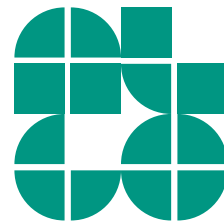


Computational Geometry · Lecture

Projects & Polygon Triangulation

INSTITUTE FOR THEORETICAL INFORMATICS · FACULTY OF INFORMATICS

Tamara Mchedlidze · Darren Strash
02.11.2015



Projects

Project Specifications

Groups:

- 2 or 3 students, assigned to a supervisor

Tools:

- Use any programming language, should run with little effort on Linux

Due date:

- 08.02.2016

Visualization:

- Need to visualize output; ipe, svg, video? This is also helpful for debugging output
- Do not need to use graphics APIs, unless you really want to

Group Presentations:

- Each groups gives a 20-minute presentation (last 2 weeks of class)

Project proposals: due in 2 weeks (16.11.2015):

- No more than 1 page
- Formalize your problem
- Describe geometric primitives
- State any simplifying assumptions
- Describe the algorithms / data structures you will use
- **Avoid brute force algorithms**

Supervisor:

- Assigned supervisor (Tamara, Darren, or Benjamin)
- Meet with supervisor in two weeks to discuss proposal.

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Now, form groups and sit by each other!

Project proposals: due in 2 weeks (16.11.2015):

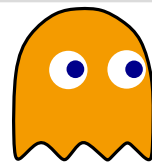
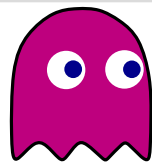
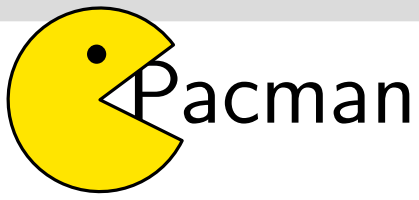
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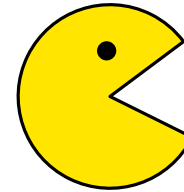
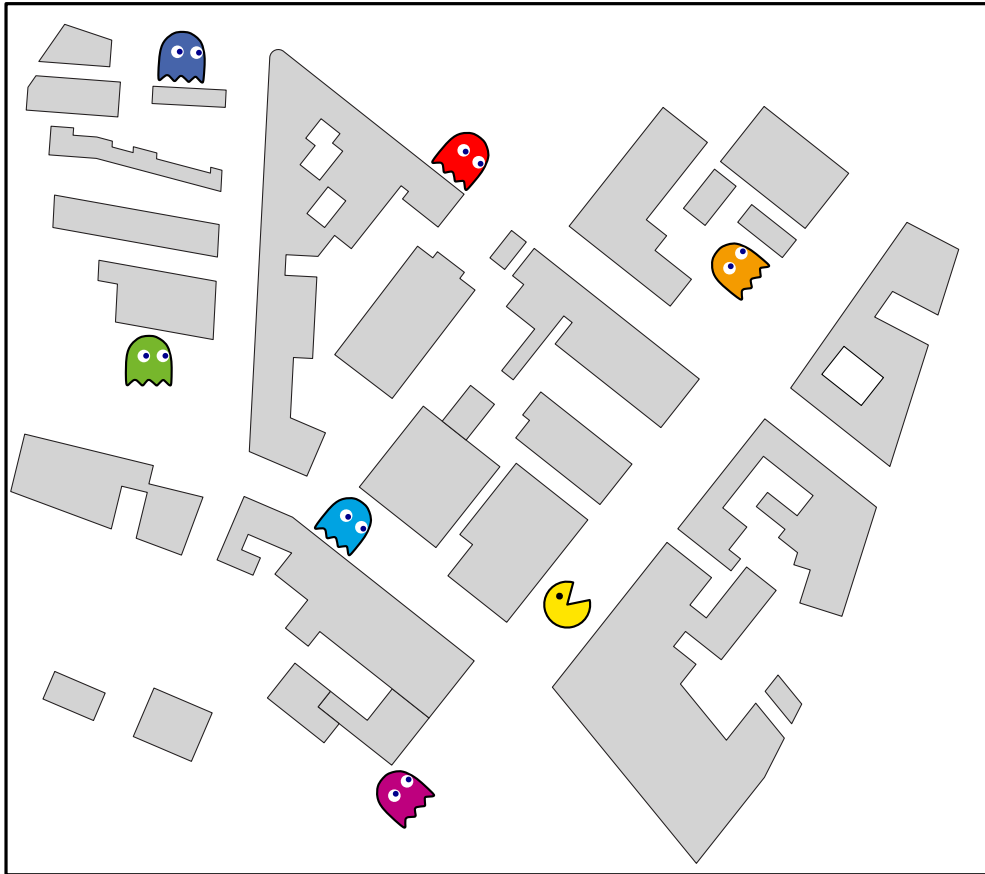
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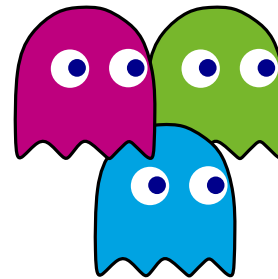
Time to present the projects...



Scenario: Development of the game Pacman.



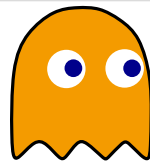
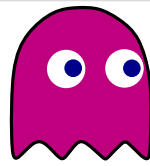
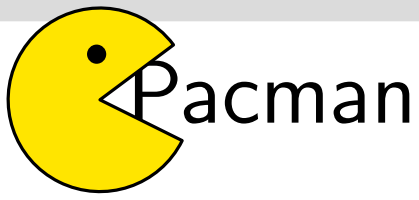
Pacman



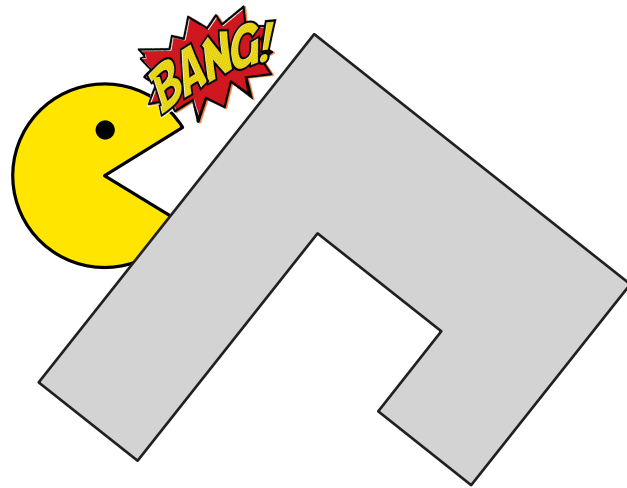
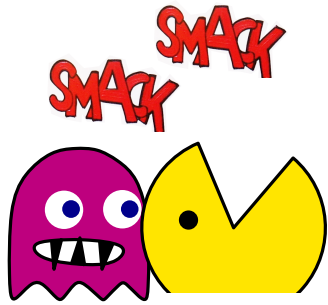
THE Ghosts.

Story:

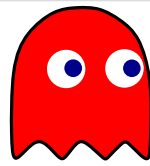
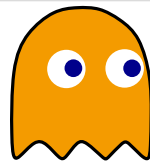
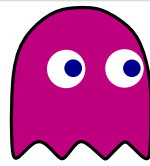
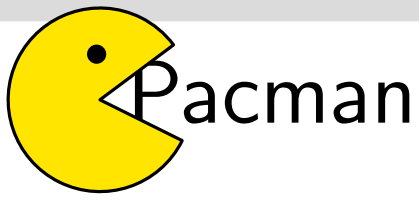
Pacman is strolling through a large city with many buildings, gathering items. However, incredibly many ghosts want to hinder Pacman by eating him.



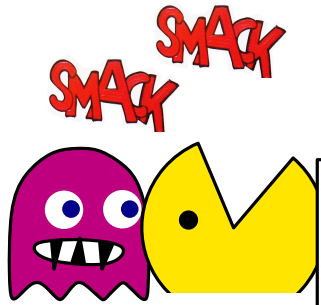
Project 1: Collision Detection



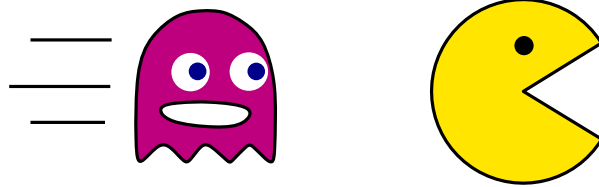
moving objects \leftrightarrow moving objects
moving objects \leftrightarrow buildings



Project 1: Collision Detection



Project 2: Artificial Intelligence I

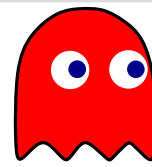
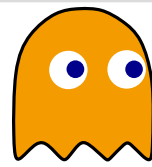
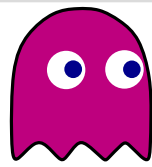
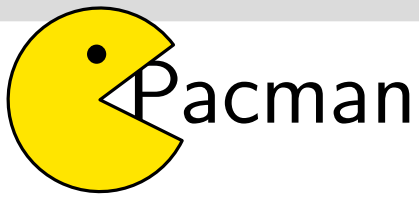


moving object
moving object

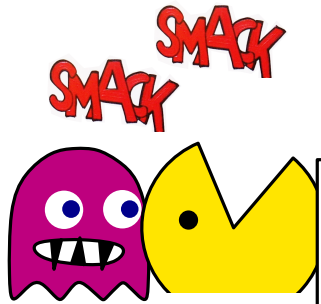
Ghosts seeing Pacman follow him until they lose eye contact.

Fast visibility check:

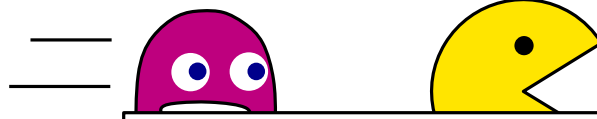
Is Pacman visible from point p ?



Project 1: Collision Detection



Project 2: Artificial Intelligence I

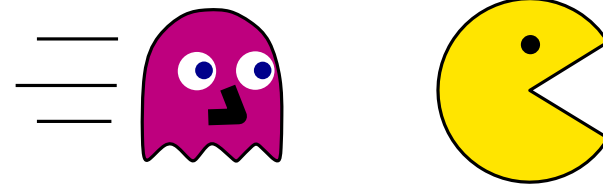


moving object
moving object

Ghosts see
until they

Fast visibility
Is Pacman

Project 3: Artificial Intelligence II



Ghosts smelling Pacman follow
him until they lose the track.

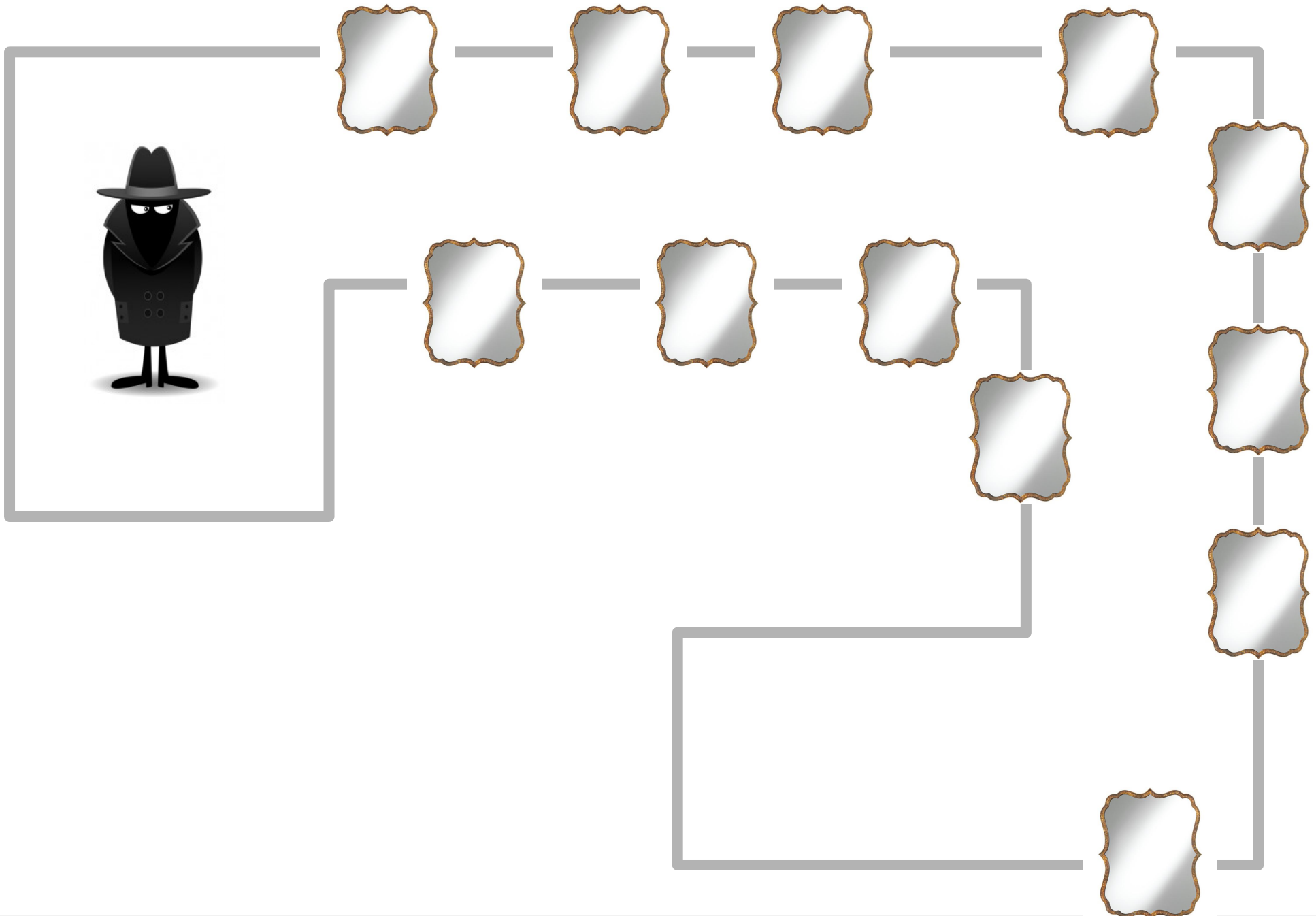
Fast smell check:

Can Pacman be smelled from point p ?

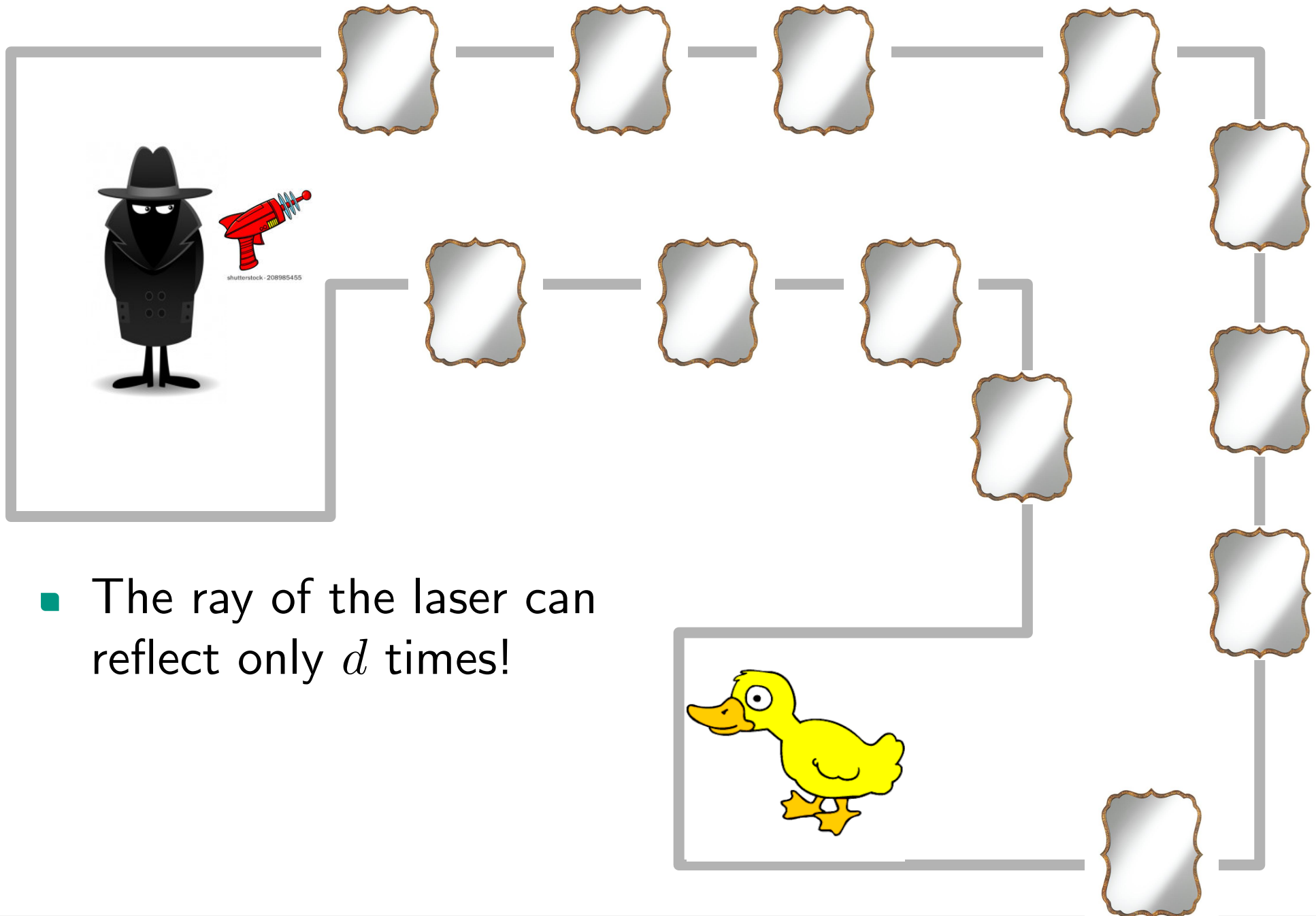
Secret Agent



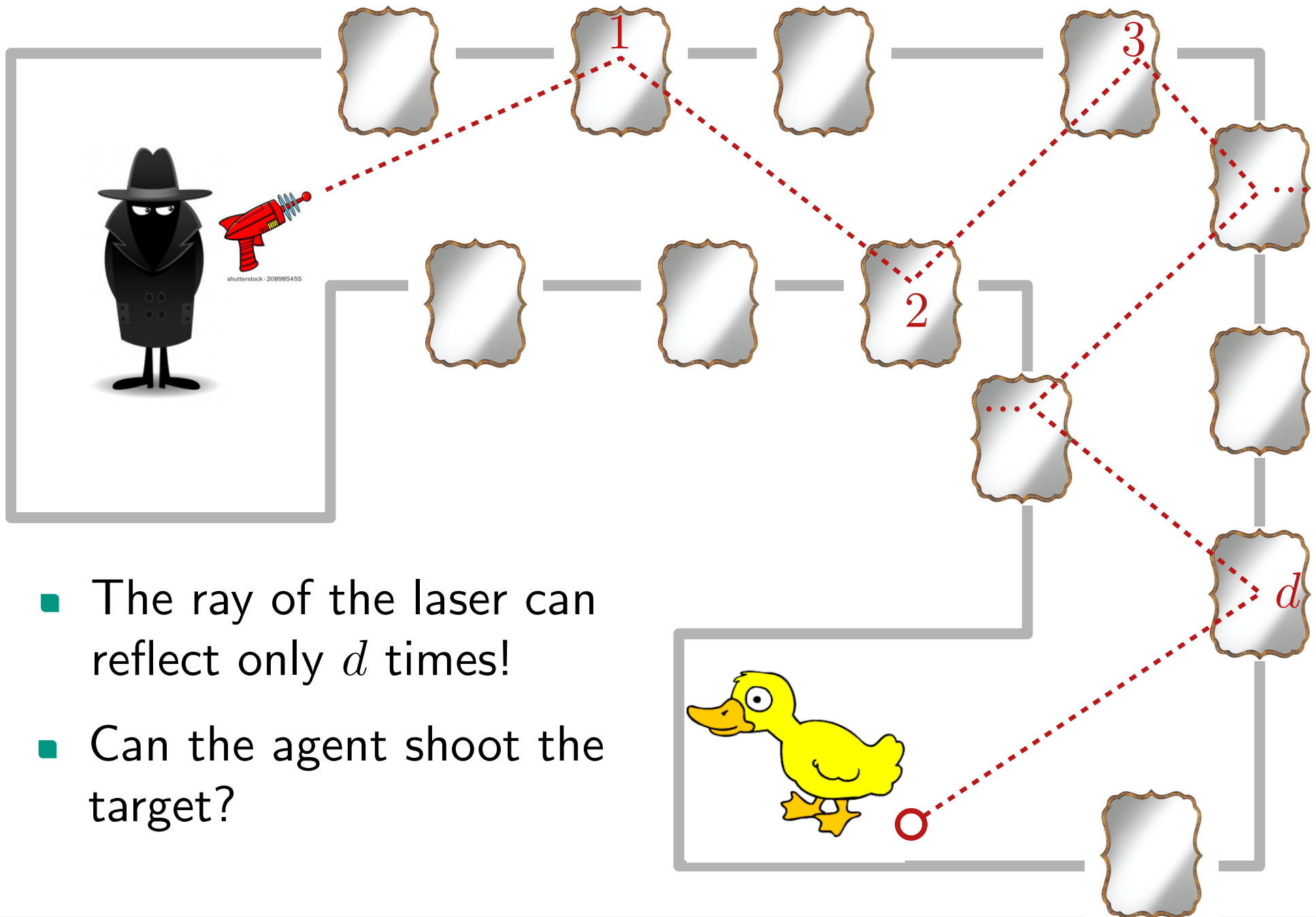
Shooting Secret Agent



Shooting Secret Agent

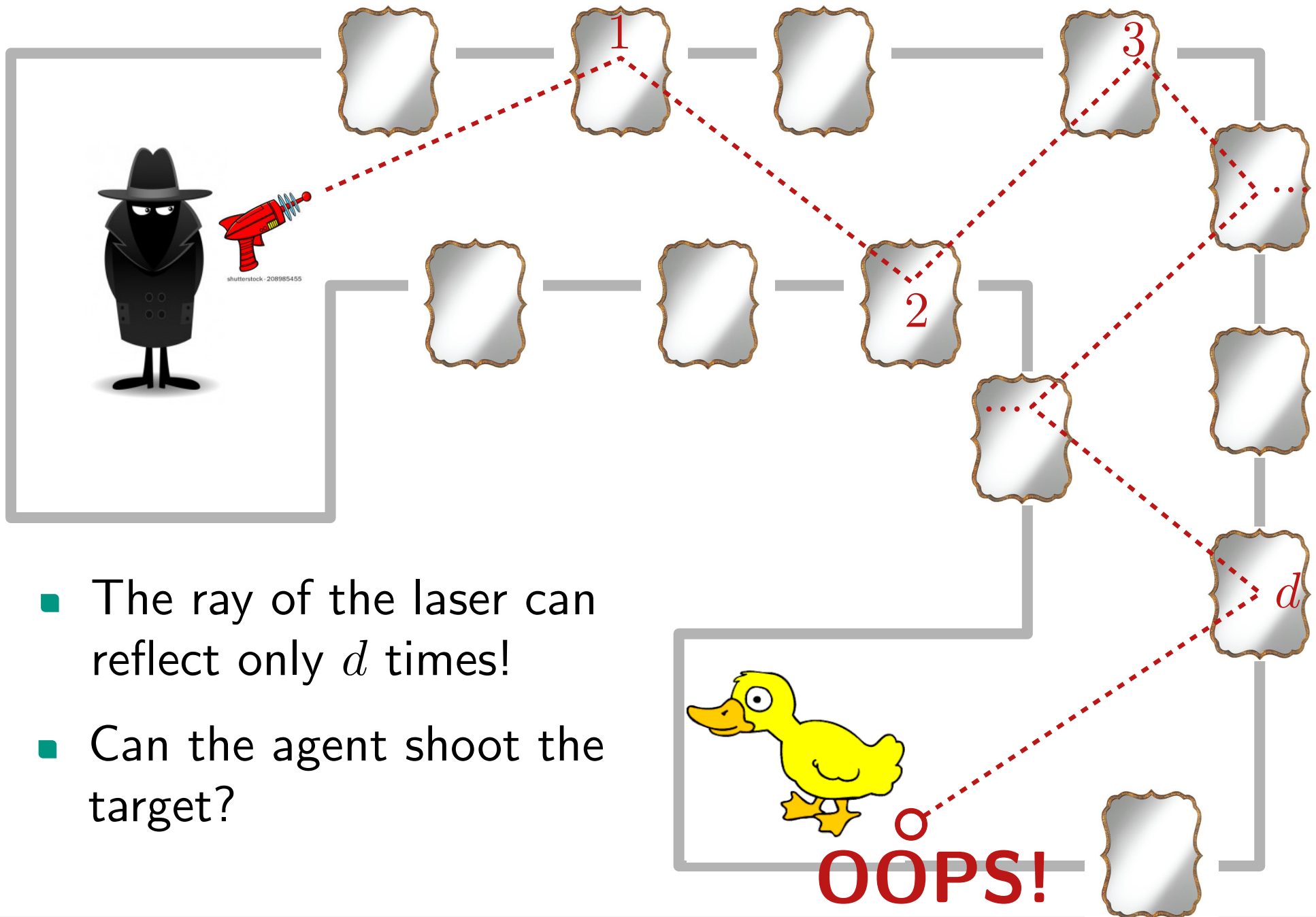


Shooting Secret Agent



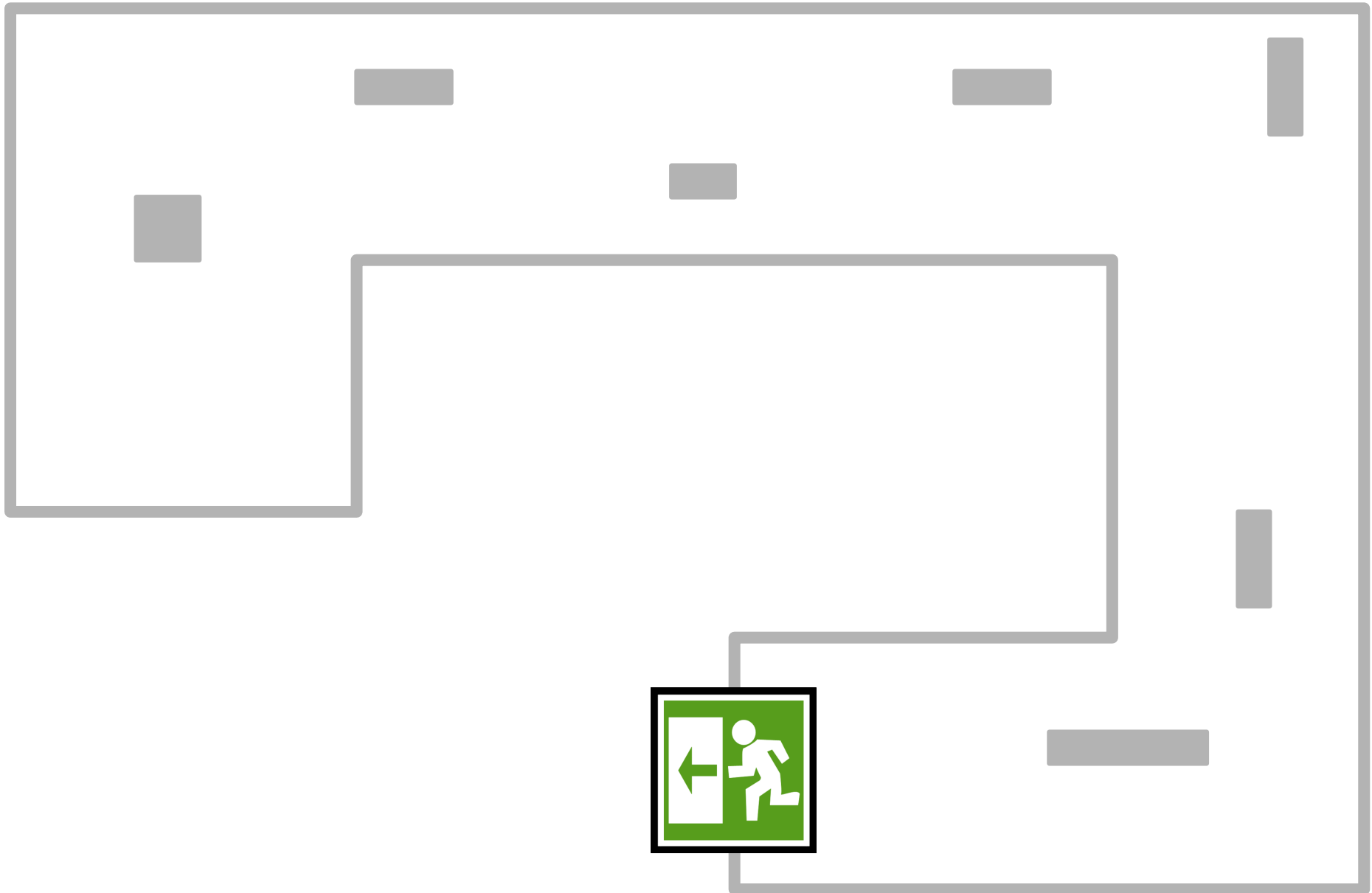
- The ray of the laser can reflect only d times!
- Can the agent shoot the target?

Shooting Secret Agent

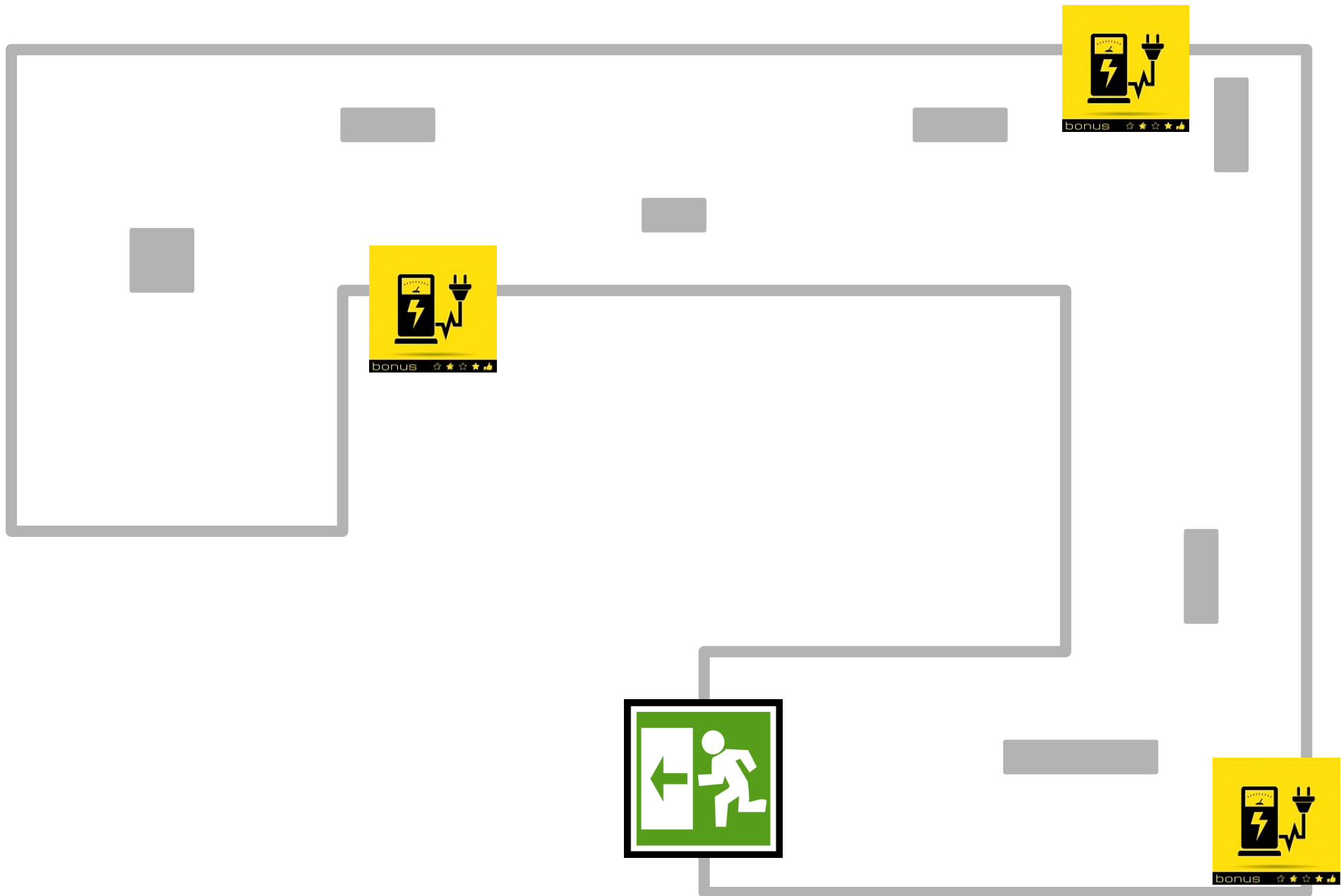


- The ray of the laser can reflect only d times!
- Can the agent shoot the target?

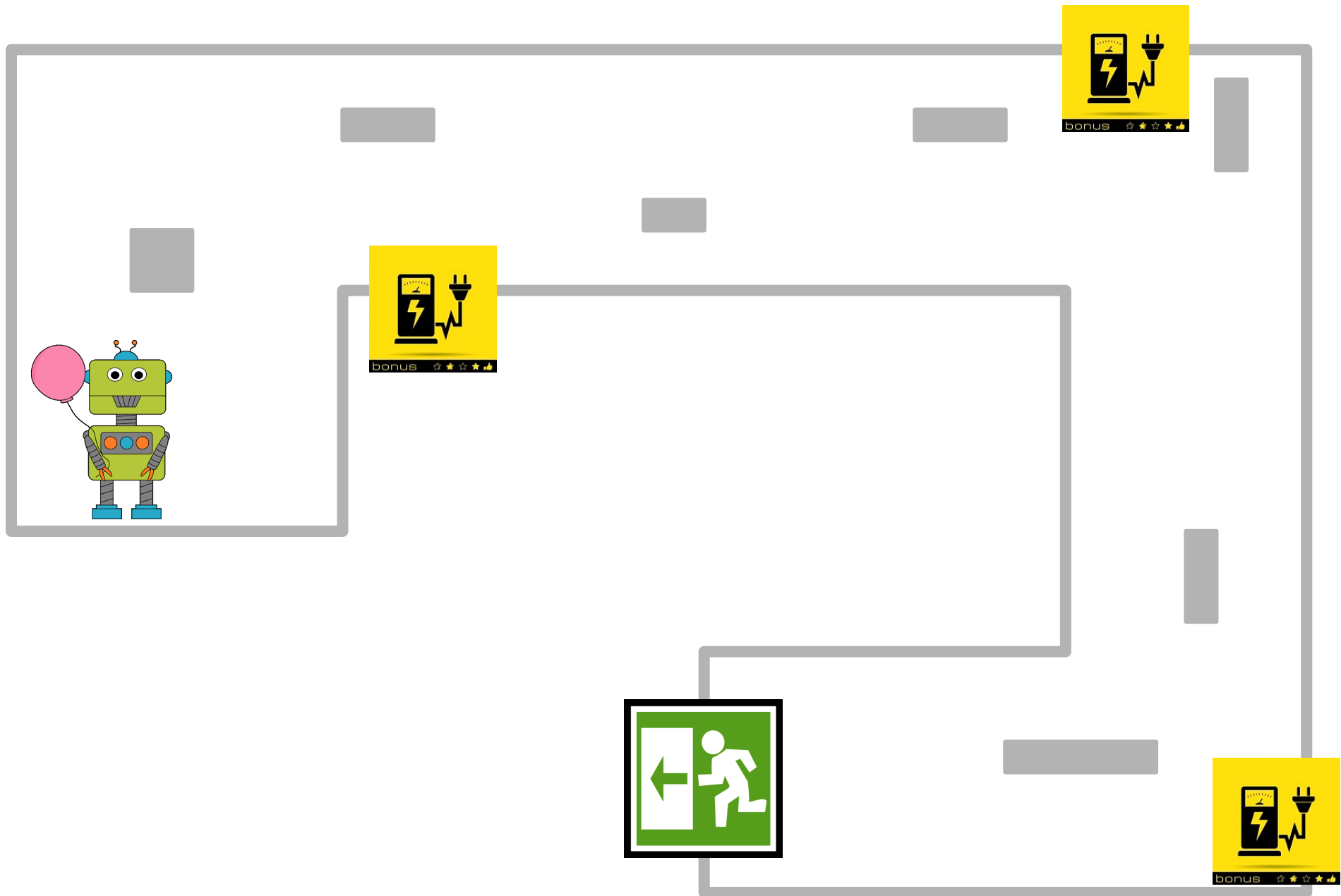
Secret Agent's Robot



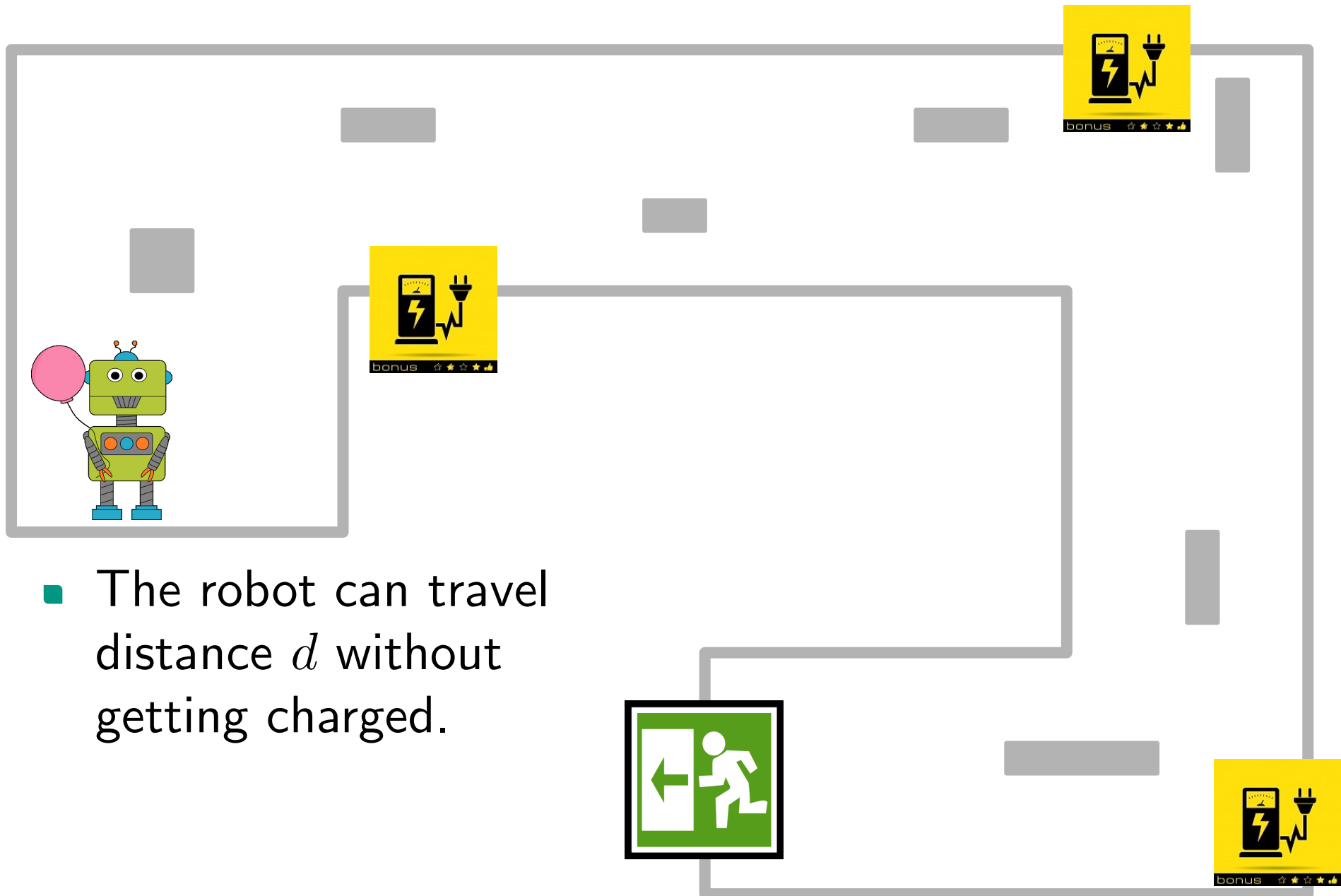
Secret Agent's Robot



Secret Agent's Robot

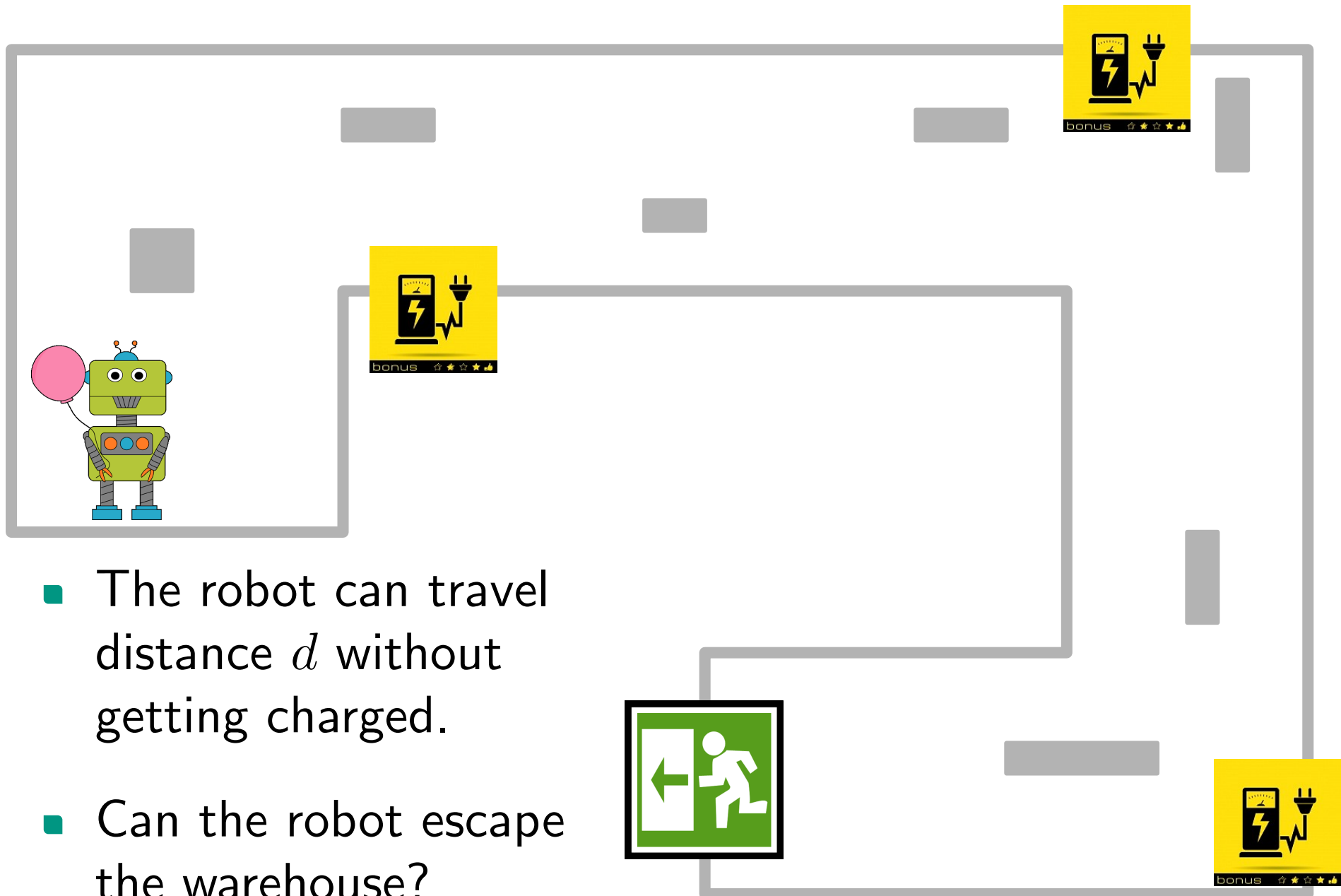


Secret Agent's Robot



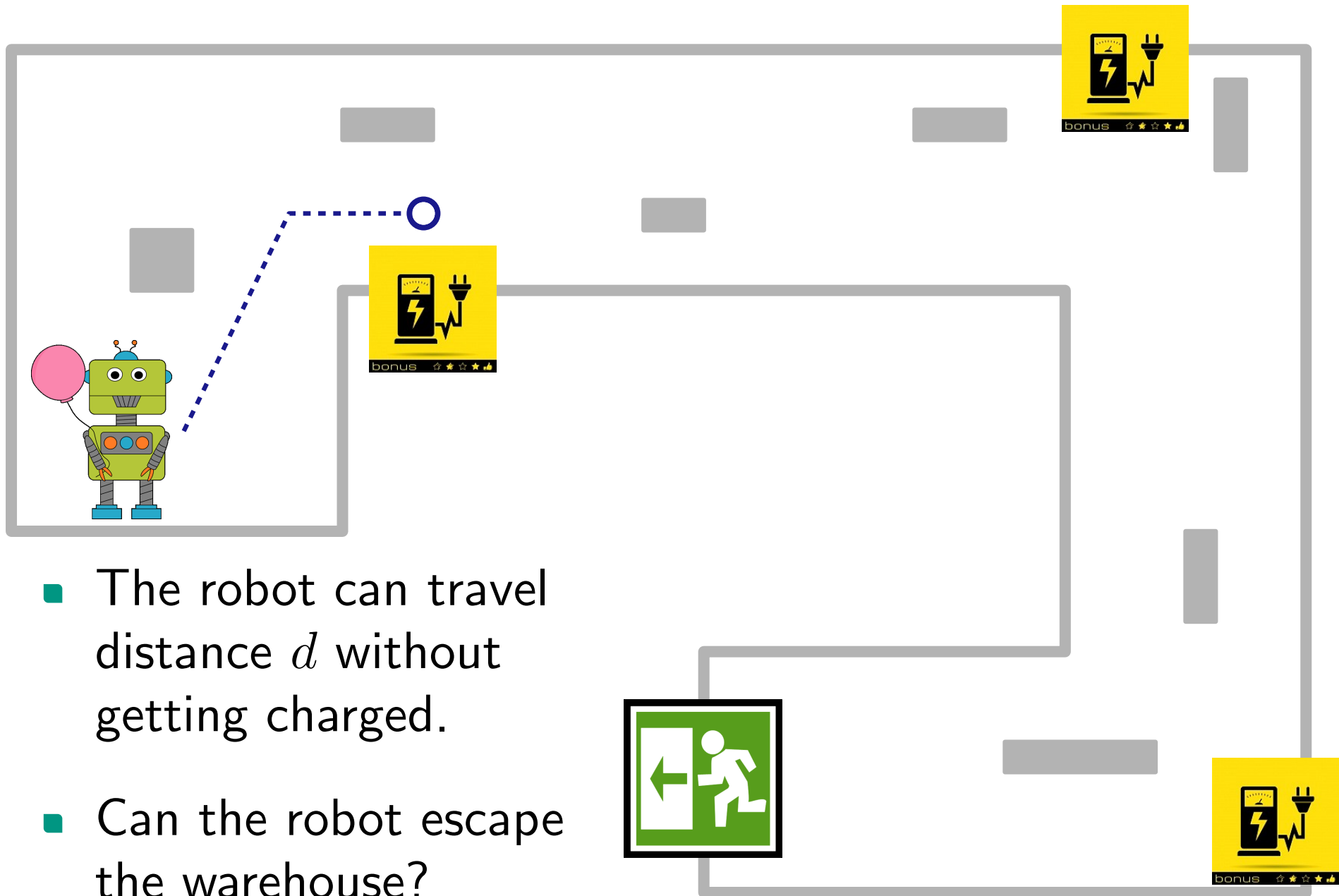
- The robot can travel distance d without getting charged.

Secret Agent's Robot



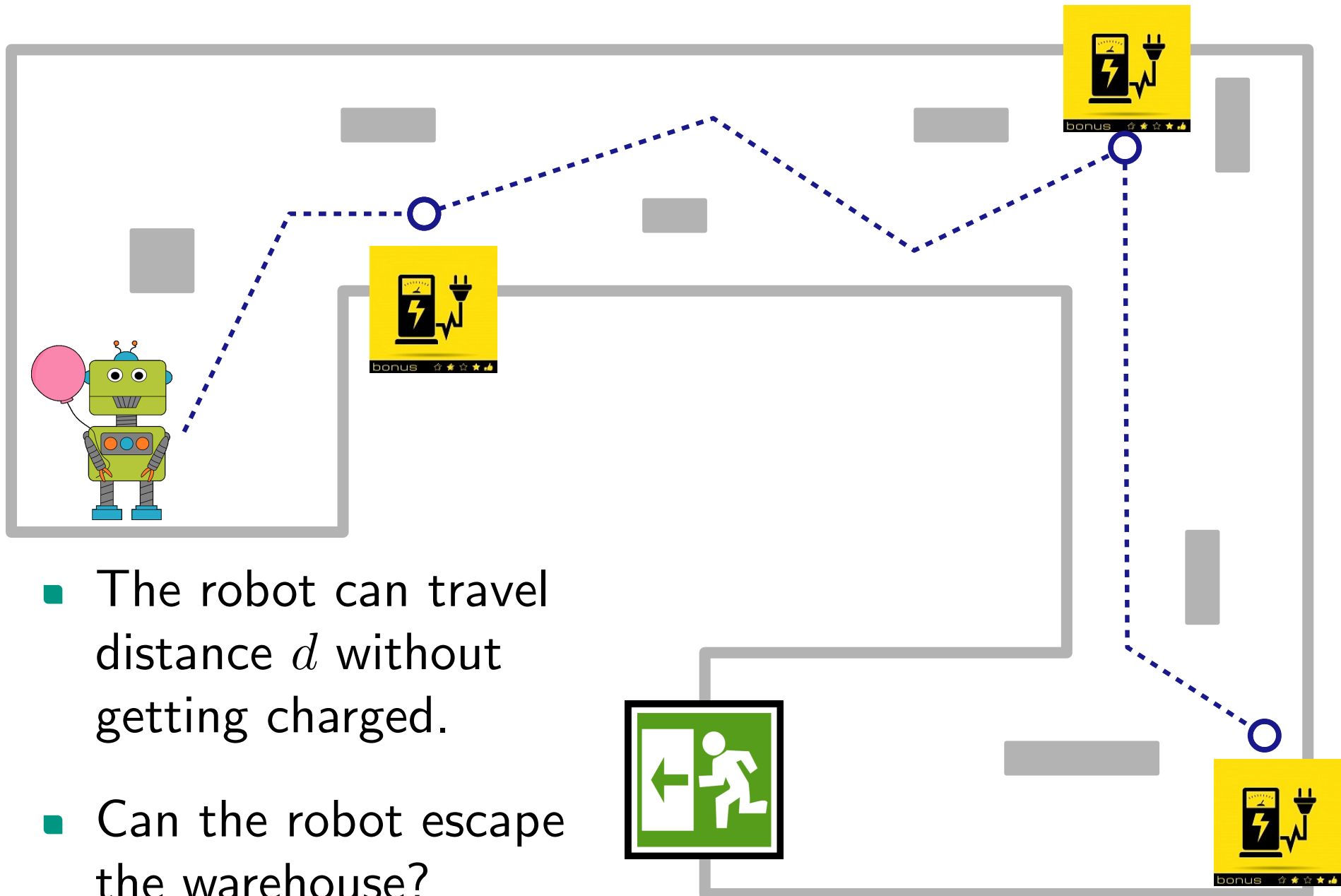
- The robot can travel distance d without getting charged.
- Can the robot escape the warehouse?

Secret Agent's Robot



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Secret Agent's Robot

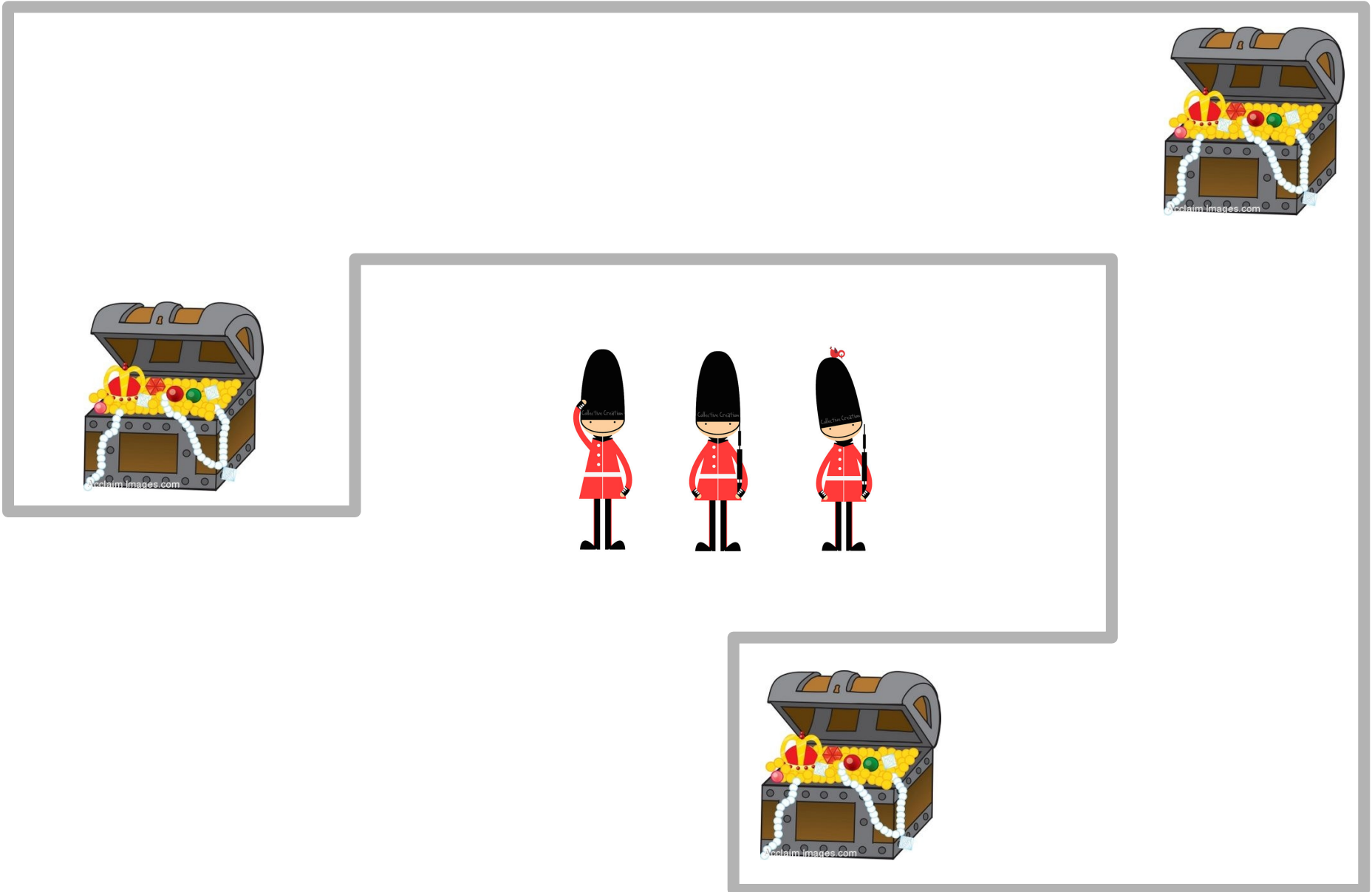


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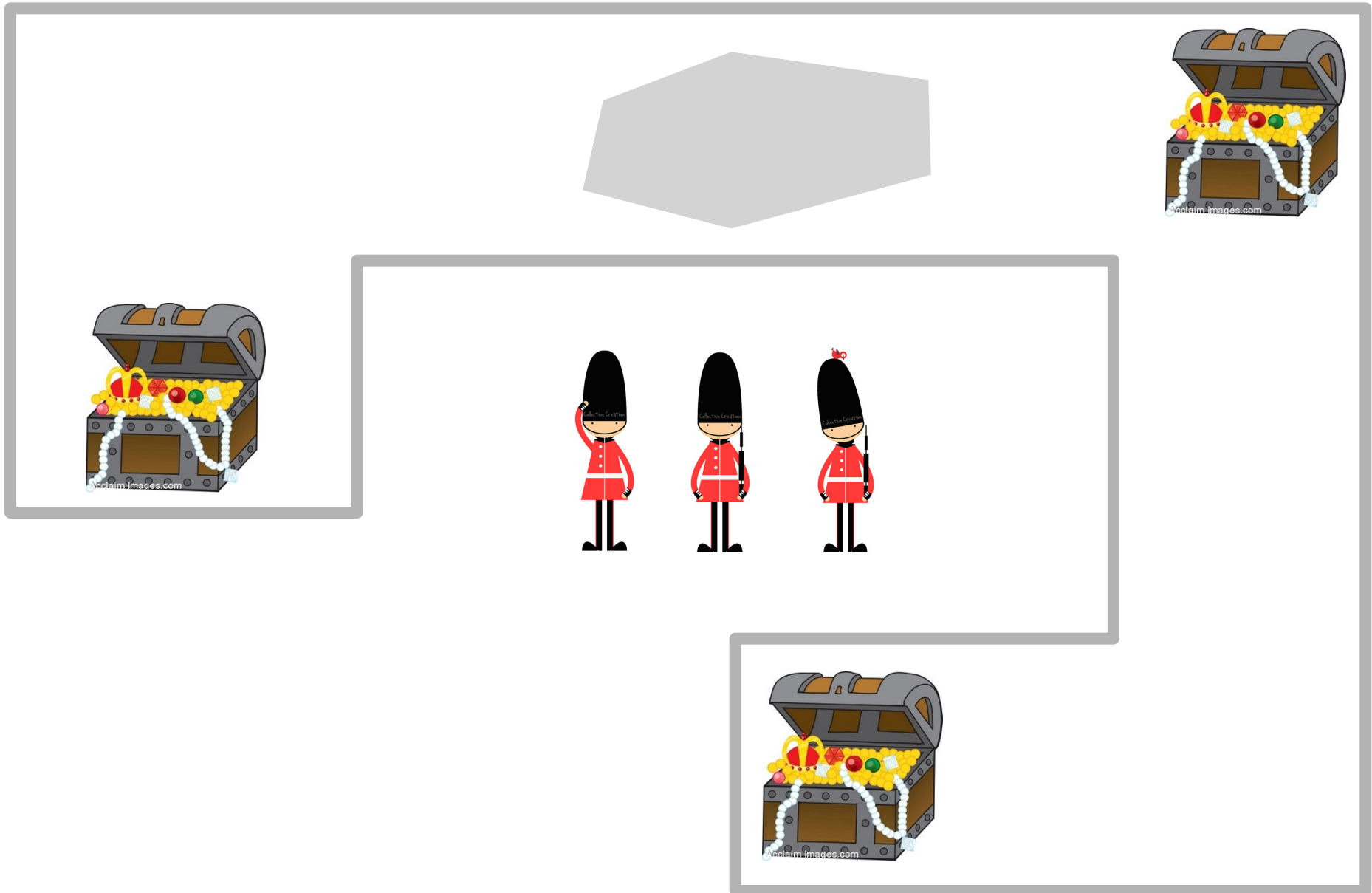
Secret Agent Protects Jewels



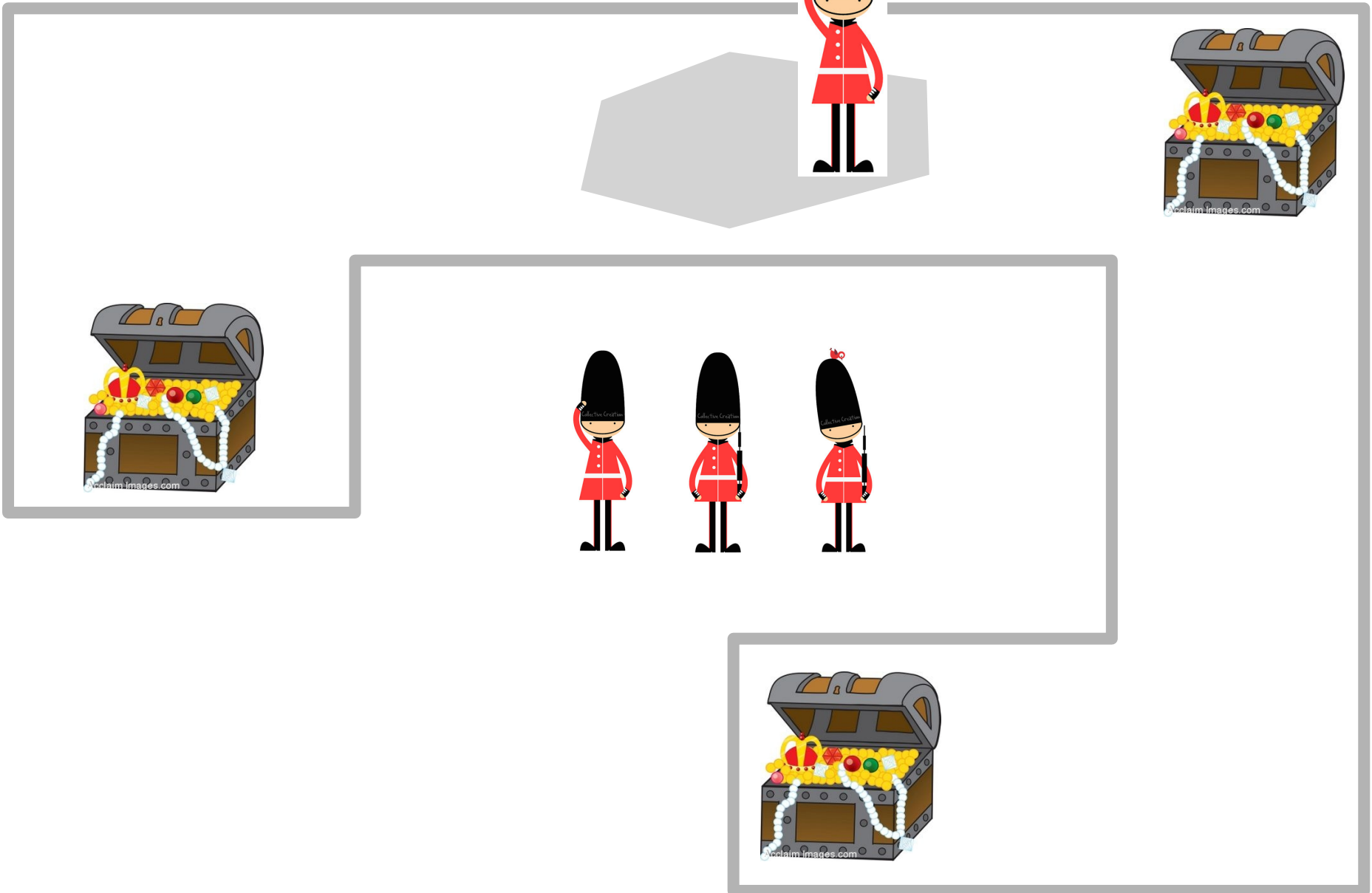
Secret Agent Protects Jewels



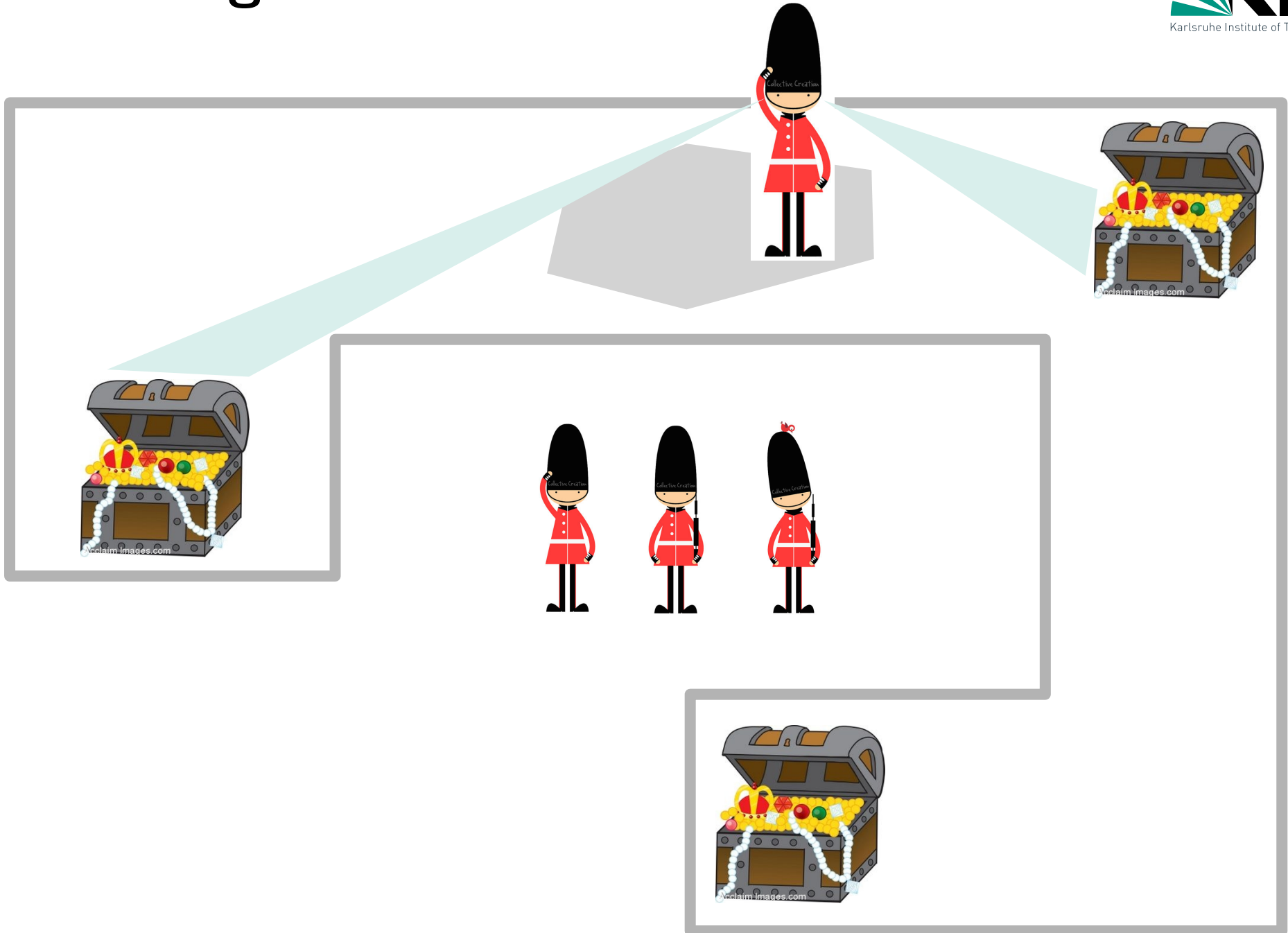
Secret Agent Protects Jewels



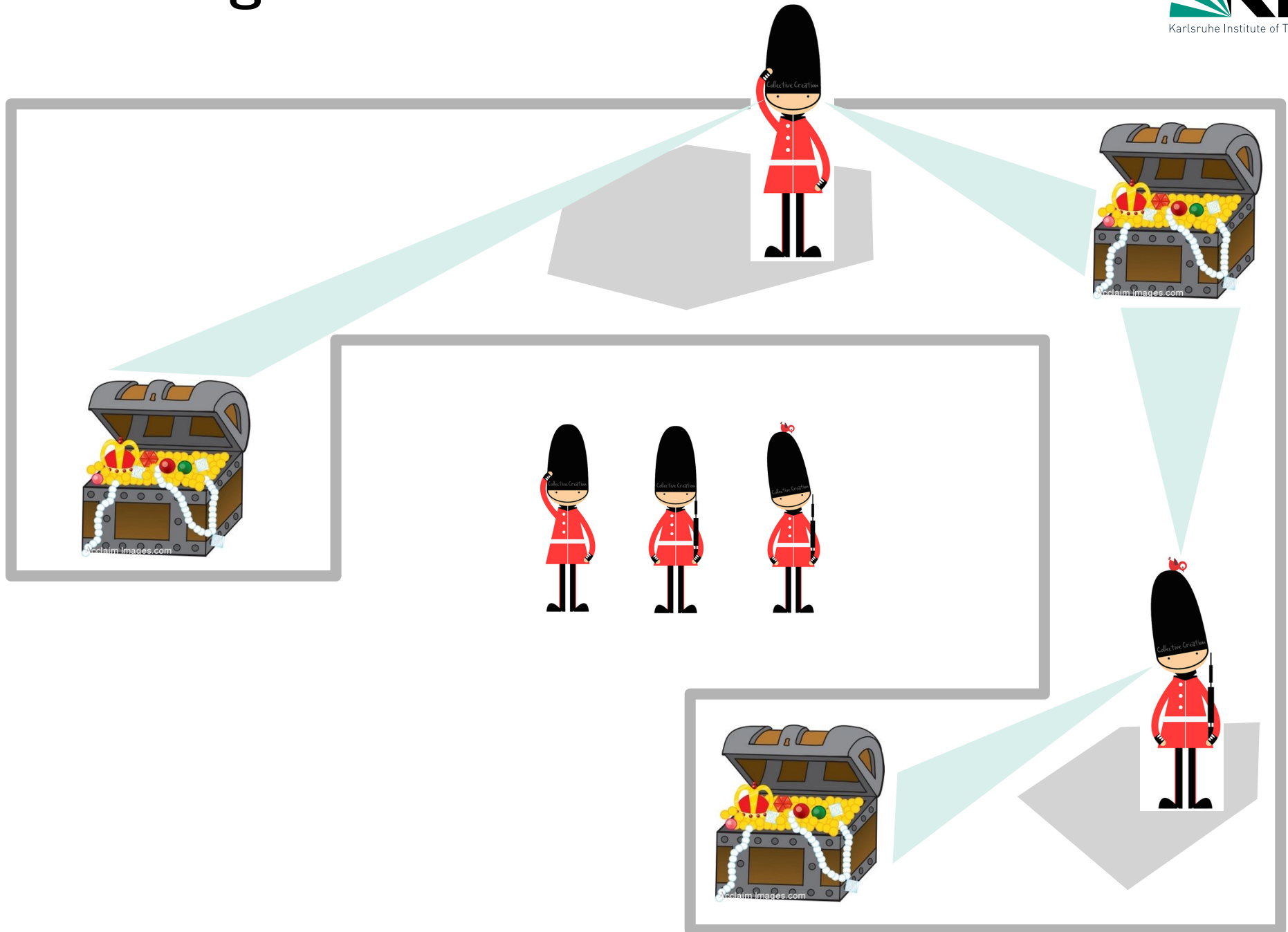
Secret Agent Protects Jewels



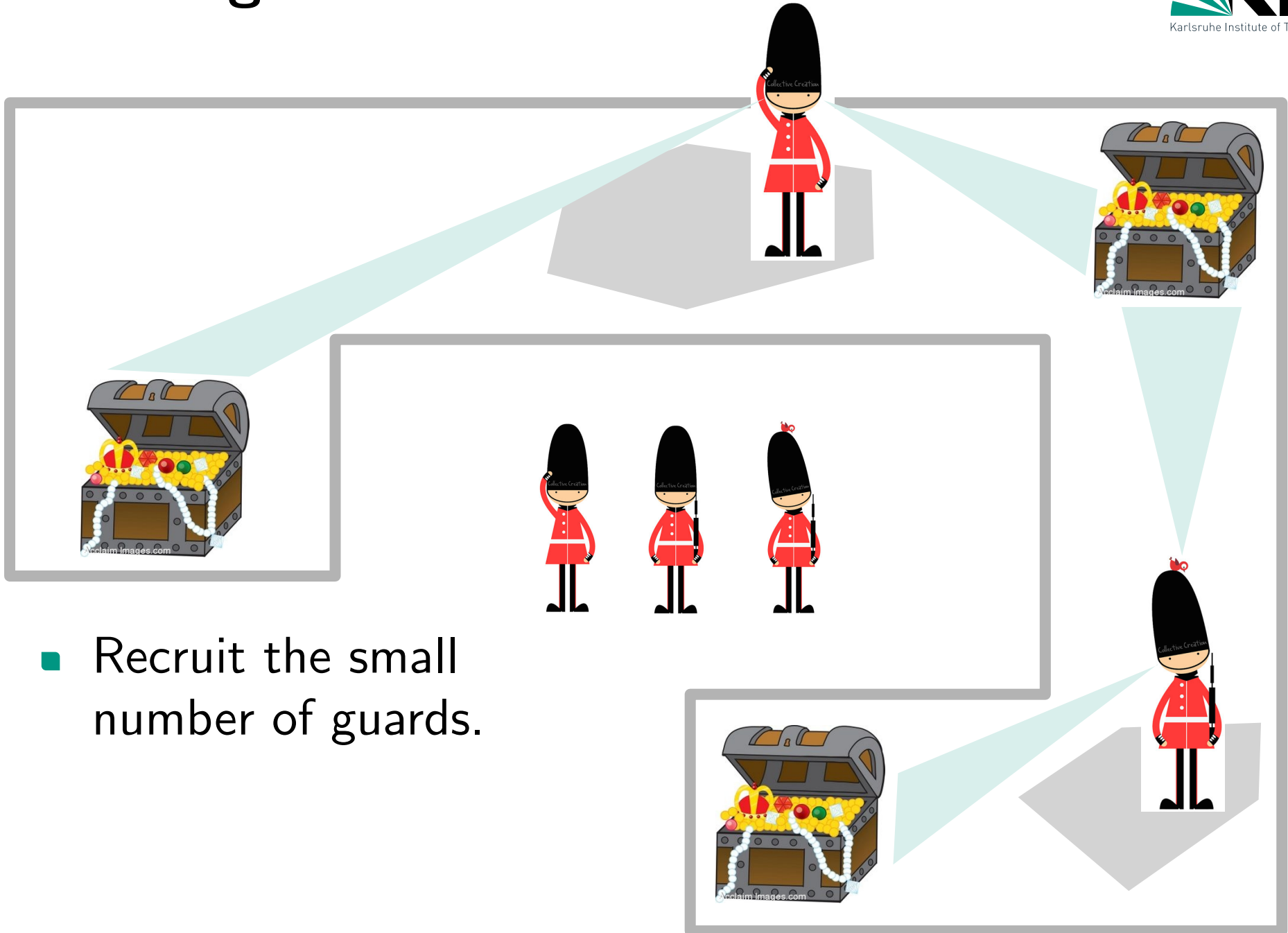
Secret Agent Protects Jewels



Secret Agent Protects Jewels

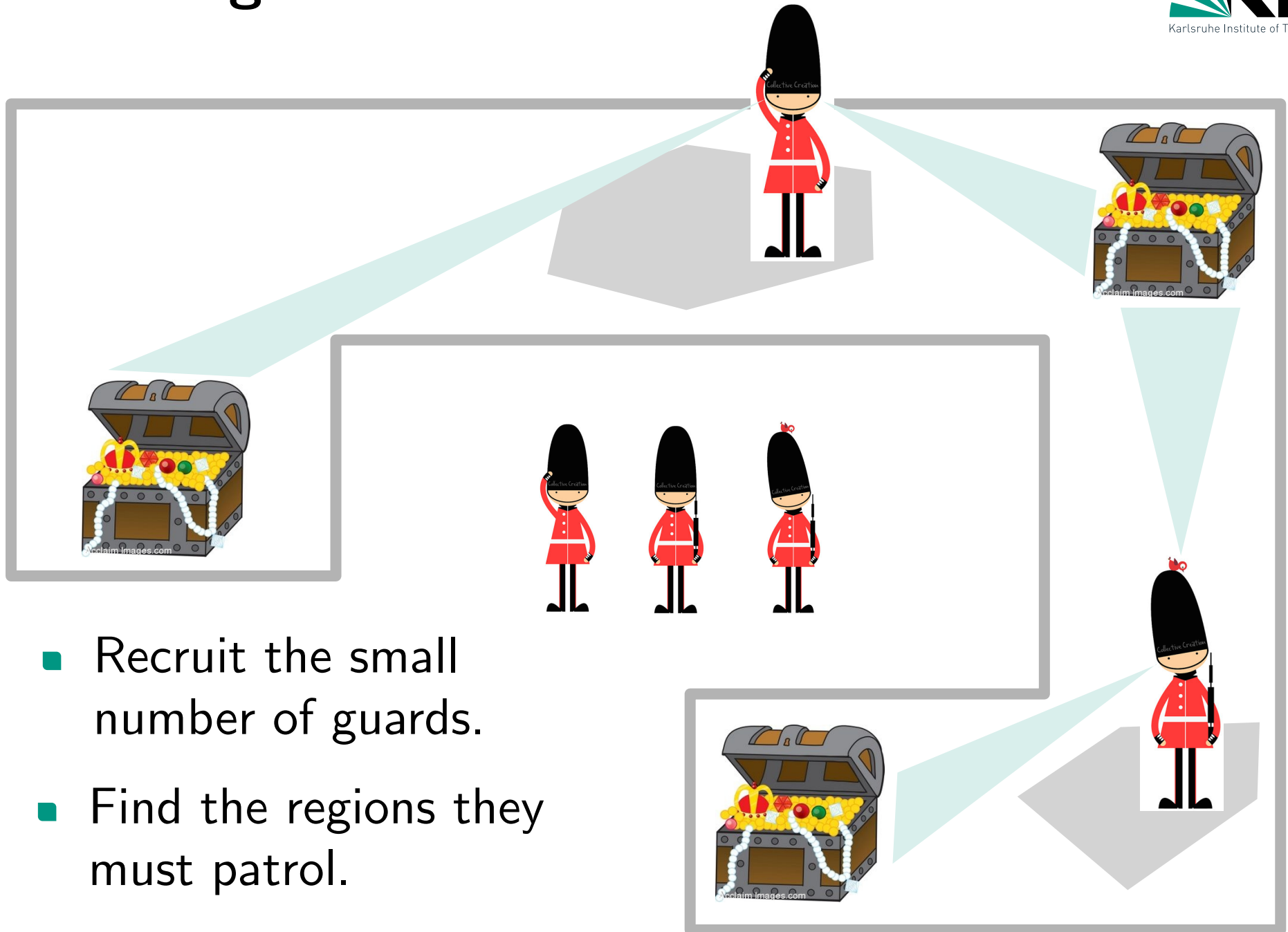


Secret Agent Protects Jewels

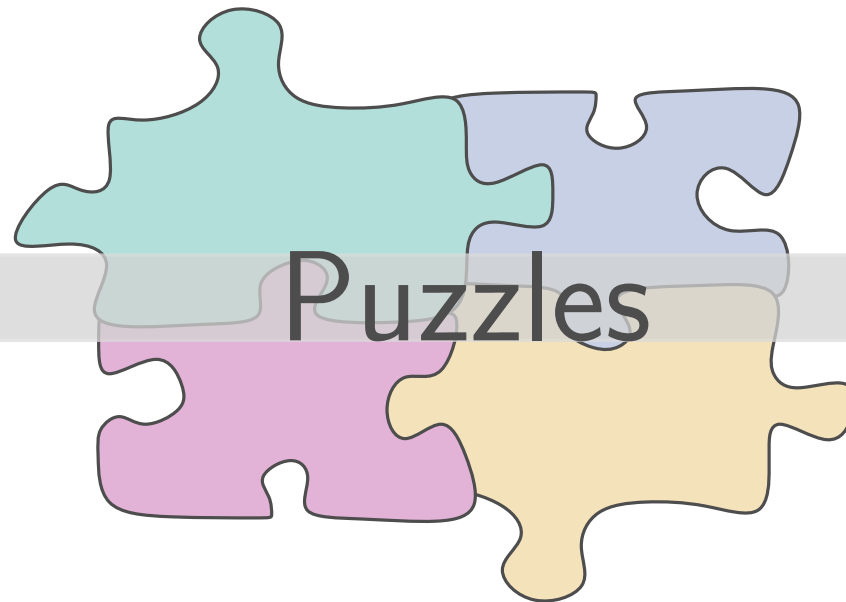


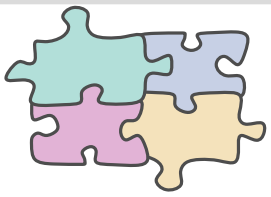
- Recruit the small number of guards.

Secret Agent Protects Jewels



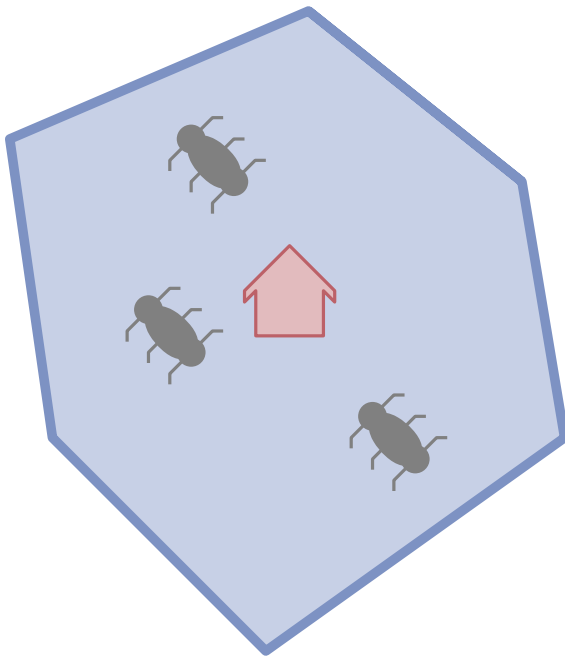
- Recruit the small number of guards.
- Find the regions they must patrol.





Puzzles

Puzzle # 1: Food fit

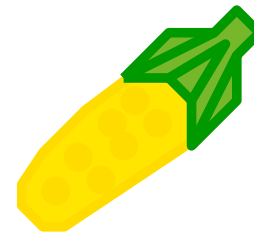
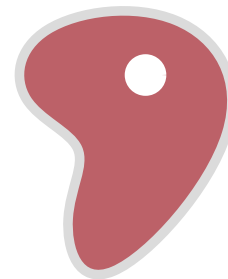


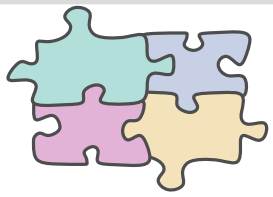
Given:

- A region representing an ant colony's home
- A "picnic" containing food items

Output:

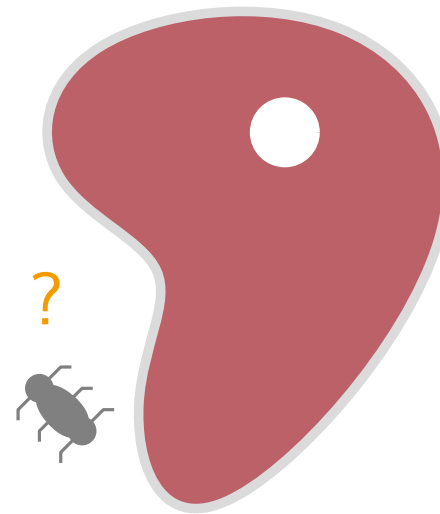
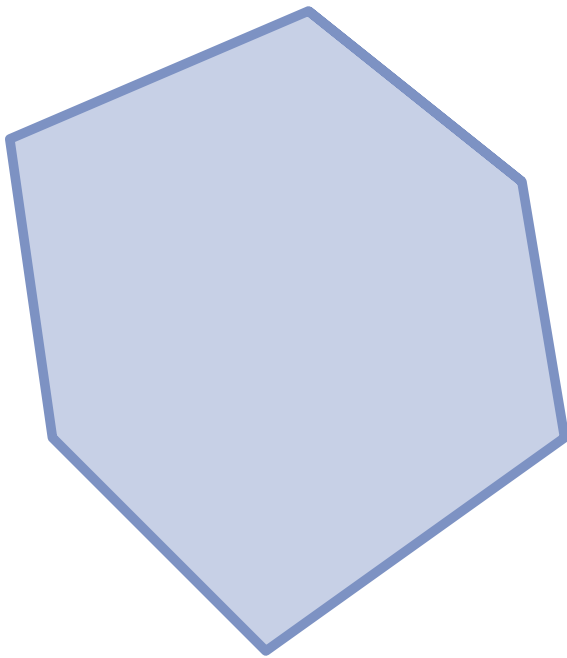
- Which food items can the ants fit in their home?

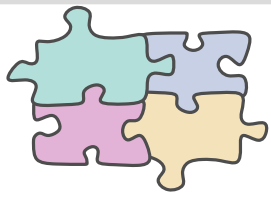




Puzzles

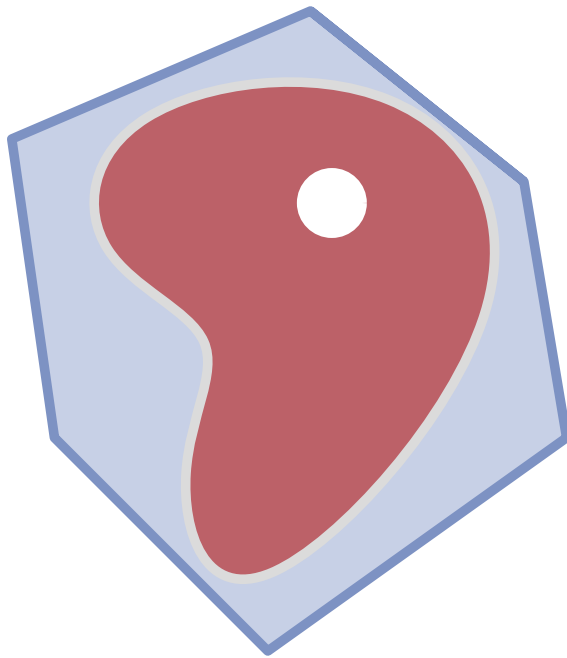
Puzzle # 1: Food fit





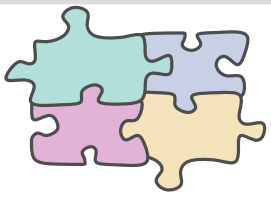
Puzzles

Puzzle # 1: Food fit



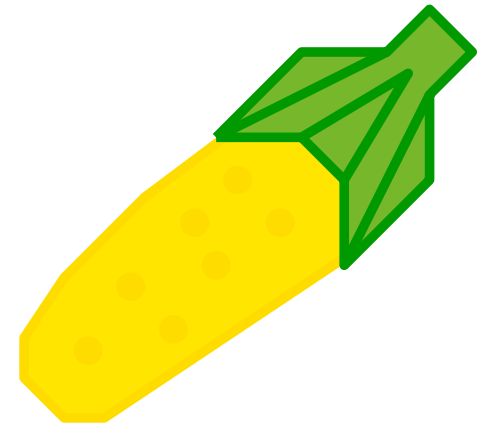
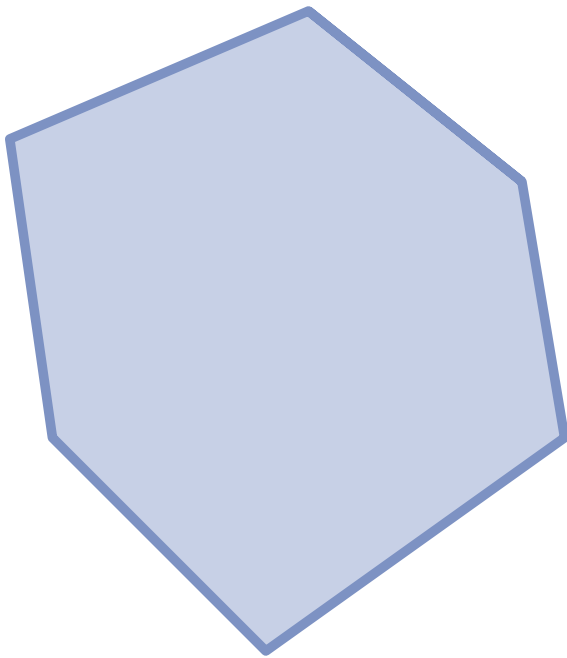
Fits!

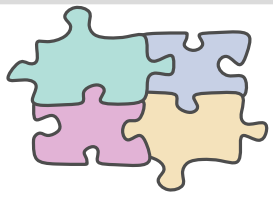




Puzzles

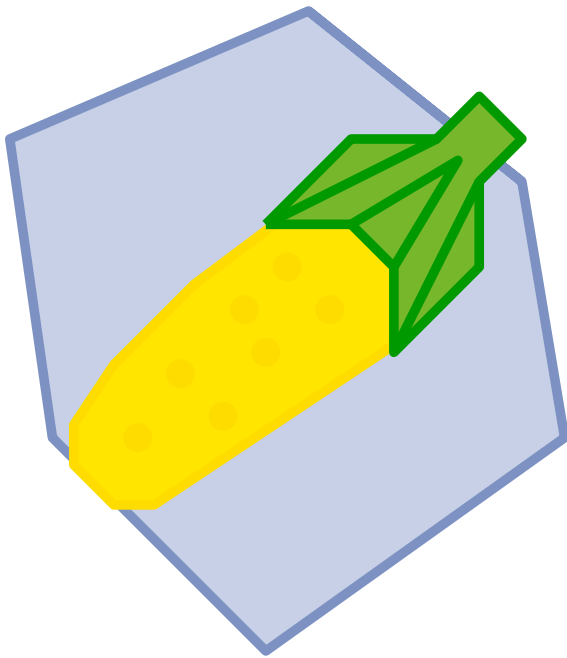
Puzzle # 1: Food fit

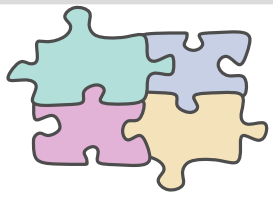




Puzzles

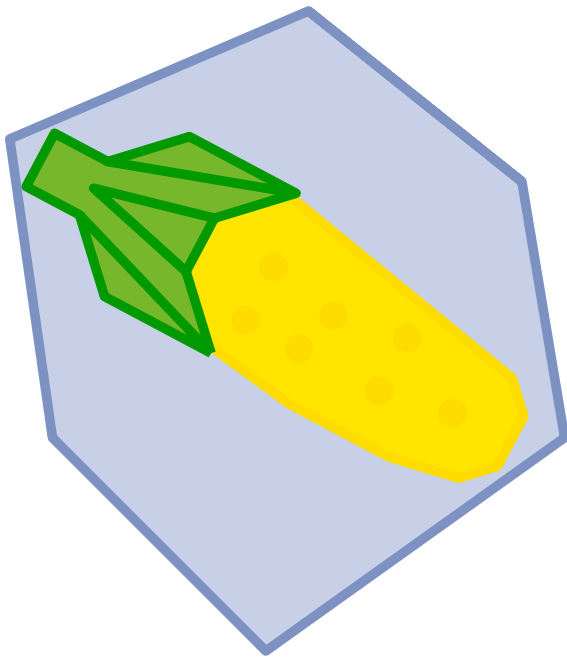
Puzzle # 1: Food fit





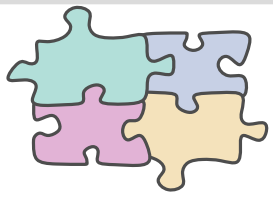
Puzzles

Puzzle # 1: Food fit



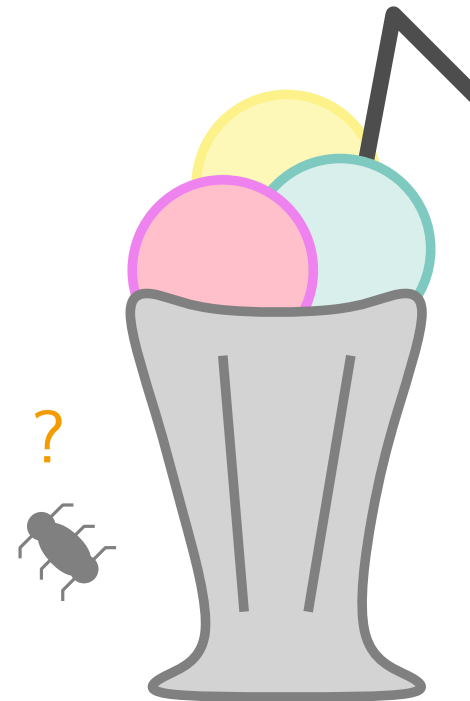
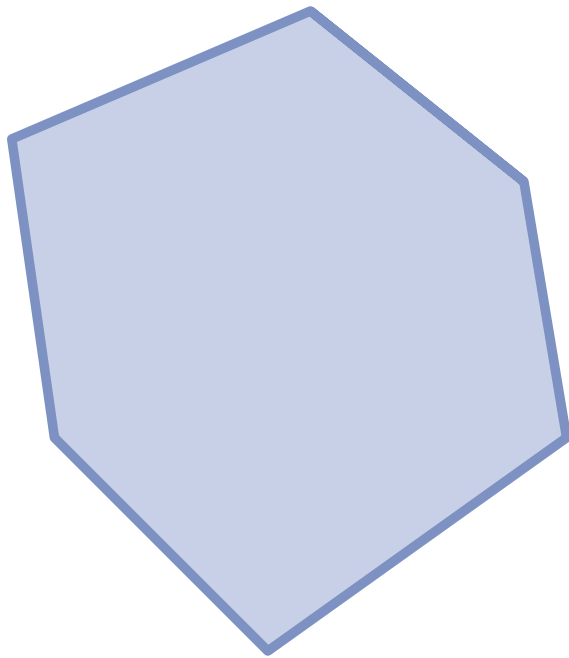
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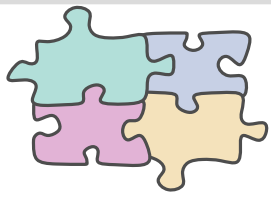




Puzzles

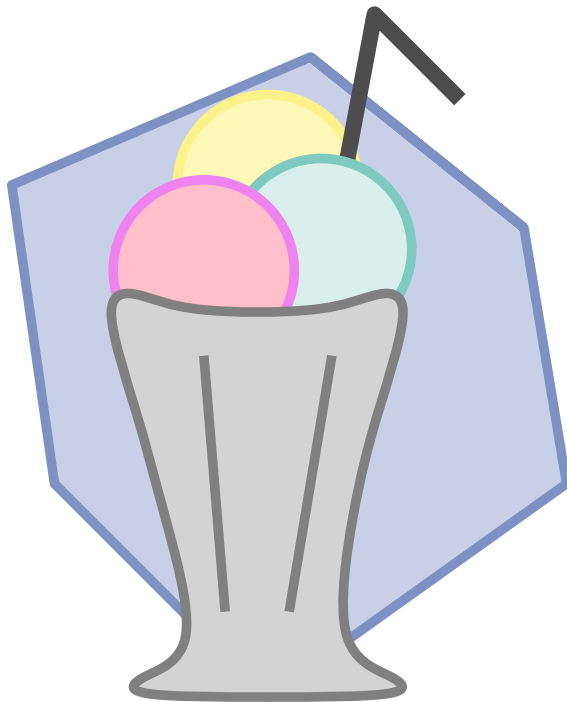
Puzzle # 1: Food fit

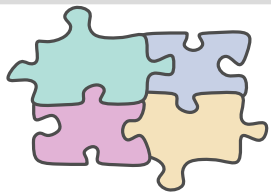




Puzzles

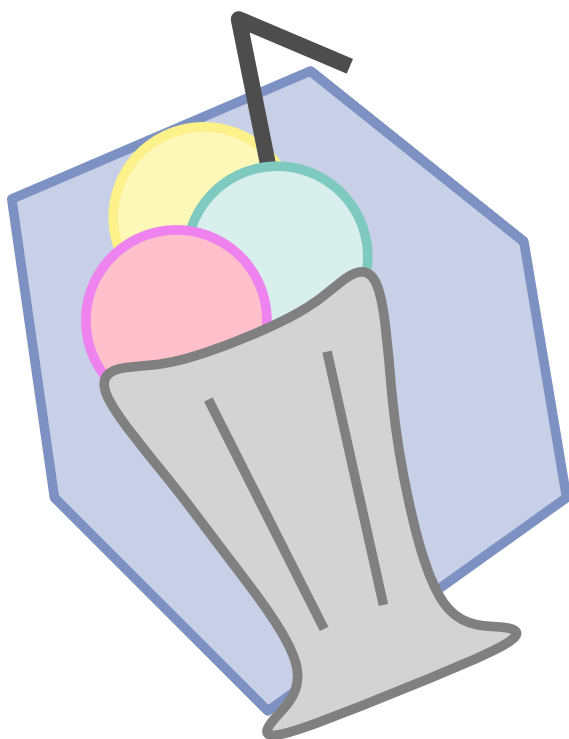
Puzzle # 1: Food fit





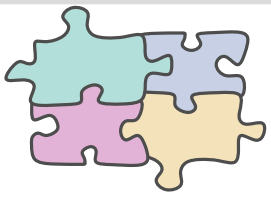
Puzzles

Puzzle # 1: Food fit



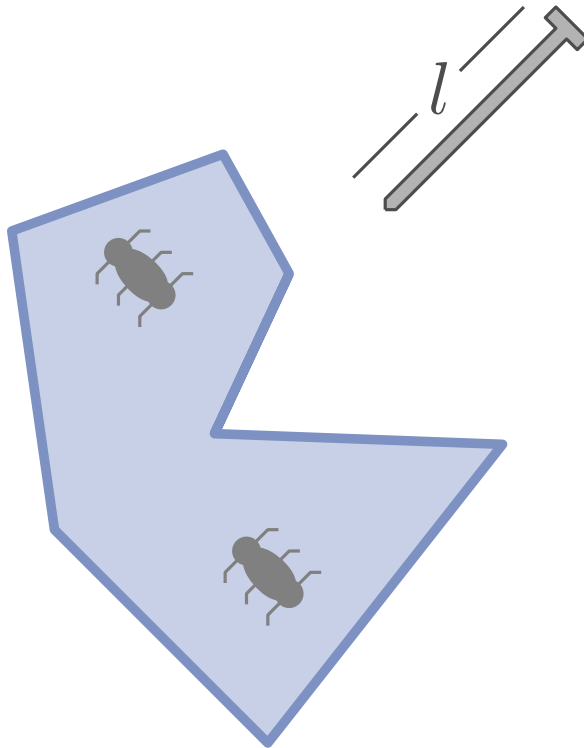
Does not fit!





Puzzles

Puzzle # 2: Protect the colony

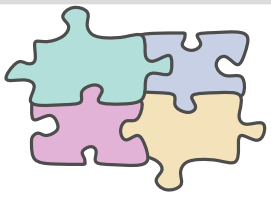


Given:

- A region representing an ant colony's home
- A nail of length l , to be hammered into the home

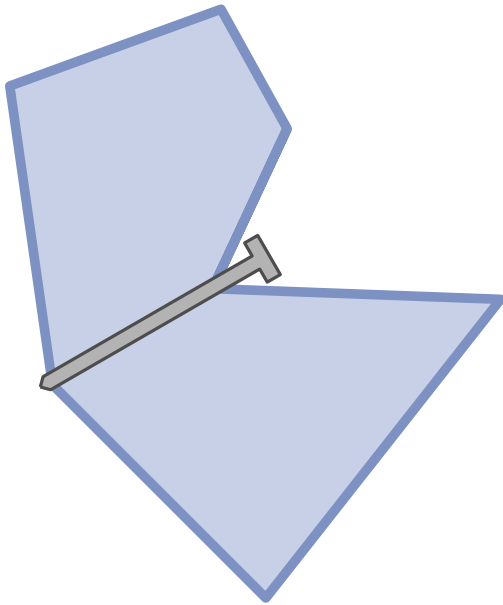
Output:

- Will the nail break the home apart?
- How can we make “small” changes to protect the home?



Puzzles

Puzzle # 2: Protect the colony

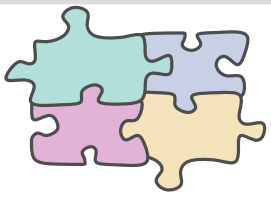


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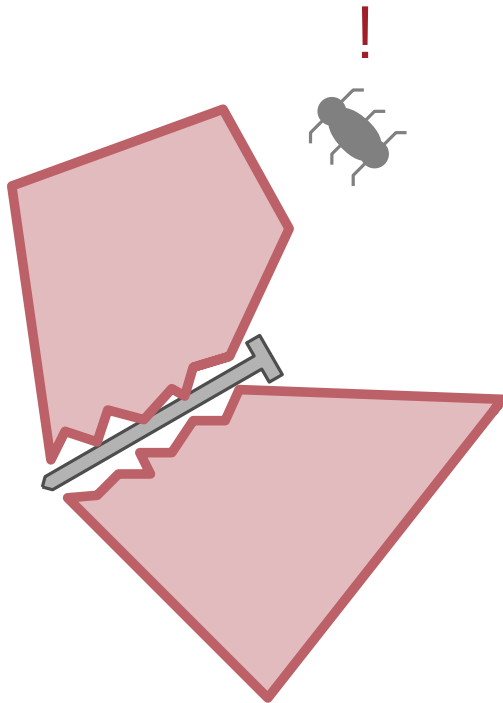
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Puzzles

Puzzle # 2: Protect the colony

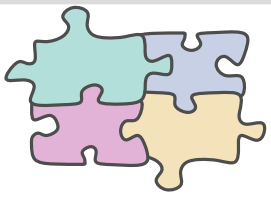


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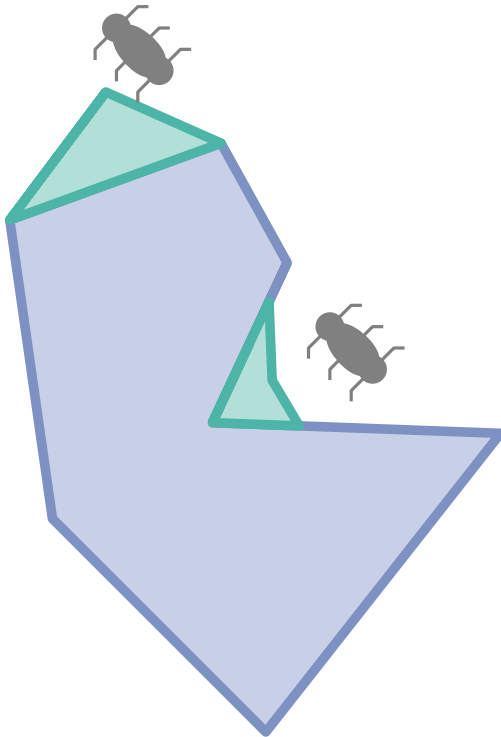
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Puzzles

Puzzle # 2: Protect the colony

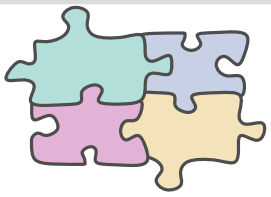


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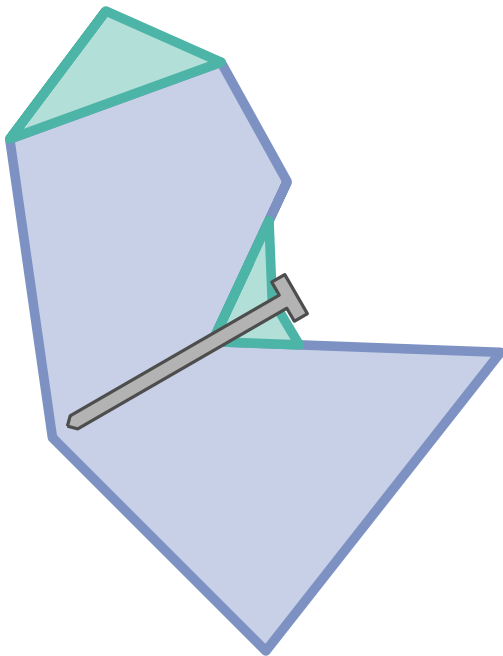
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Puzzles

Puzzle # 2: Protect the colony

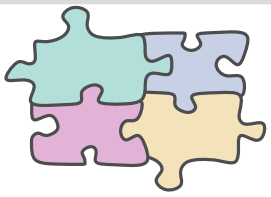


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- A region representing an ant colony's home
- A nail of length l , to be hammered into the home

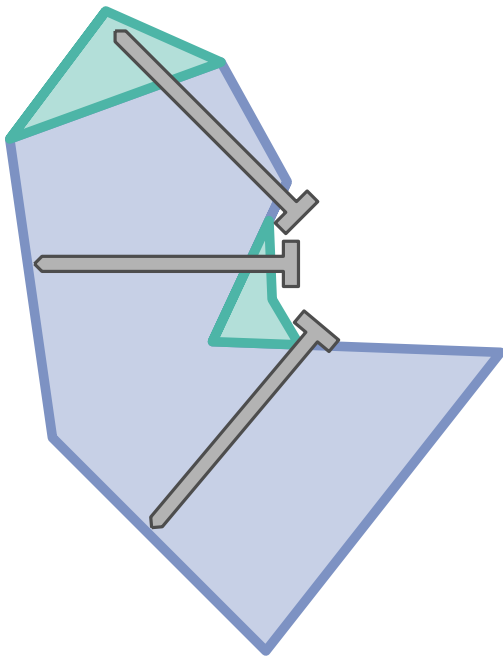
Output:

- Will the nail break the home apart?
- How can we make “small” changes to protect the home?



Puzzles

Puzzle # 2: Protect the colony

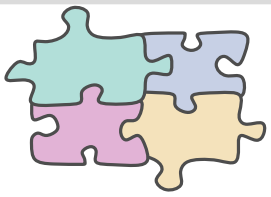


Given:

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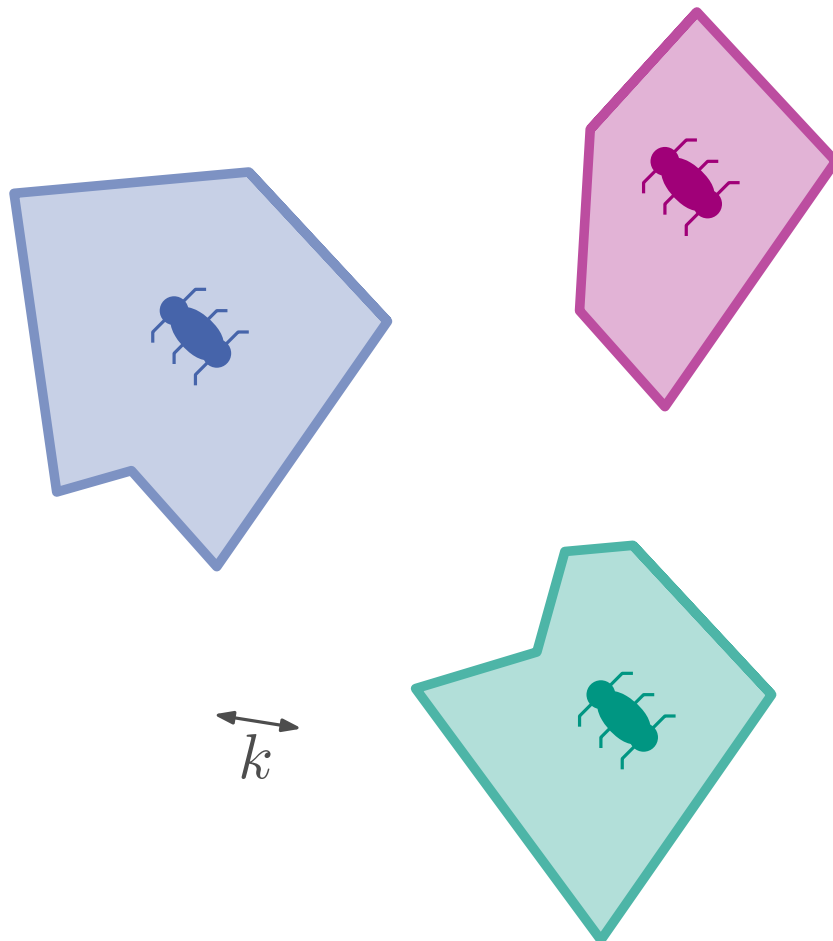
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Puzzles

Puzzle # 3: Keep away

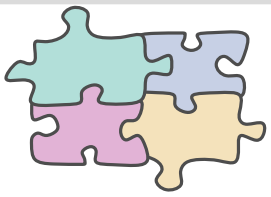


Given:

- A collection of ant colonies that grow over time
- A keep-away distance k

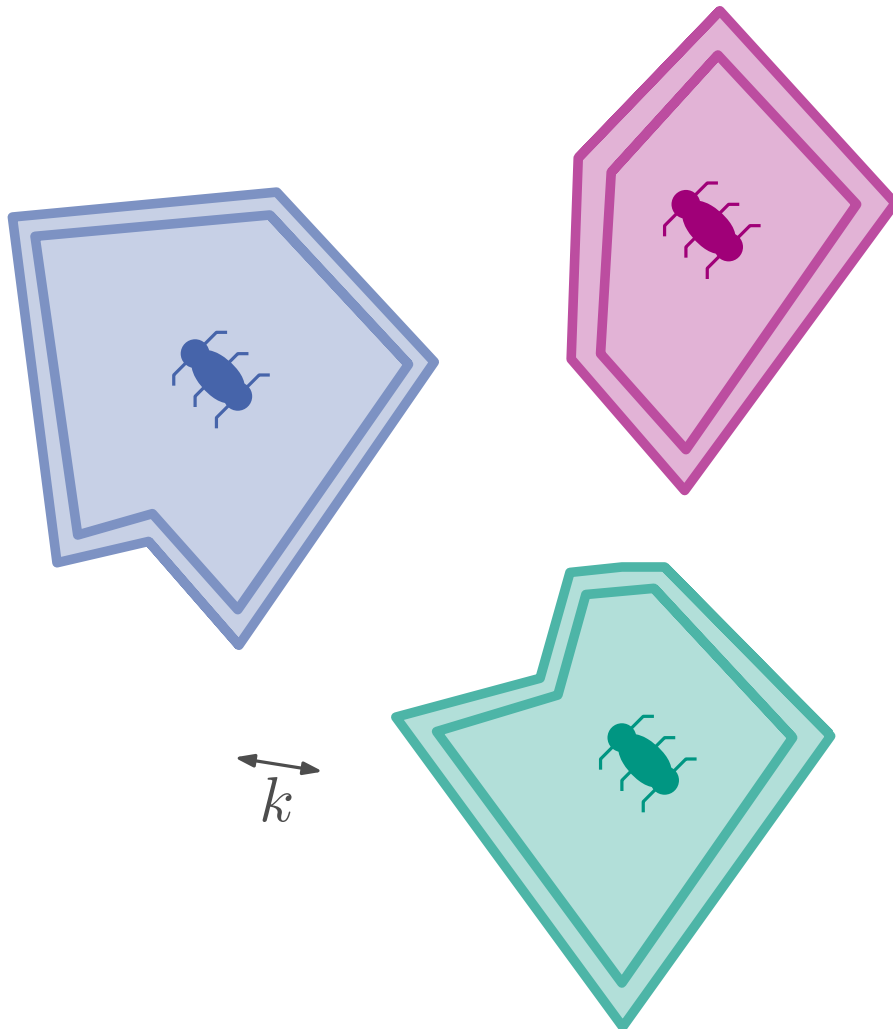
Output:

- The state of the colonies after t time steps



Puzzles

Puzzle # 3: Keep away

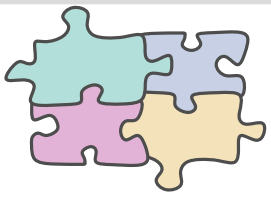


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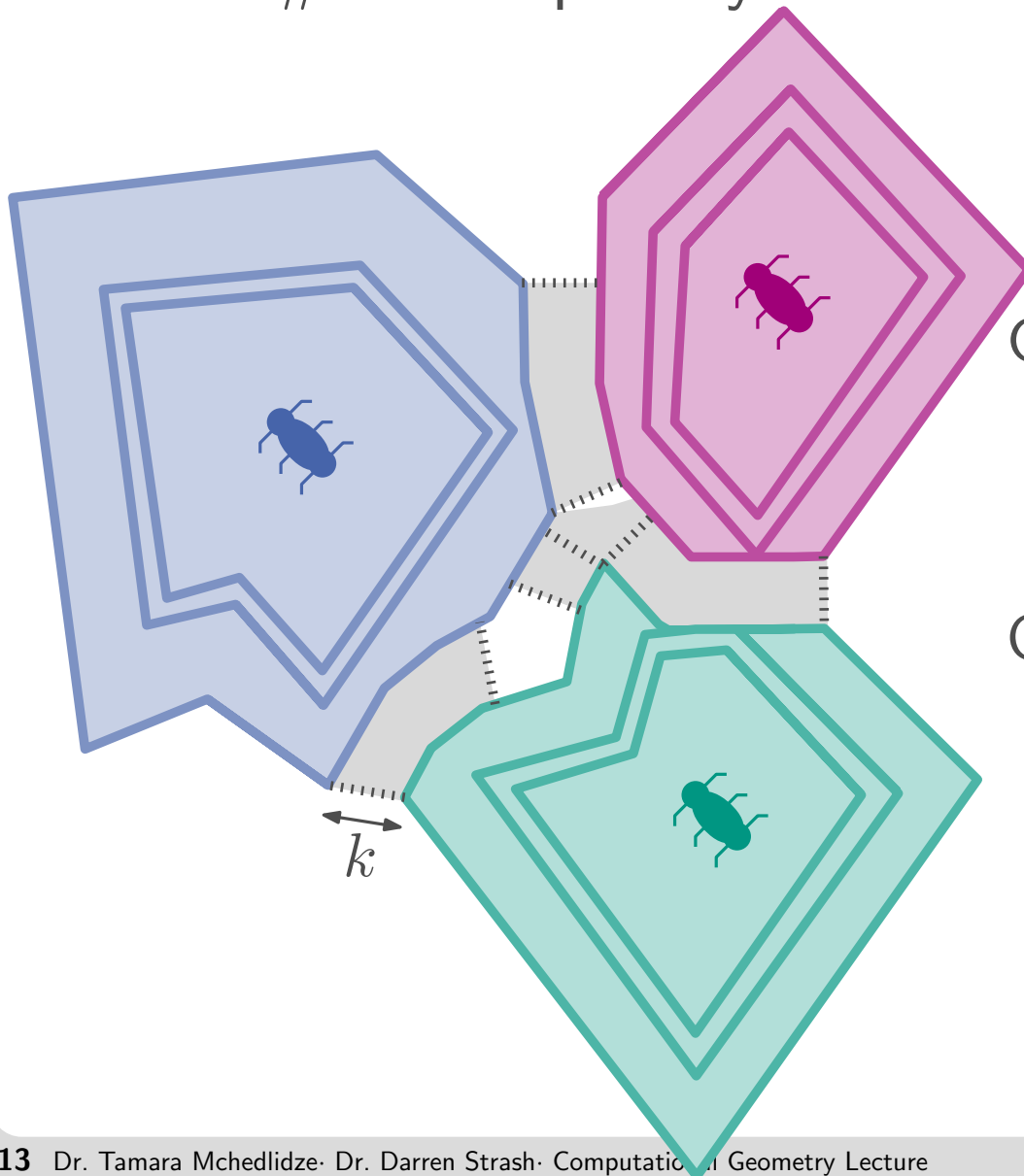
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Puzzles

Puzzle # 3: Keep away



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Output:

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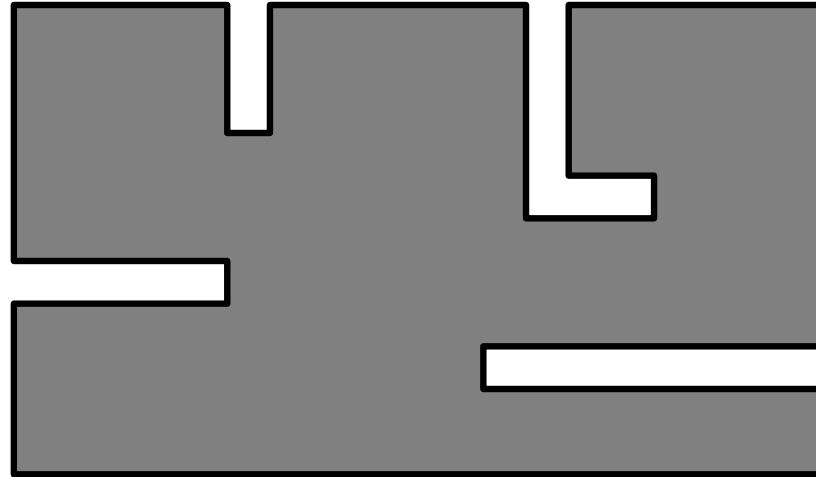
Project Selection

1. **Pacman:** Collision detection
2. **Pacman:** Ghosts activate on sight
3. **Pacman:** Ghosts activate on smell
4. **Secret Agent:** Shoot the laser
5. **Secret Agent:** Save the robot
6. **Secret Agent:** Guard the jewels
7. **Puzzle:** Food fit
8. **Puzzle:** Protect the colony
9. **Puzzle:** Keep away

Polygon Triangulation

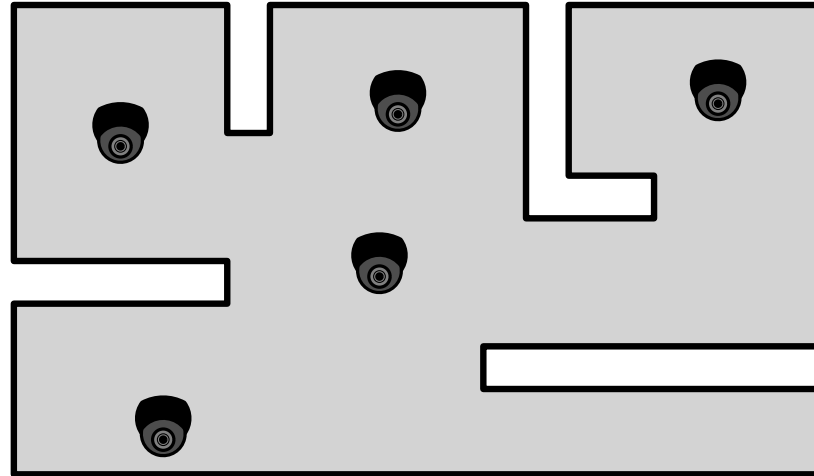
The Art-Gallery-Problem

Task: Install a number of cameras in an art gallery so that every part of the gallery is visible to at least one of them.



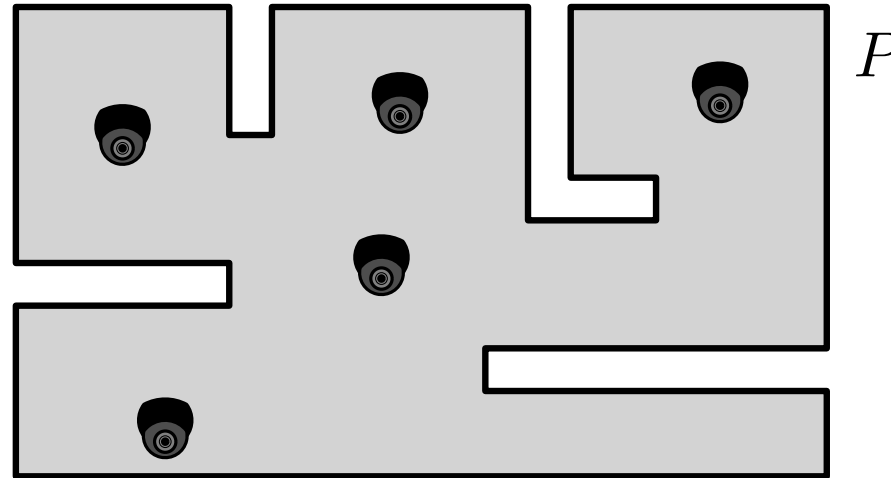
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The Art-Gallery-Problem

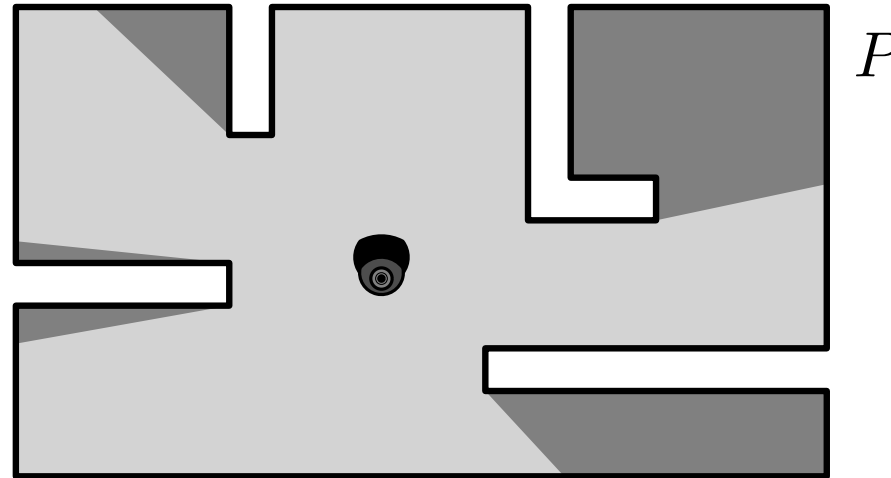
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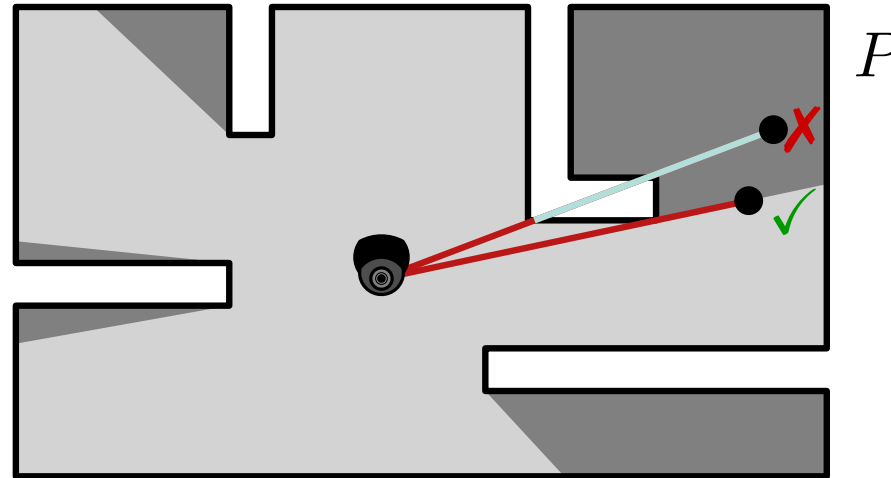


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Observation: each camera observes a star-shaped region

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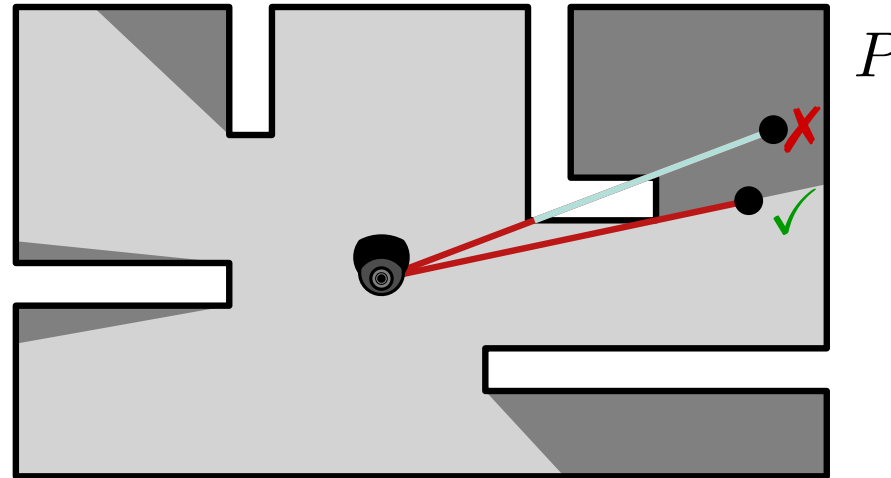
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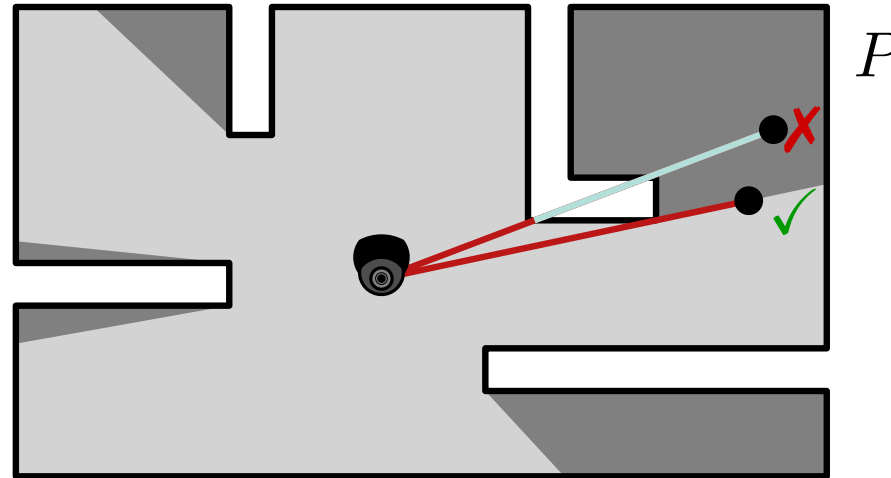
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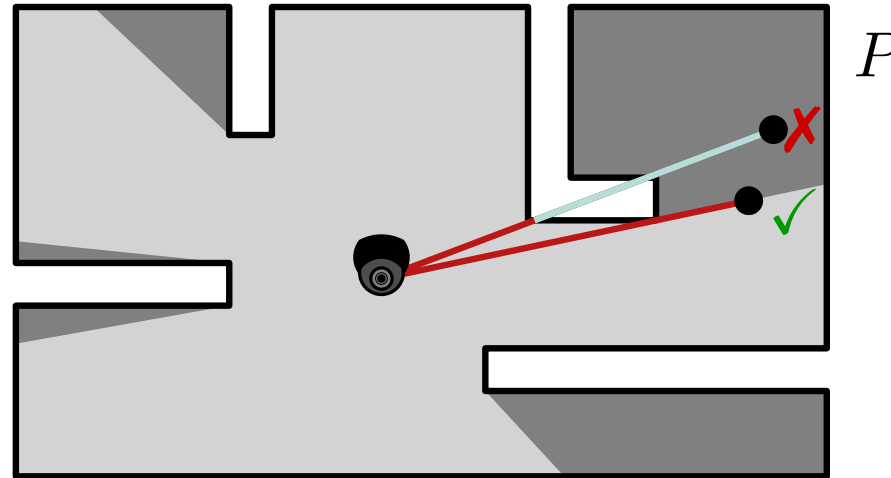
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→ The number depends on the number of corners n and on the shape of P

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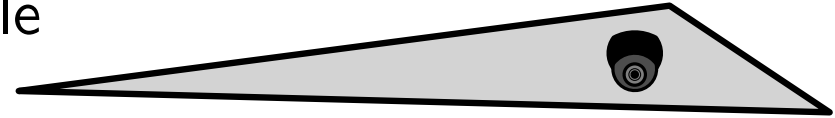
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NP-hard!

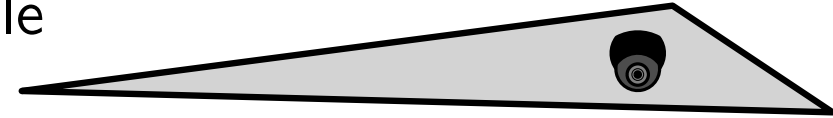
Problem Simplification

Observation: It is easy to guard a triangle

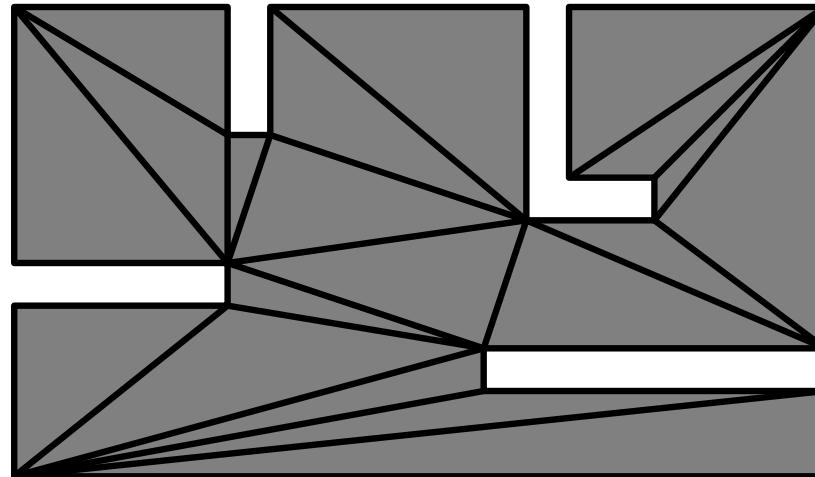


Problem Simplification

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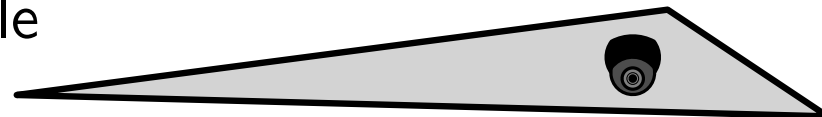


Idea: Decompose P into triangles and guard each of them

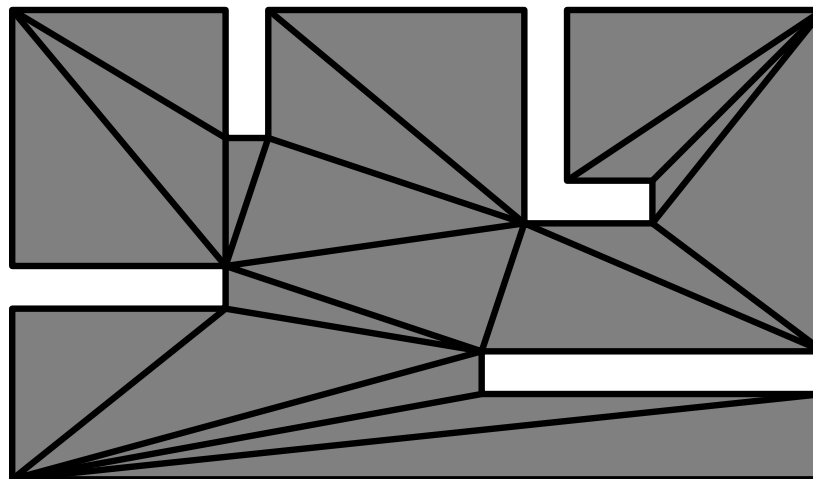


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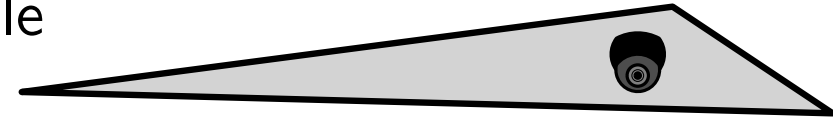
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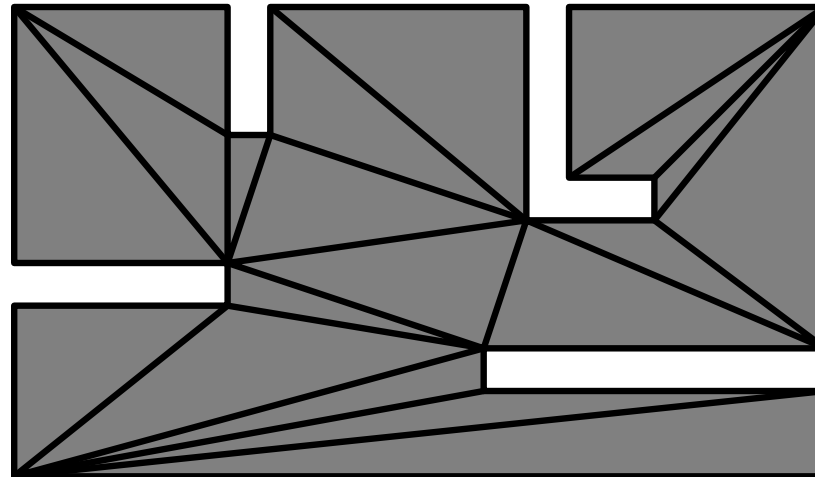
Theorem 1: Each simple polygon with n corners admits a triangulation; any such triangulation contains exactly $n - 2$ triangles.

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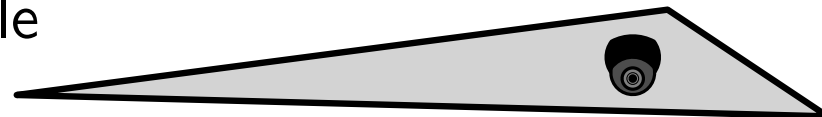


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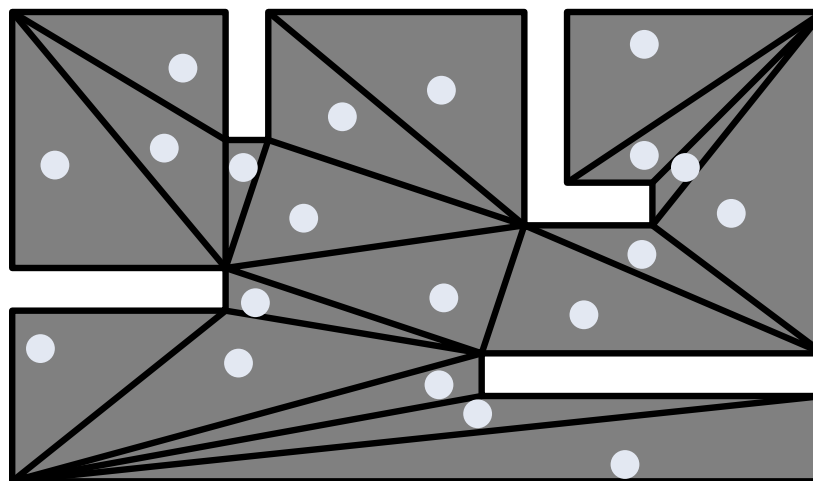
The proof implies a recursive $O(n^2)$ -Algorithm!

Problem Simplification

Observation: It is easy to guard a triangle



Idea: Decompose P into triangles and guard each of them

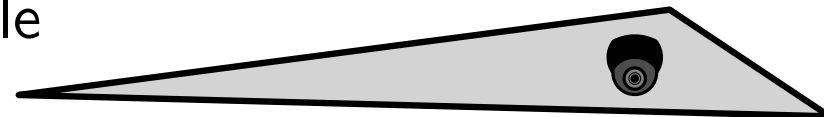


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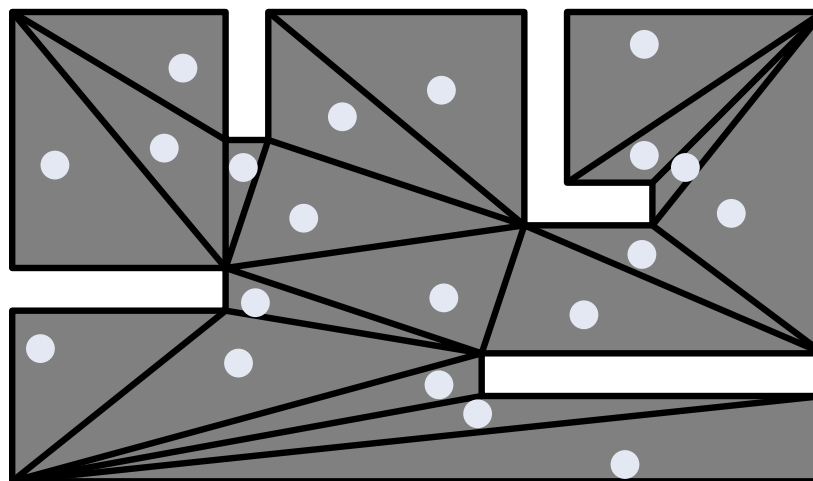
- P could be guarded by $n - 2$ cameras placed in the triangles

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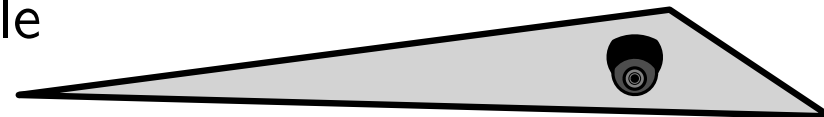
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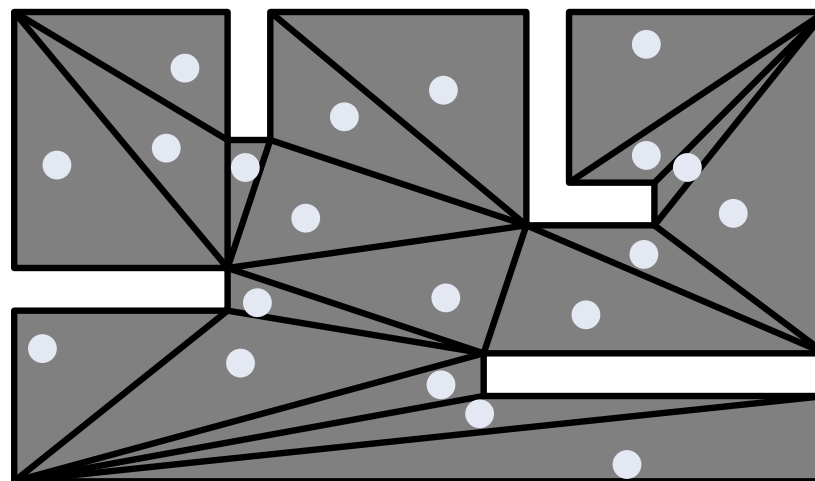
Can we do better?

Problem Simplification

Observation: It is easy to guard a triangle



Idea: Decompose P into triangles and guard each of them

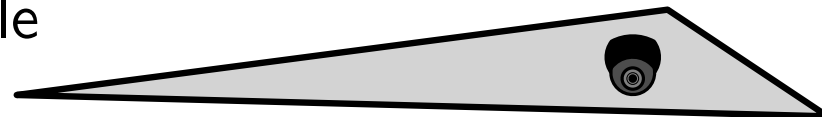


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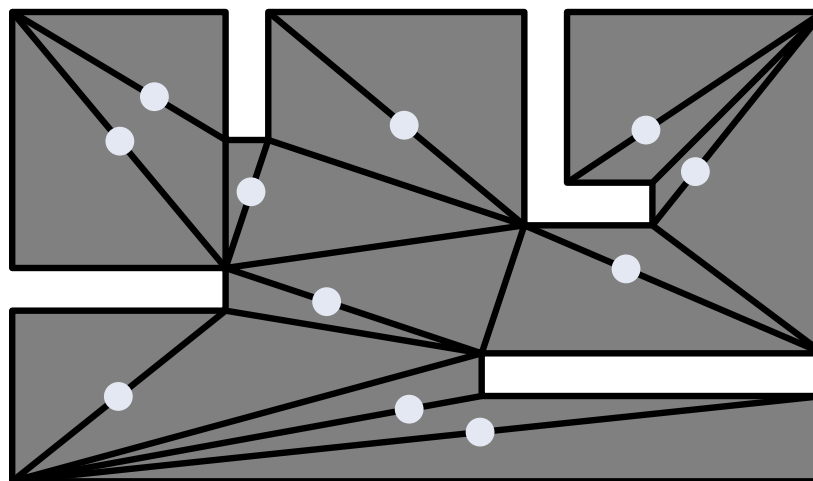
- P could be guarded by $n - 2$ cameras placed in the triangles
- P can be guarded by $\approx n/2$ cameras placed on the diagonals

Problem Simplification

Observation: It is easy to guard a triangle



Idea: Decompose P into triangles and guard each of them

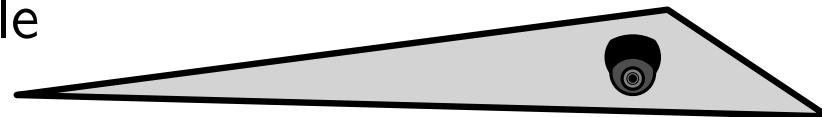


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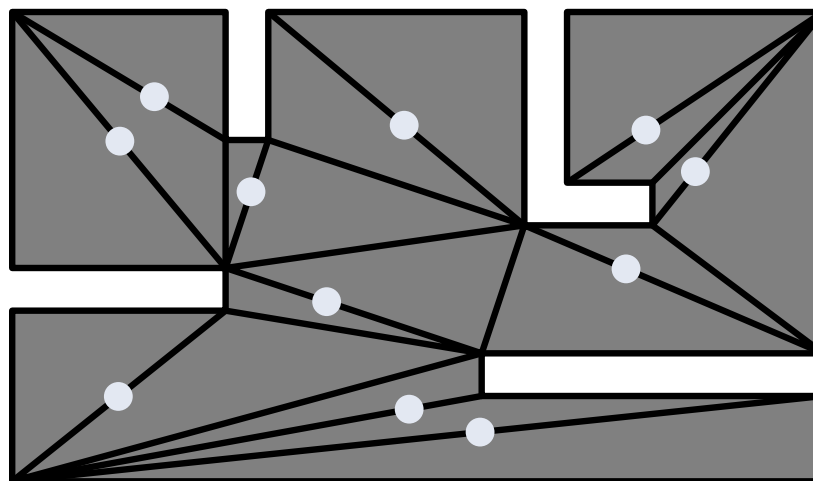
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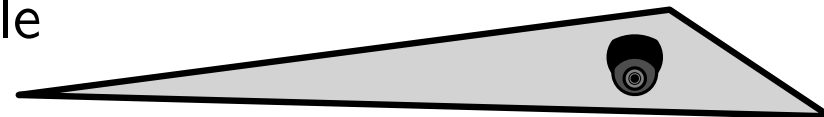


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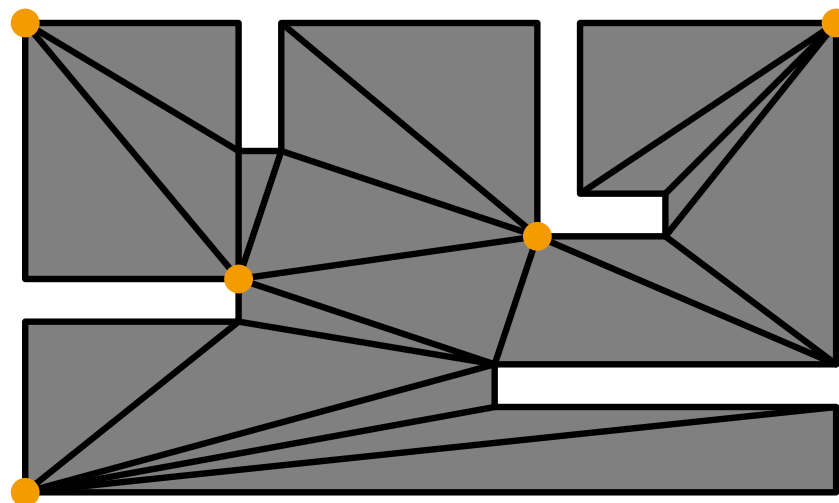
- P could be guarded by $n - 2$ cameras placed in the triangles
- P can be guarded by $\approx n/2$ cameras placed on the diagonals
- P can be observed by even smaller number of cameras placed on the corners

Problem Simplification

Observation: It is easy to guard a triangle



Idea: Decompose P into triangles and guard each of them



Theorem 1: Each simple polygon with n corners admits a triangulation; any such triangulation contains exactly $n - 2$ triangles.

- P could be guarded by $n - 2$ cameras placed in the triangles
- P can be guarded by $\approx n/2$ cameras placed on the diagonals
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The Art-Gallery-Theorem [Chvátal '75]

Theorem 2: For a simple polygon with n vertices, $\lfloor n/3 \rfloor$ cameras are sometimes necessary and always sufficient to guard it.

The Art-Gallery-Theorem [Chvátal '75]

Theorem 2: For a simple polygon with n vertices, $\lfloor n/3 \rfloor$ cameras are sometimes necessary and always sufficient to guard it.

Proof:

- Find a simple polygon with n corners that requires $\approx n/3$ cameras!

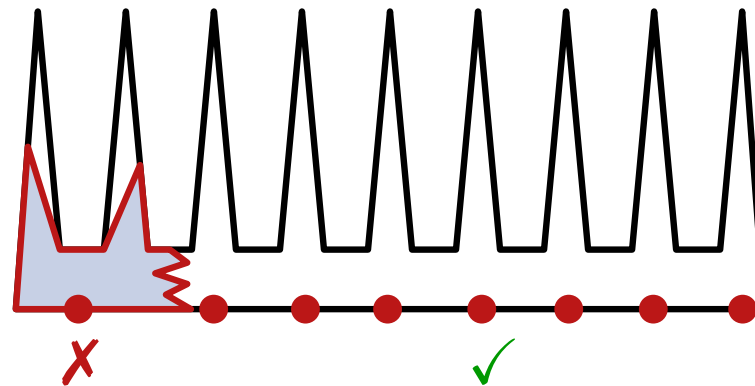
Discuss it with your neighbour for 2 minutes

The Art-Gallery-Theorem [Chvátal '75]

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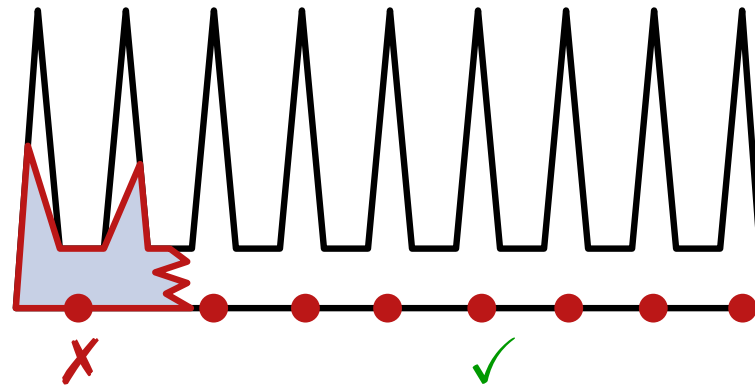


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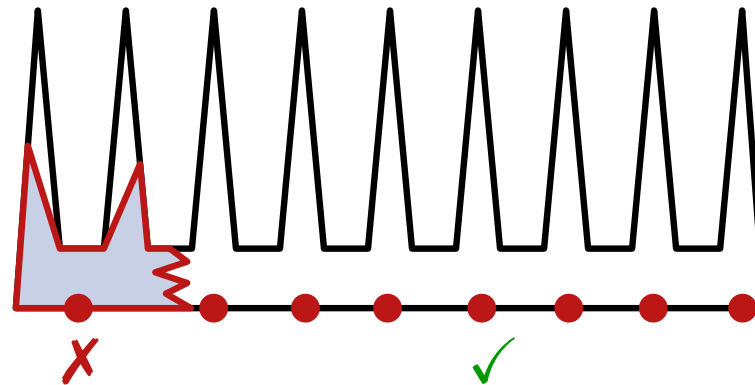
- Sufficiency on the board

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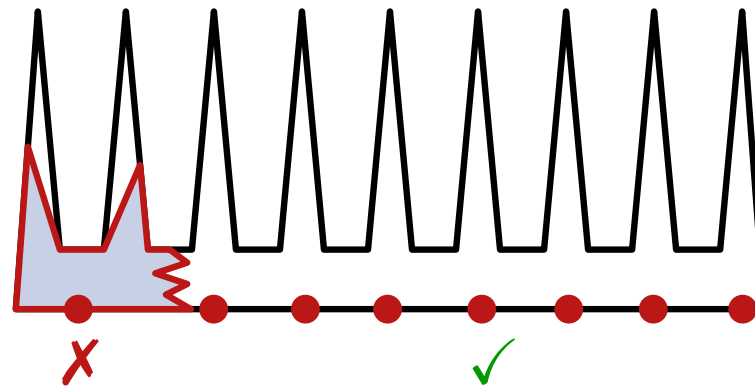
Conclusion: Given a triangulation, the $\lfloor n/3 \rfloor$ cameras that guard the polygon can be placed in $O(n)$ time.

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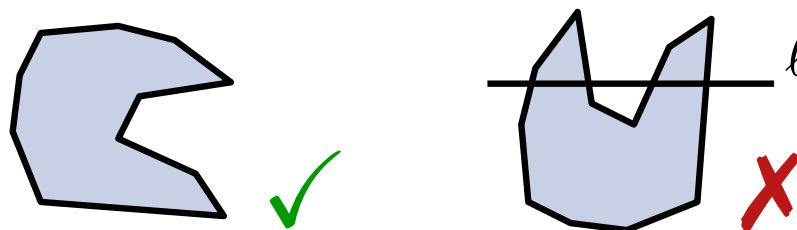
Can we do better than $O(n^2)$ described before?

Proof of Art-Gallery-Theorem: Overview

3-step process:

- Step 1: Decompose P into y -monotone polygons

Definition: A polygon is y -monotone, if for any horizontal line ℓ , the intersection $\ell \cap P$ is connected.



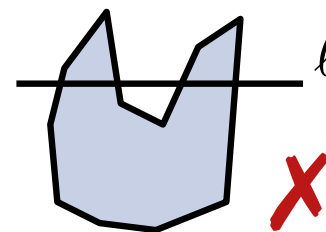
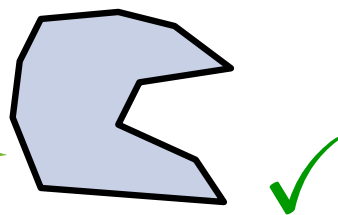
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The two paths from the topmost to the bottommost point bounding the polygon, never go upward



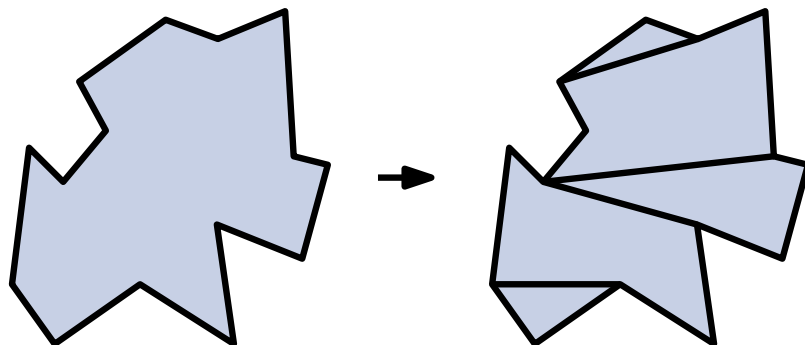
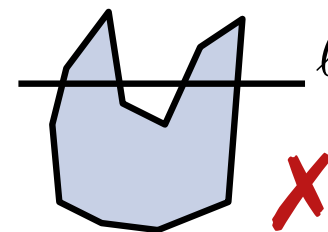
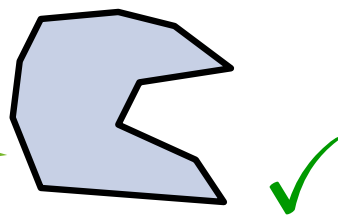
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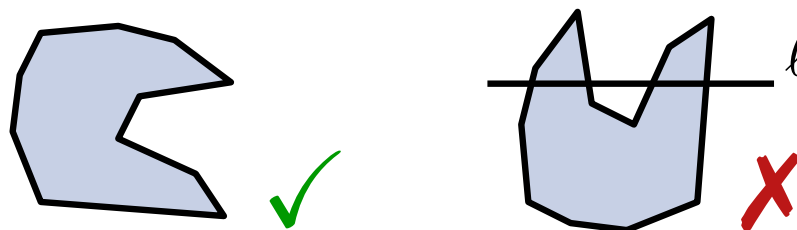


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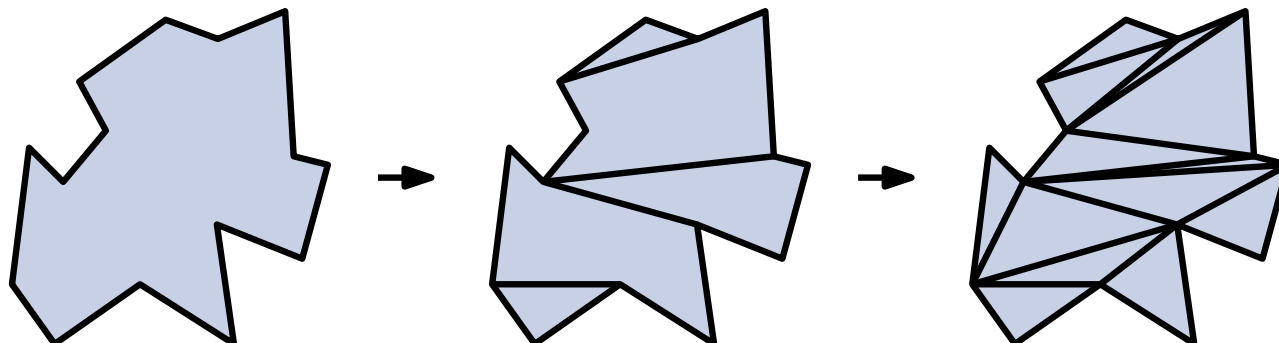
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- Step 2: Triangulate the resulting y -monotone polygons

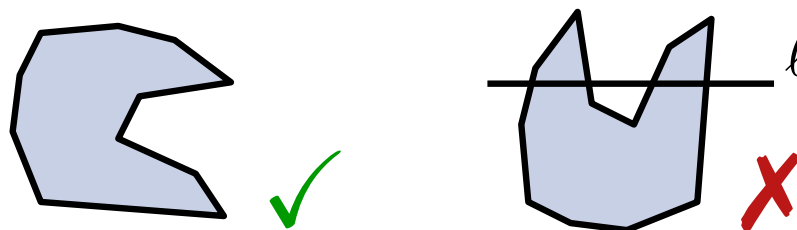


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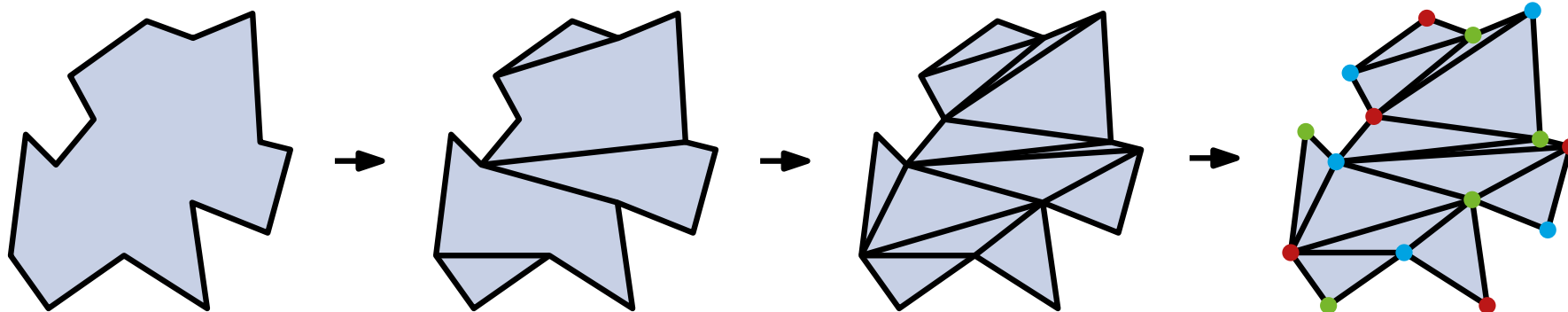
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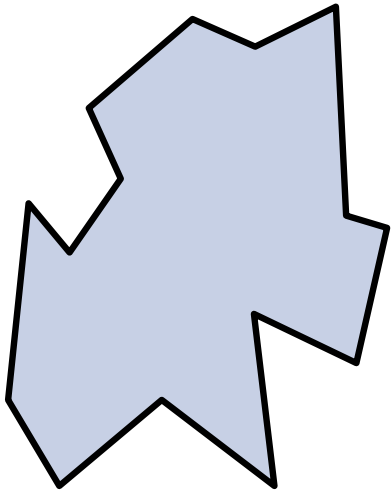


- Step 2: Triangulate the resulting y -monotone polygons
- Step 3: use DFS to color the vertices of the polygon



Partition into y -monotone Polygons

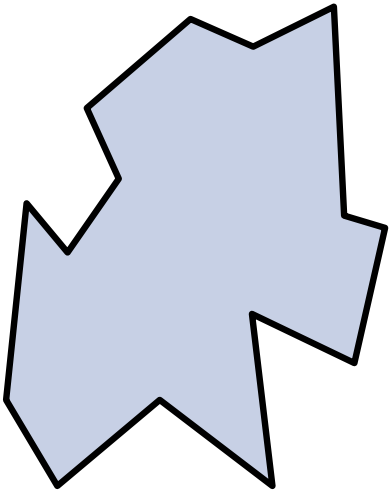
Idea: Five different types of vertices



Partition into y -monotone Polygons

Idea: Five different types of vertices

– *Turn vertices:*

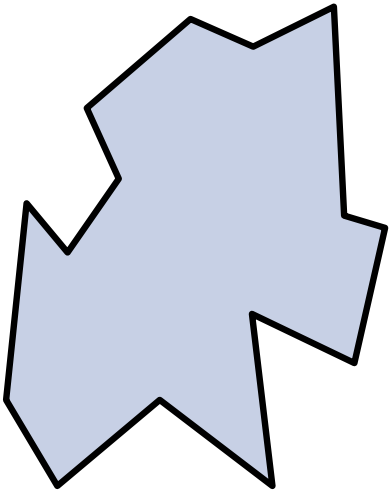


– *regular vertices*

Partition into y -monotone Polygons

Idea: Five different types of vertices

- *Turn vertices:*
vertical change in direction

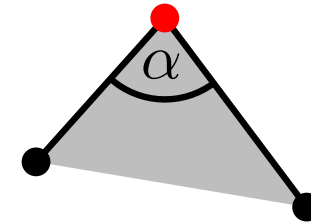
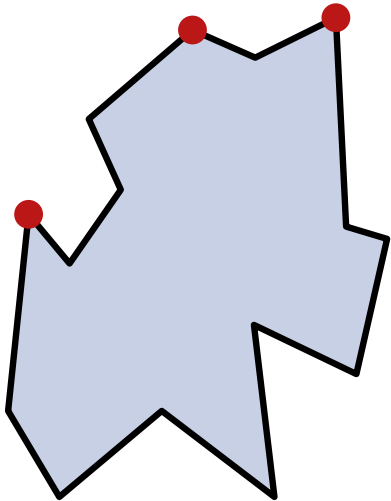


- *regular vertices*

Partition into y -monotone Polygons

Idea: Five different types of vertices

- *Turn vertices:*
vertical change in direction
 - *start vertices*



if $\alpha < 180^\circ$

- *regular vertices*

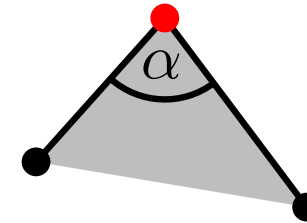
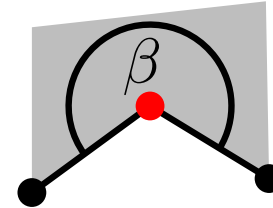
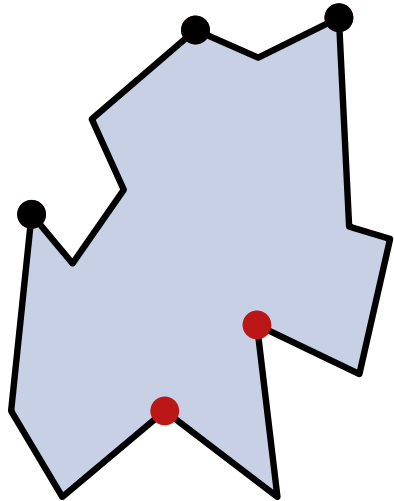
Partition into y -monotone Polygons

Idea: Five different types of vertices

– *Turn vertices:*
vertical change in direction

■ *start* vertices

■ *split* vertices



if $\alpha < 180^\circ$

if $\beta > 180^\circ$

– *regular* vertices

Partition into y -monotone Polygons

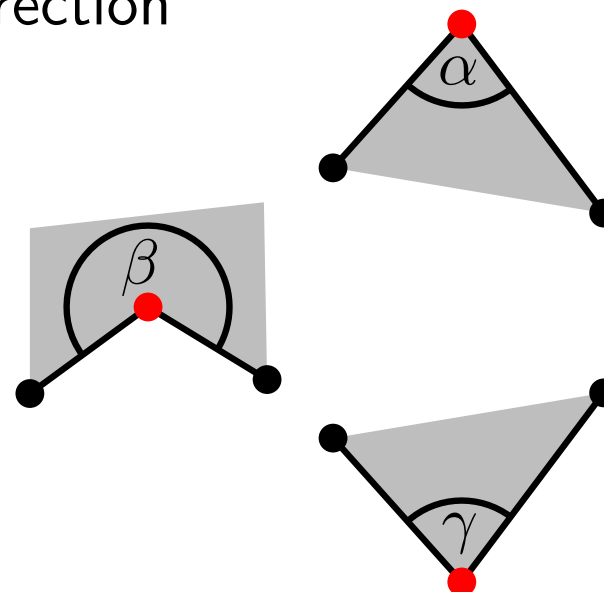
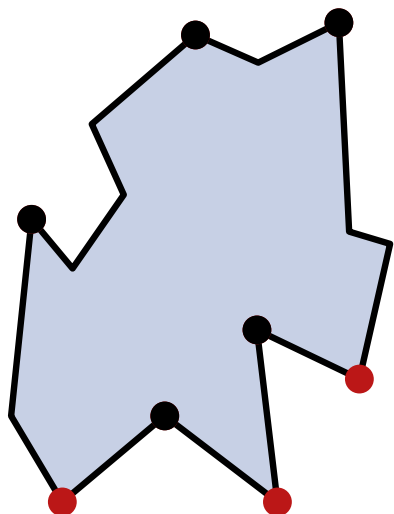
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– *Turn vertices:*
vertical change in direction

■ *start* vertices

■ *split* vertices

■ *end* vertices



if $\alpha < 180^\circ$

if $\beta > 180^\circ$

if $\gamma < 180^\circ$

– *regular* vertices

Partition into y -monotone Polygons

Idea: Five different types of vertices

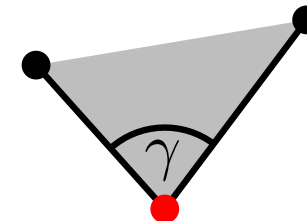
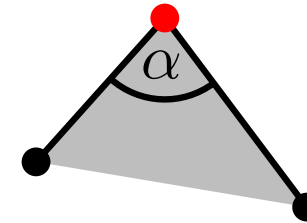
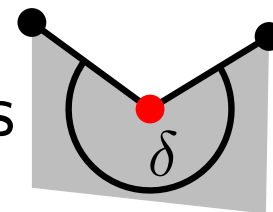
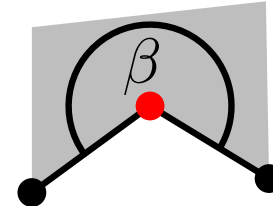
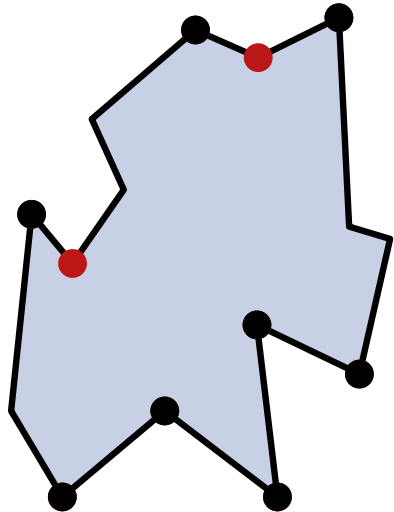
– *Turn vertices:*
vertical change in direction

■ *start* vertices

■ *split* vertices

■ *end* vertices

■ *merge* vertices



if $\alpha < 180^\circ$

if $\beta > 180^\circ$

if $\gamma < 180^\circ$

if $\delta > 180^\circ$

– *regular* vertices

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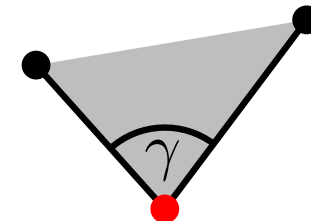
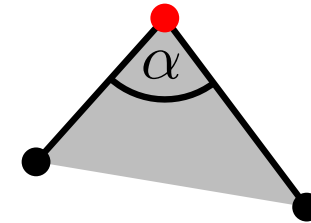
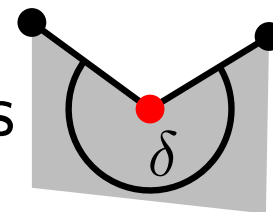
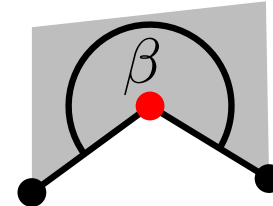
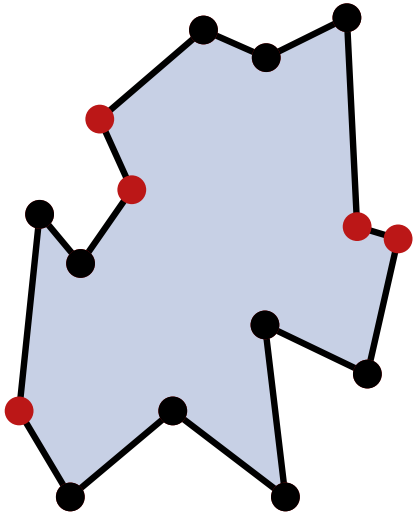
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Lemma 1: A polygon is y -monotone if it has no split vertices or merge vertices.

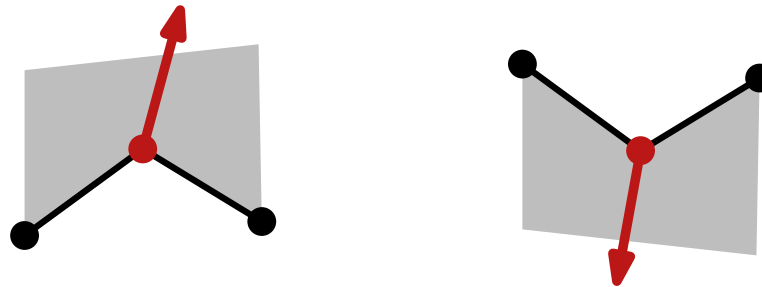
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Proof: On the blackboard

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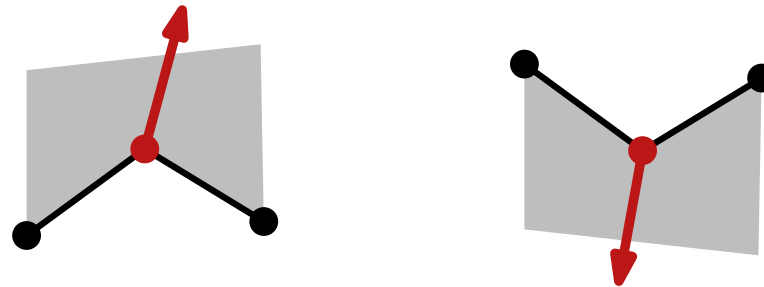
\Rightarrow We need to eliminate all split and merge vertices by using diagonals



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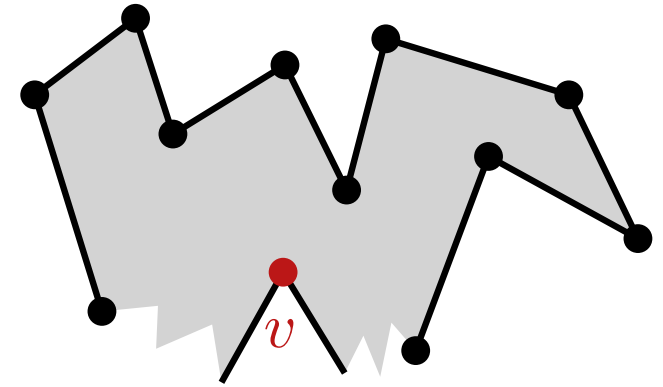
\Rightarrow We need to eliminate all split and merge vertices by using diagonals



Observation: The diagonals should neither cross the edges of P nor the other diagonals

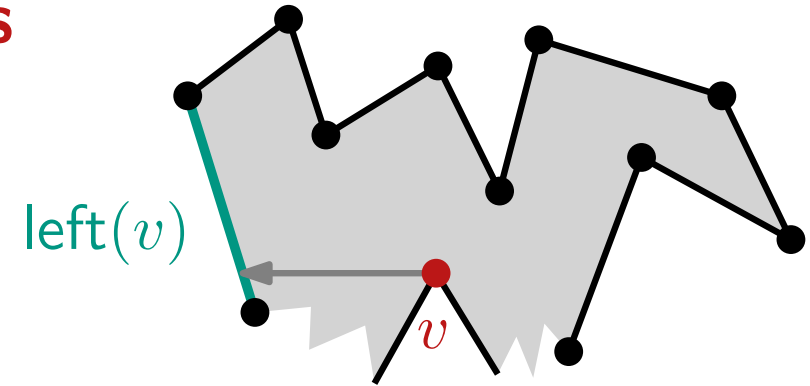
Ideas for Sweep-Line-Algorithm

1) Diagonals for the split vertices



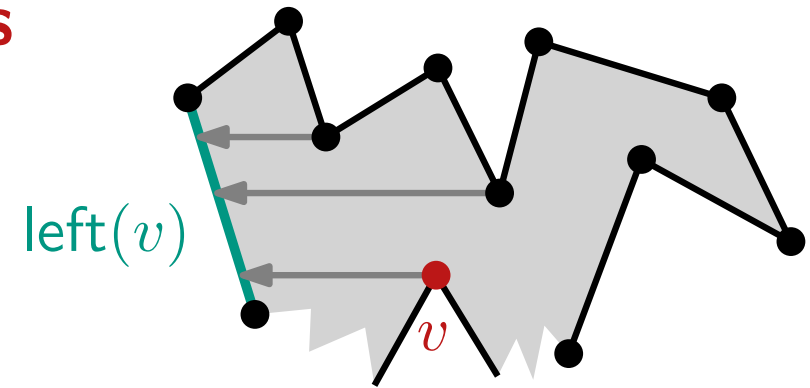
1) Diagonals for the split vertices

- compute for each vertex v its left adjacent edge $\text{left}(v)$ with respect to the horizontal sweep line ℓ



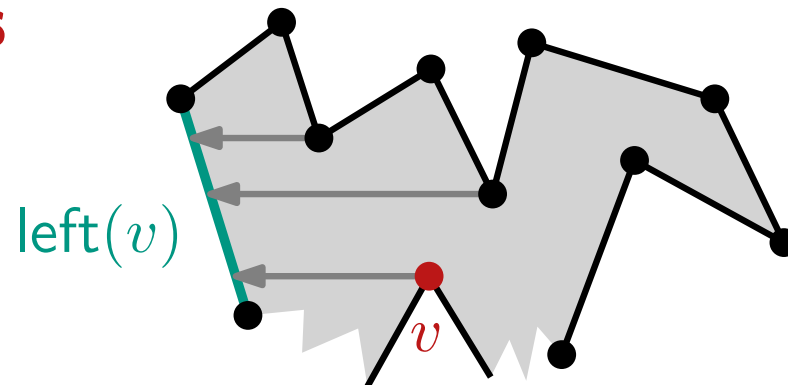
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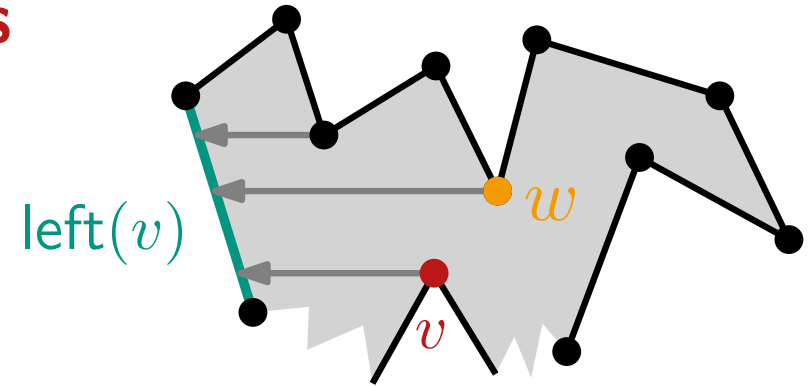
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- compute for each vertex v its left adjacent edge $\text{left}(v)$ with respect to the horizontal sweep line ℓ
- connect split vertex v to the nearest vertex w above v , such that $\text{left}(w) = \text{left}(v)$



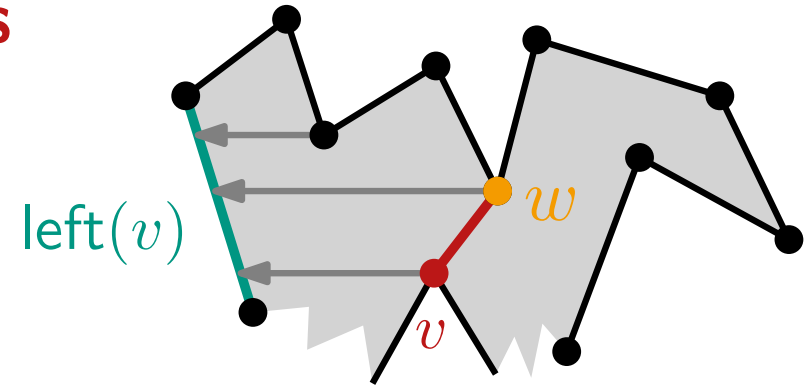
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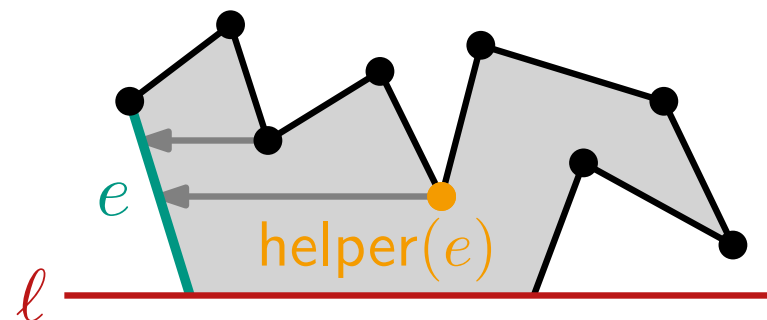
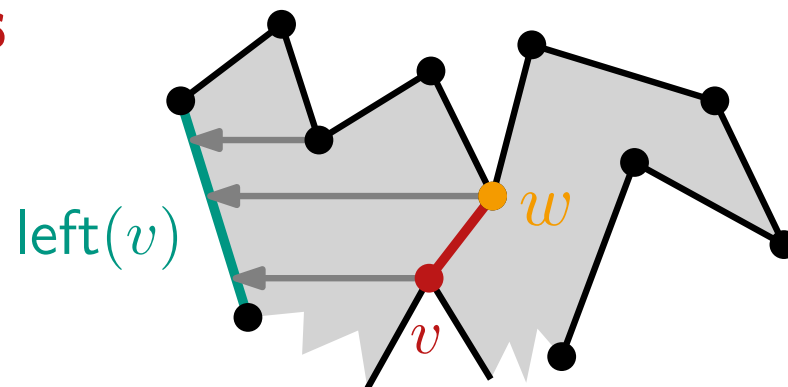
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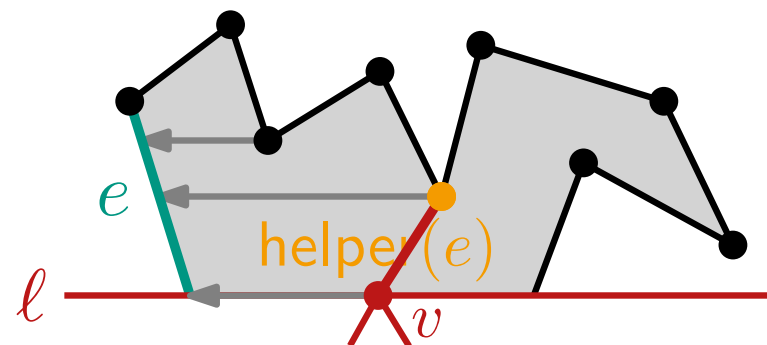
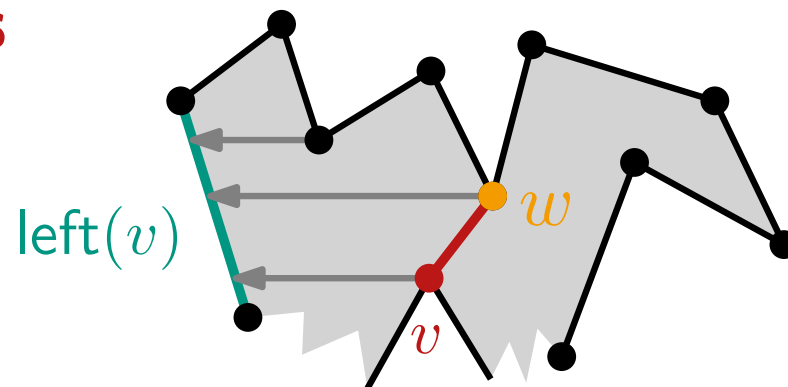
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- for each edge e save the bottommost vertex w such that $\text{left}(w) = e$; notation $\text{helper}(e) := w$



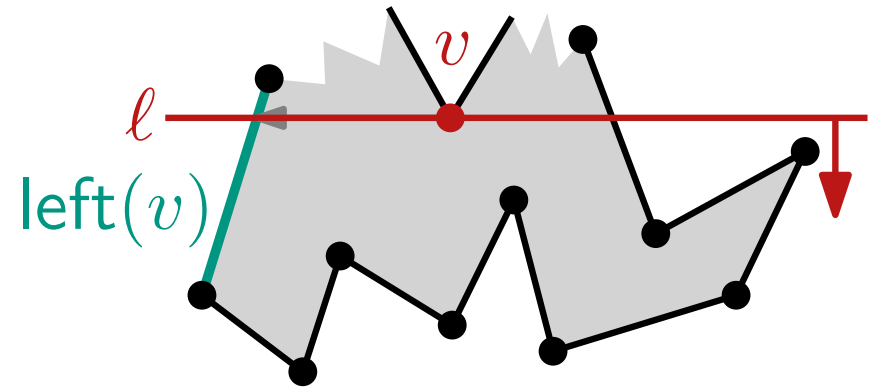
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- when ℓ passes through a split vertex v , we connect v with $\text{helper}(\text{left}(v))$



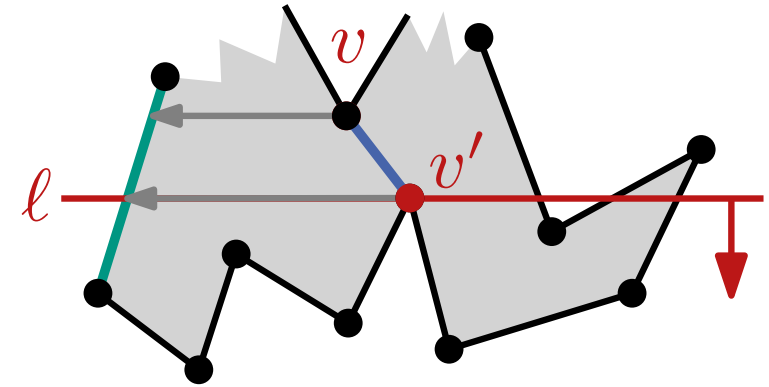
2) Diagonals for merge vertices

- when the vertex v is reached, we set $\text{helper}(\text{left}(v)) = v$



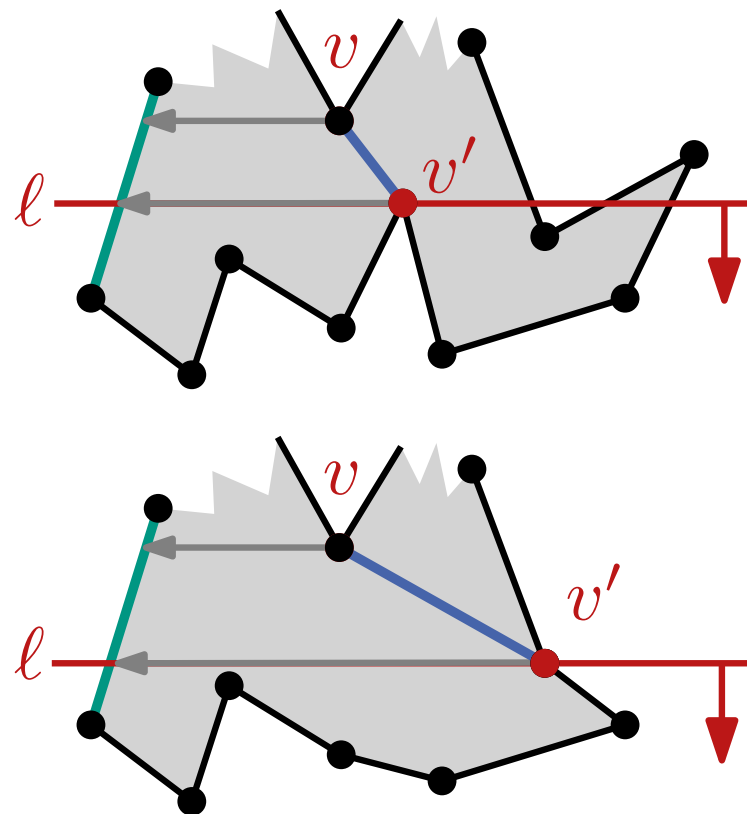
2) Diagonals for merge vertices

- when the vertex v is reached, we set $\text{helper}(\text{left}(v)) = v$
- when we reach a split vertex v' such that $\text{left}(v') = \text{left}(v)$ the diagonal (v, v') is introduced



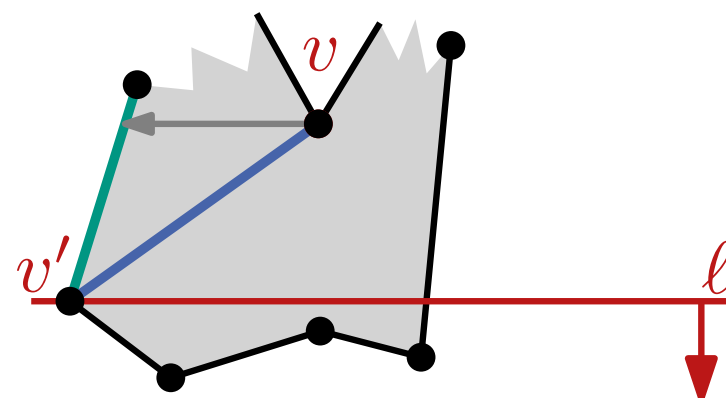
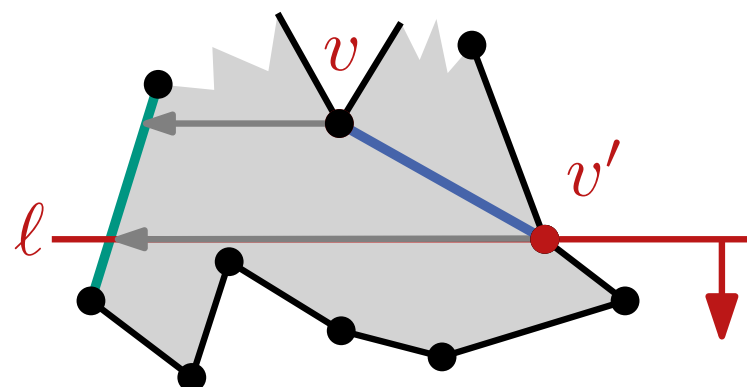
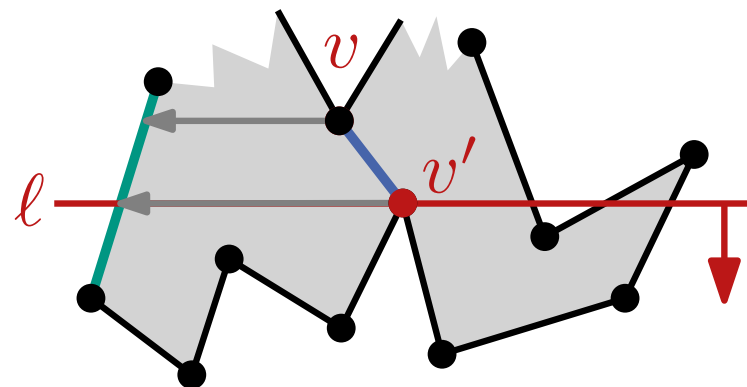
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- if the end of v' of $\text{left}(v)$ is reached, then the diagonal (v, v') is introduced



Algorithm MakeMonotone(P)

MakeMonotone(Polygon P)

$\mathcal{D} \leftarrow$ doubly-connected edge list for $(V(P), E(P))$

$\mathcal{Q} \leftarrow$ priority queue for $V(P)$ sorted lexicographically; $\mathcal{T} \leftarrow \emptyset$ (binary search tree for sweep-line status)

while $\mathcal{Q} \neq \emptyset$ **do**

$v \leftarrow \mathcal{Q}.\text{nextVertex}()$
 $\mathcal{Q}.\text{deleteVertex}(v)$
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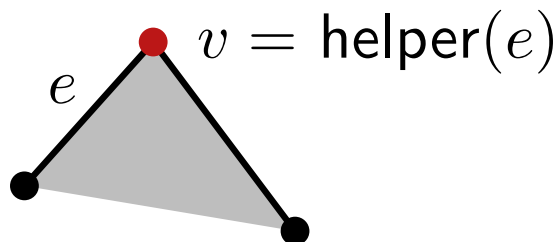
$v \leftarrow \mathcal{Q}.\text{nextVertex}()$
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handleStartVertex(vertex v)

$\mathcal{T} \leftarrow$ add the left edge e

$\text{helper}(e) \leftarrow v$



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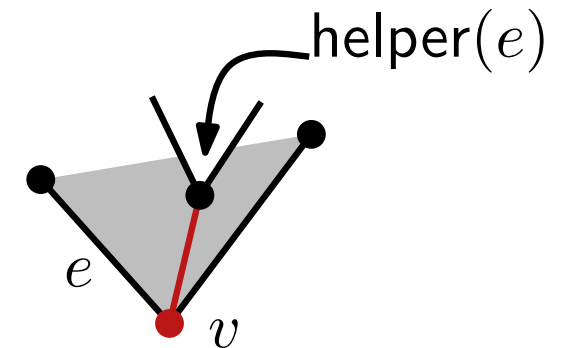
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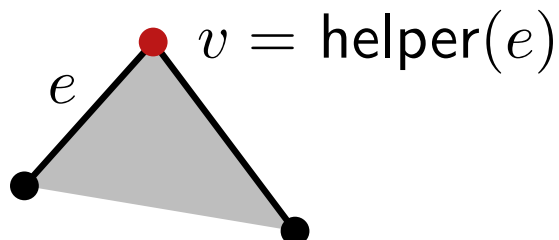
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handleStartVertex(vertex v)

$\mathcal{T} \leftarrow$ add the left edge e

helper(e) $\leftarrow v$



handleEndVertex(vertex v)

$e \leftarrow$ left edge

if isMergeVertex(helper(e)) **then**

$\mathcal{D} \leftarrow$ add edge (helper(e), v)

remove e from \mathcal{T}

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handleSplitVertex(vertex v)

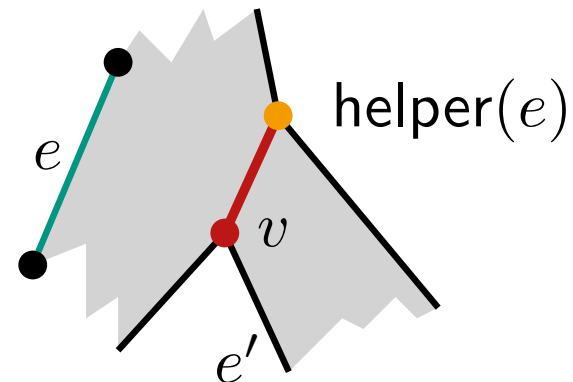
$e \leftarrow$ Edge to the left of v in \mathcal{T}

$\mathcal{D} \leftarrow$ add edge ($\text{helper}(e), v$)

$\text{helper}(e) \leftarrow v$

$\mathcal{T} \leftarrow$ add the right edge e' of v

$\text{helper}(e') \leftarrow v$



Algorithm MakeMonotone(P)

MakeMonotone(Polygon P)

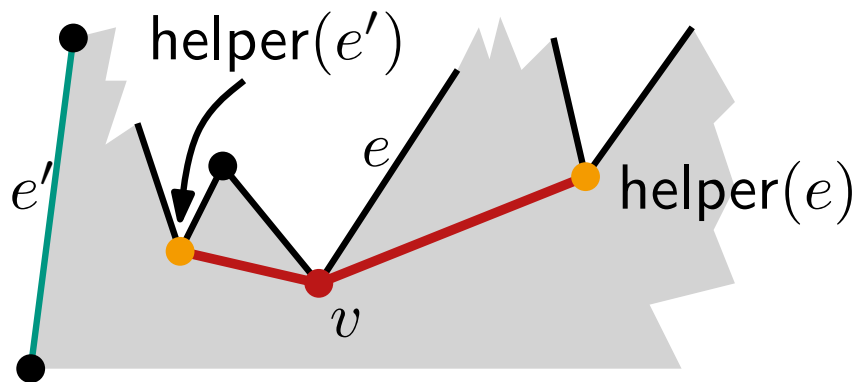
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handleMergeVertex(vertex v)

$e \leftarrow$ right edge

if isMergeVertex(helper(e)) **then**

$\mathcal{D} \leftarrow$ add edge (helper(e), v)

remove e from \mathcal{T}

$e' \leftarrow$ edge to the left of v in \mathcal{T}

if isMergeVertex(helper(e')) **then**

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Algorithm MakeMonotone(P)

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 handleVertex(v)

return \mathcal{D}

handleRegularVertex(vertex v)

if P lies locally to the left of v **then**

$e, e' \leftarrow$ above, below edge

if isMergeVertex(helper(e)) **then**

$\mathcal{D} \leftarrow$ add edge (helper(e), v)

 remove e from \mathcal{T}

$\mathcal{T} \leftarrow$ add e' ; helper(e') $\leftarrow v$

else

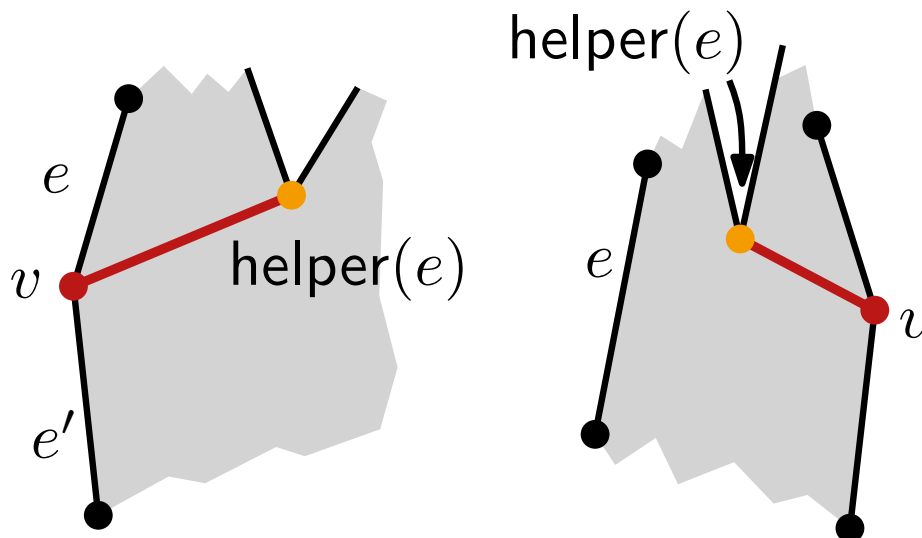
$e \leftarrow$ edge to the left of v

 add e to \mathcal{T}

if isMergeVertex(helper(e)) **then**

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Lemma 2: The algorithm `MakeMonotone` computes a set of crossing-free diagonals of P , which partitions P into y -monotone polygons.

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Theorem 3: A simple polygon with n vertices can be partitioned into y -monotone polygons in $O(n \log n)$ time and $O(n)$ space.

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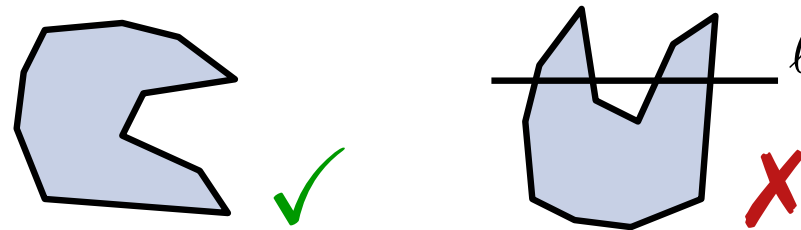
- Construct priority queue Q : $O(n)$
- Initialize sweep-line status \mathcal{T} : $O(1)$
- Handle a single event: $O(\log n)$
 - $Q.deleteMax$: $O(\log n)$
 - Find, remove, add element in \mathcal{T} : $O(\log n)$
 - Add diagonals to \mathcal{D} : $O(1)$
- Space: obviously $O(n)$

Proof of Art-Gallery-Theorem: Overview

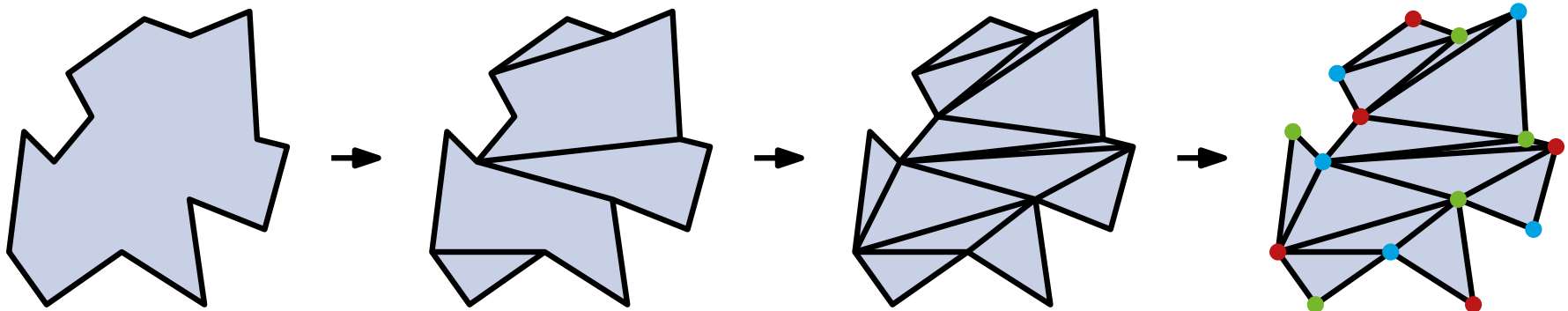
Three-step procedure:

- Step 1: Decompose P in y -monotone polygons ✓

Definition: A polygon P is y -monotone, if for each horizontal line ℓ the intersection $\ell \cap P$ is connected.



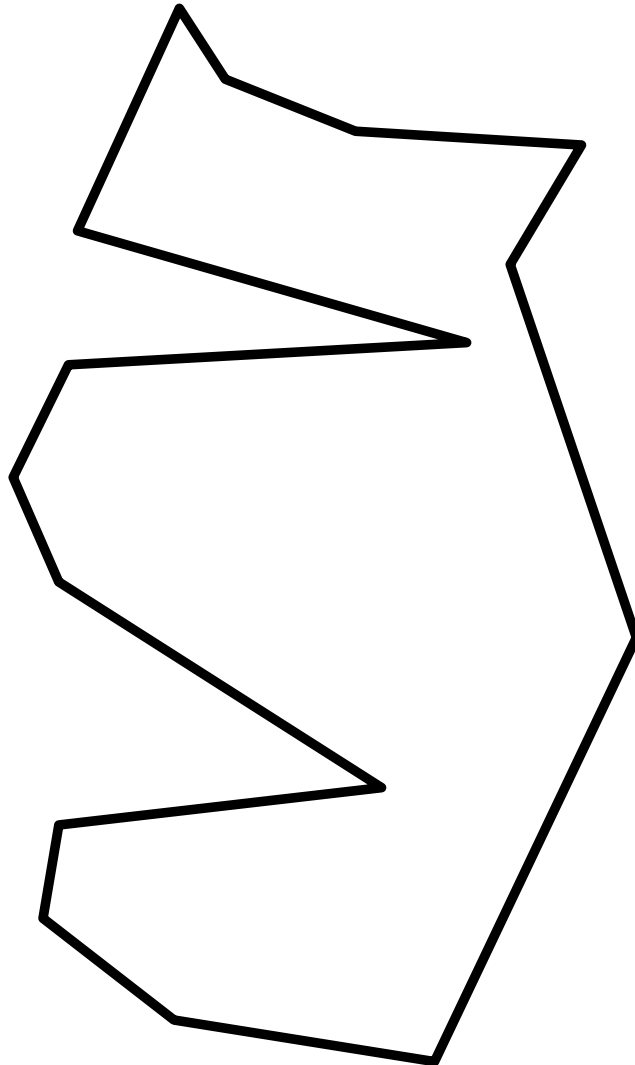
- Step 2: Triangulate y -monotone polygons **ToDo!**
- Step 3: use DFS to color the triangulated polygon ✓



Triangulate y -monotone Polygon

Reminder: The left and the right boundary of the polygon have decreasing y -coordinates

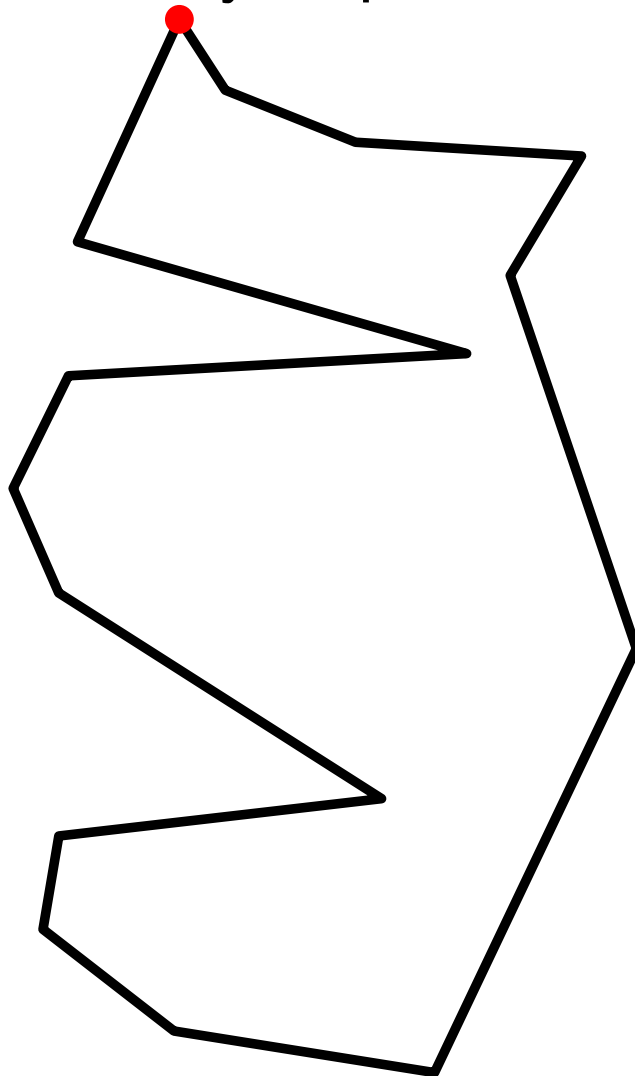
Approach: Greedy, top down traversal of both sides



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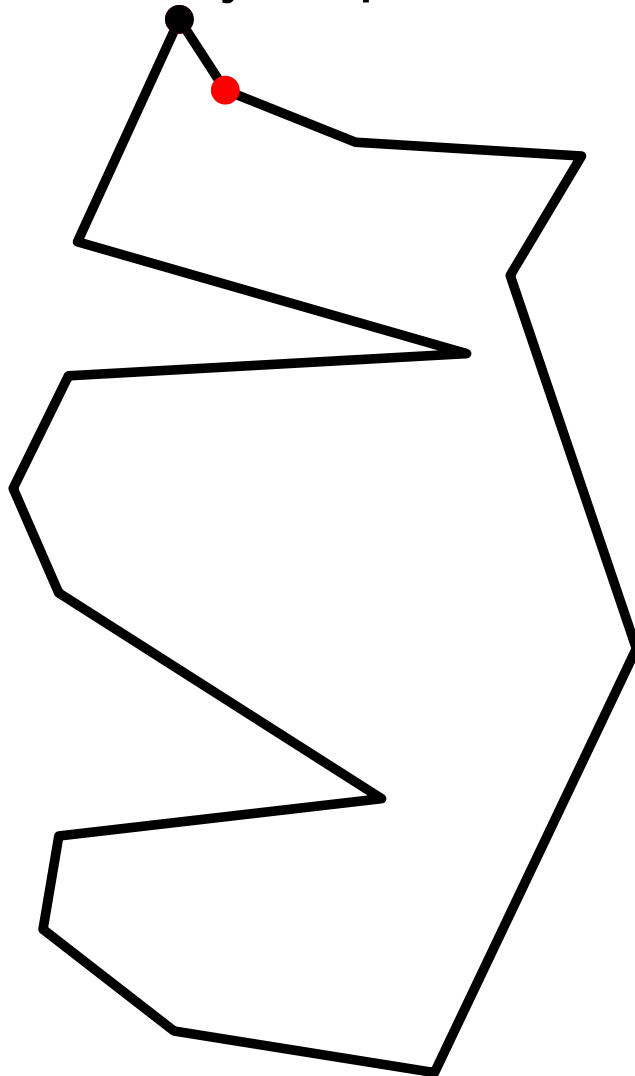
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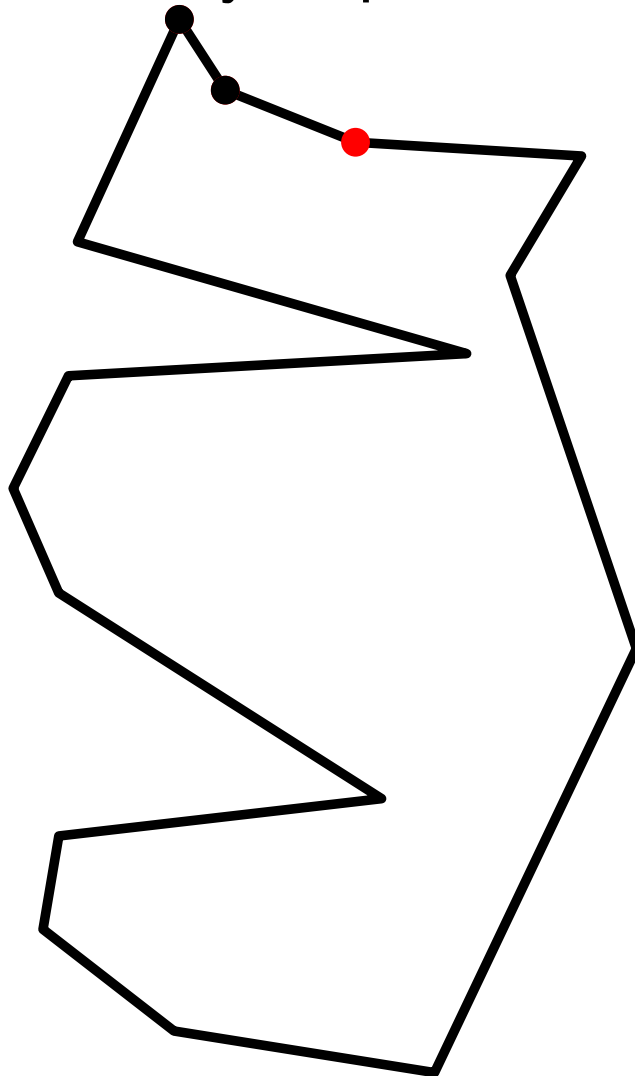
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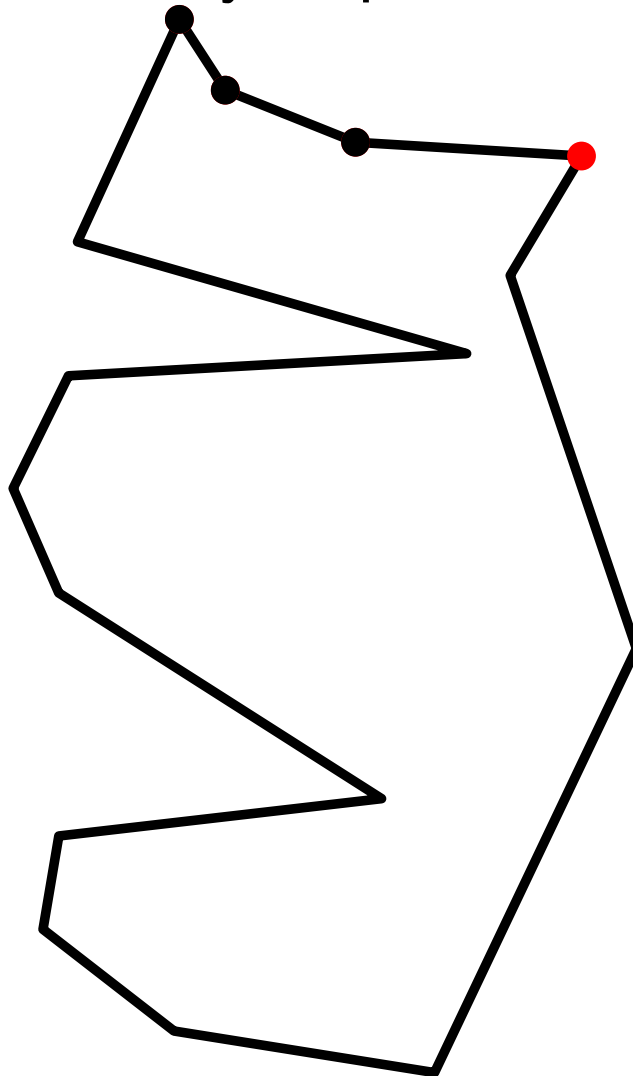
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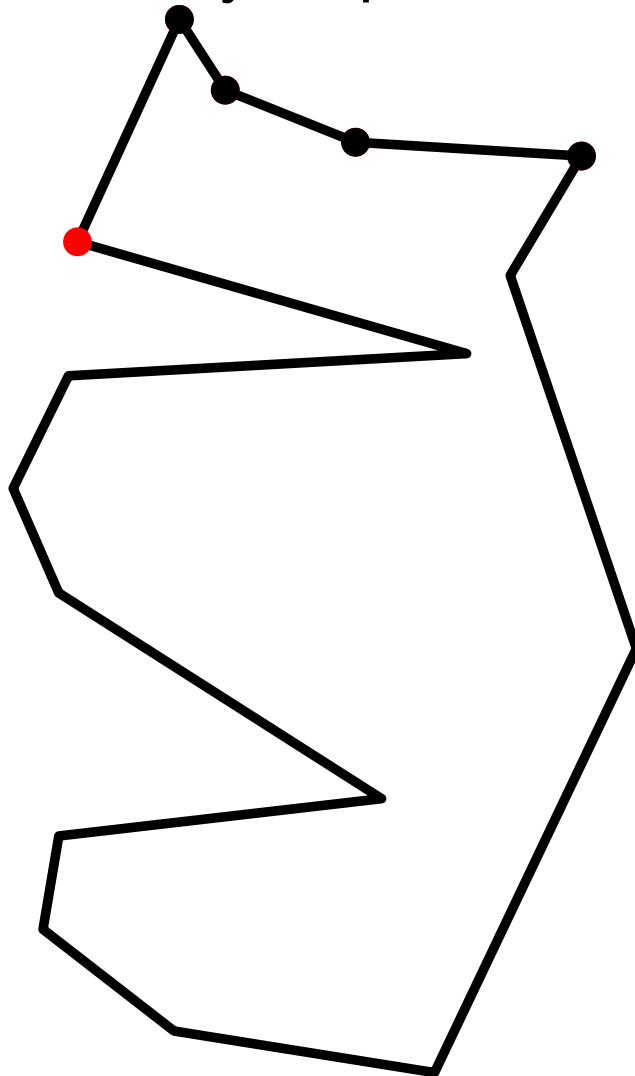
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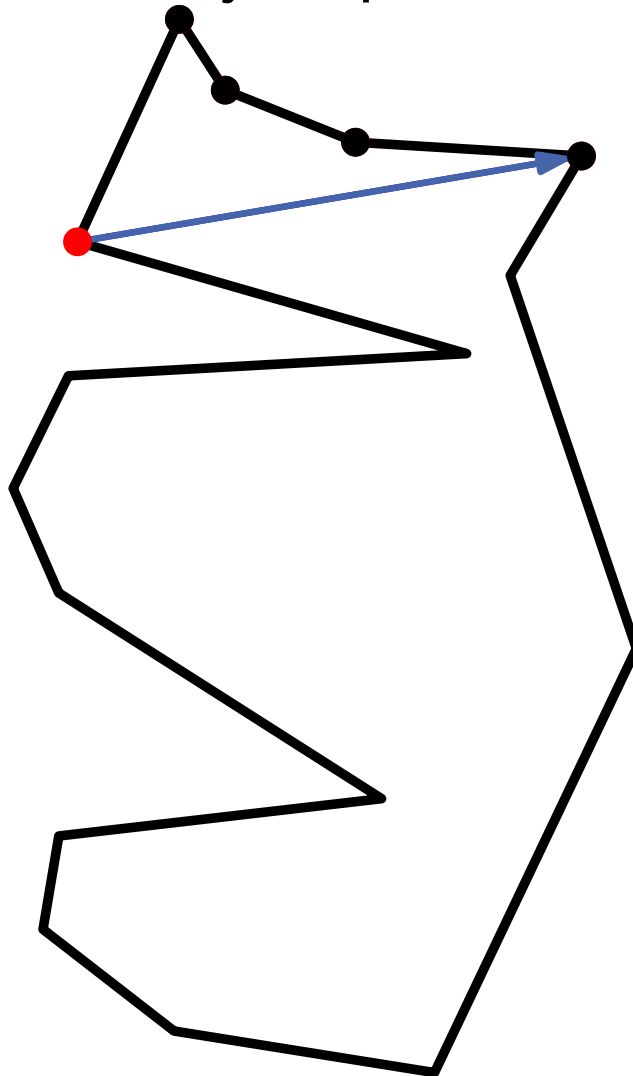
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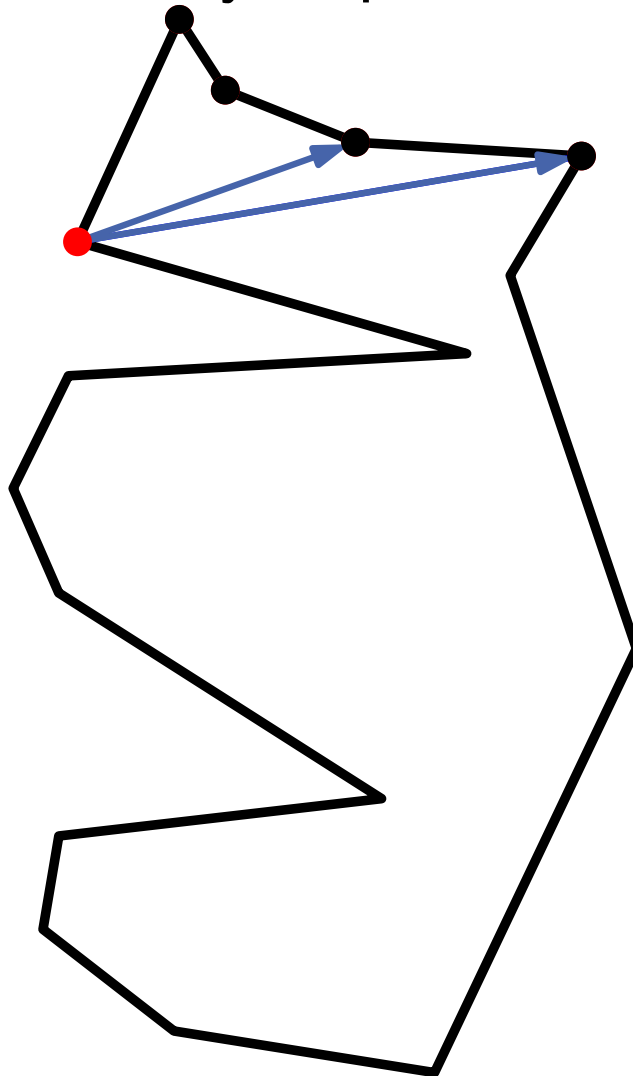
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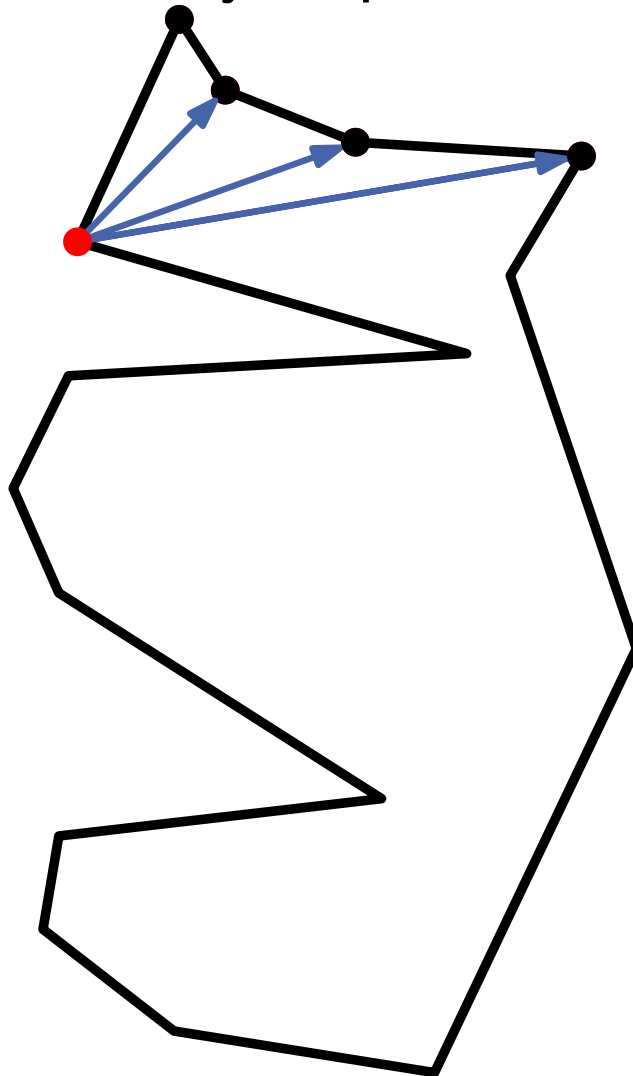
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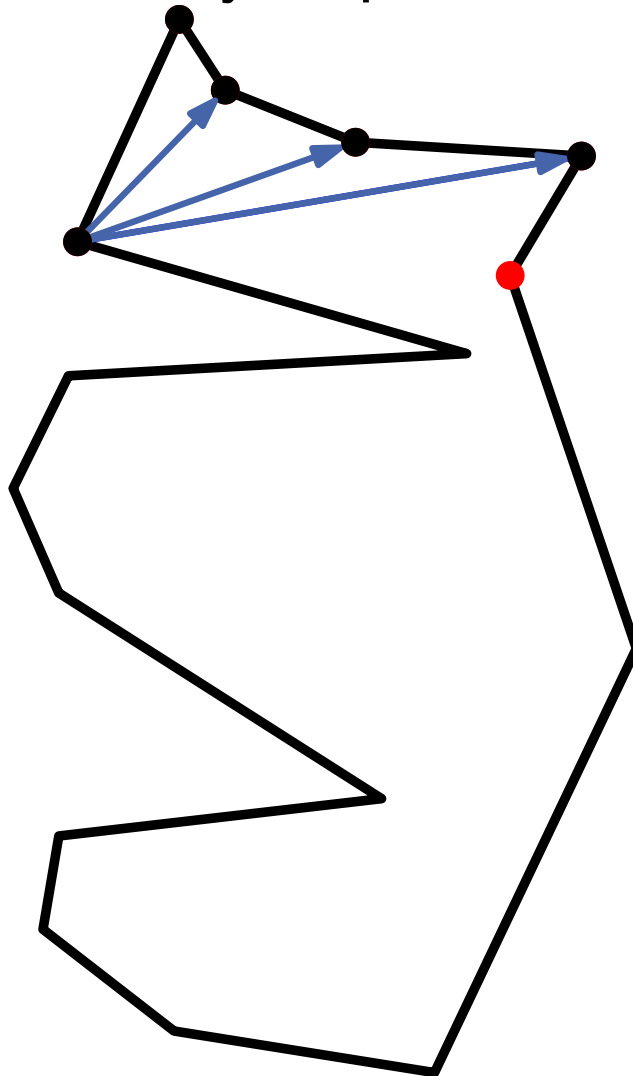
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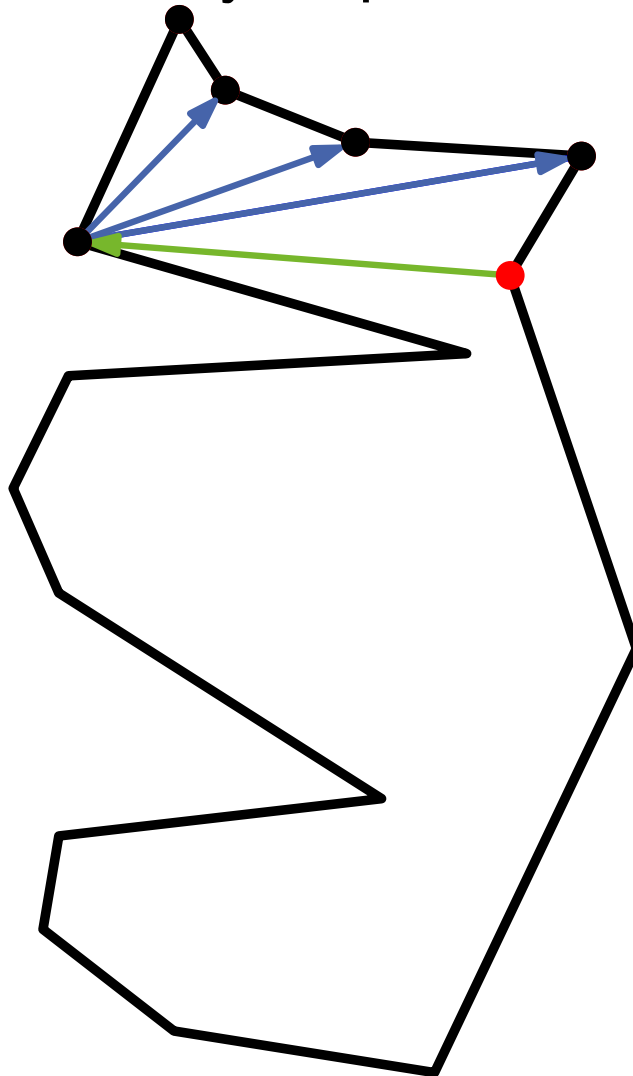
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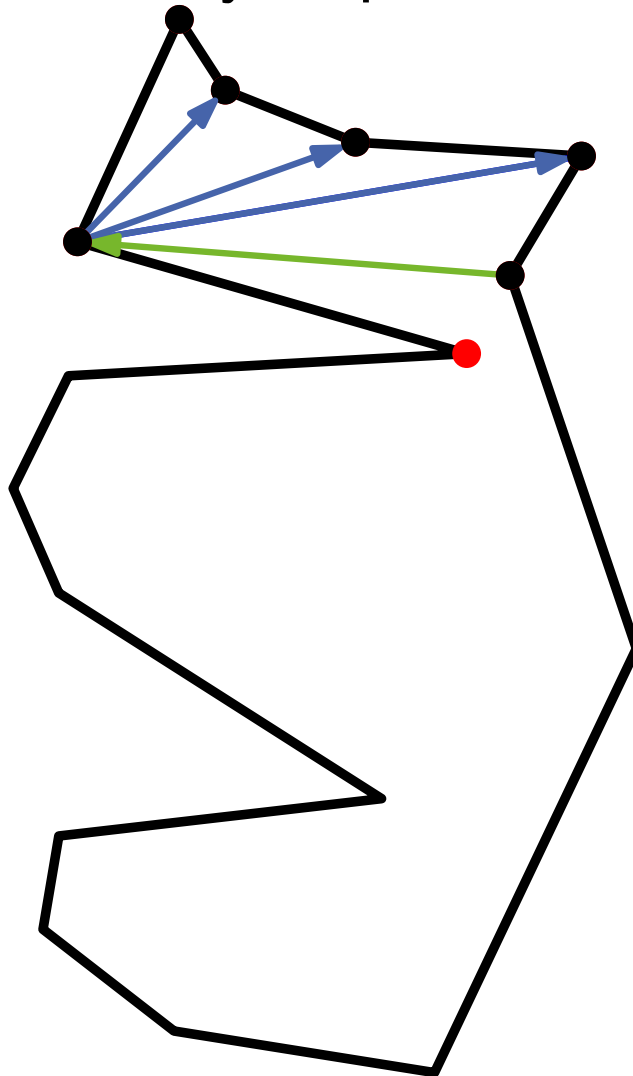
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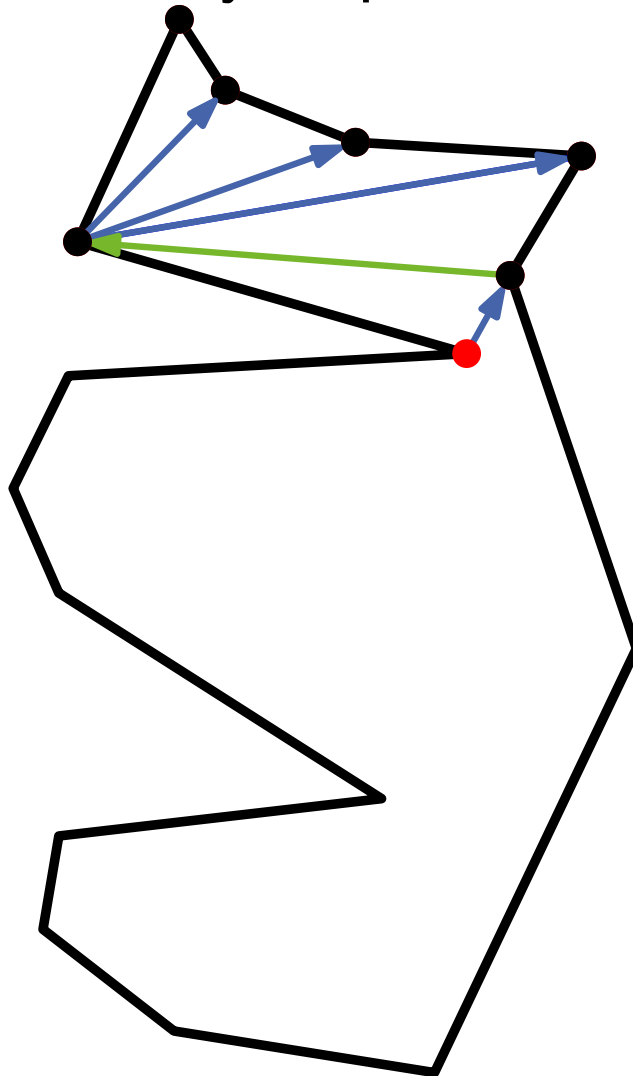
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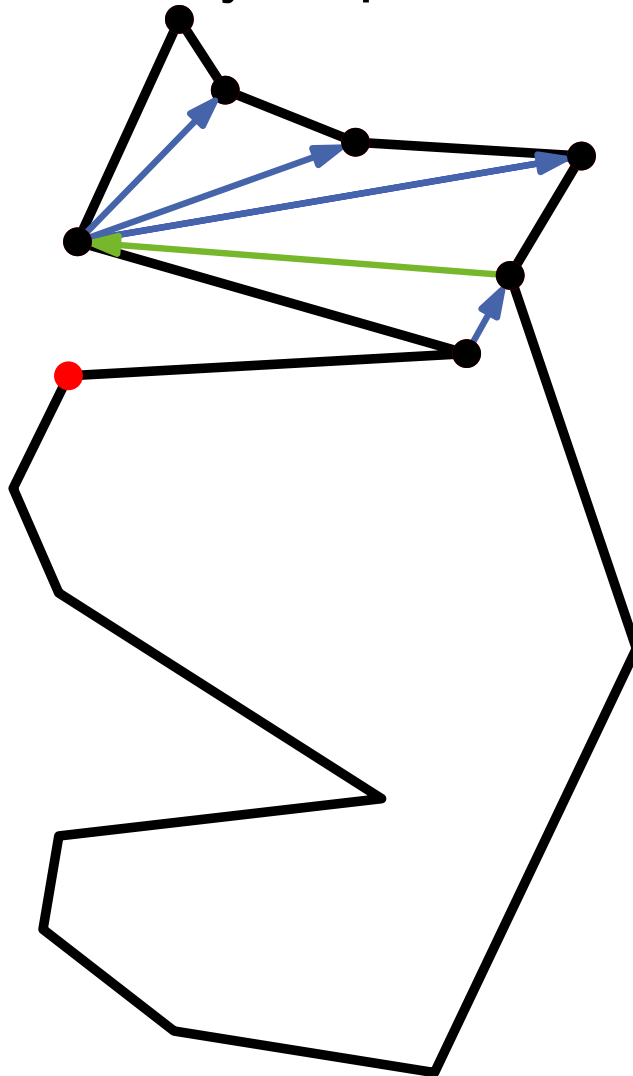
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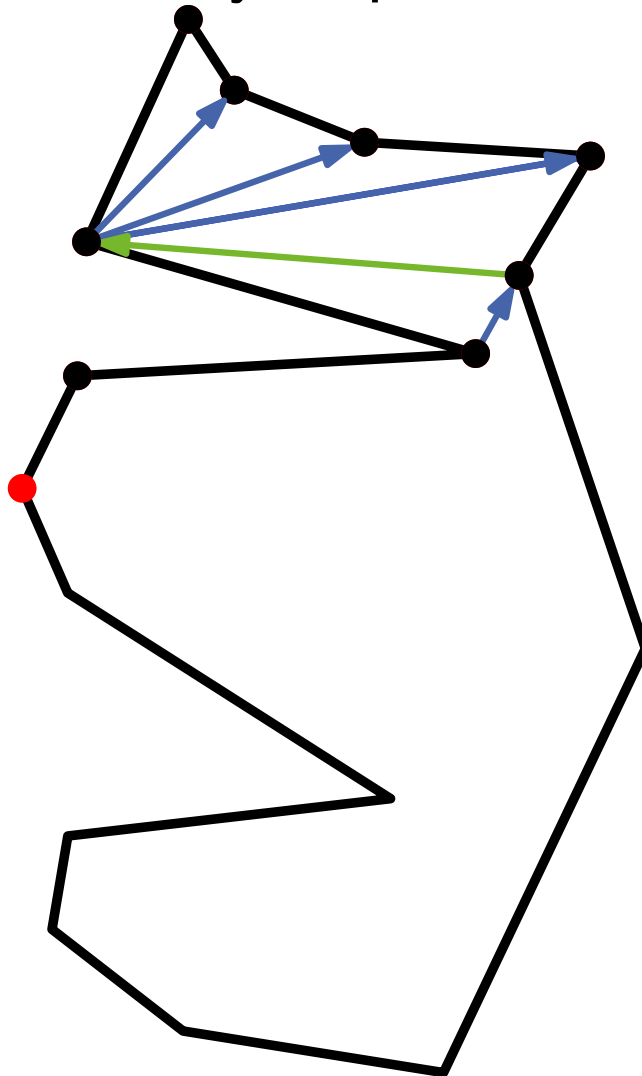
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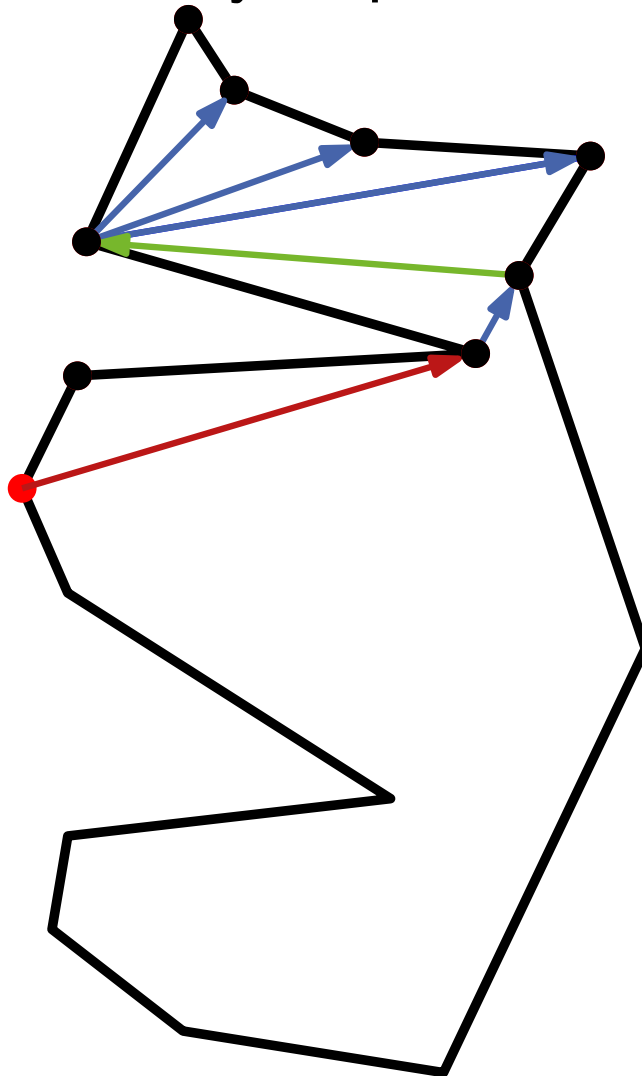
Approach: Greedy, top down traversal of both sides



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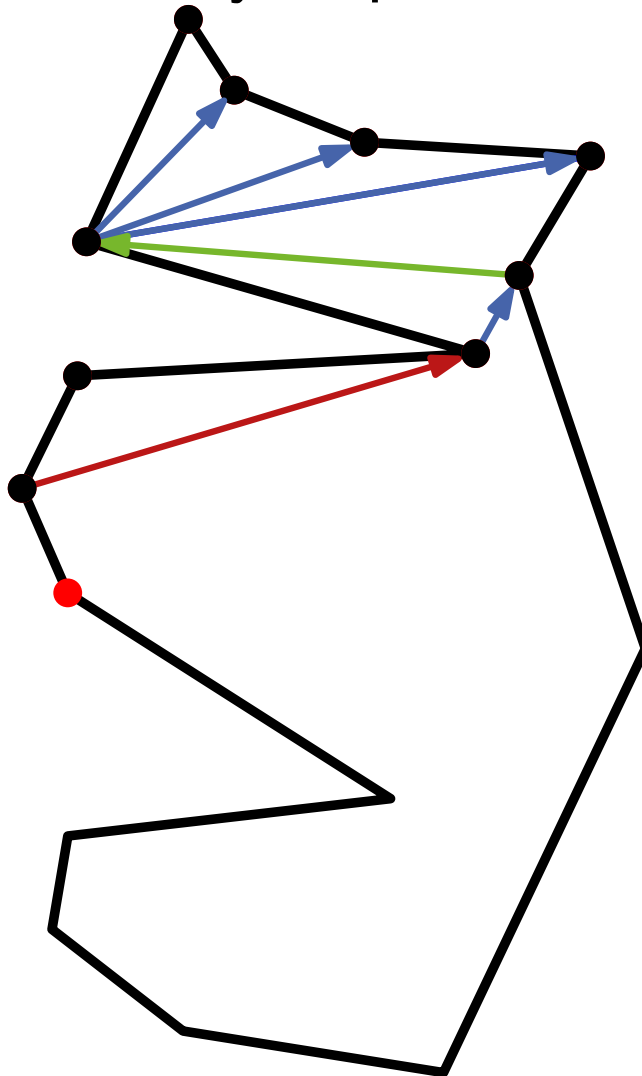
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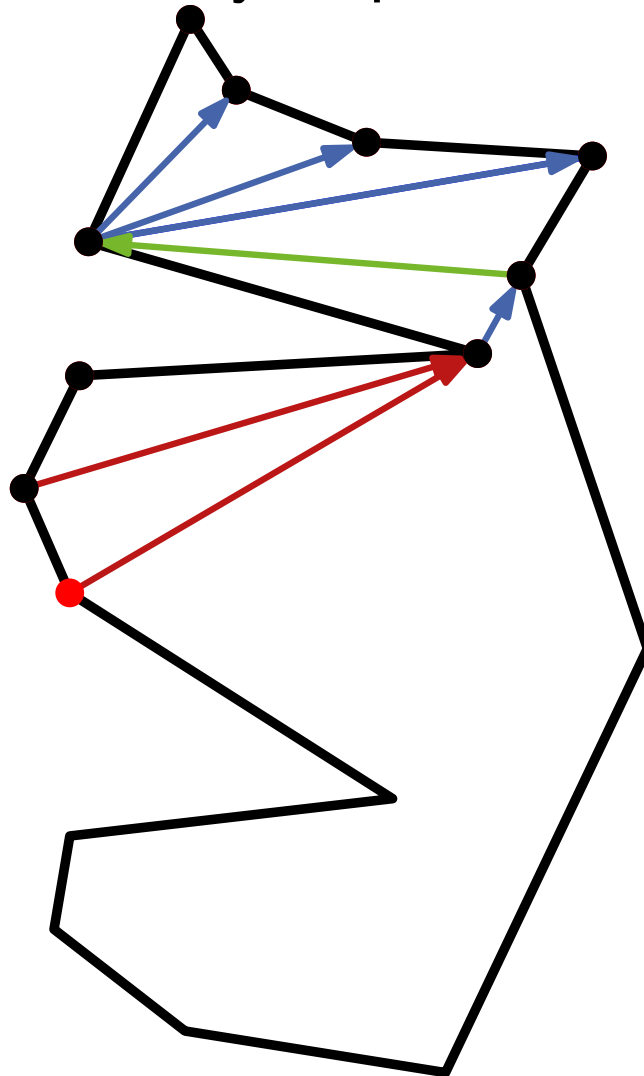
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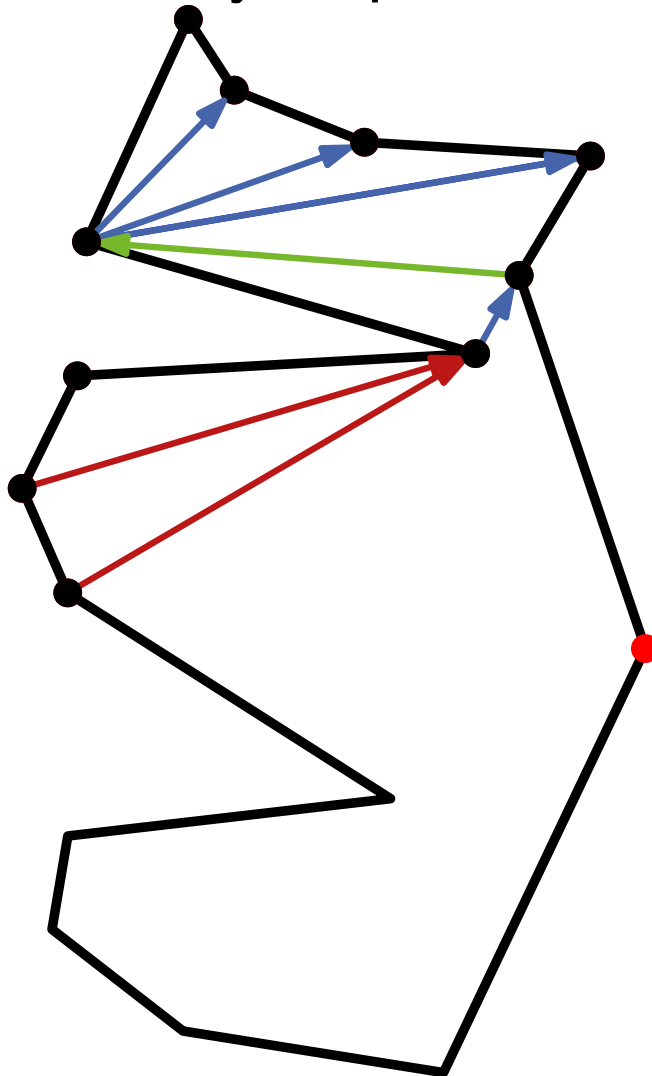
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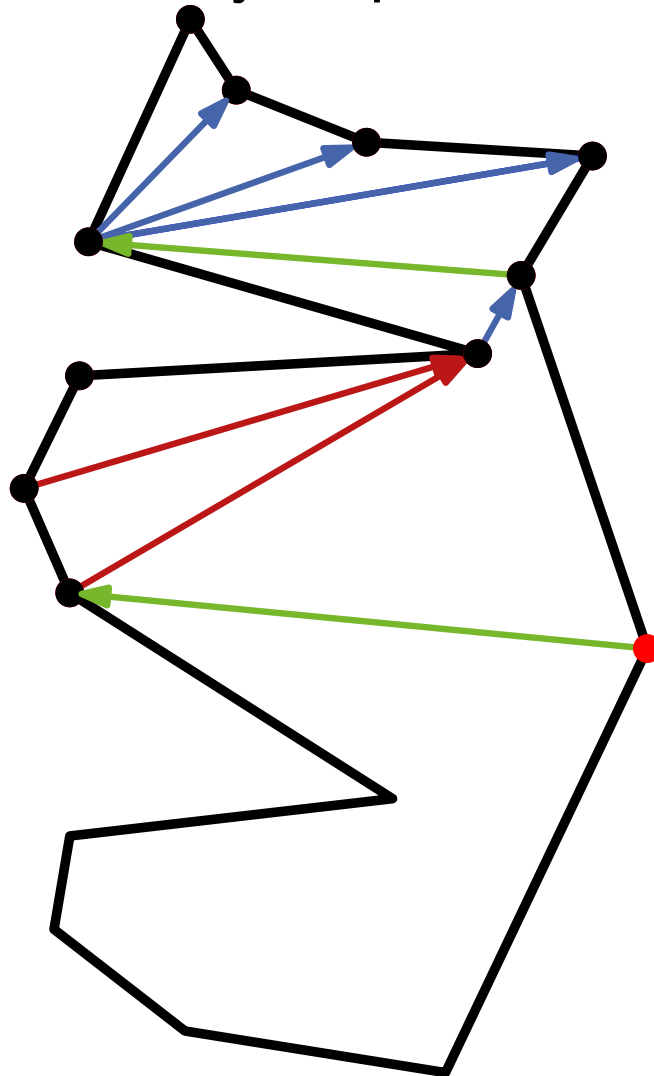
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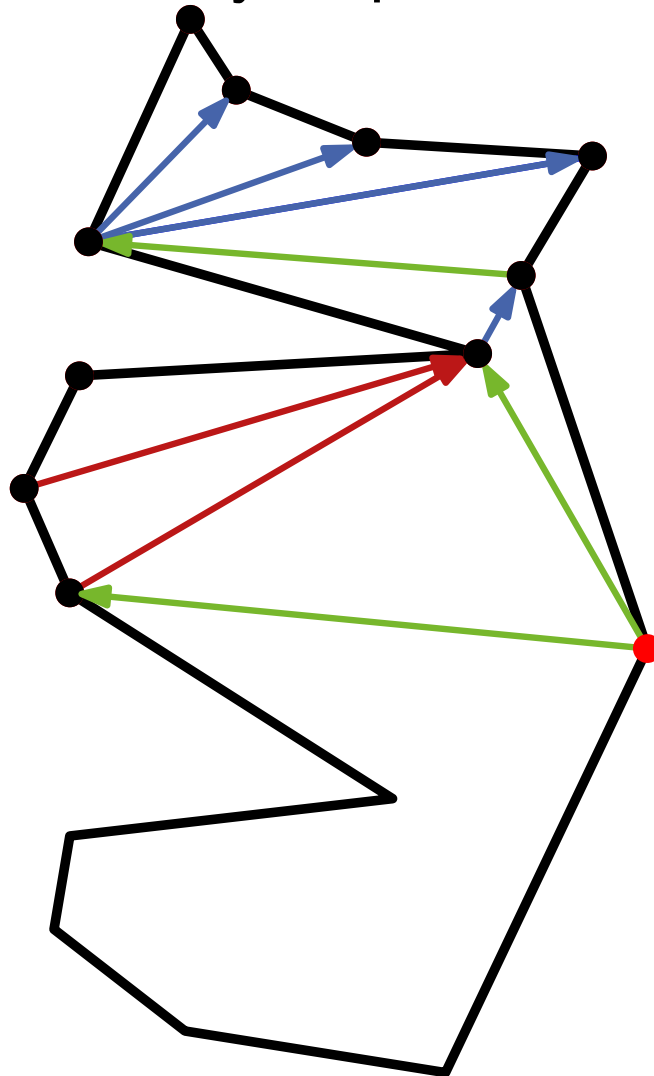
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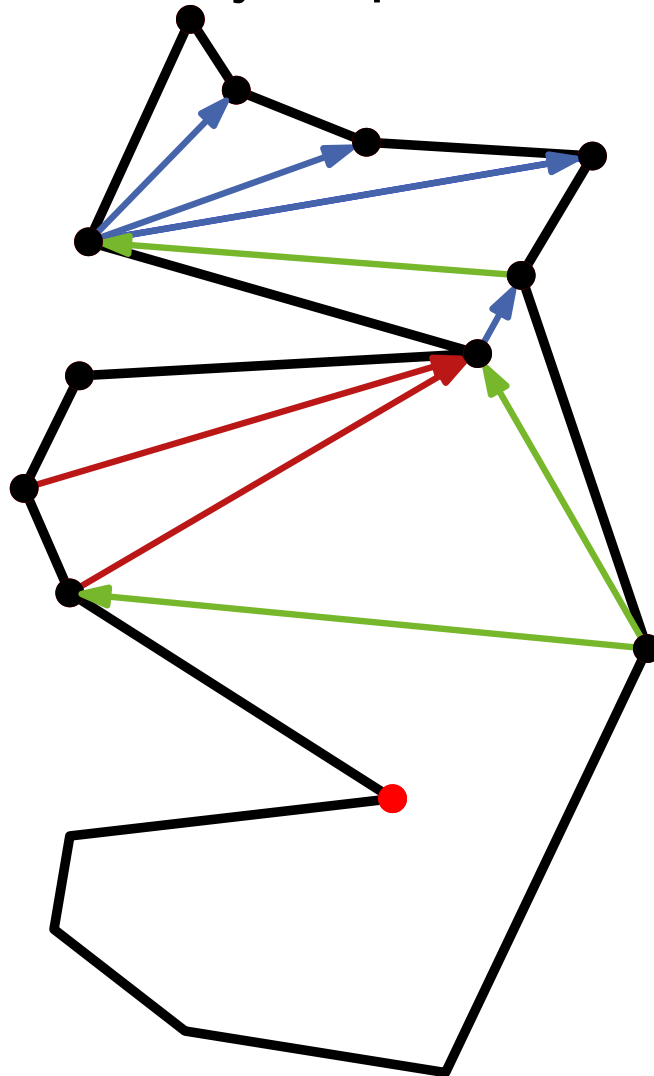
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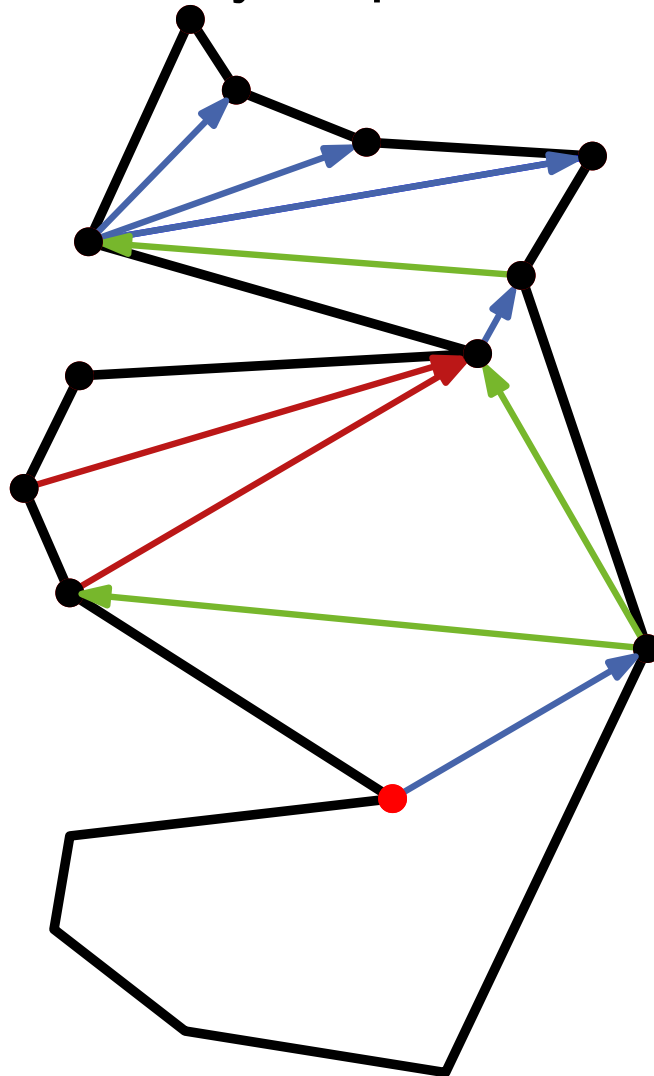
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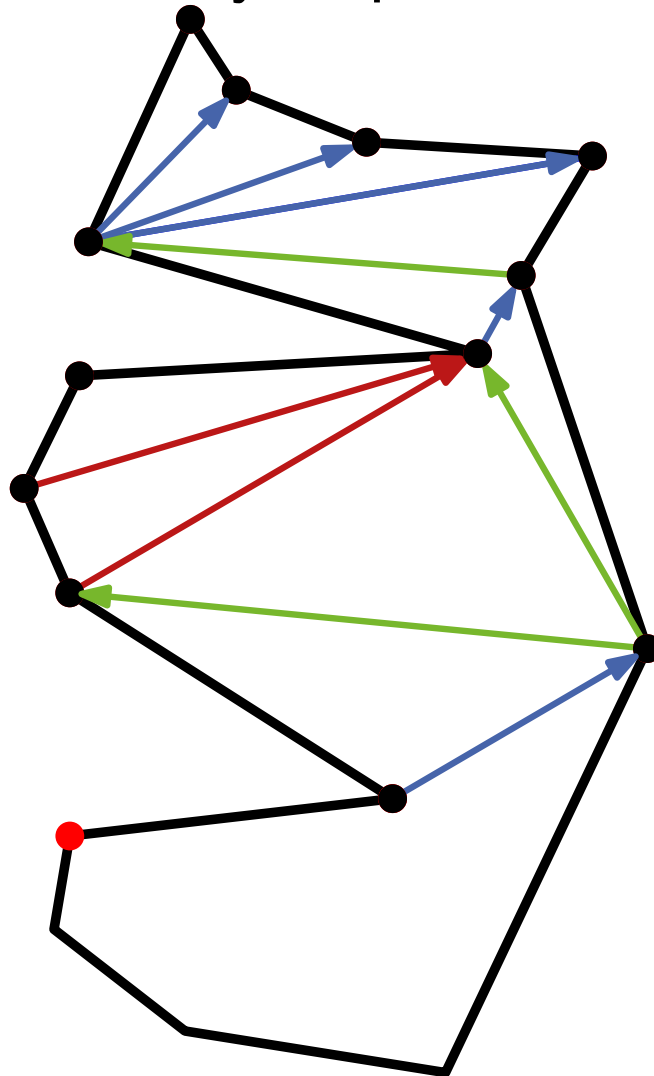
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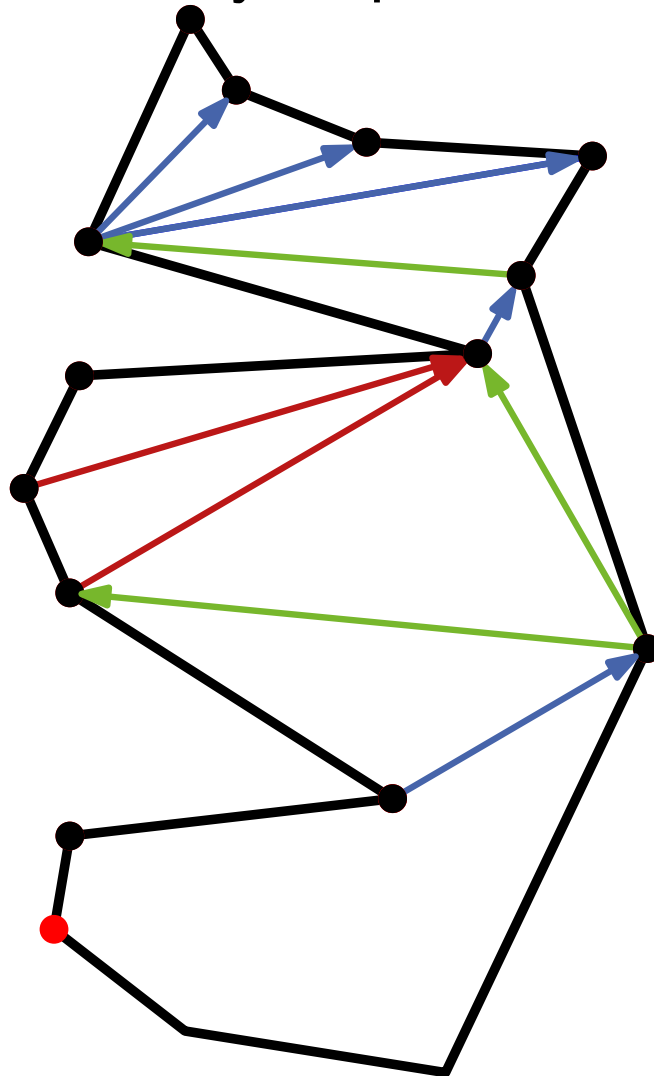
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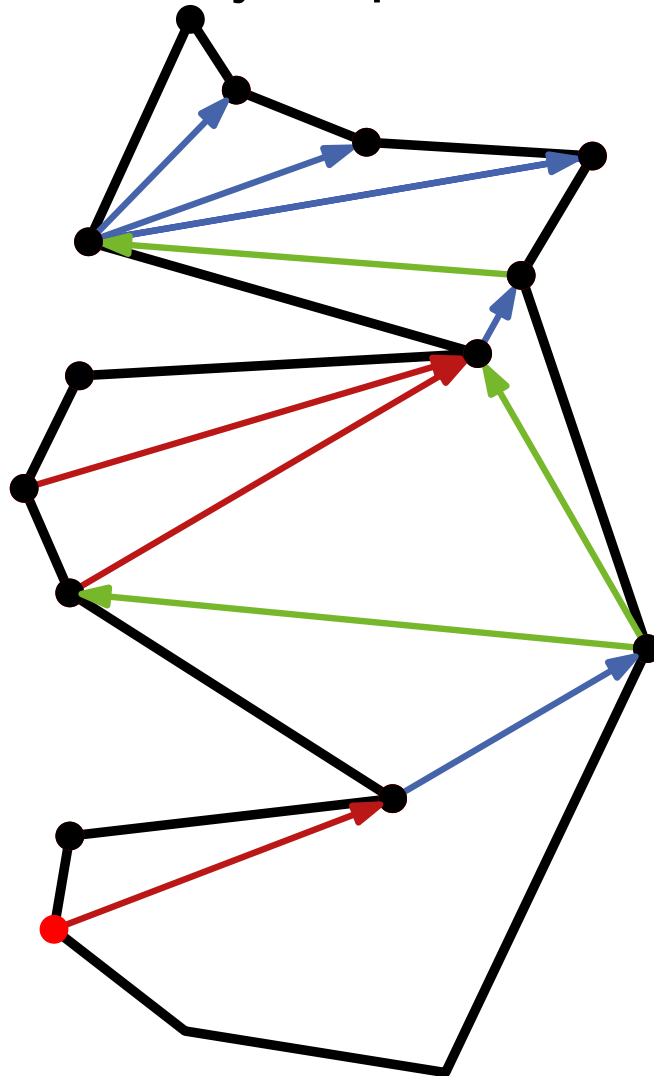
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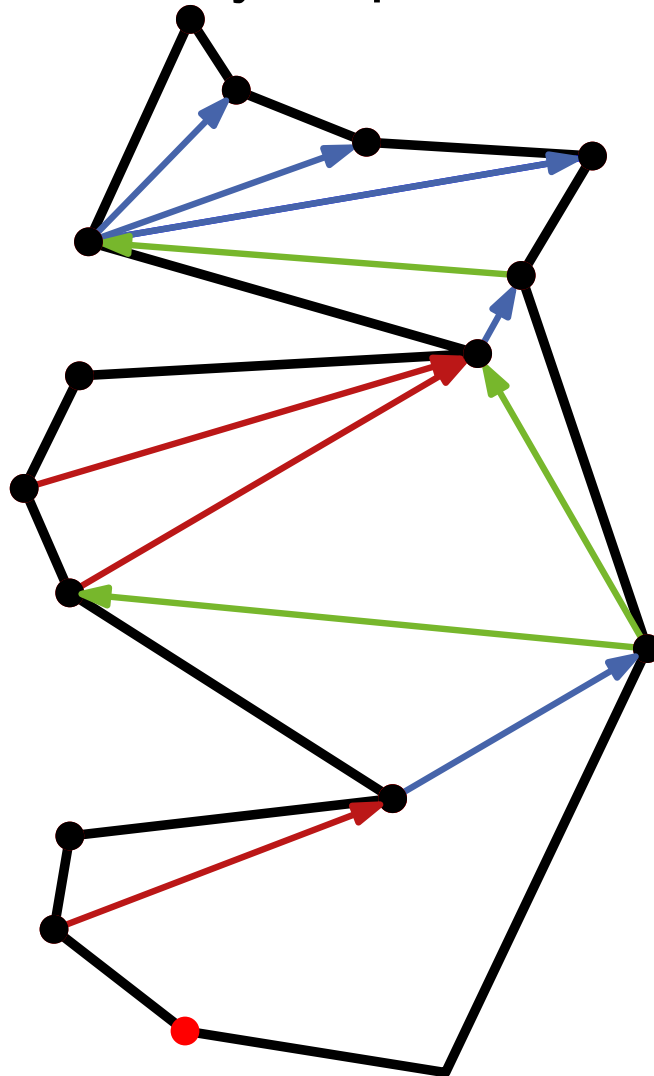
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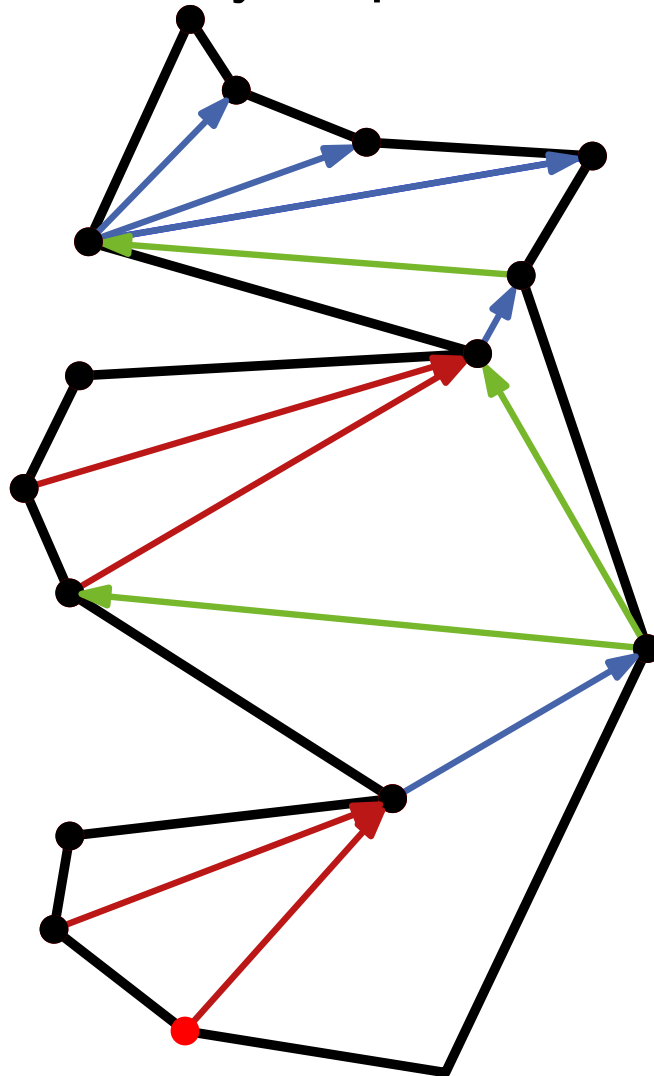
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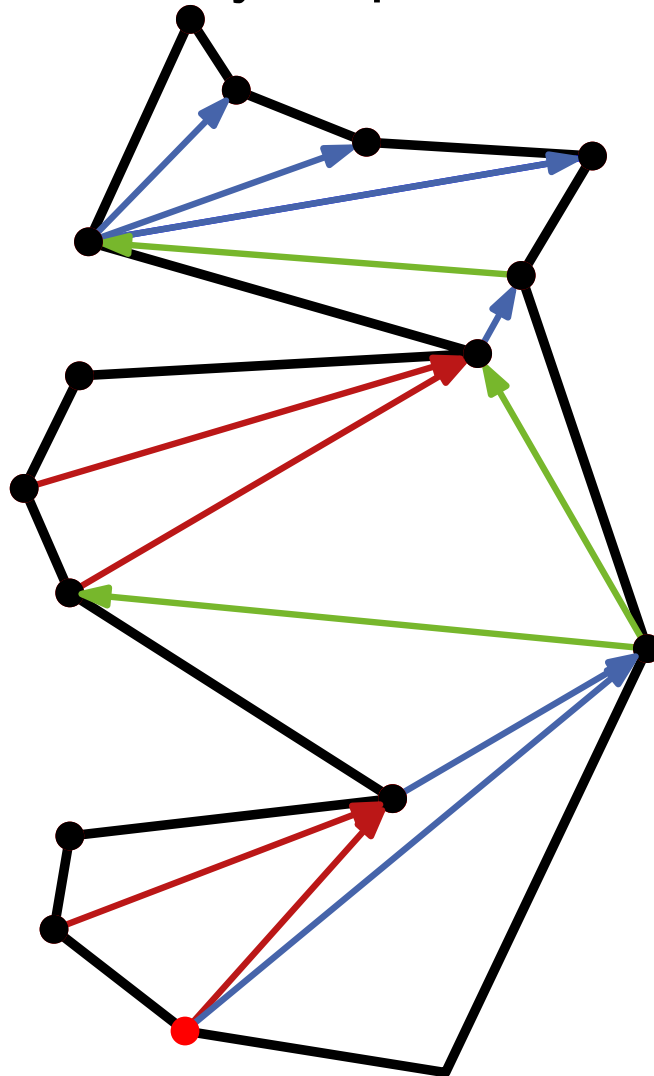
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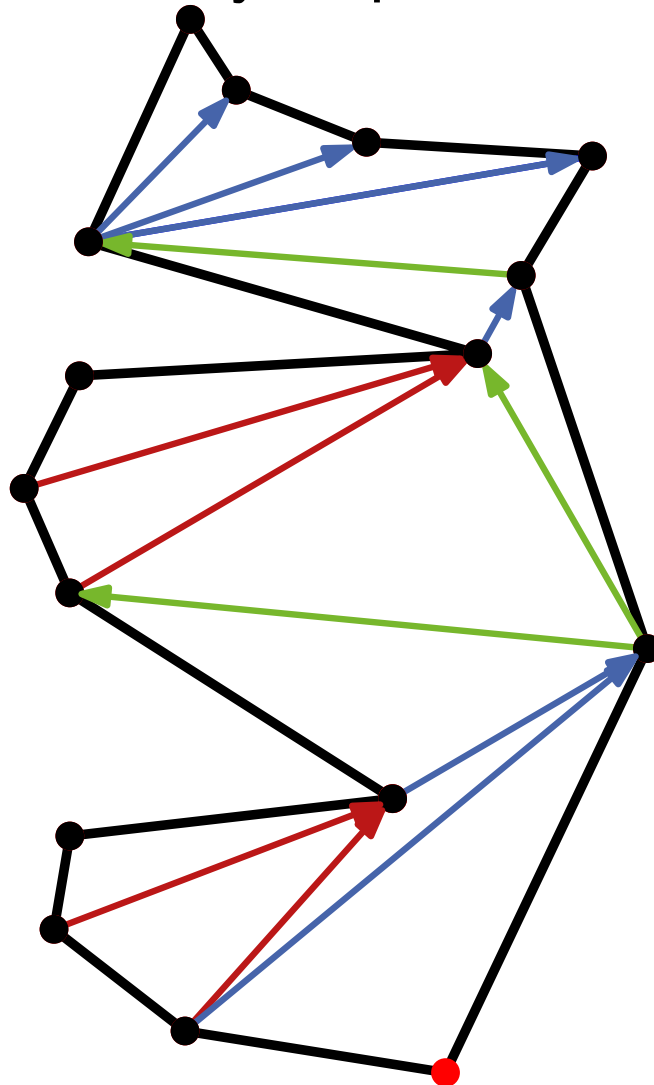
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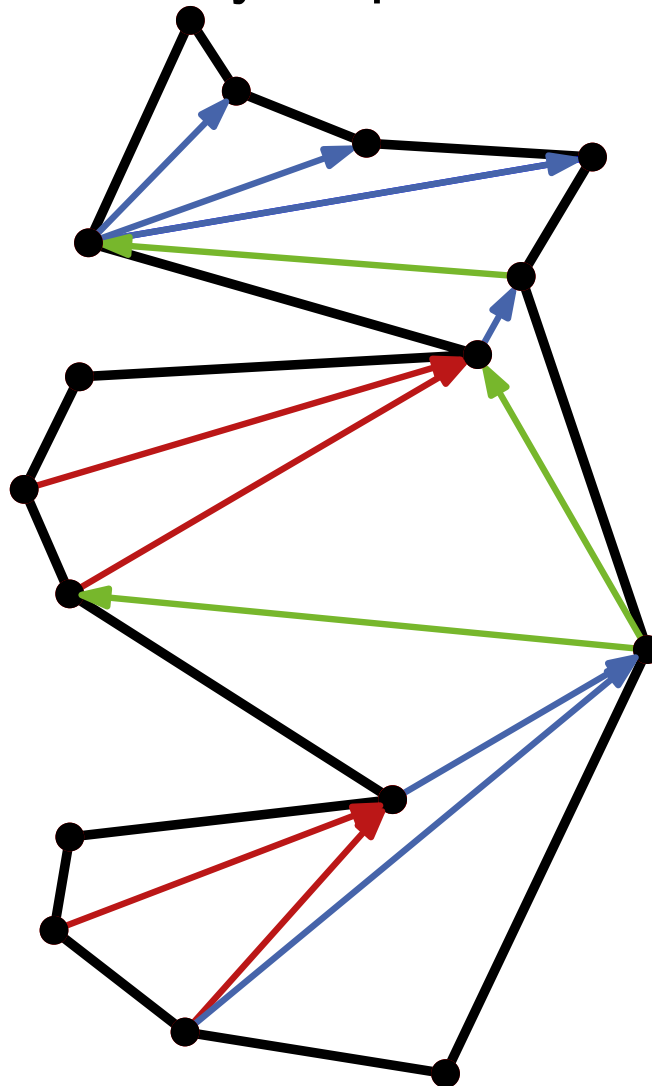


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Invariant?

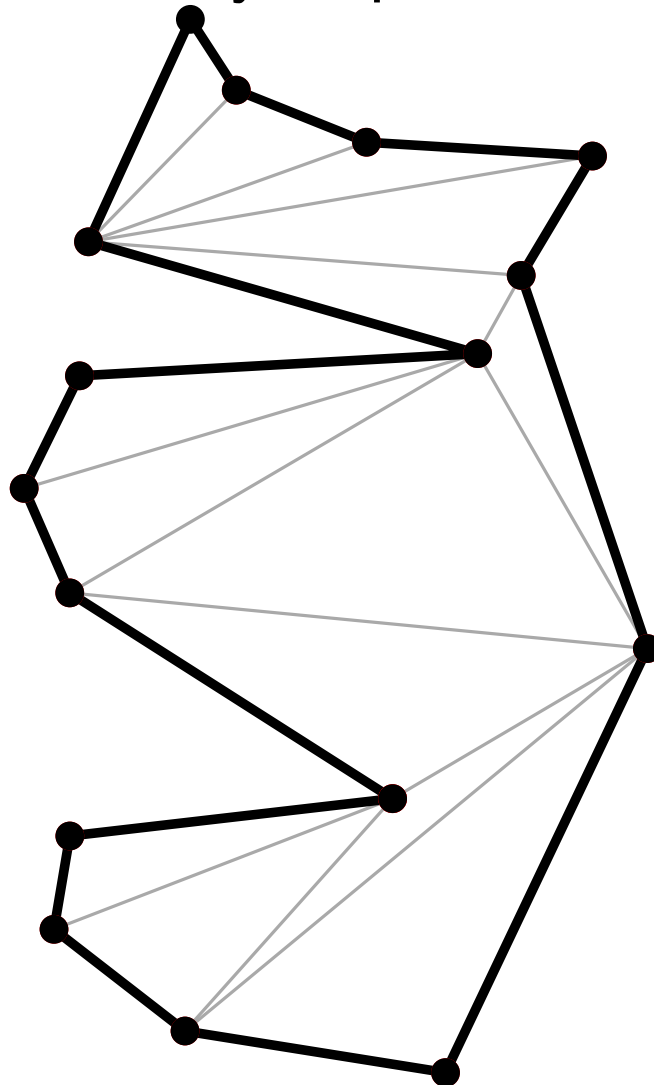


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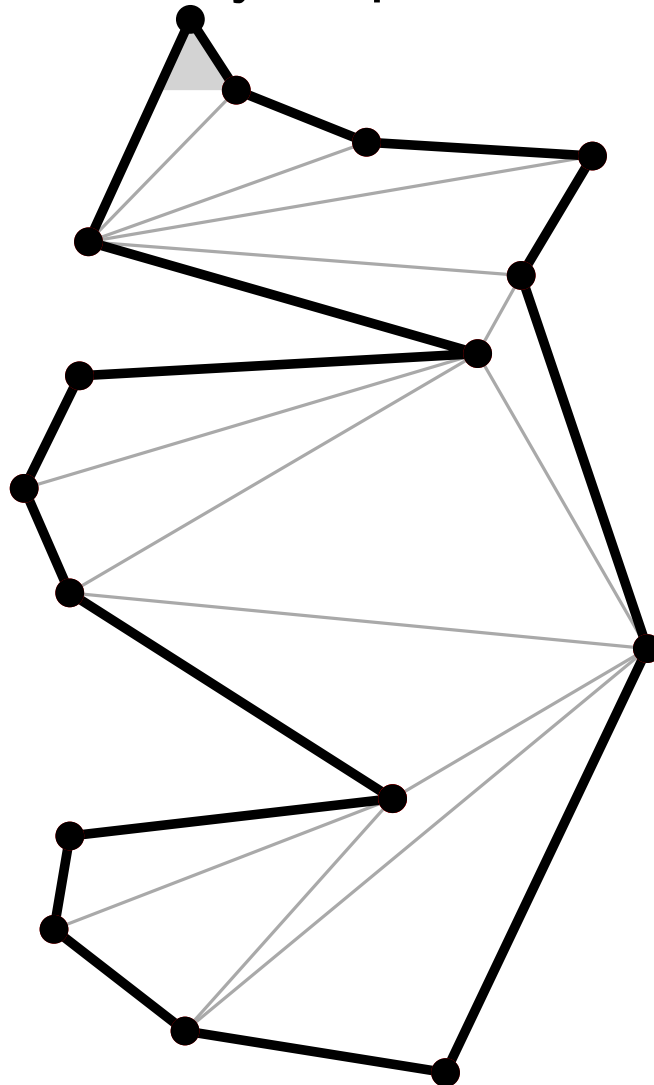


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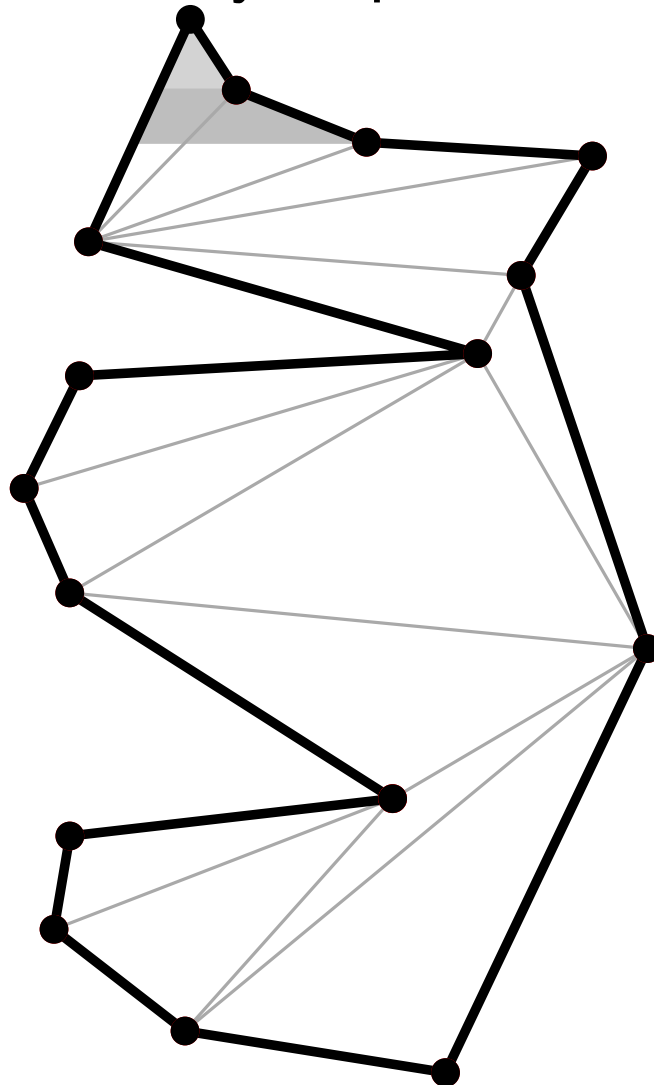


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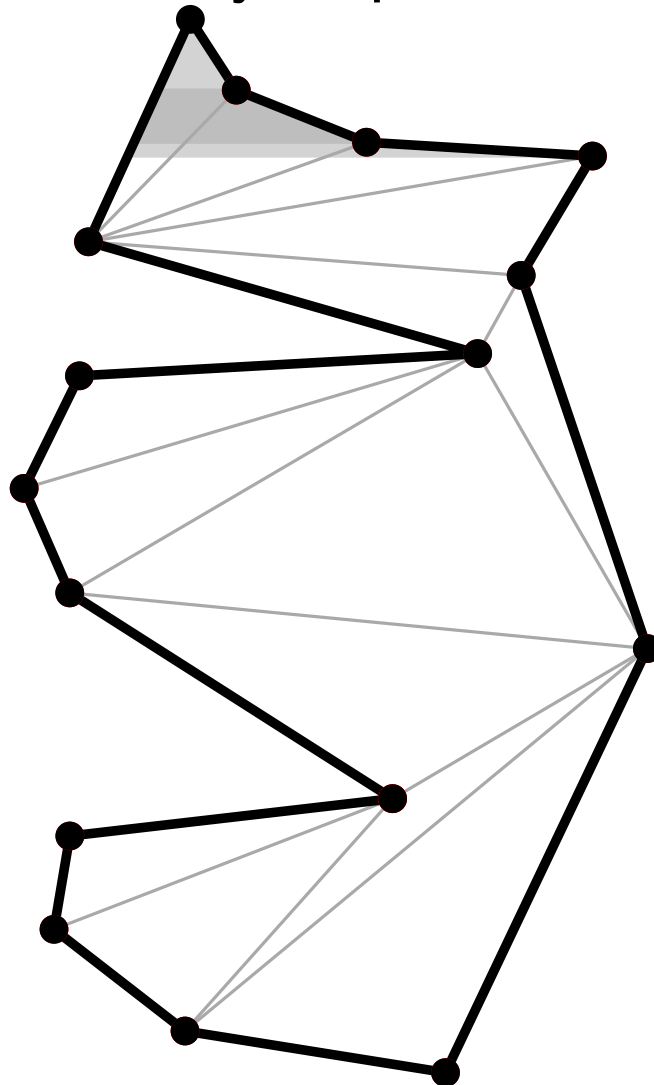


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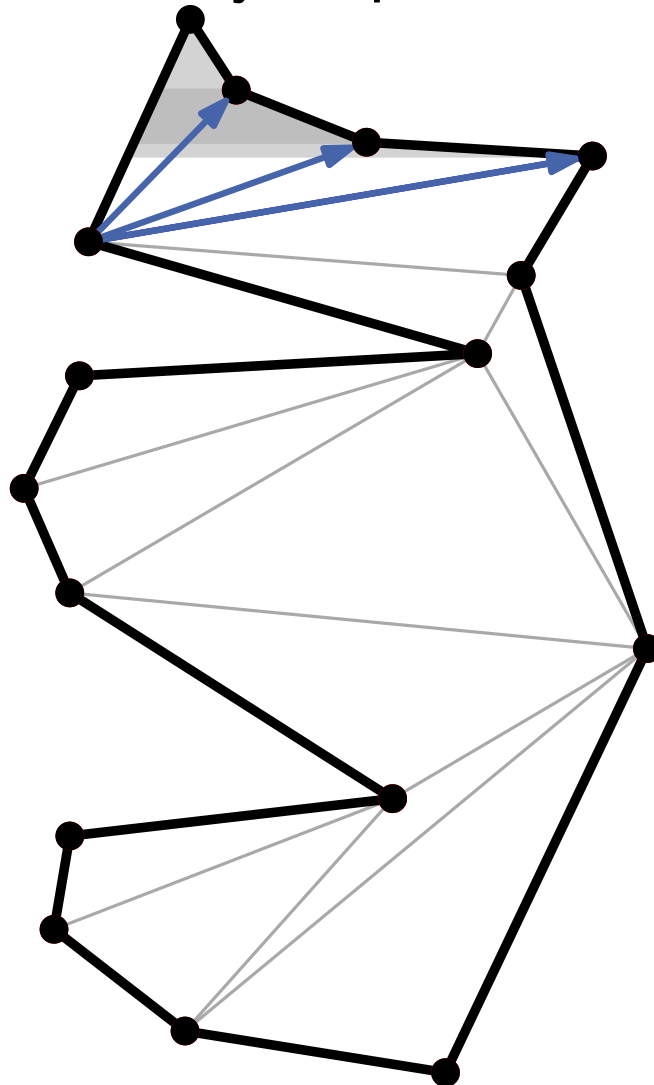


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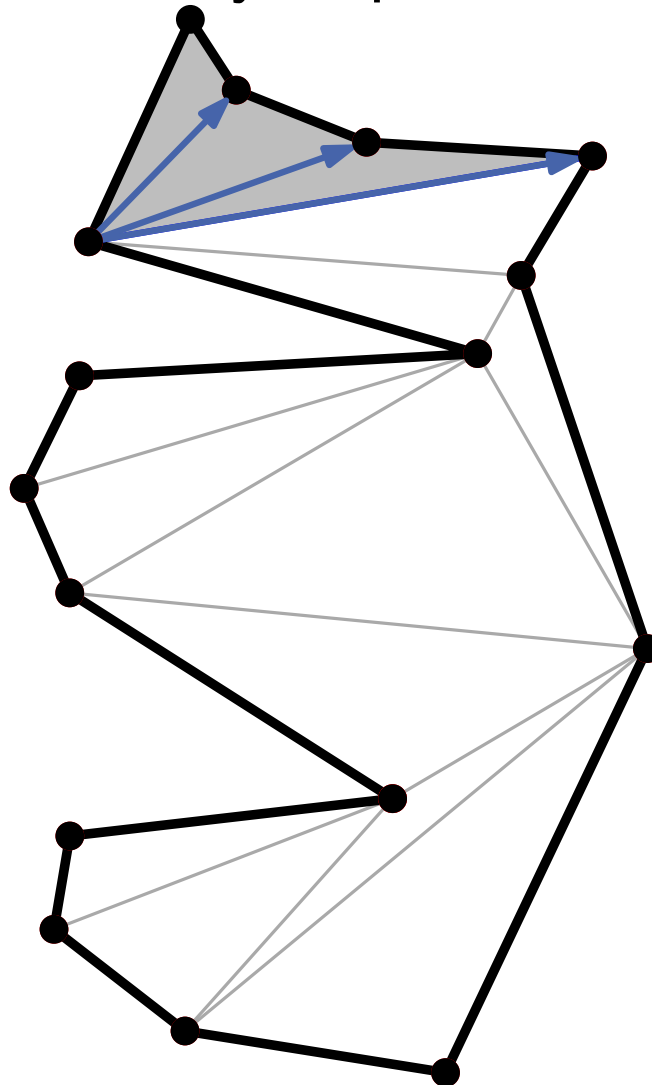
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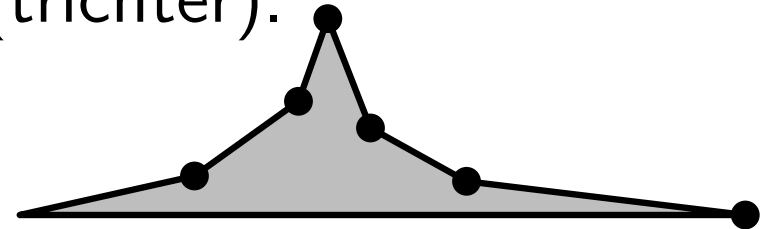
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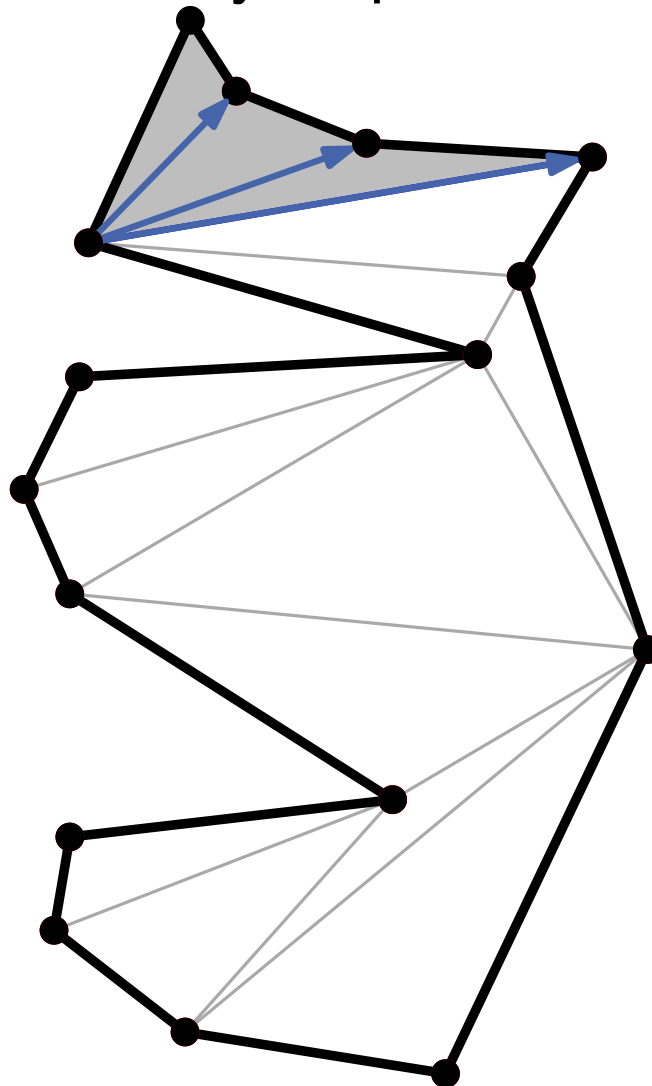
The already visited but not triangulated polygon has the shape of a *funnel* (trichter).



Triangulate y -monotone Polygon

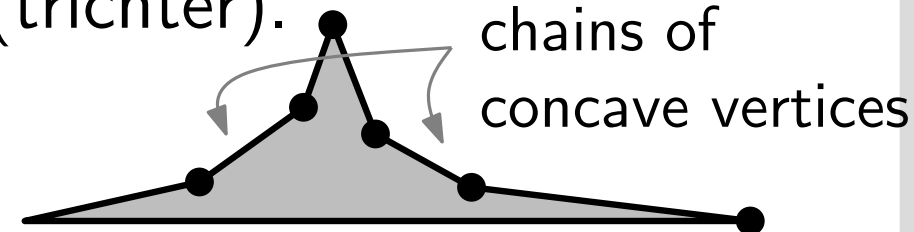
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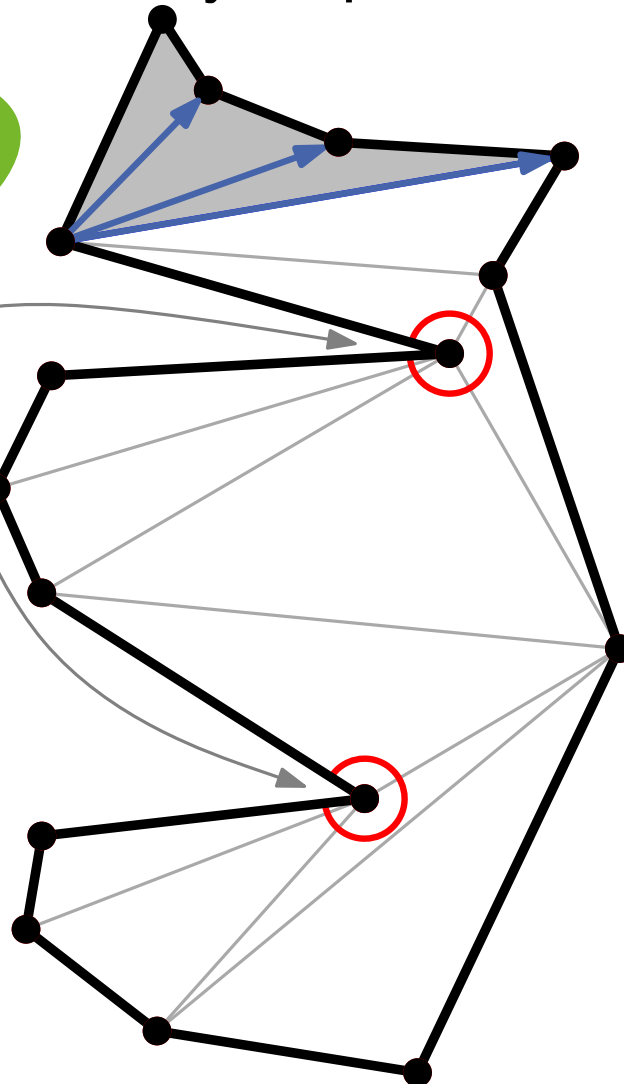
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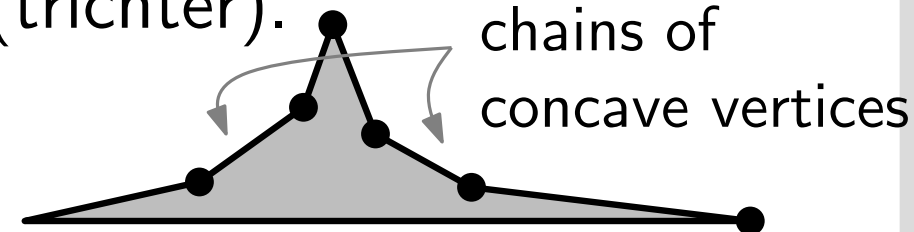
Angle in P
 $> 180^\circ$

concave



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Triangulate y -monotone Polygon

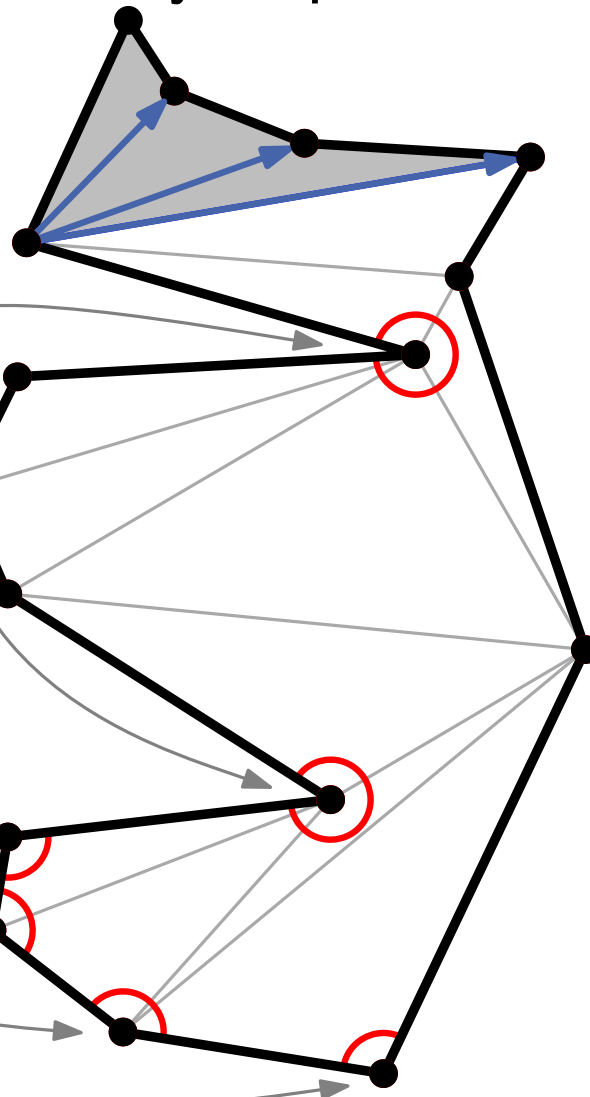
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Angle in P
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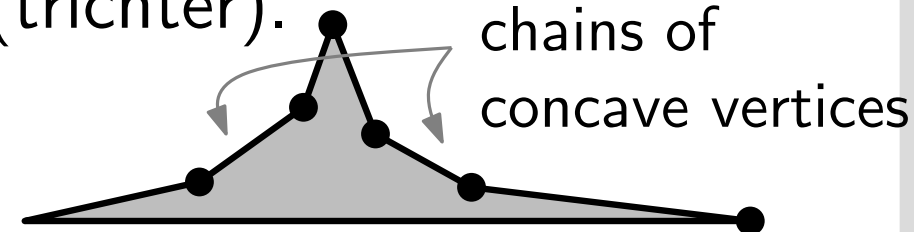
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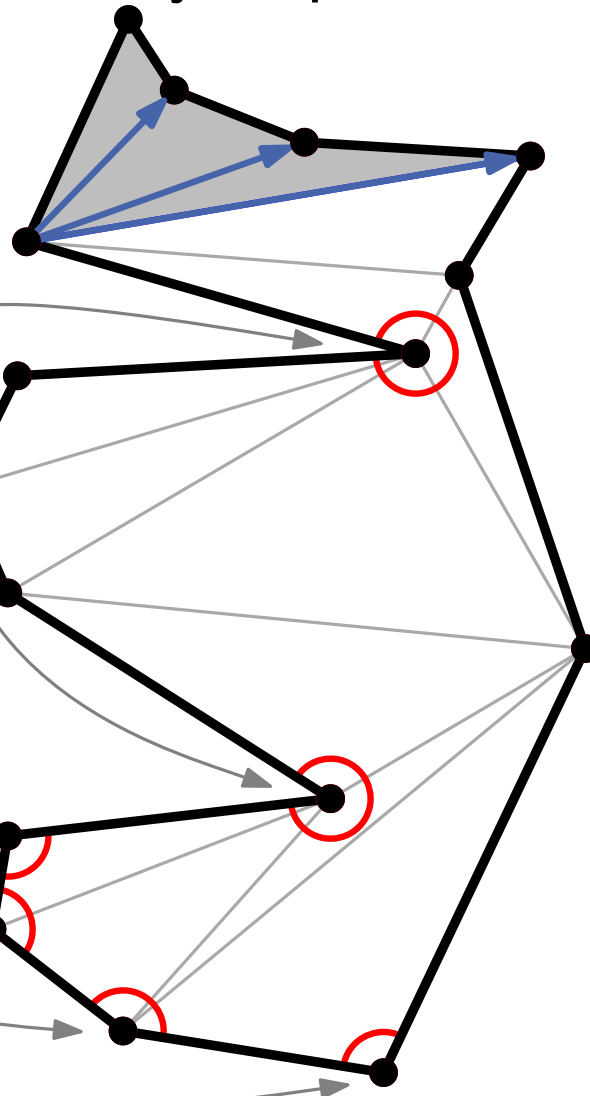
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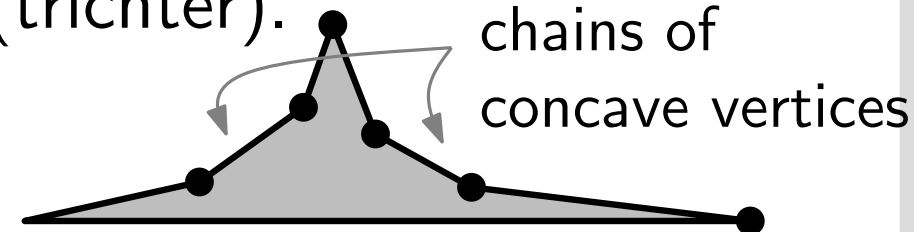
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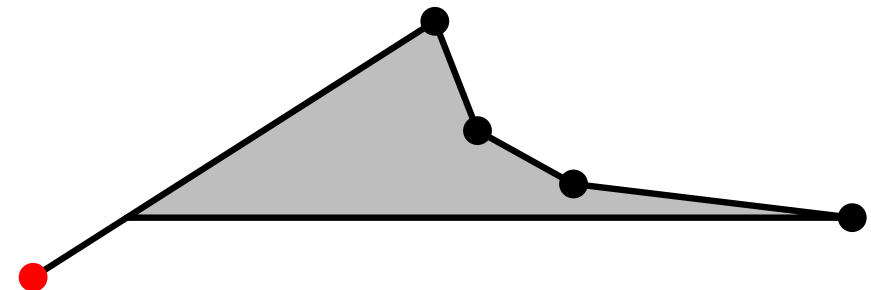


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In our case:



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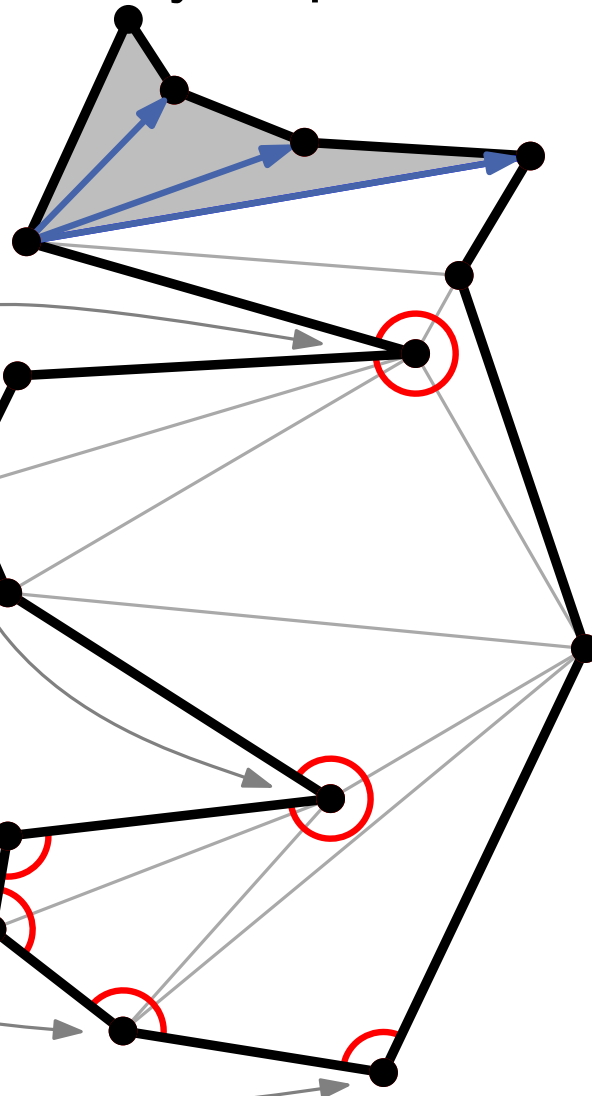
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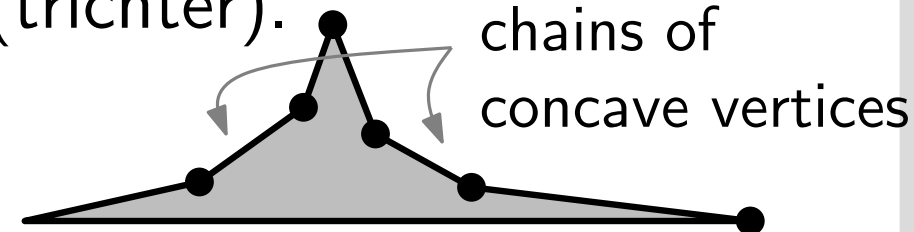
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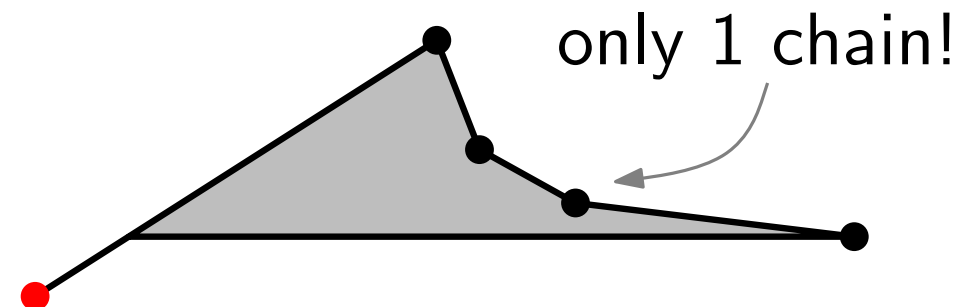


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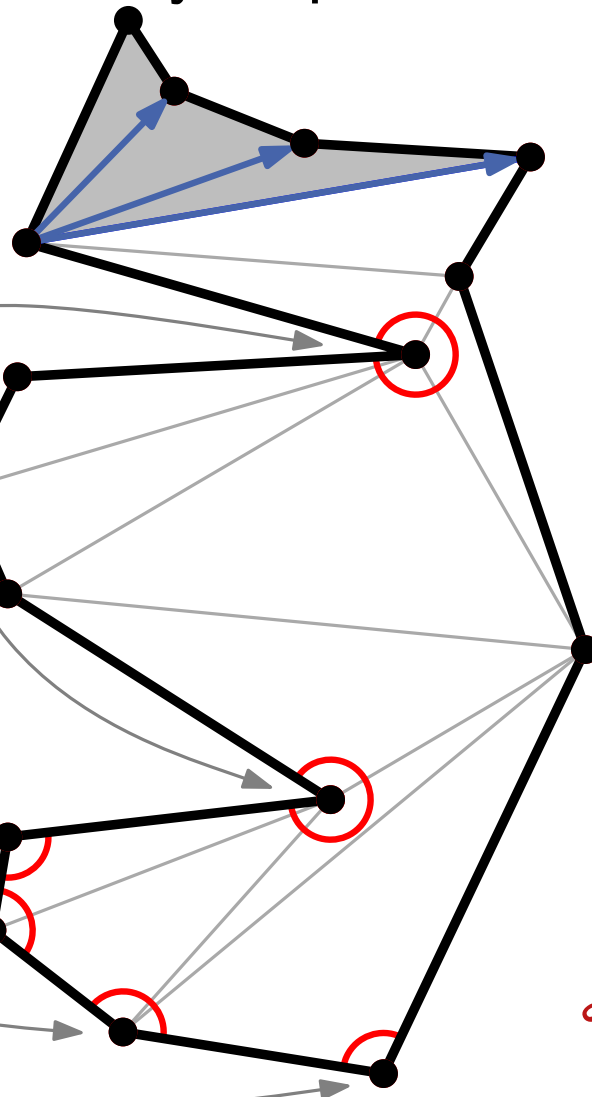
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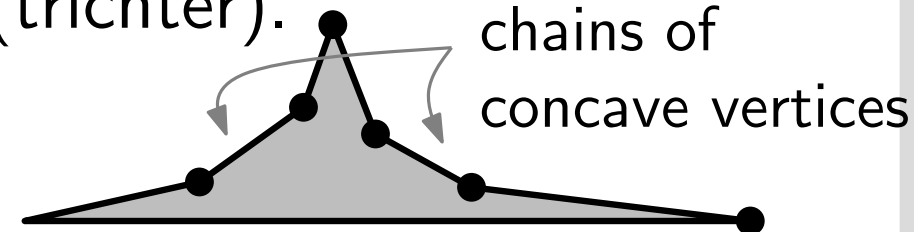
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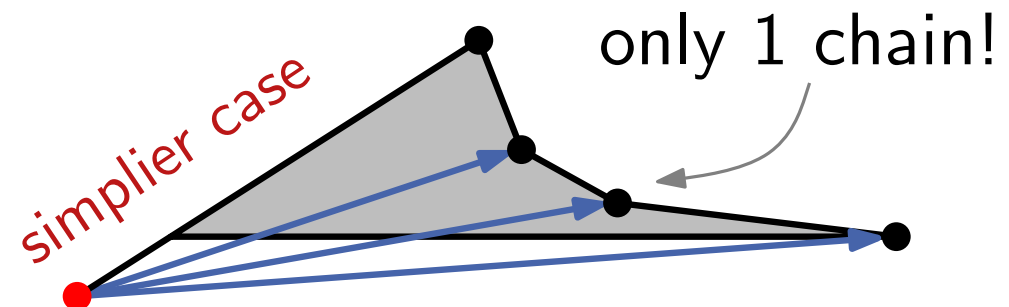


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Algorithm TriangulateMonotonePolygon

TriangulateMonotonePolygon(Polygon P as doubly-connected list of edges)

Merge vertices on left and right chains into desc. seq. $\rightarrow u_1, \dots, u_n$

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for $j \leftarrow 3$ **to** $n - 1$ **do**

if u_j and $S.top()$ from different paths **then**

while not $S.empty()$ **do**

$v \leftarrow S.pop()$

if not $S.empty()$ **then** draw (u_j, v)

$S.push(u_{j-1})$; $S.push(u_j)$

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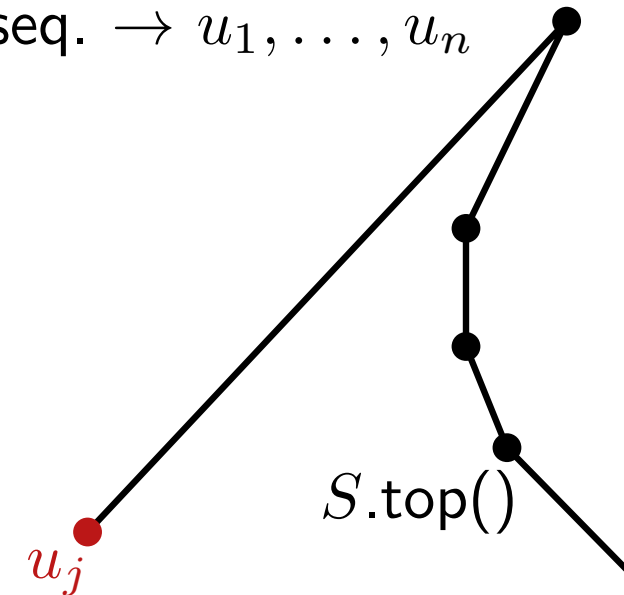
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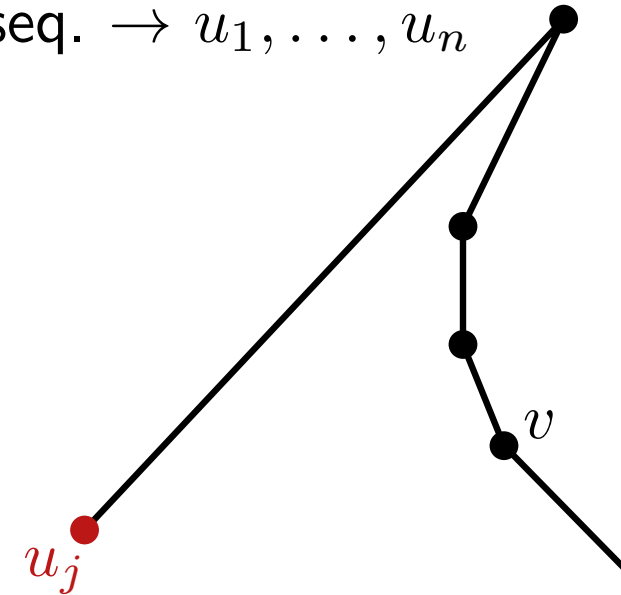
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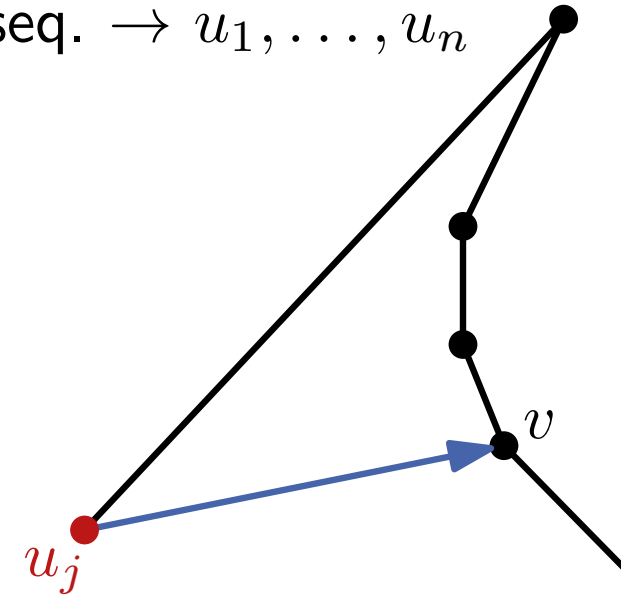
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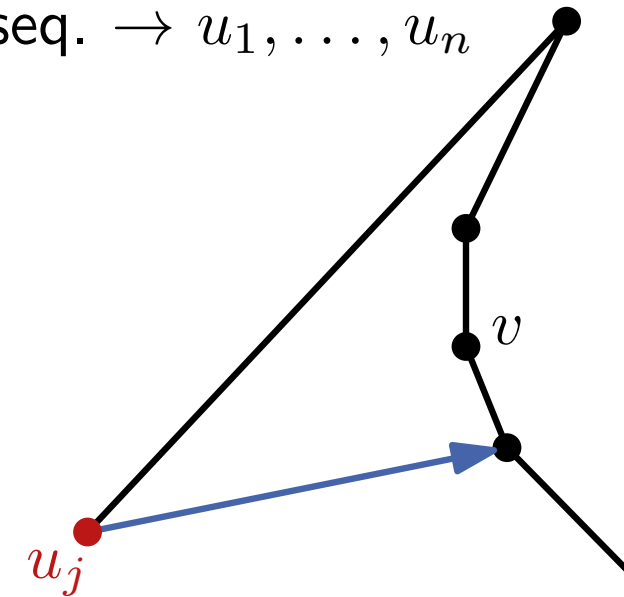
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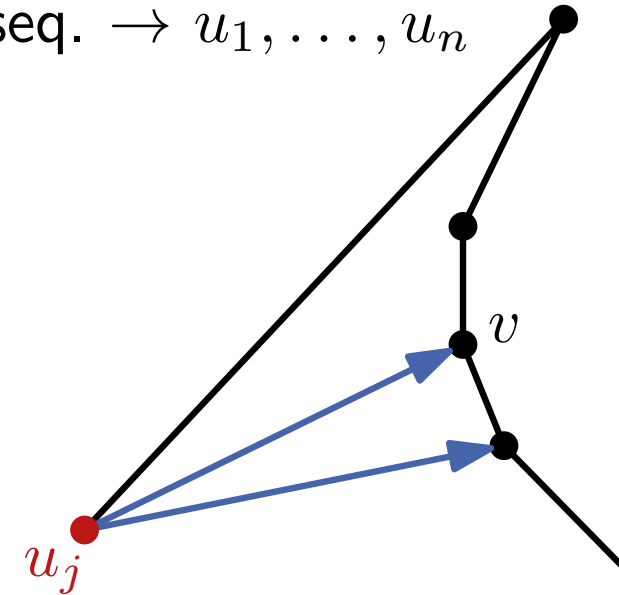
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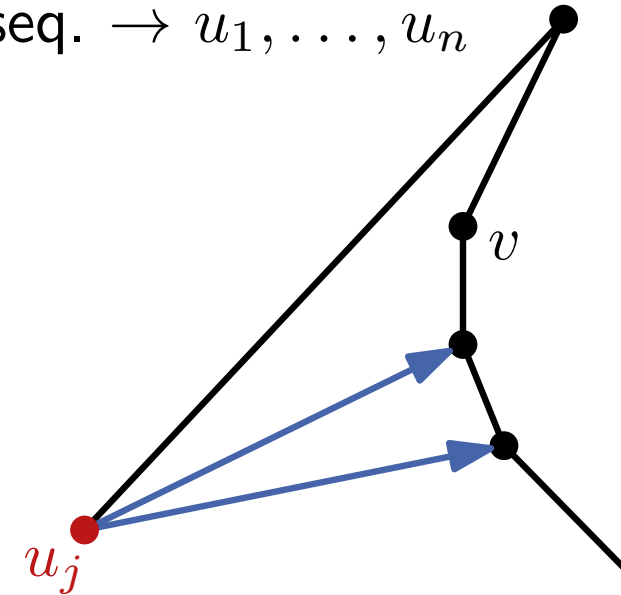
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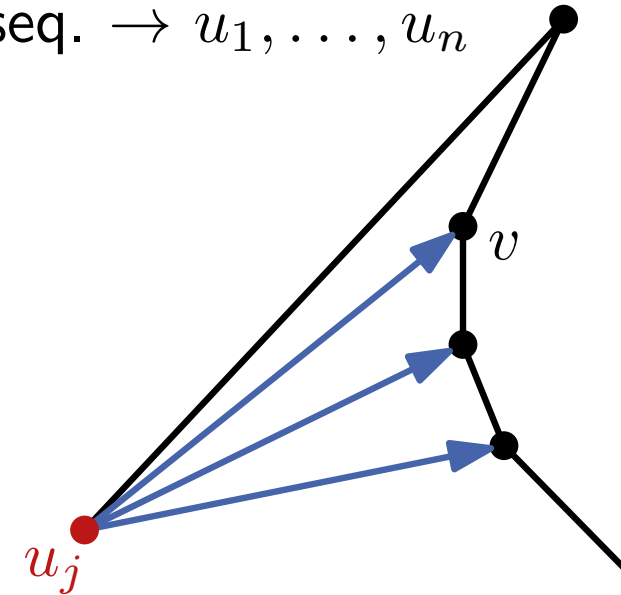
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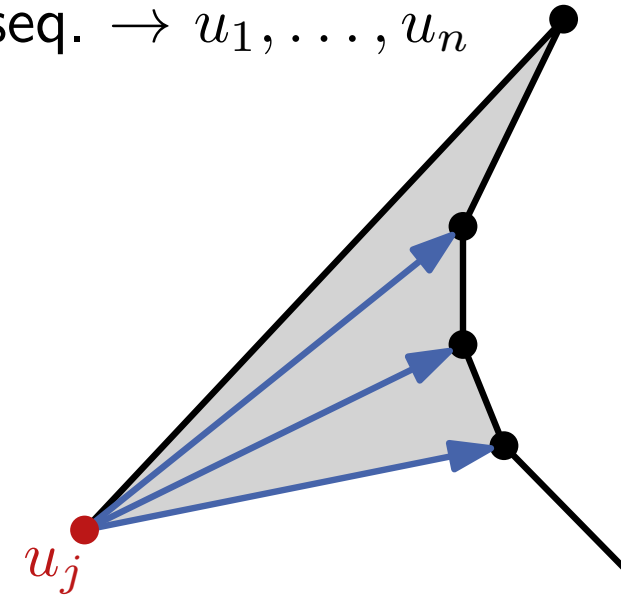
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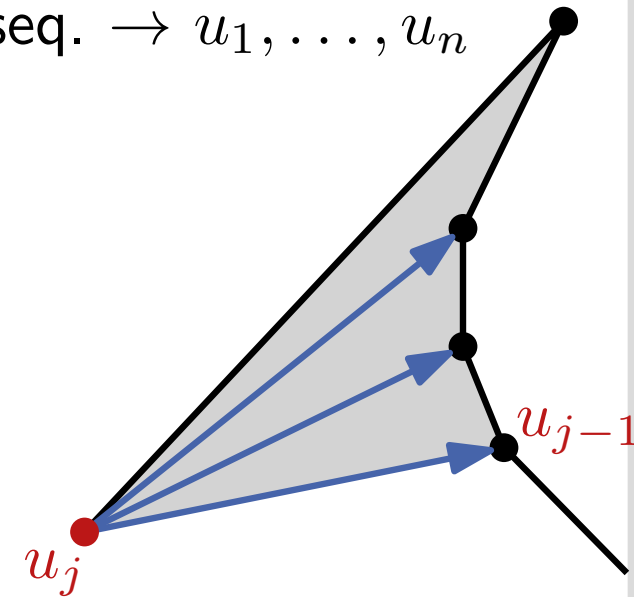
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for $j \leftarrow 3$ **to** $n - 1$ **do**

if u_j and $S.top()$ from different paths **then**

while not $S.empty()$ **do**

$v \leftarrow S.pop()$

if not $S.empty()$ **then** draw (u_j, v)

$S.push(u_{j-1})$; $S.push(u_j)$

else

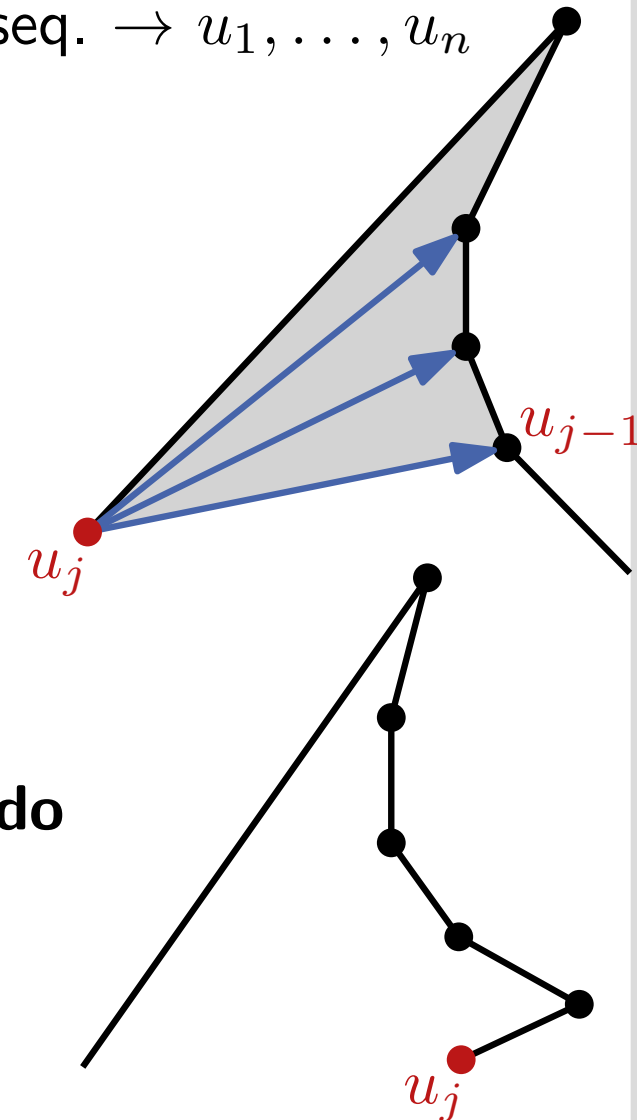
$v \leftarrow S.pop()$

while not $S.empty()$ **and** u_j sees $S.top()$ **do**

$v \leftarrow S.pop()$

draw diagonal (u_j, v)

$S.push(v)$; $S.push(u_j)$



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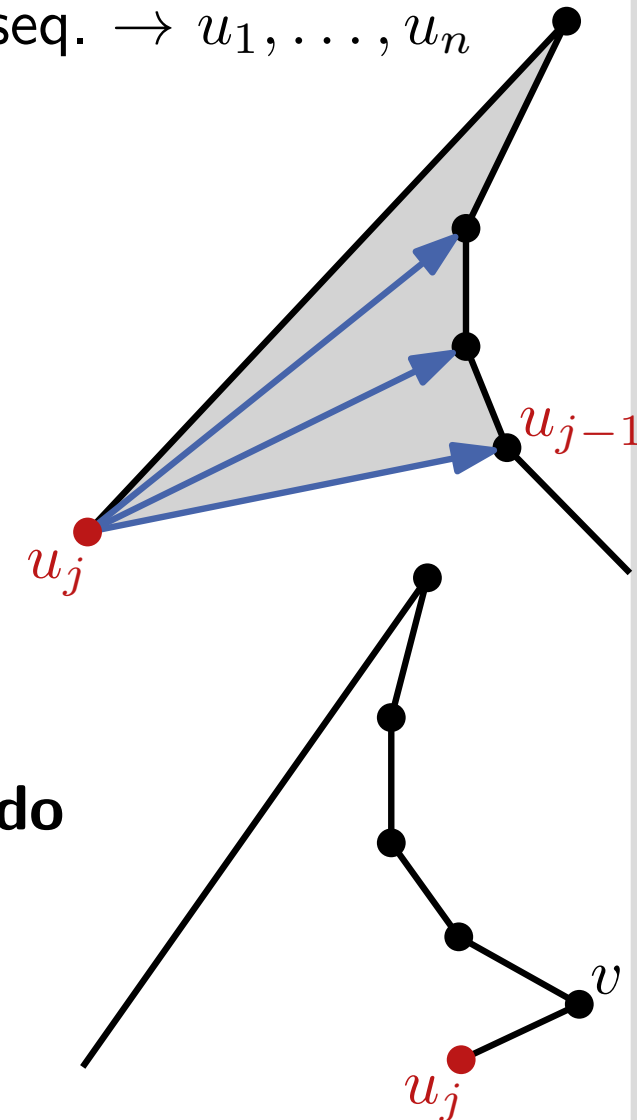
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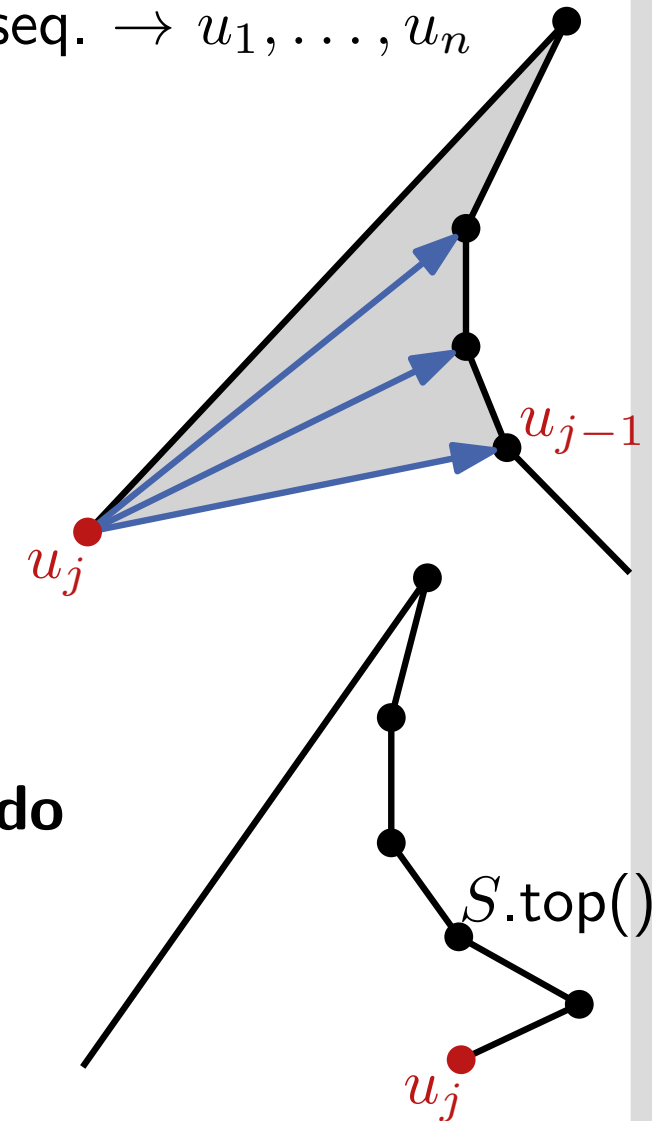
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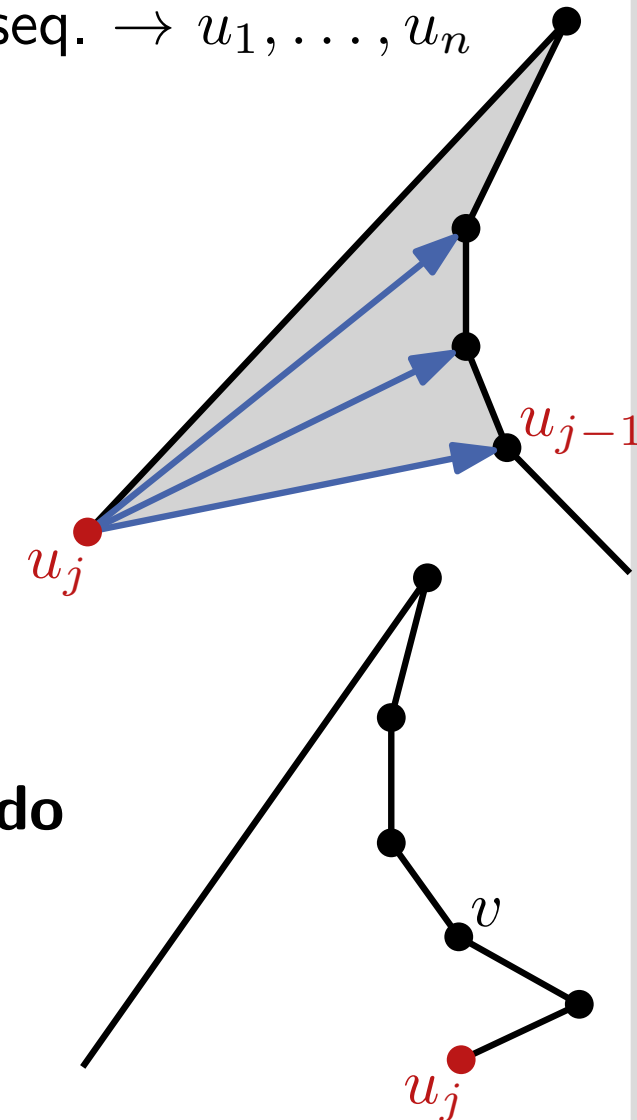
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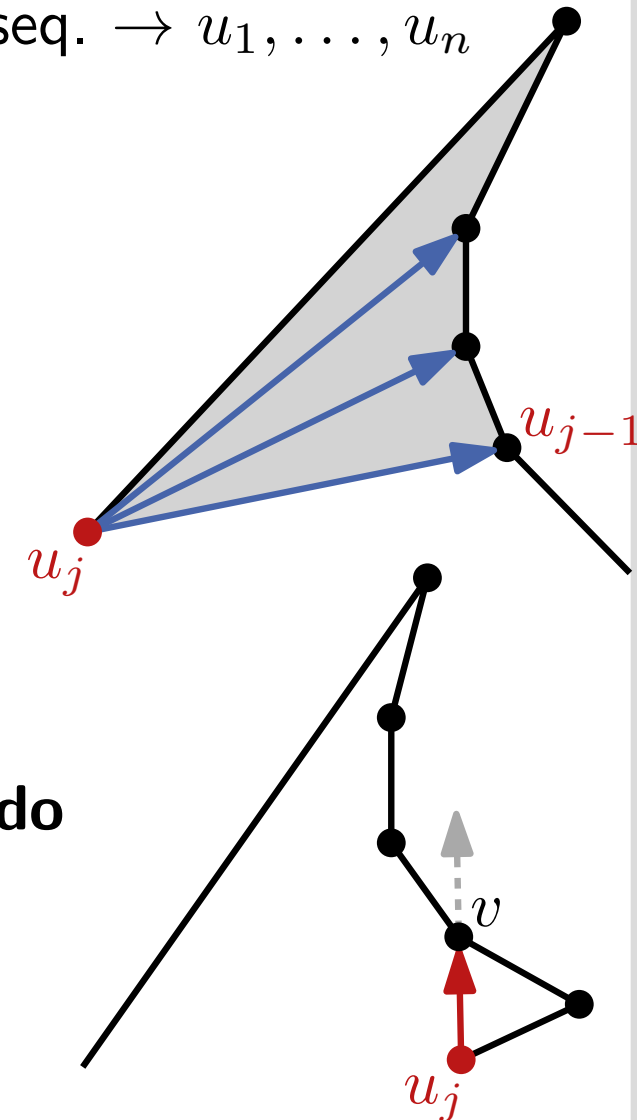
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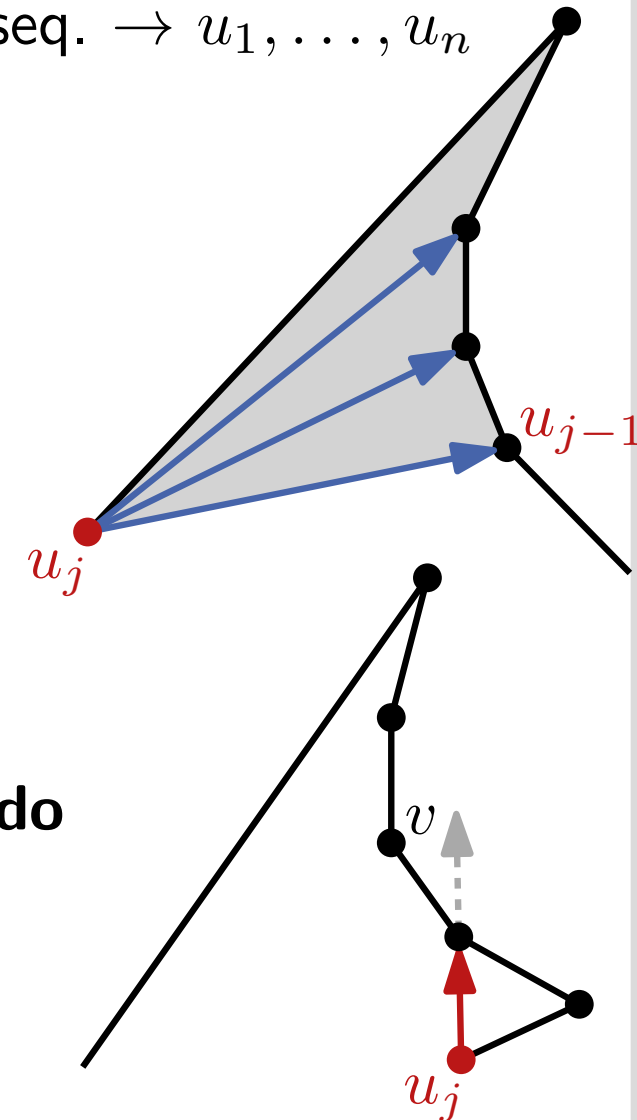
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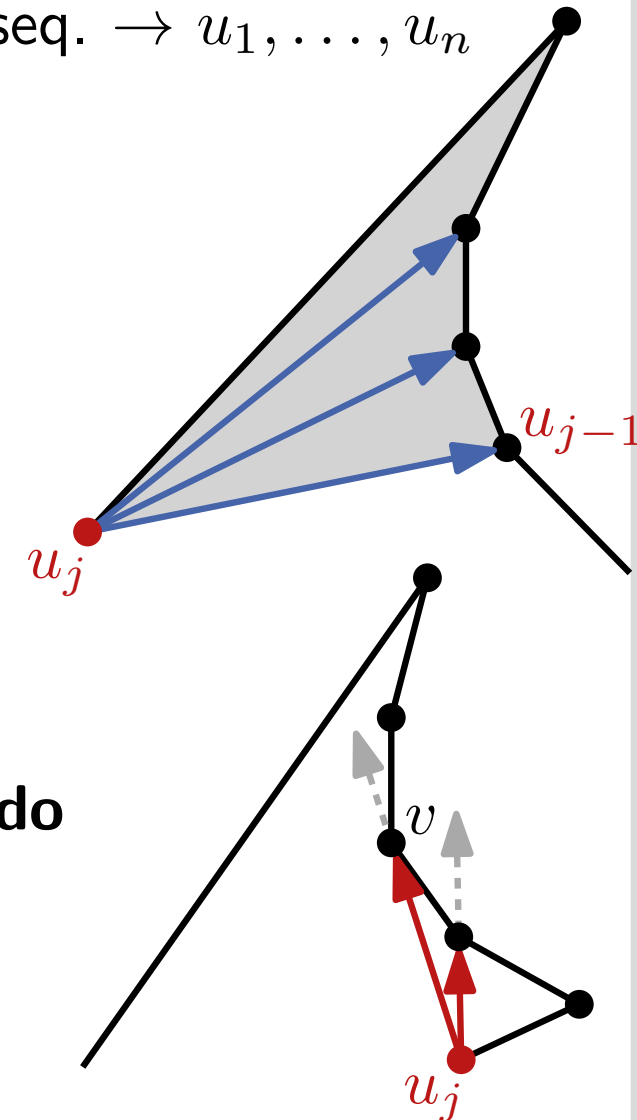
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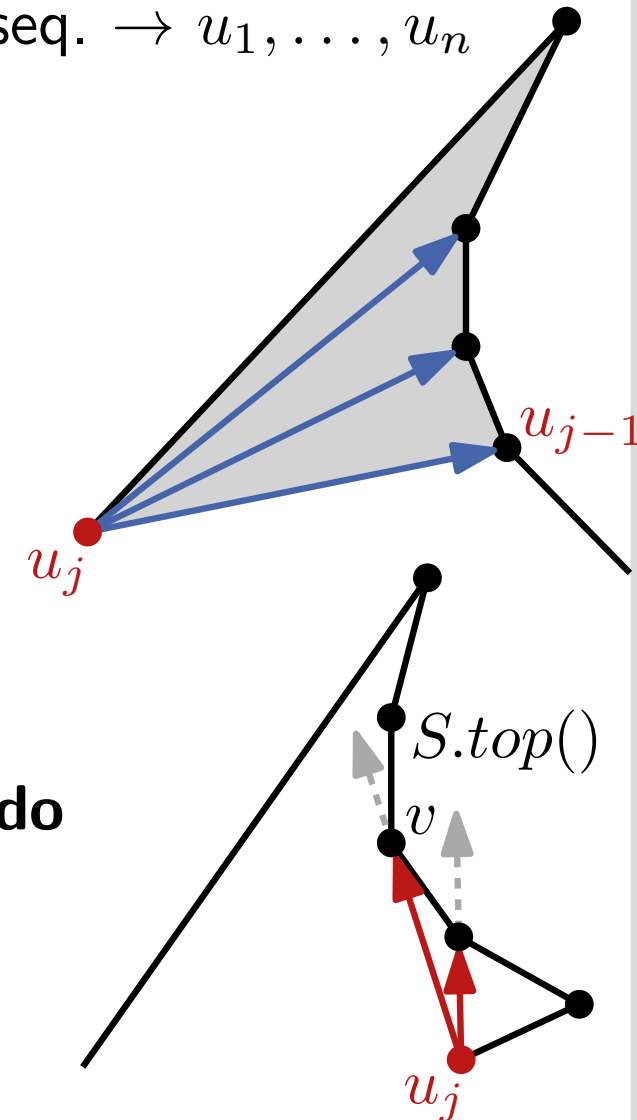
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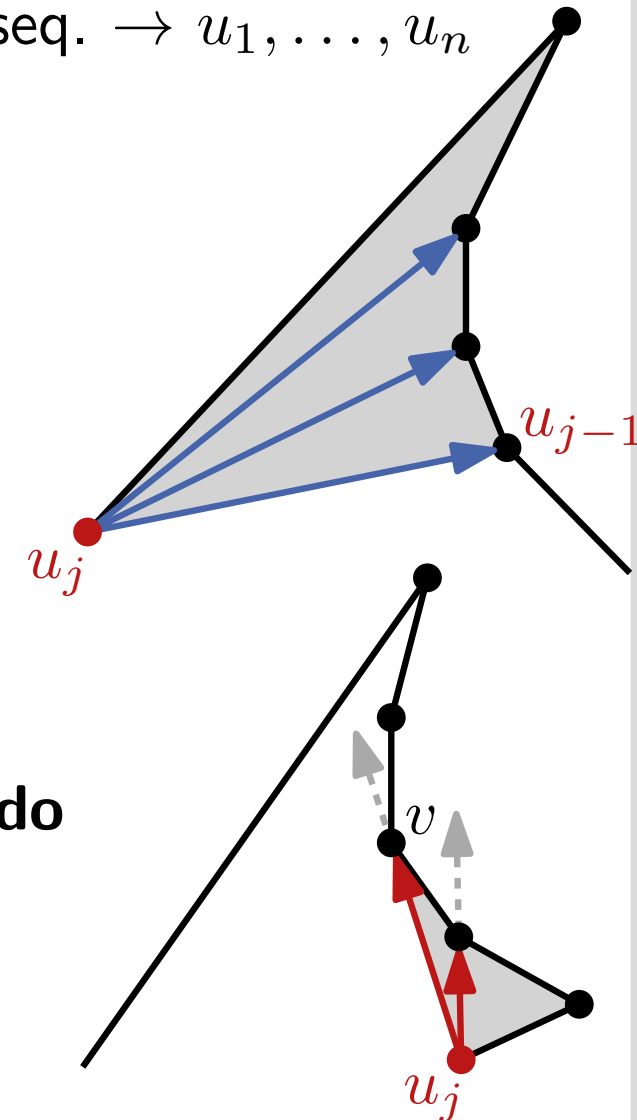
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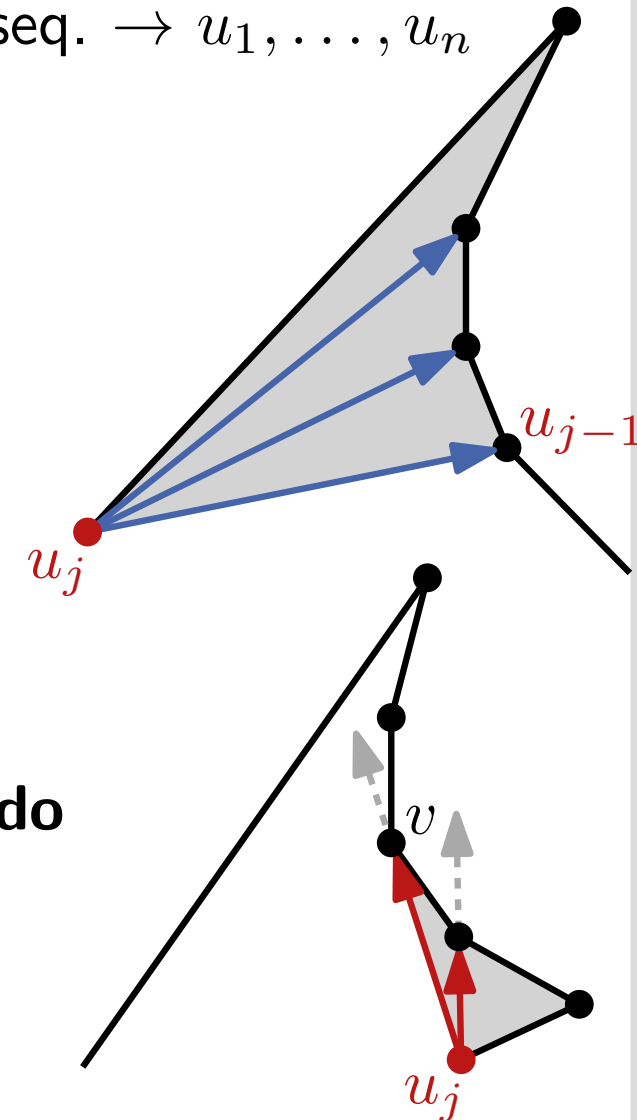
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Task:

What is the running time?

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recall

Summary

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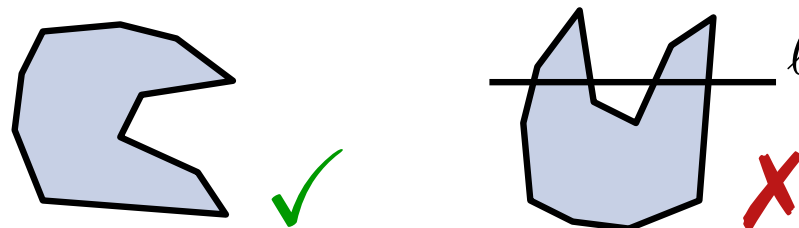
Theorem 5: A simple polygon with n vertices can be triangulated in $O(n \log n)$ time and $O(n)$ space.

Proof of Art-Gallery-Theorem: Overview

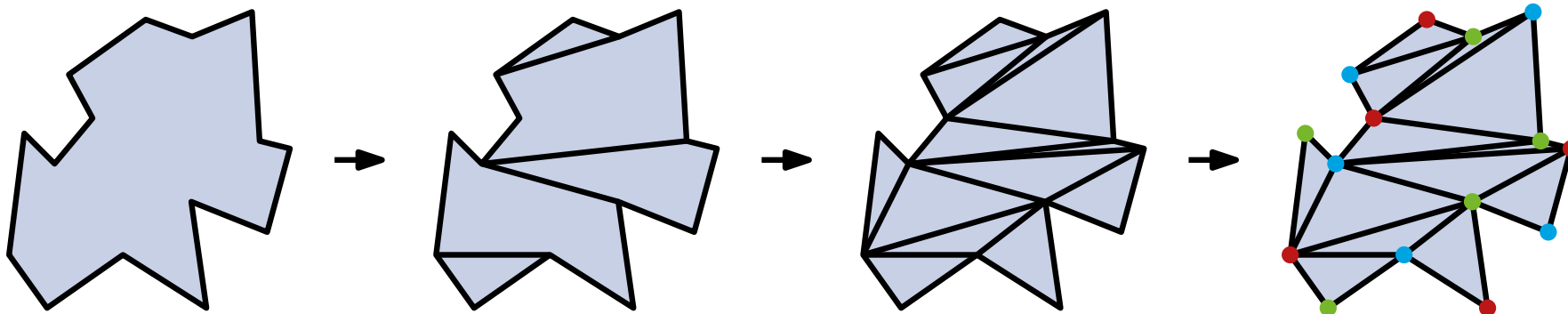
Three-step procedure:

- Step 1: Decompose P in y -monotone polygons ✓

Definition: A polygon P is y -monotone, if for each horizontal line ℓ the intersection $\ell \cap P$ is connected.



- Step 2: Triangulate y -monotone polygons ✓
- Step 3: use DFS to color the triangulated polygon ✓

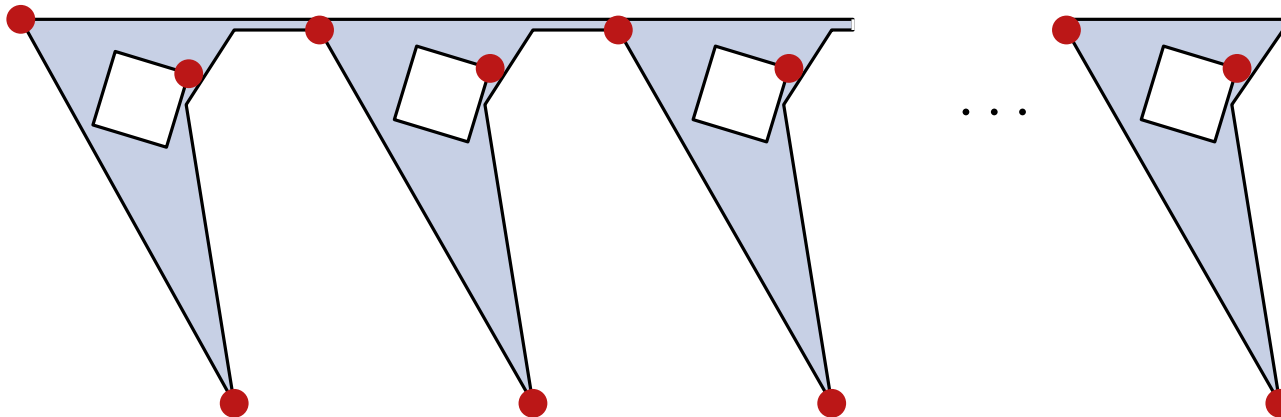


Discussion

Can the triangulation algorithm be expanded to work with polygons with holes?

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- But are $\lfloor n/3 \rfloor$ cameras still sufficient to guard it?
No, a generalization of Art-Gallery-Theorems says that $\lfloor (n + h)/3 \rfloor$ cameras are sometimes necessary, and always sufficient, where h is the number of holes. [Hoffmann et al., 1991]



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Can we solve the triangulation problem faster for simple polygons?

Yes. The question whether it is possible was open for more than a decade. In the end of 80's a faster randomized algorithm was given, and in 1990 Chazelle presented a deterministic linear-time algorithm (complicated).