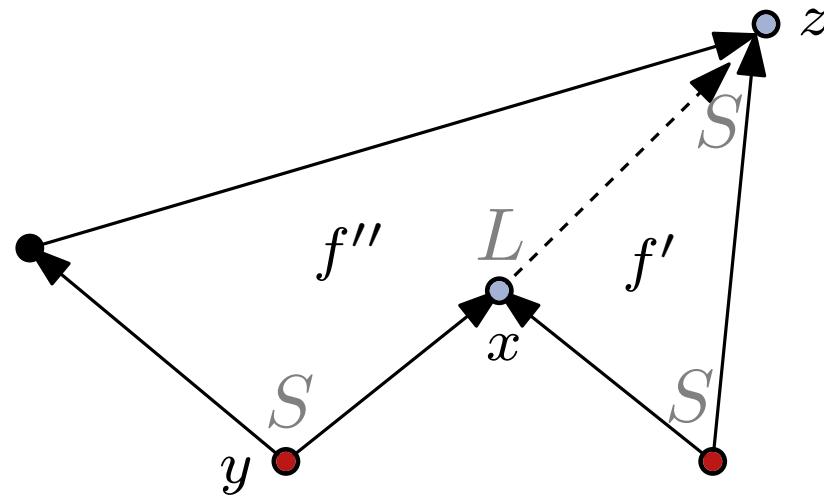
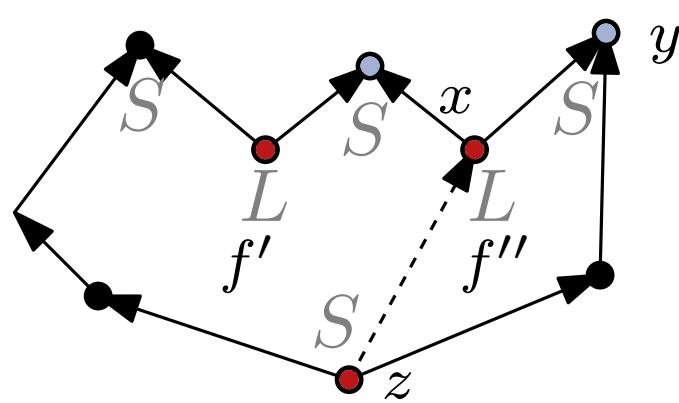
Proof of Theorem 5

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Proof of Theorem 5

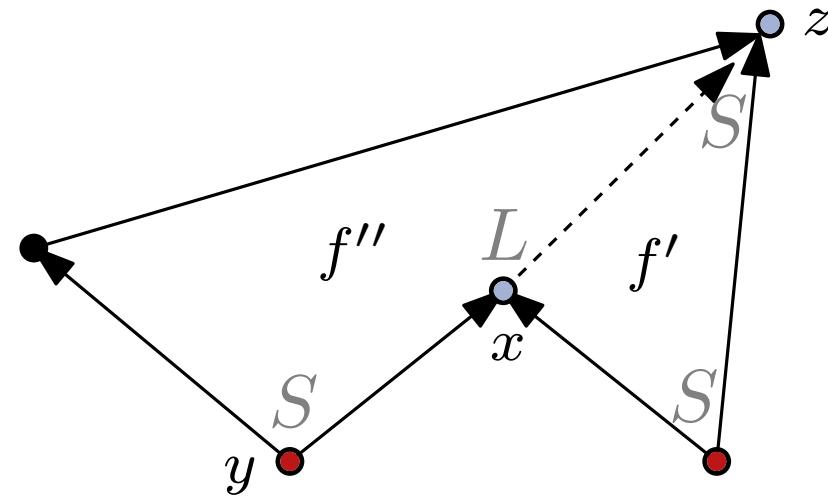
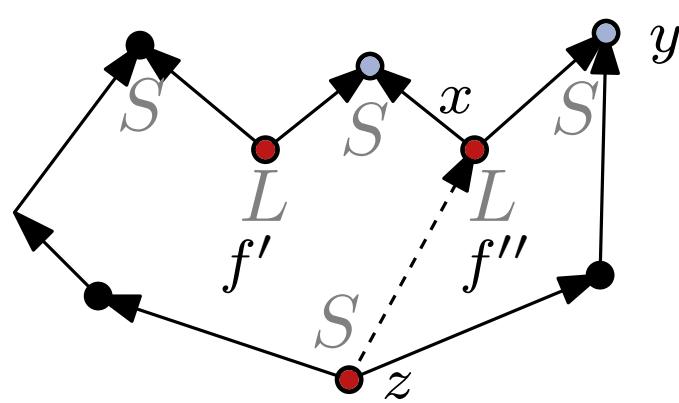
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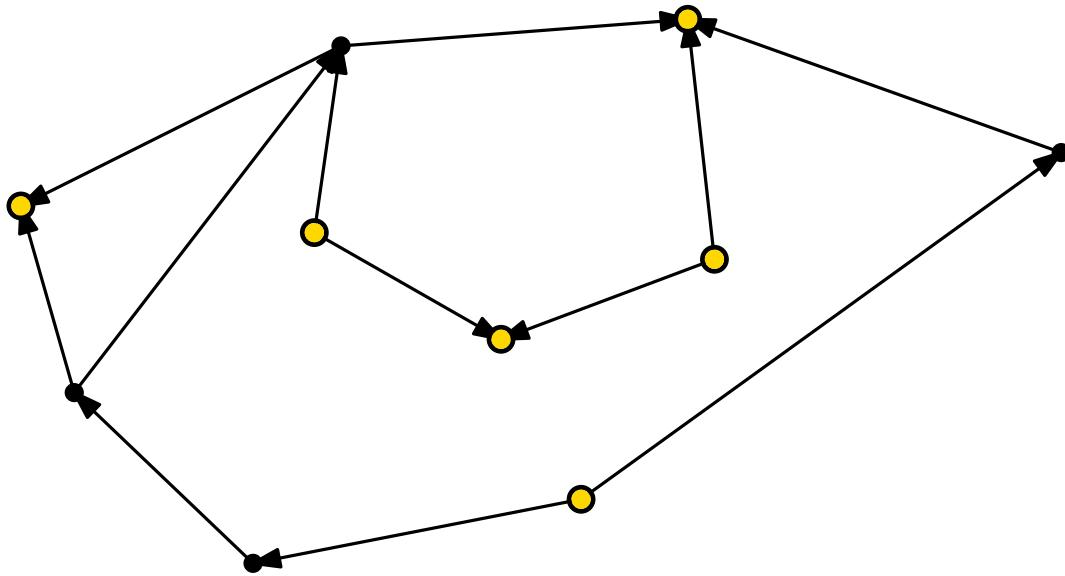
How to check whether a consistent assignment exists?

Flow Network

Def: Flow network $N(D, \mathcal{F}, f_0) = ((W, A_N); \ell; u; b)$

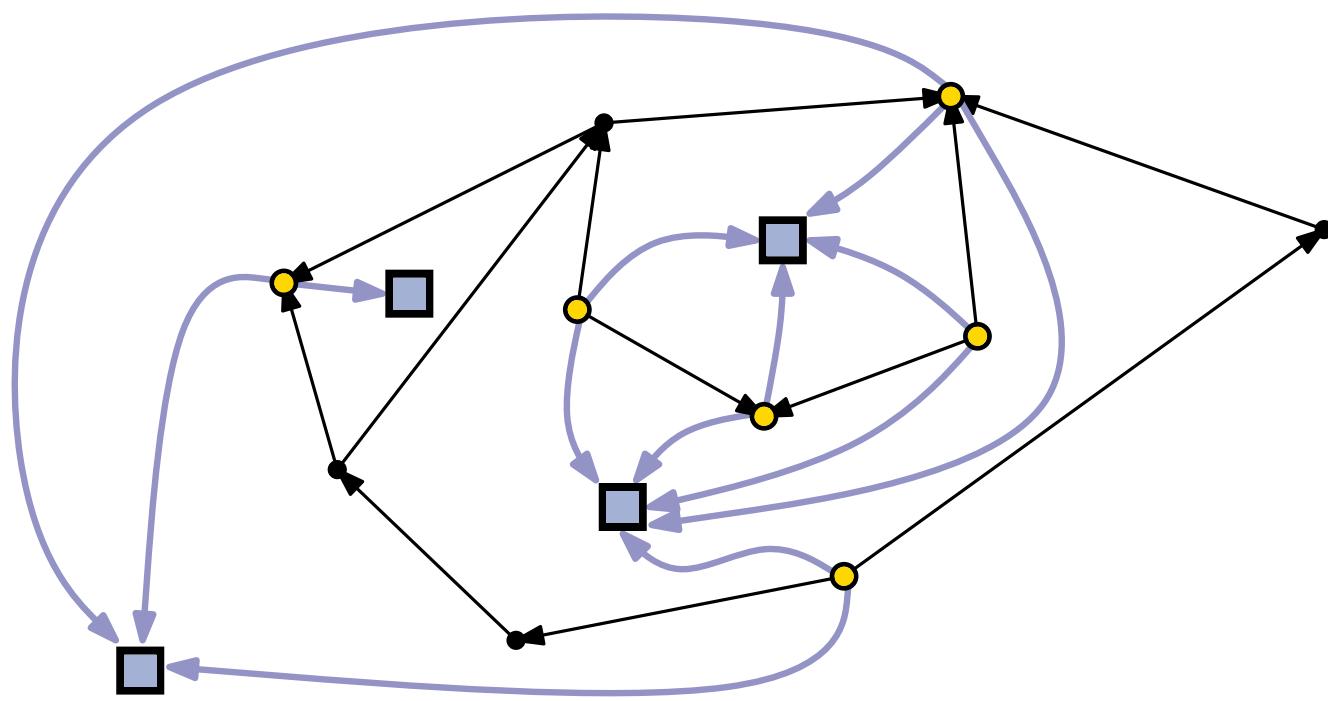
- $W = \{v \in V \mid v \text{ is source or sink}\} \cup \mathcal{F}$
 - $A_N = \{(v, f) \mid v \text{ incident to } f\}$
 - $l(a) = 0 \quad \forall a \in A_N$
 - $u(a) = 1 \quad \forall a \in A_N$
- $b(q) = \begin{cases} 1 & \forall q \in W \cap V \\ -(A(q) - 1) & \forall q \in \mathcal{F} \setminus \{f_0\} \\ -(A(q) + 1) & q = f_0 \end{cases}$

Example



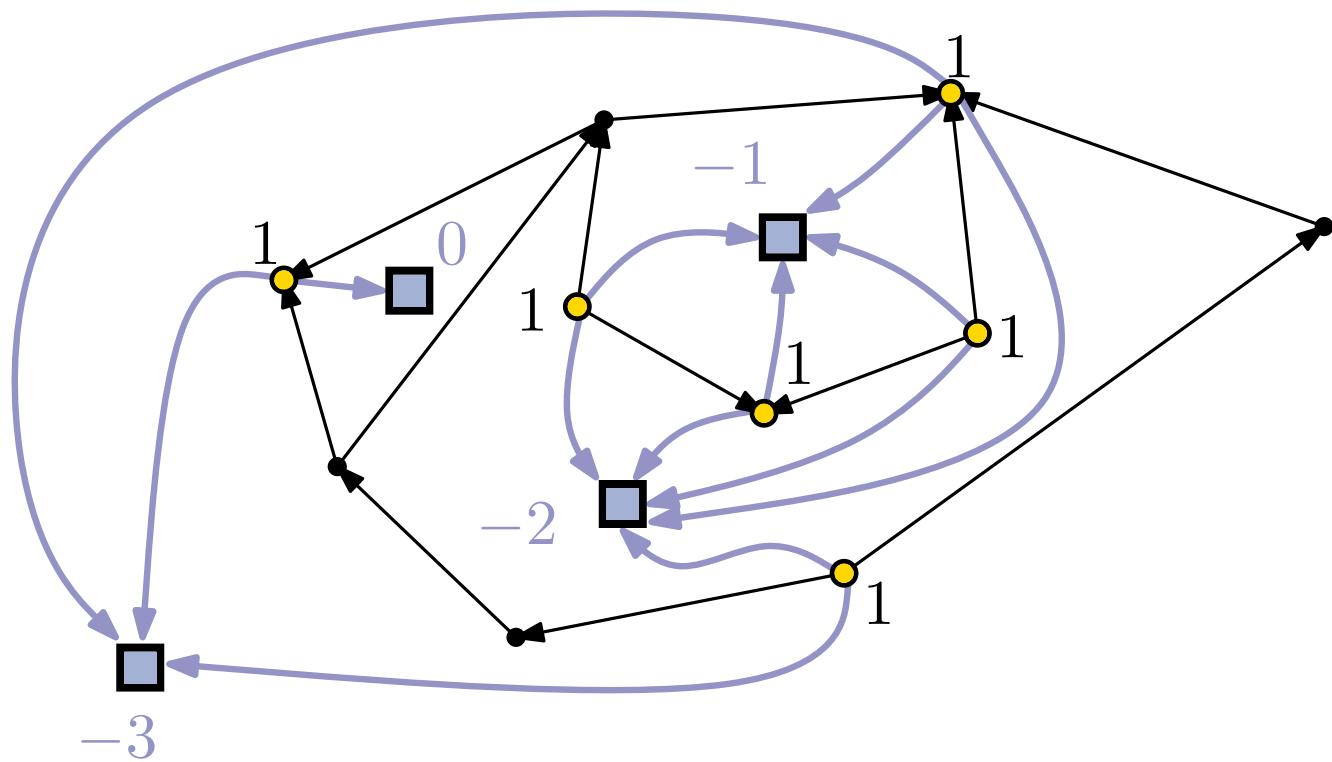
- normal nodes
- sources/sinks

Example



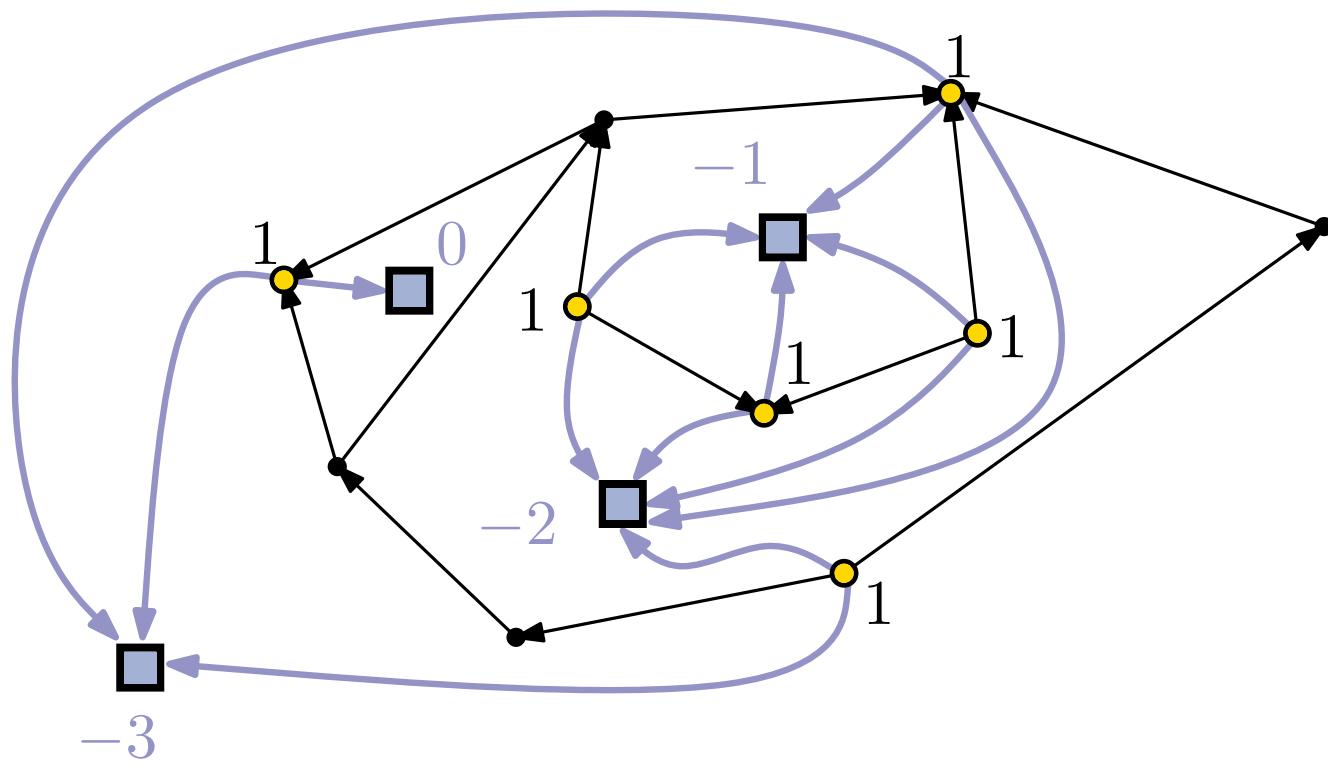
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Example



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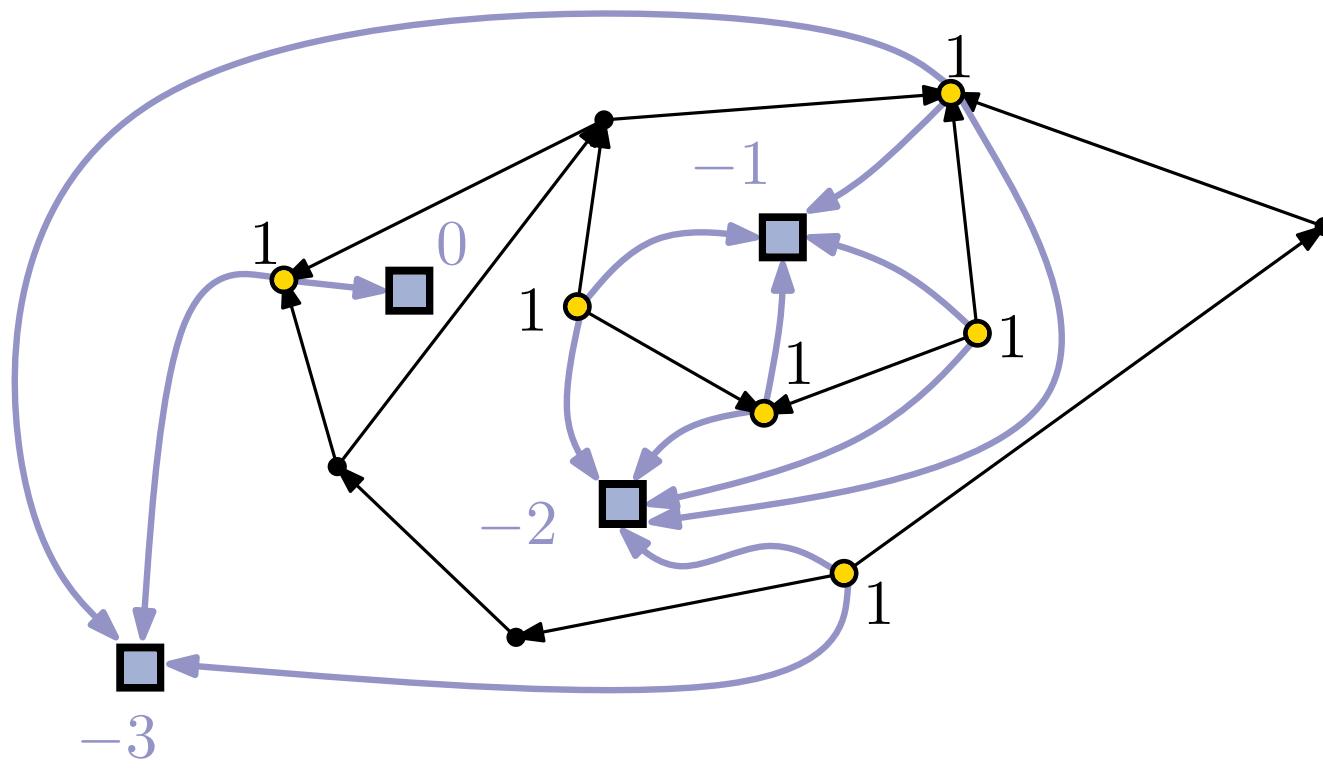
Example



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- face nodes

Thm 6: Let G be a directed acyclic digraph with embedding F and outer face f_0 . Bipartite flow network $N(D, \mathcal{F}, f_0)$ admits a valid flow of value r (<# of sources/sinks>) iff G has a consistent assignment of sources and sinks to faces.

Example



- normal nodes
- sources/sinks
- face nodes

- start with zero flow
- search for augmenting path (r times for total of r sources and sinks)

Final Remarks

- $O(rn)$ to decide whether consistent assignment exists
- works also without fixed outer face f_0 : first compute all faces as internal and then add two units of demand to a face vertex and test whether the total flow can be augmented by two units. Do it for every face.

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The layout can be constructed in the same time: $O(n)$ to augment to st -digraphs and $O(n)$ to draw the st -digraph

Discussion

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- There exists a fixed parameter tractable algorithm to test upward planarity, with parameter number of triconnected components [Healy, Lynch SOFSEM 2005]
- The decision of Theorem 2 can be done in $O(n + r^{1.5})$ time where $r = \# \text{ sources/sinks}$ [Abbasi, Healy, Rextin IPL 2010]
- many related concepts have been studied recently: quasi-planarity, upward drawings of mixed graphs

