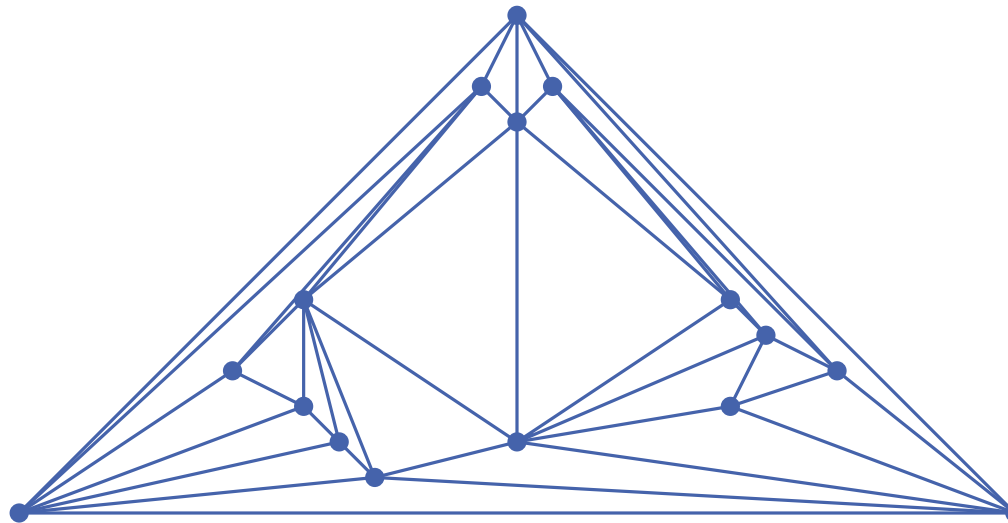


Algorithms for graph visualization

Layouts for planar graphs. Shift method.

WINTER SEMESTER 2014/2015

Tamara Mchedlidze – MARTIN NÖLLENBURG



Motivation

- Till now we look at planar and straight-line drawings of trees and SP-graphs

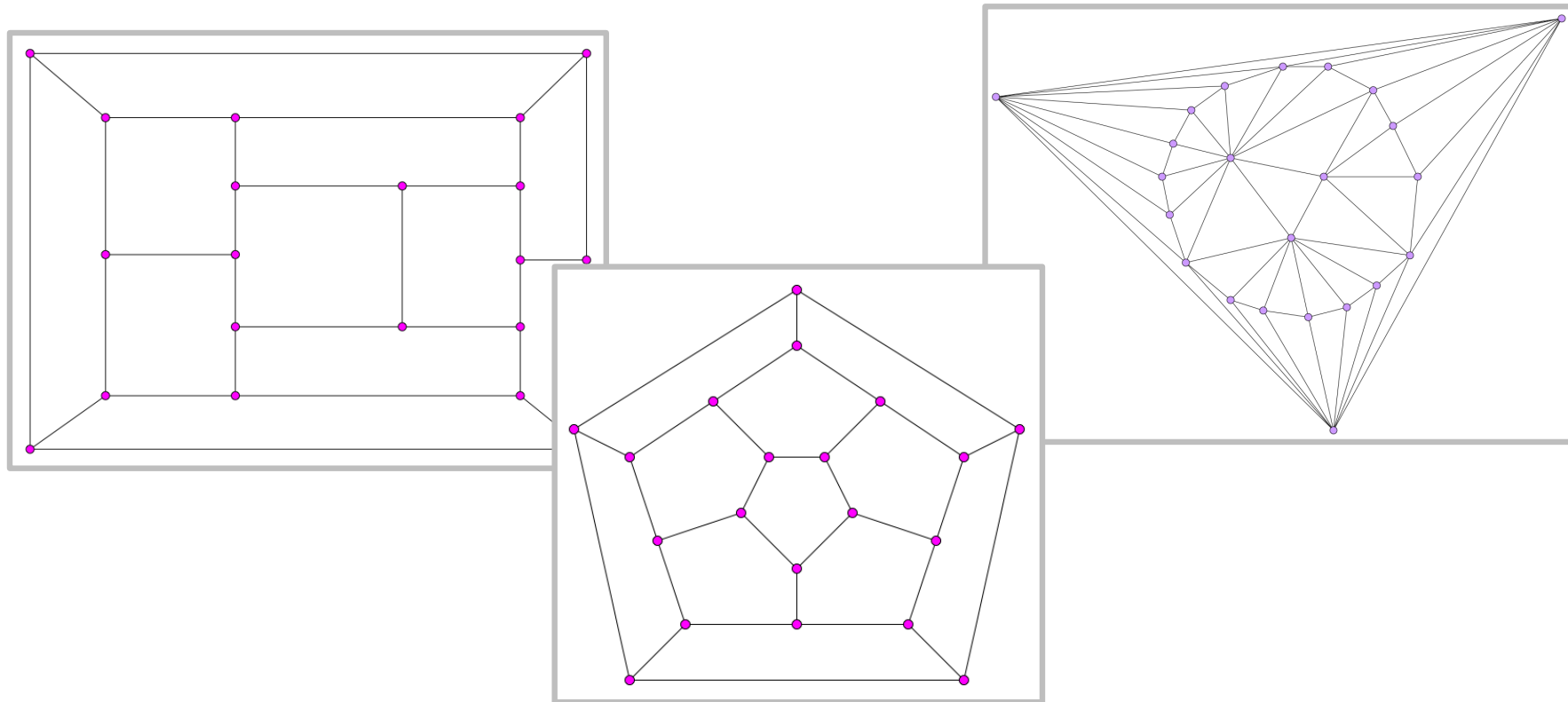
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3.2. Edge Placement Heuristics

By far the most agreed-upon edge placement heuristic is to *minimize the number of edge crossings* in a graph [BMRW98, Har98, DH96, Pur02, TR05, TBB88]. The importance of avoiding edge crossings has also been extensively validated in terms of user preference and performance (see Section 4). Similarly, based on perceptual principles, it is beneficial to *minimize the number of edge bends* within a graph [Pur02, TR05, TBB88]. Edge bends make edges more difficult to follow because an edge with a sharp bend is more likely to be perceived as two separate objects. This leads to the heuristic of *keeping edge bends uniform* with respect to the bend's position on the edge and its angle [TR05]. If an edge must be bent to satisfy other aesthetic criteria, the angle of the bend should be as little as possible, and the bend placement should evenly divide the edge.

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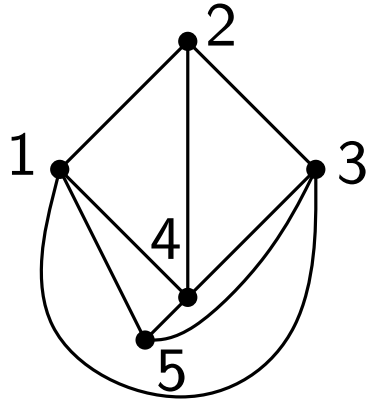
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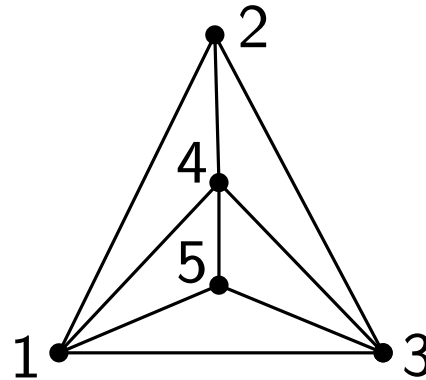
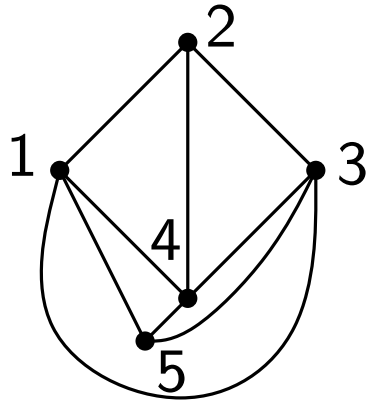
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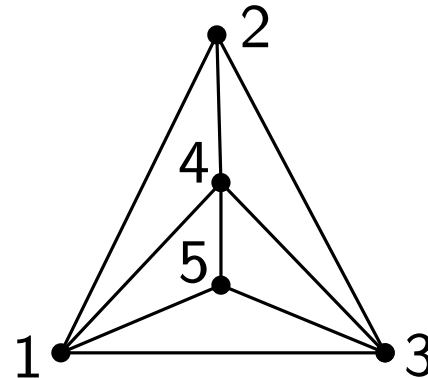
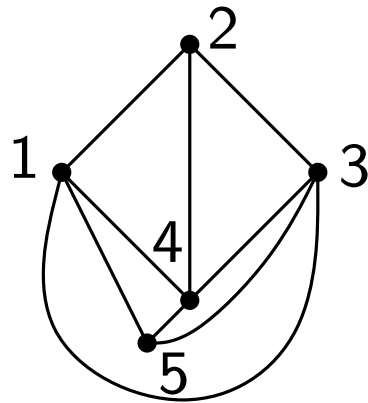
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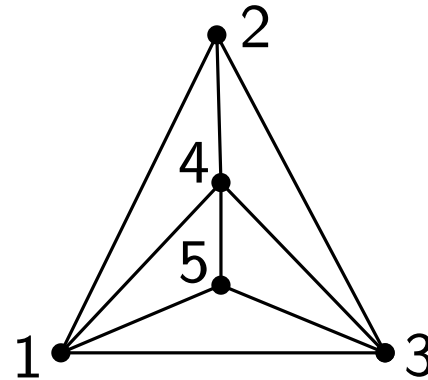
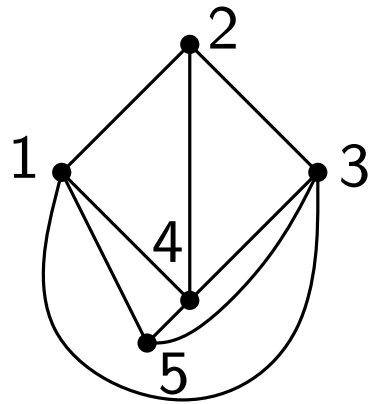
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Theorem [Wagner '36, Fary '48, Stein '51]

Every planar graph has a planar straight-line drawing.

- Straight line drawing of a planar graph



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Every planar graph has a planar straight-line drawing.

- These algorithms produce drawings with area **not bounded** by any polynomial on n .

This lecture:

Theorem [De Fraysseix, Pach, Pollack '90]

Every n -vertex planar graph has a planar straight-line drawing of a size $(2n - 4) \times (n - 2)$.

Next lecture:

Theorem [Schnyder '90]

Every n -vertex planar graph has a planar straight-line drawing of a size $(n - 2) \times (n - 2)$.

Definition: Canonical Ordering

Let $G = (V, E)$ be a triangulated planar embedded graph of $n \geq 3$ vertices. An ordering $\pi = (v_1, v_2, \dots, v_n)$ is called a **canonical ordering**, if the following conditions hold for each k , $3 \leq k \leq n$.

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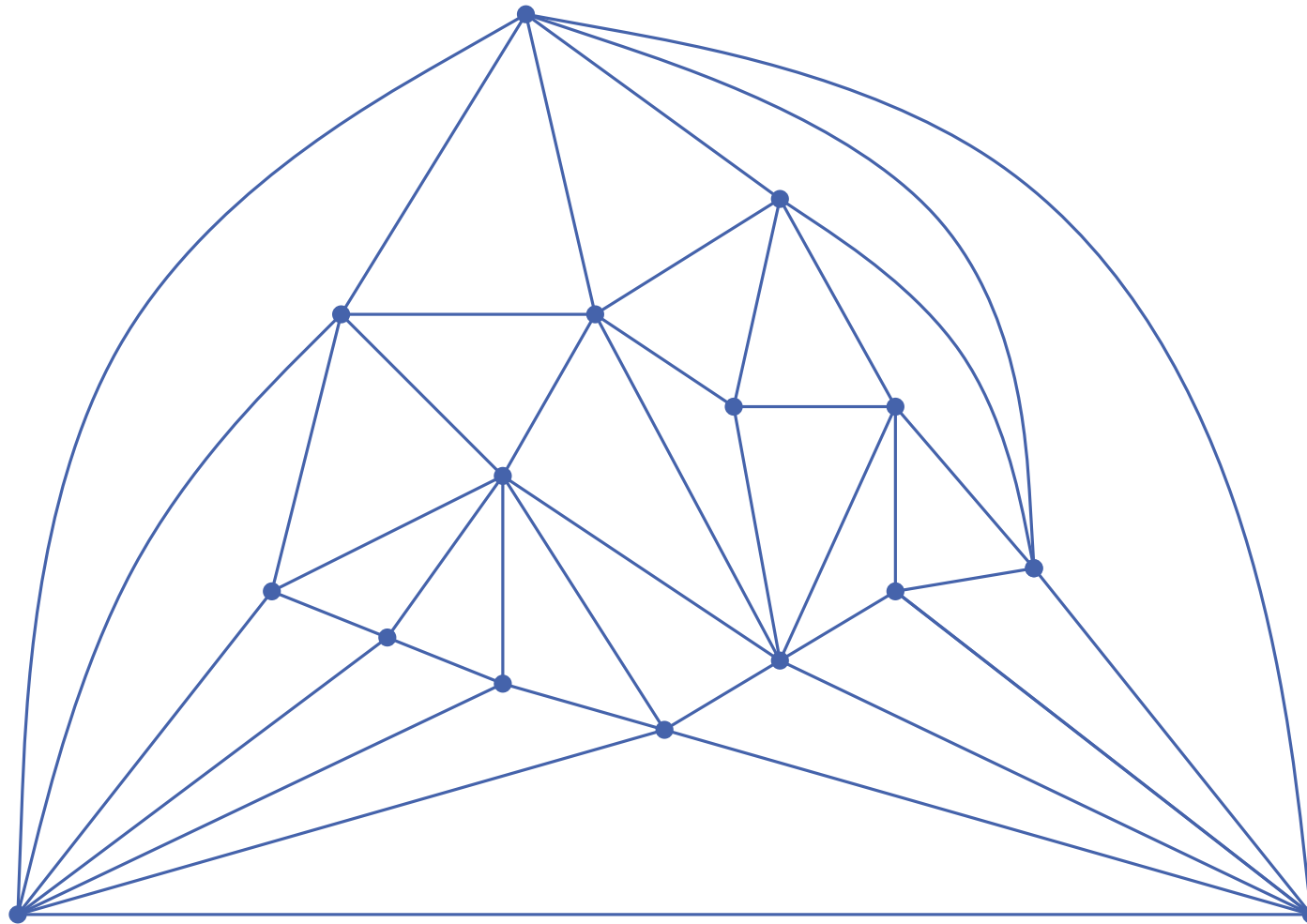
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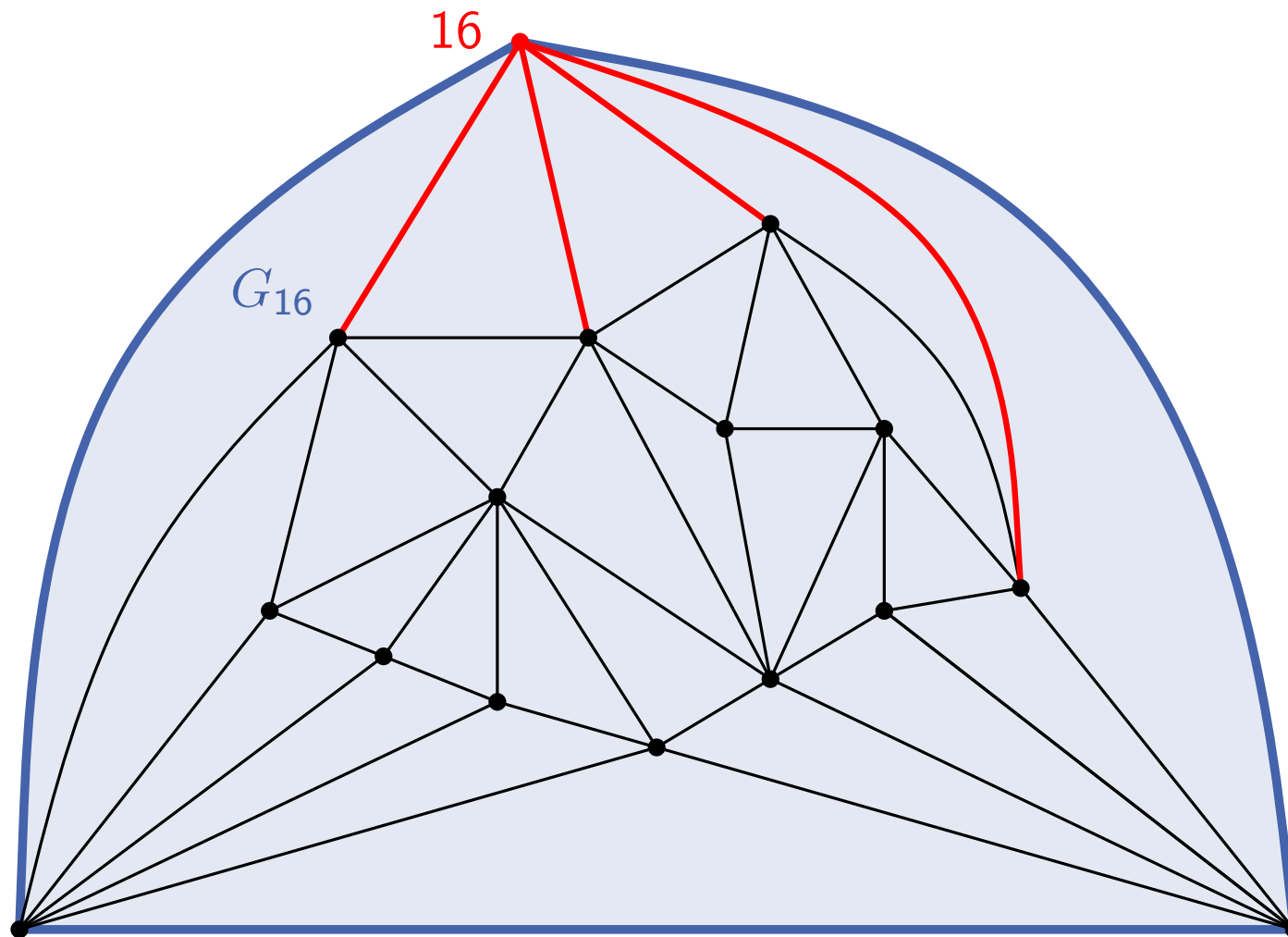
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- (C3) If $k < n$ then vertex v_{k+1} lies in the outer face of G_k , and all neighbors of v_{k+1} in G_k appear on the boundary of G_k consecutively.

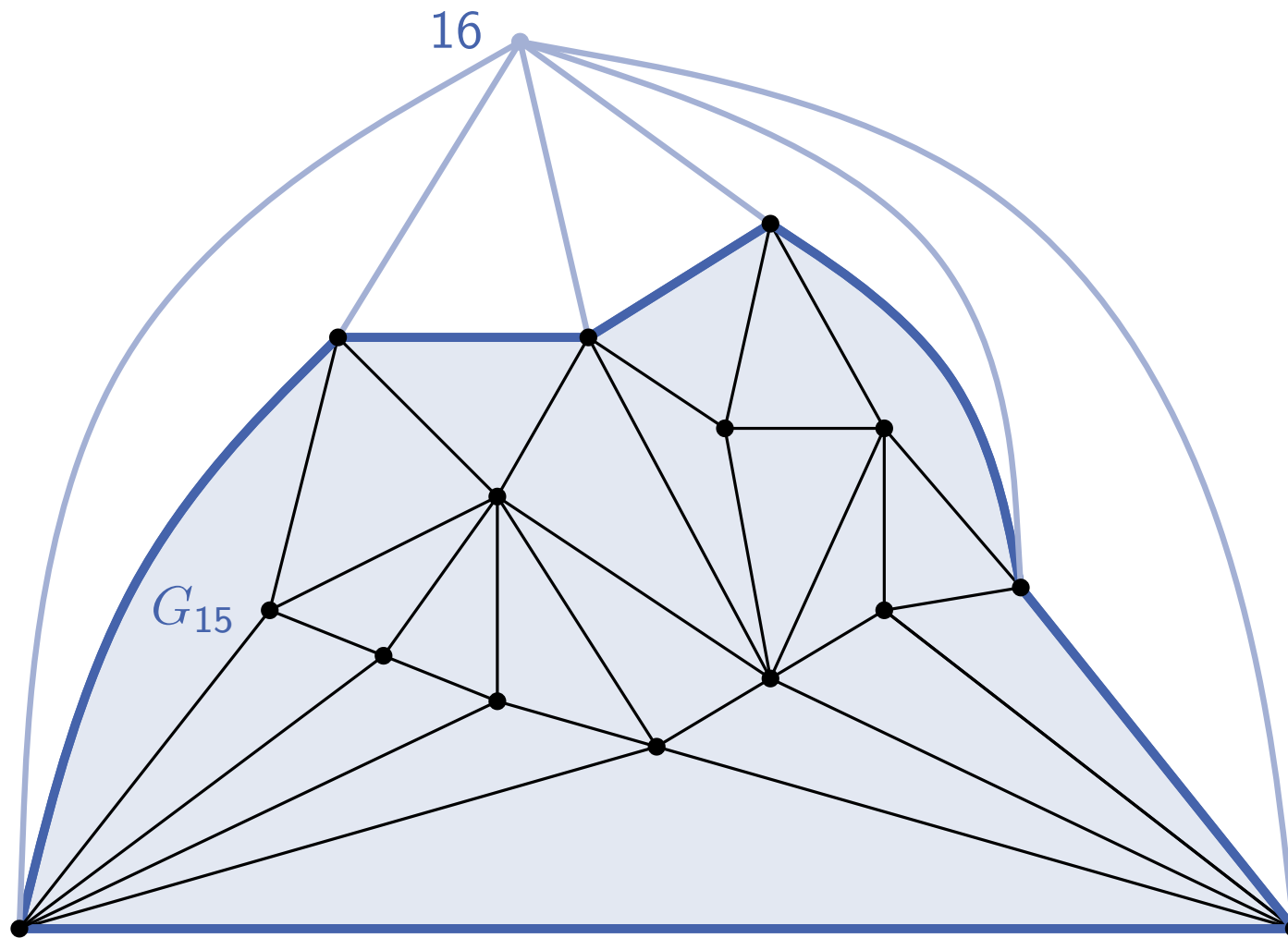
Example of Canonical Ordering



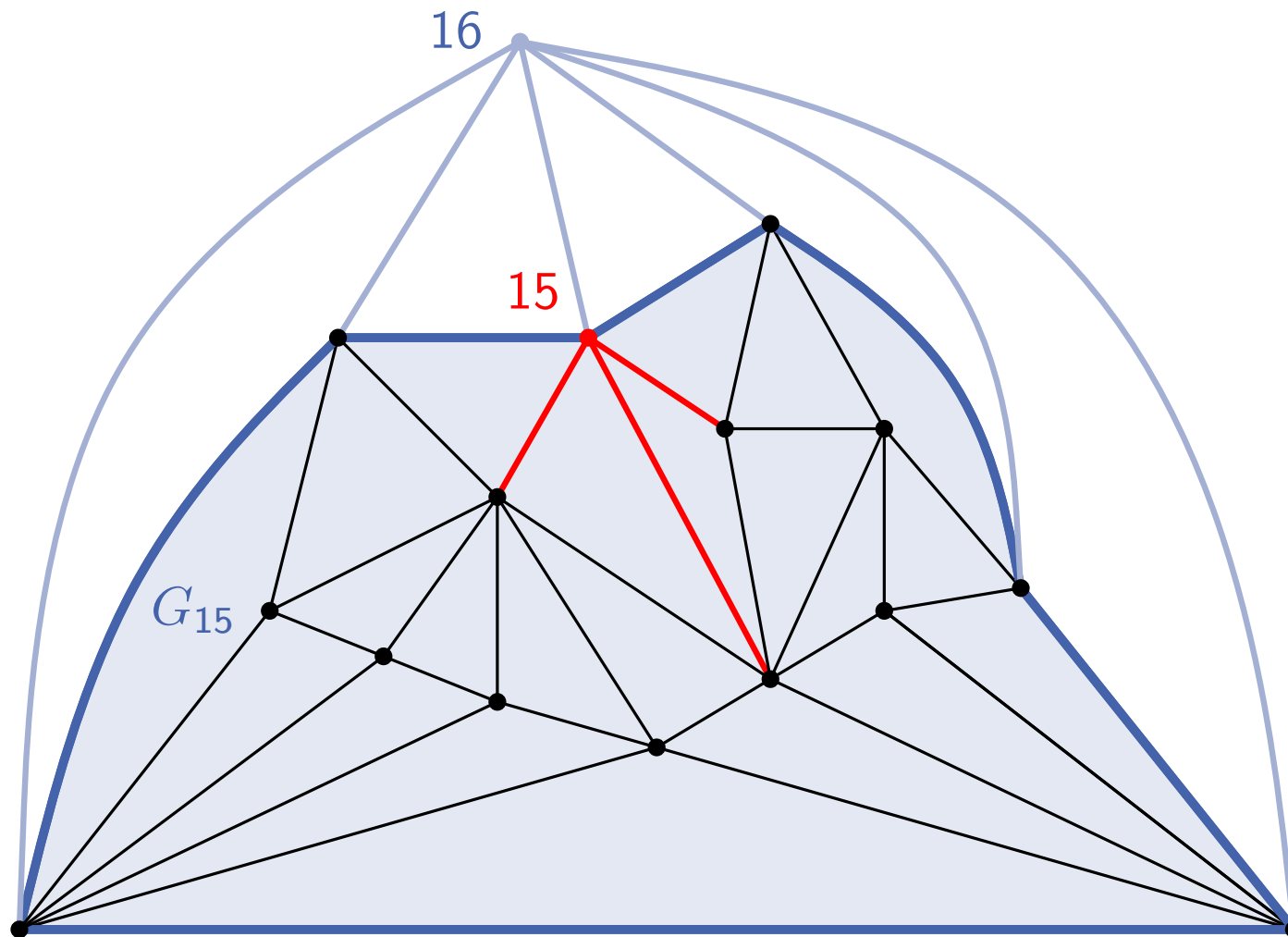
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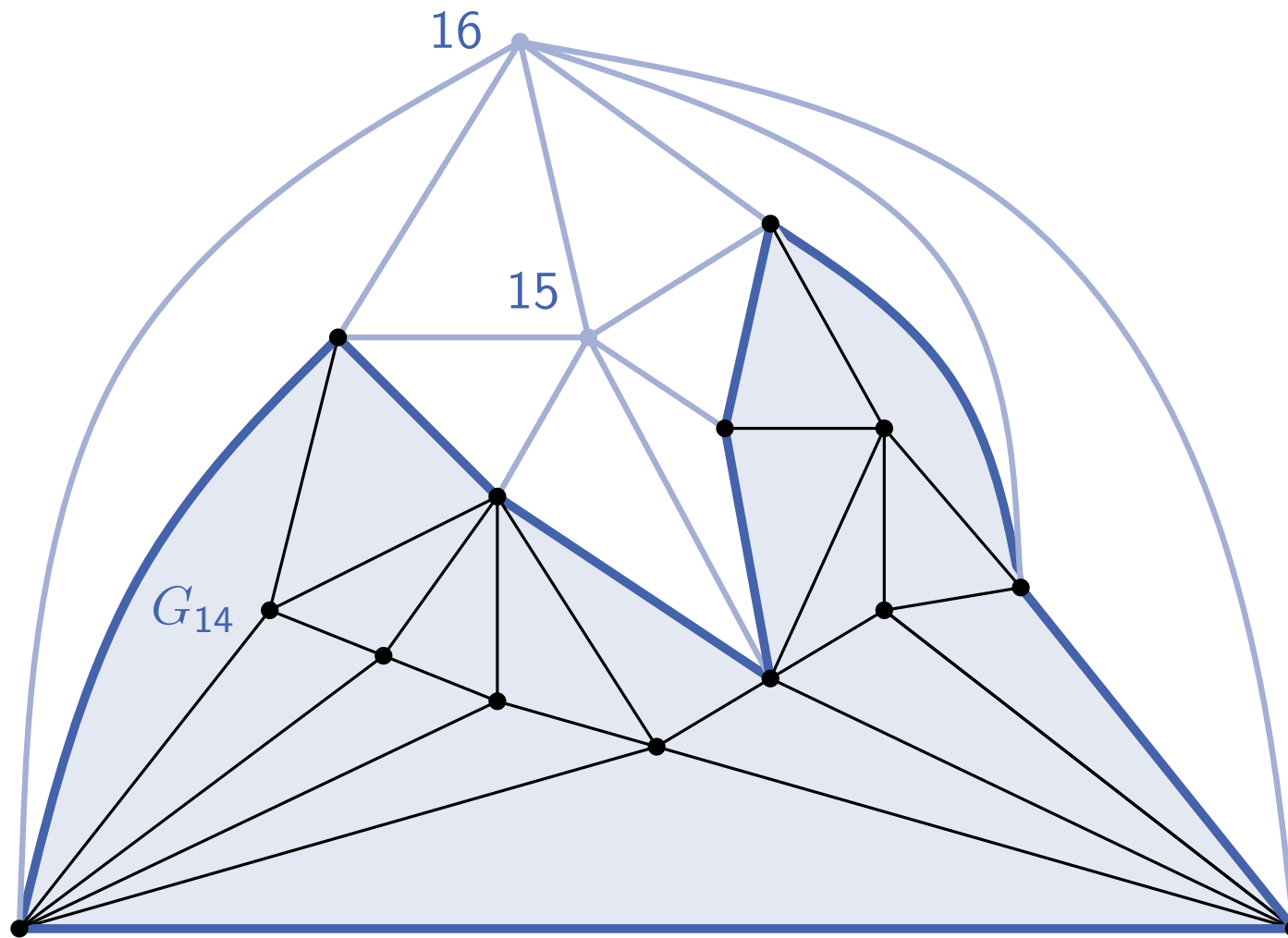
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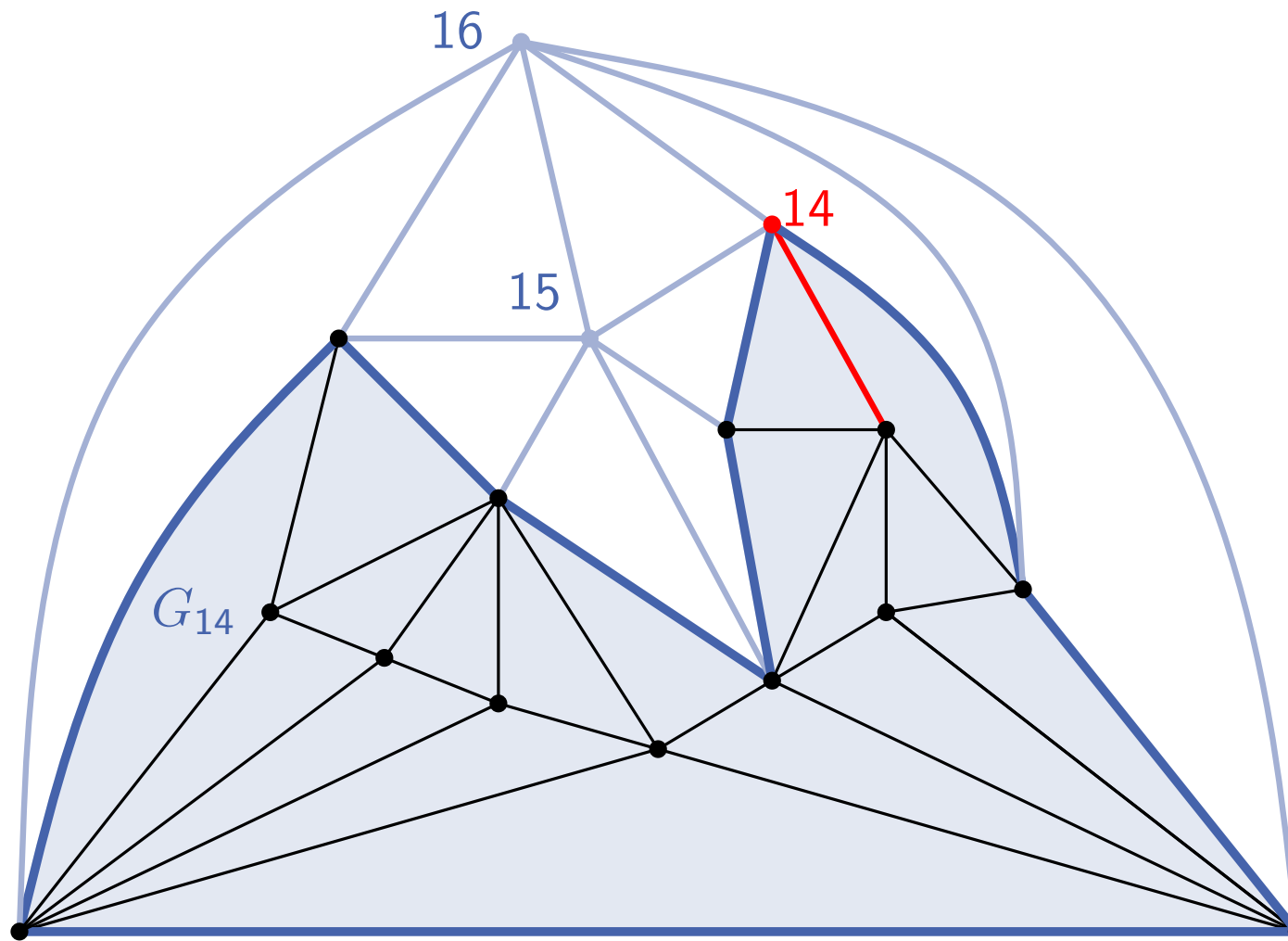
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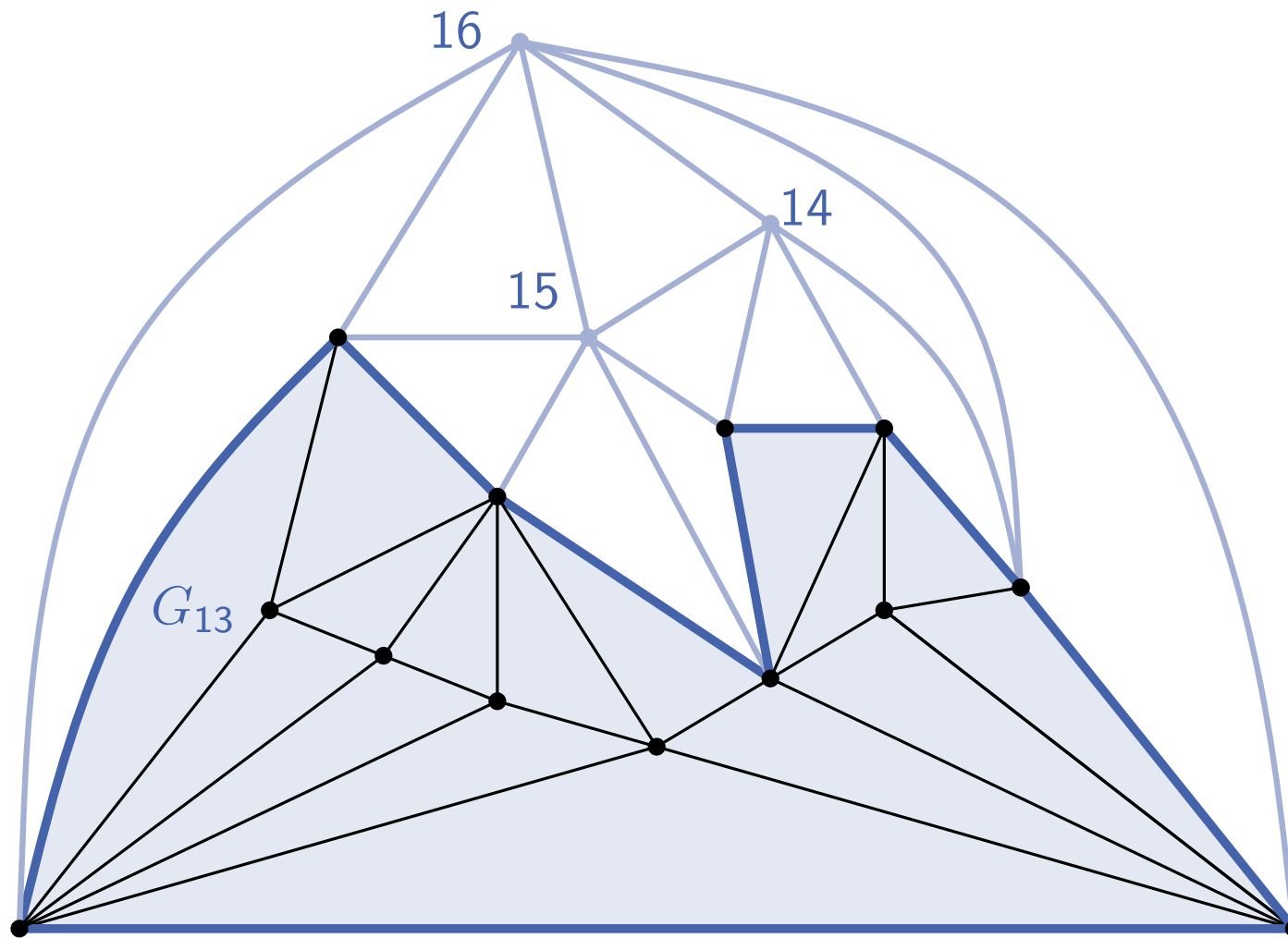
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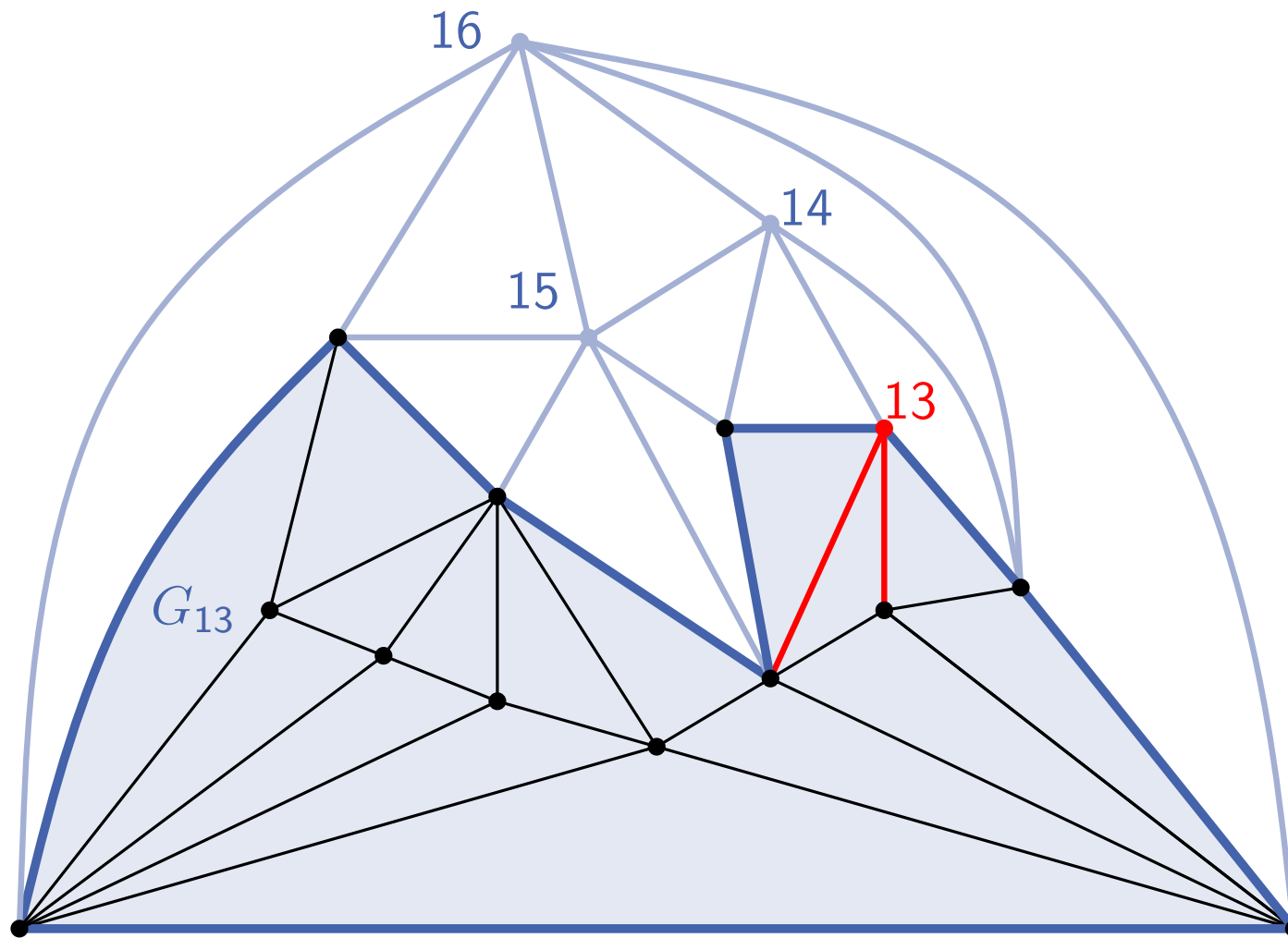
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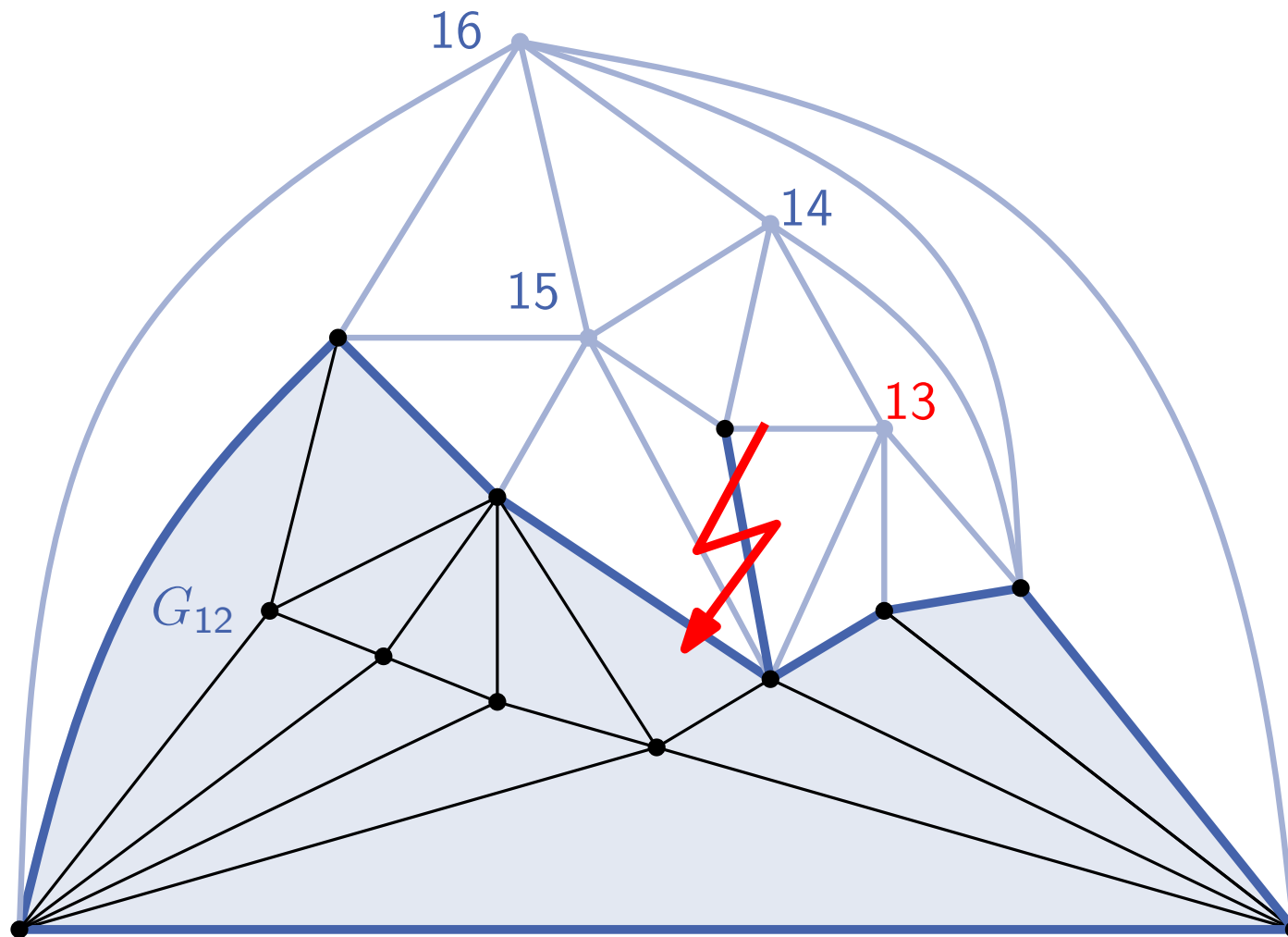
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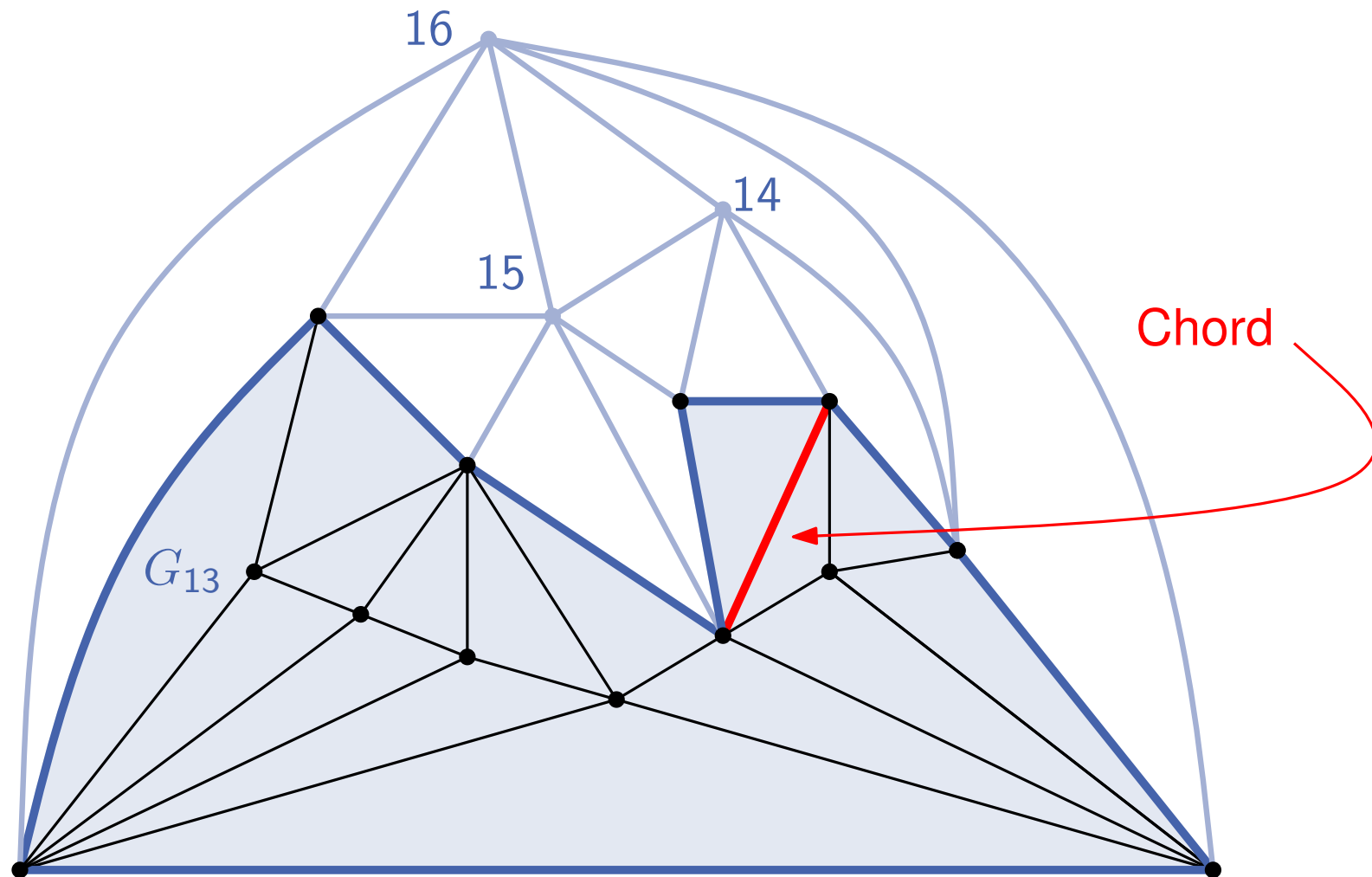
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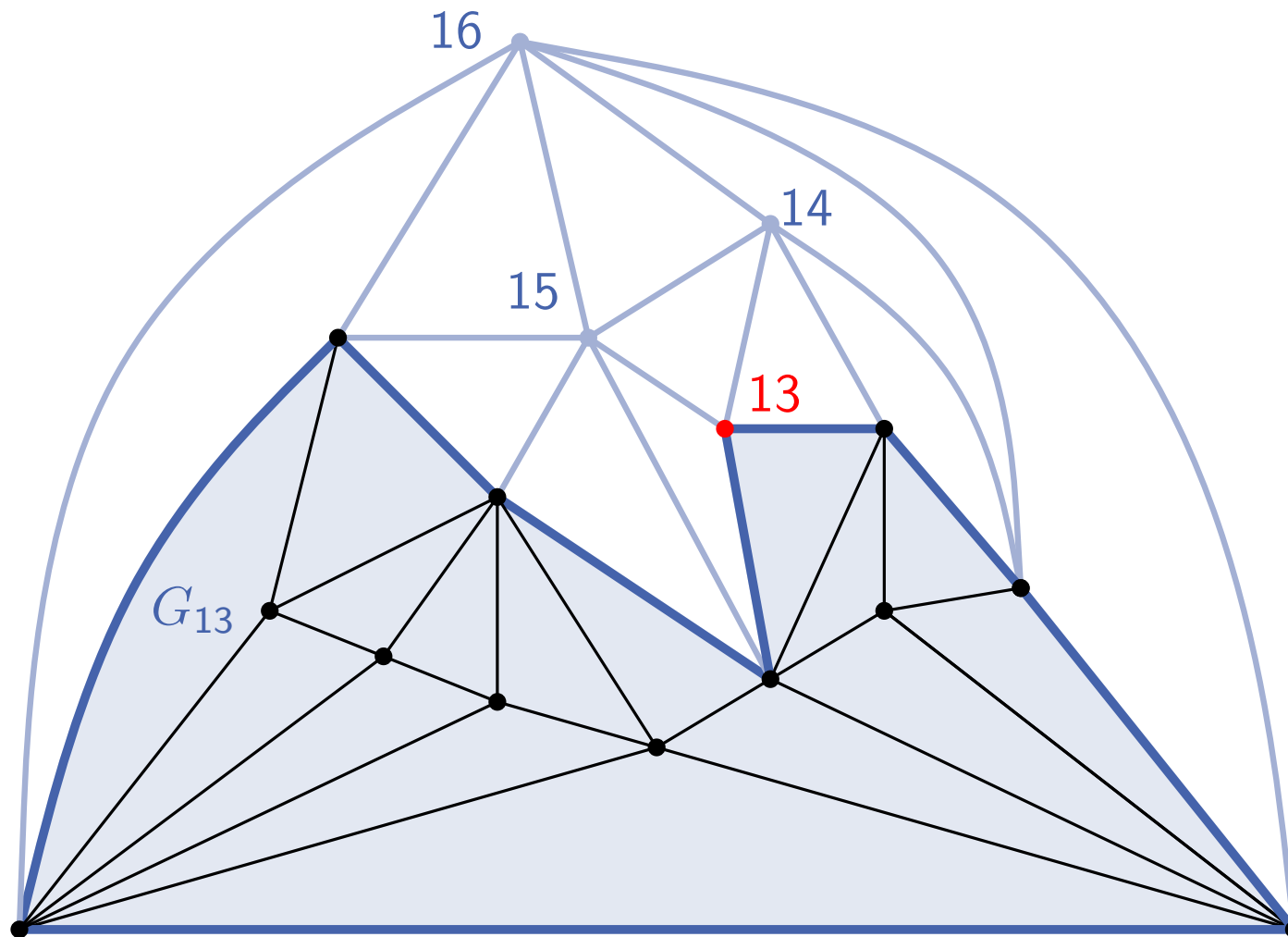
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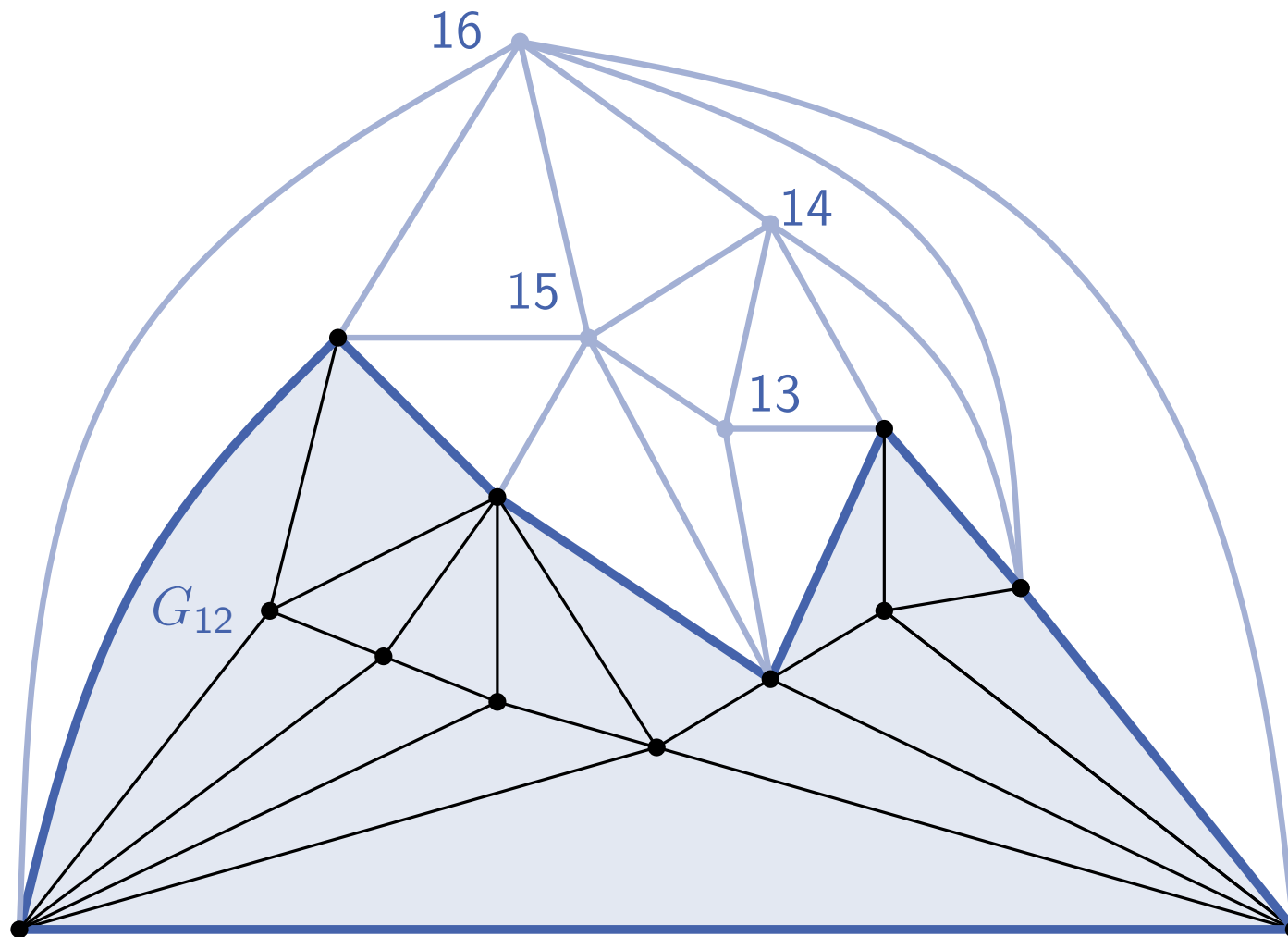
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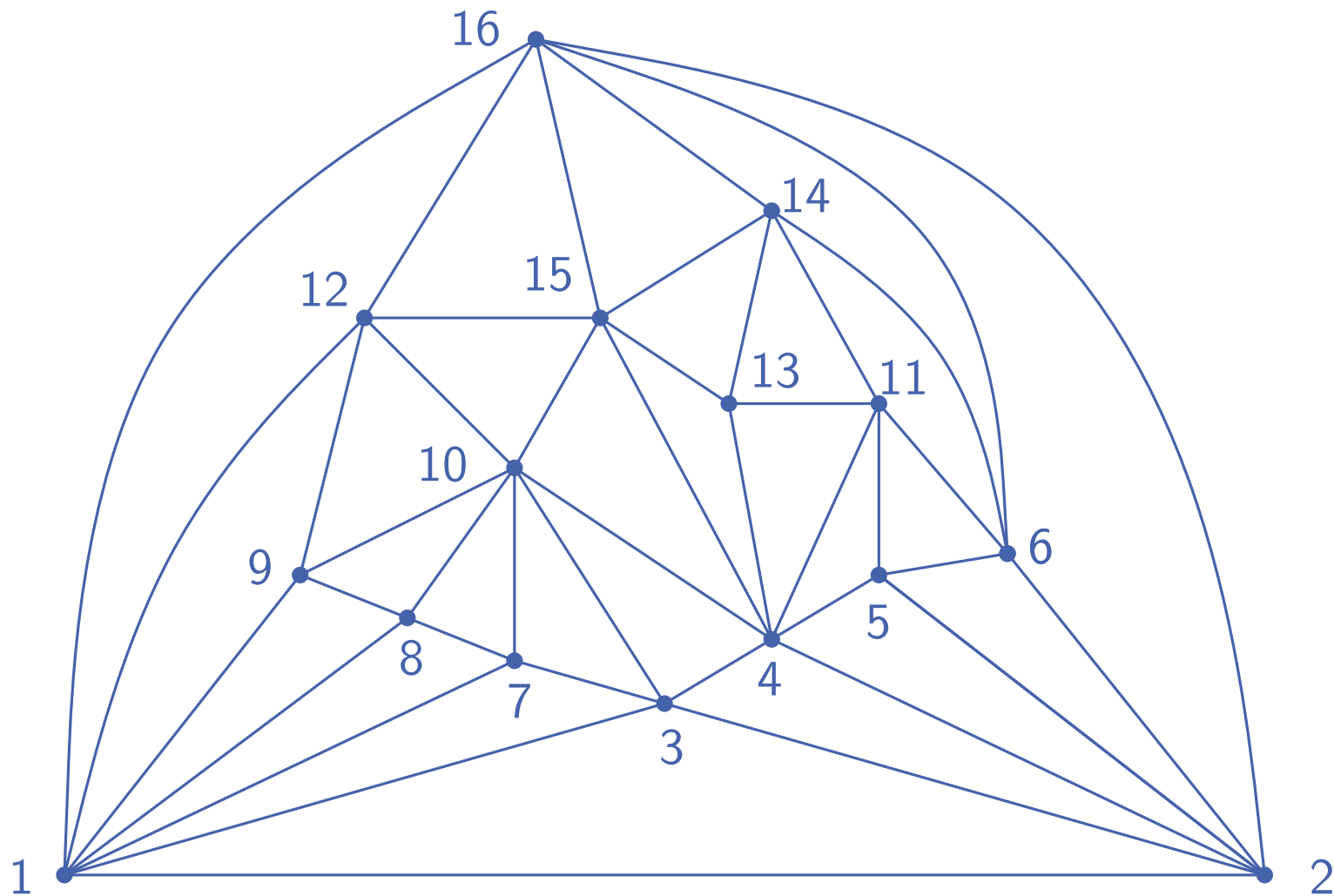
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Lemma

Every triangulated plane graph has a canonical ordering.

- Let $G_n = G$, and let v_1, v_2, v_n be the vertices of the outer face of G_n . Conditions C1-C3 hold.

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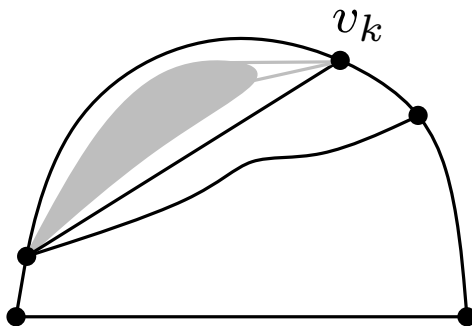
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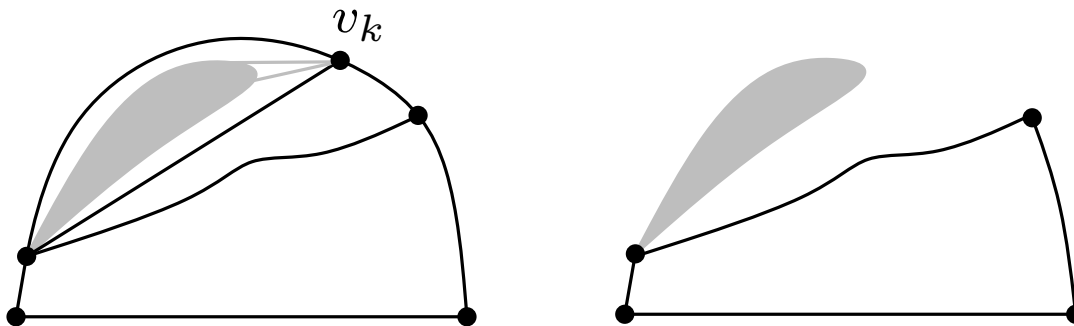
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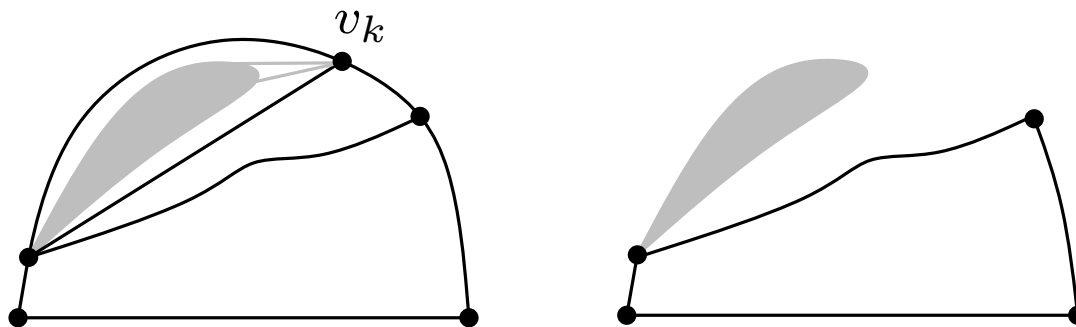
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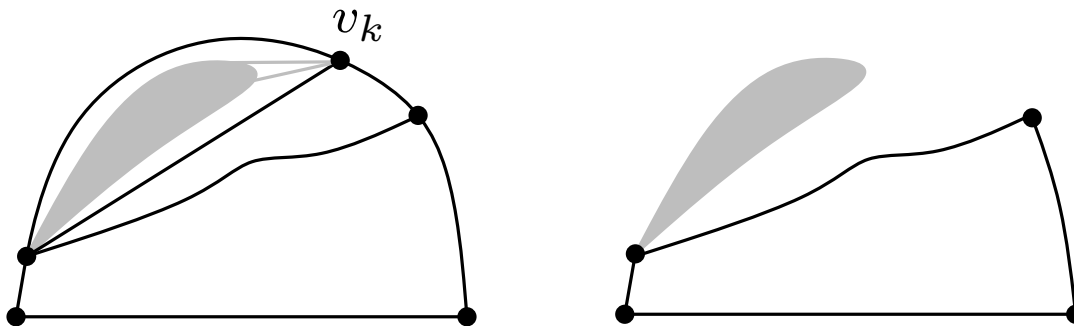
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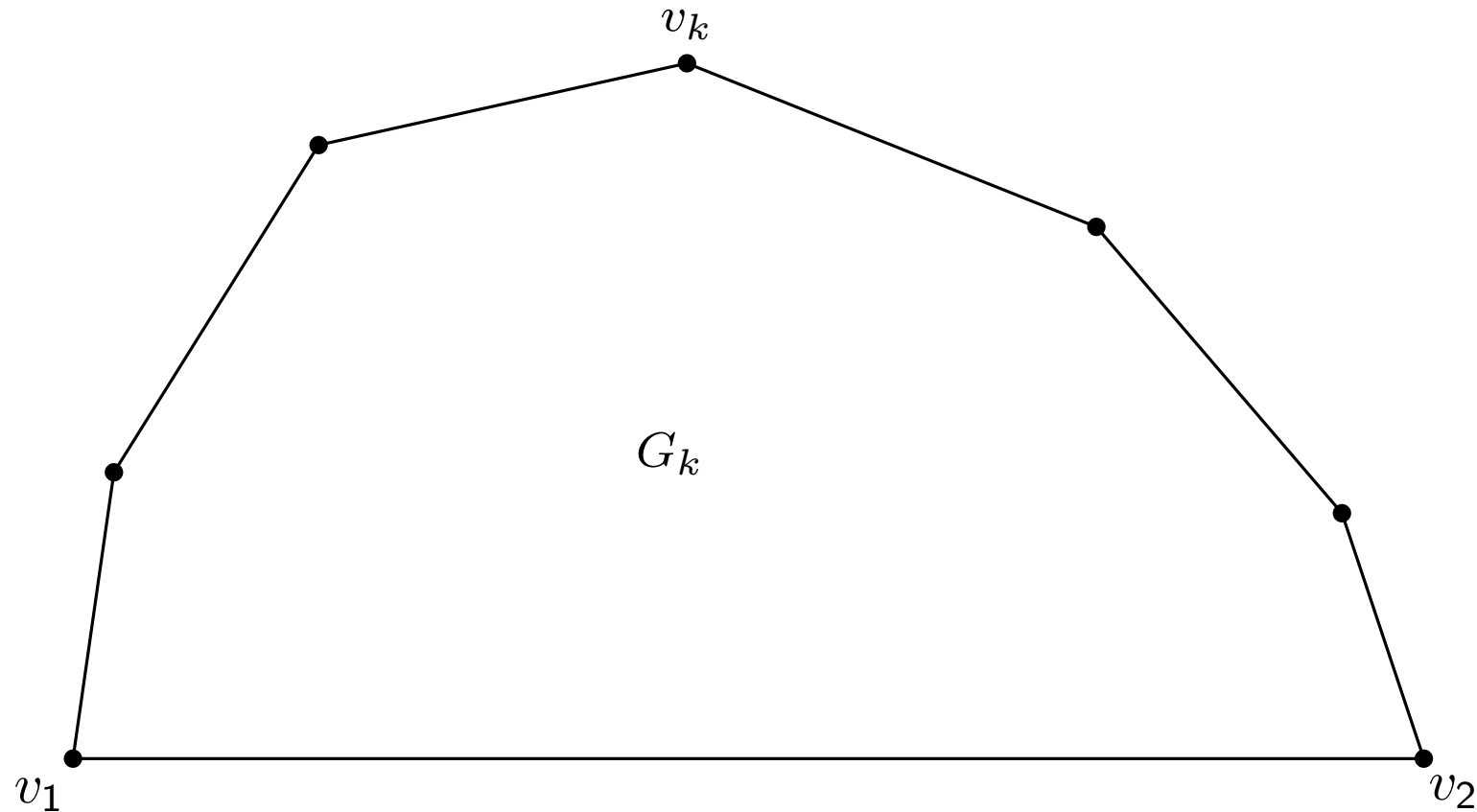


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Is it sufficient?

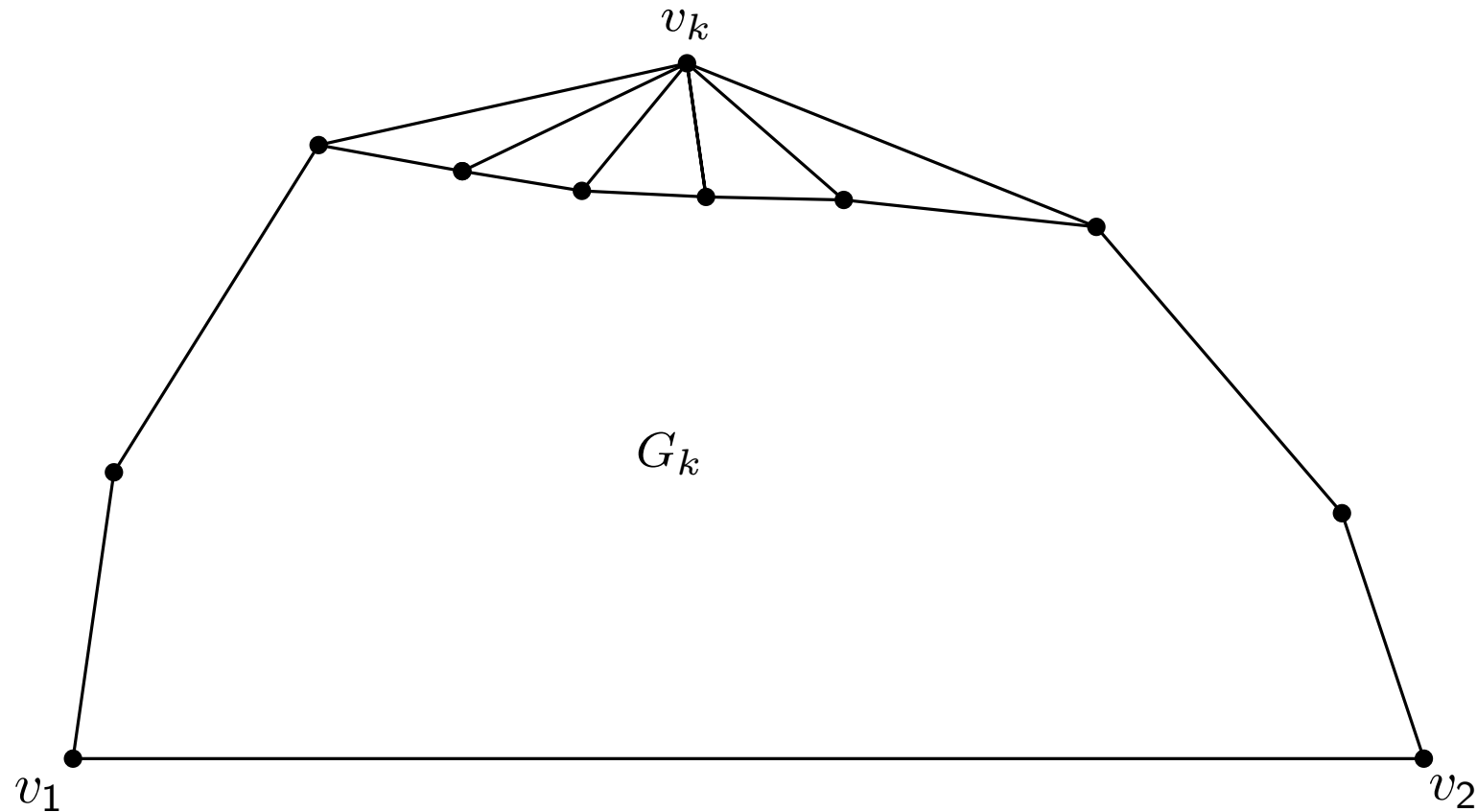
Canonical Ordering Existence

Statement If v_k is not adjacent to a chord then removal of v_k leaves the graph biconnected.



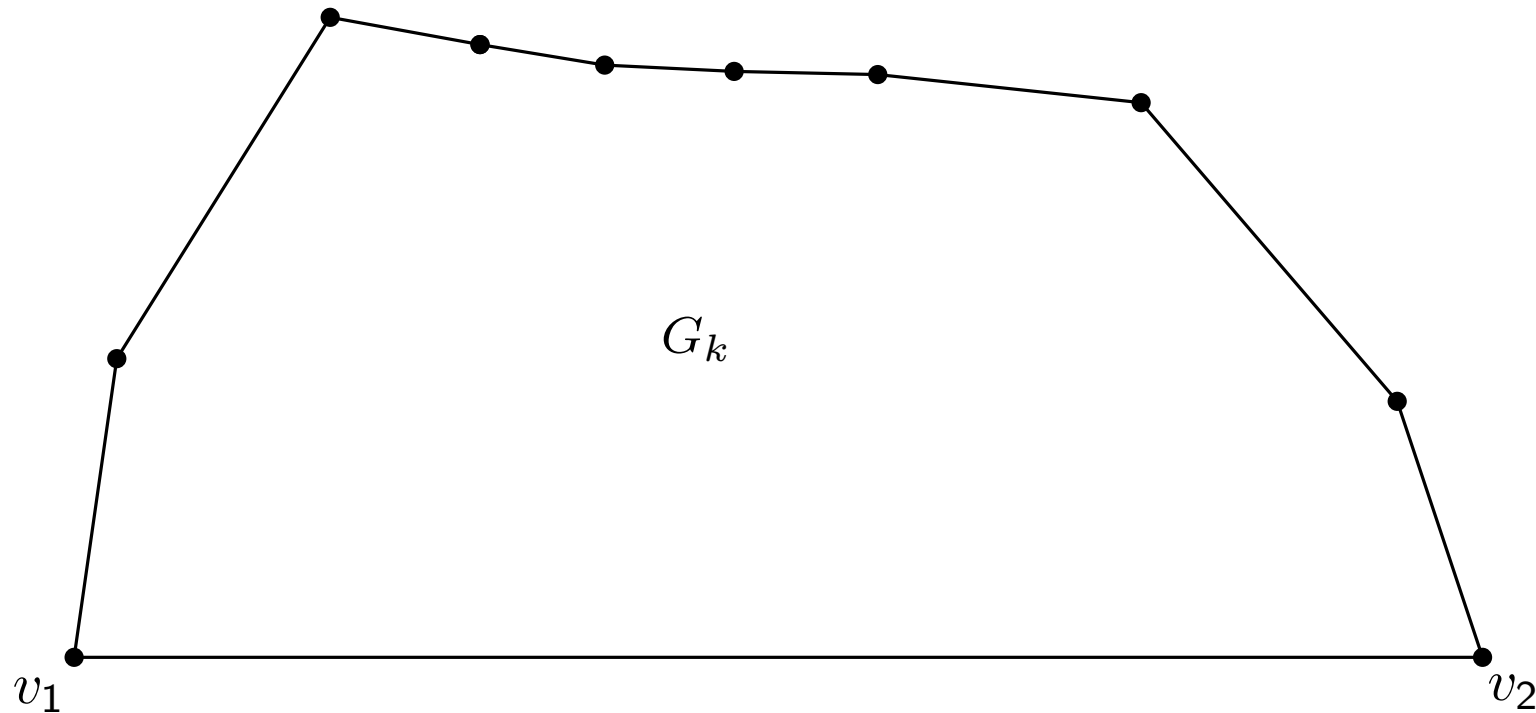
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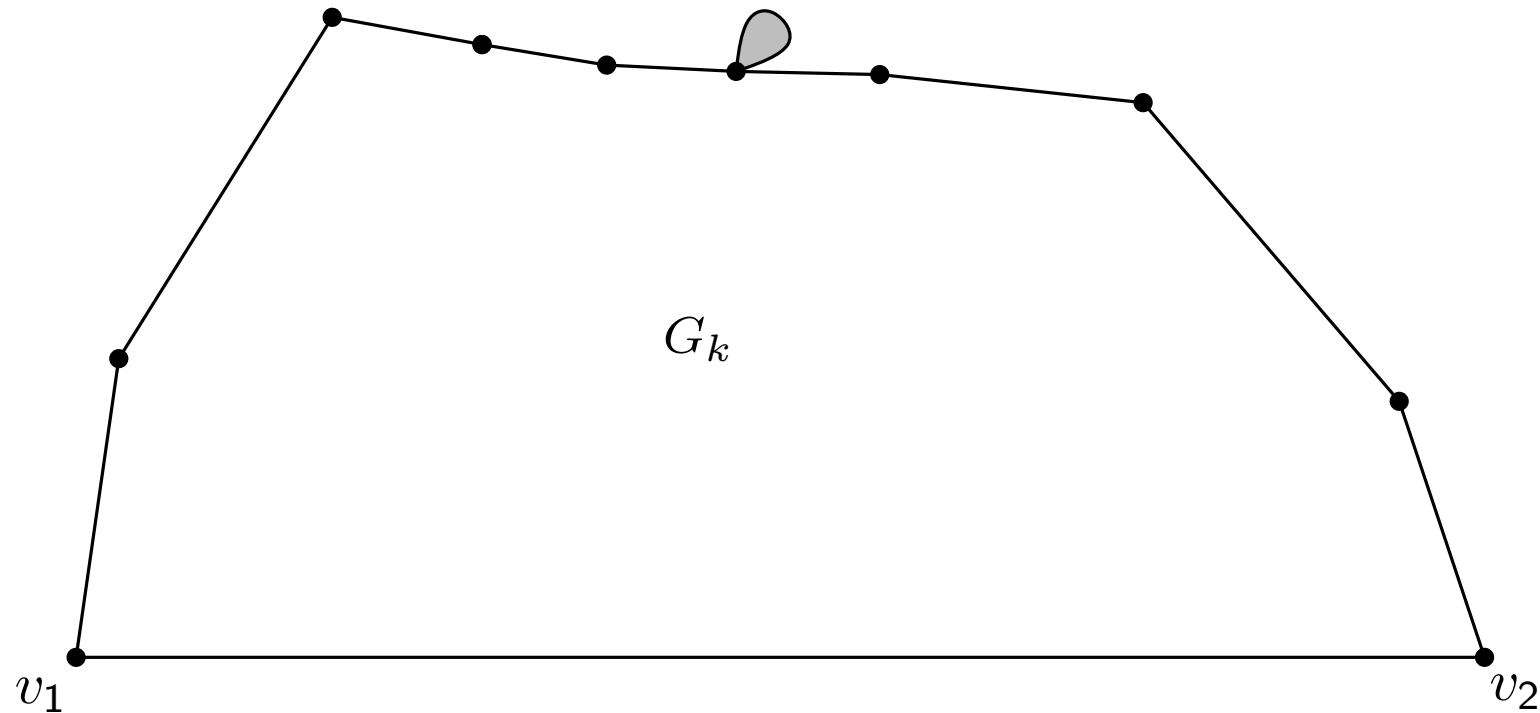
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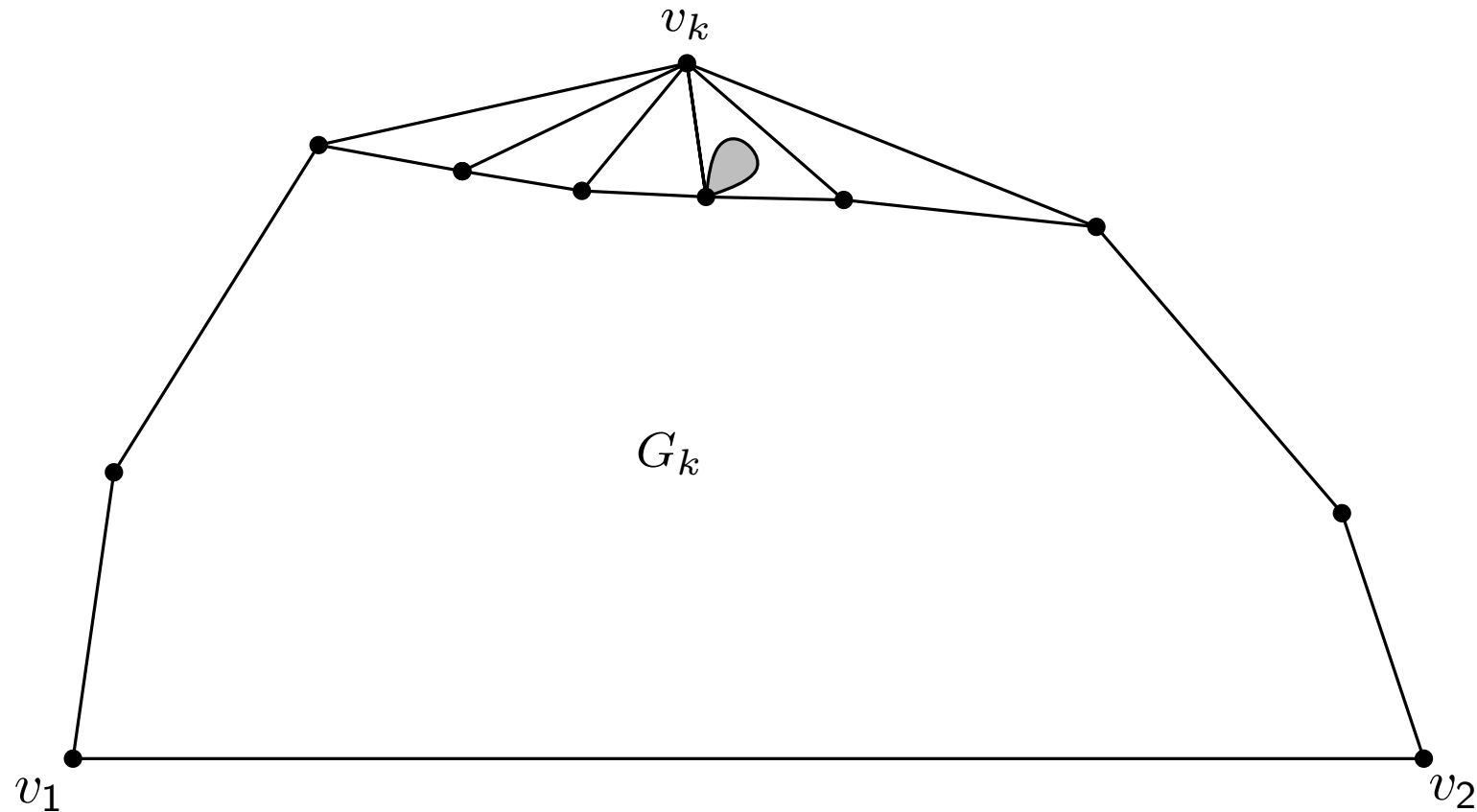
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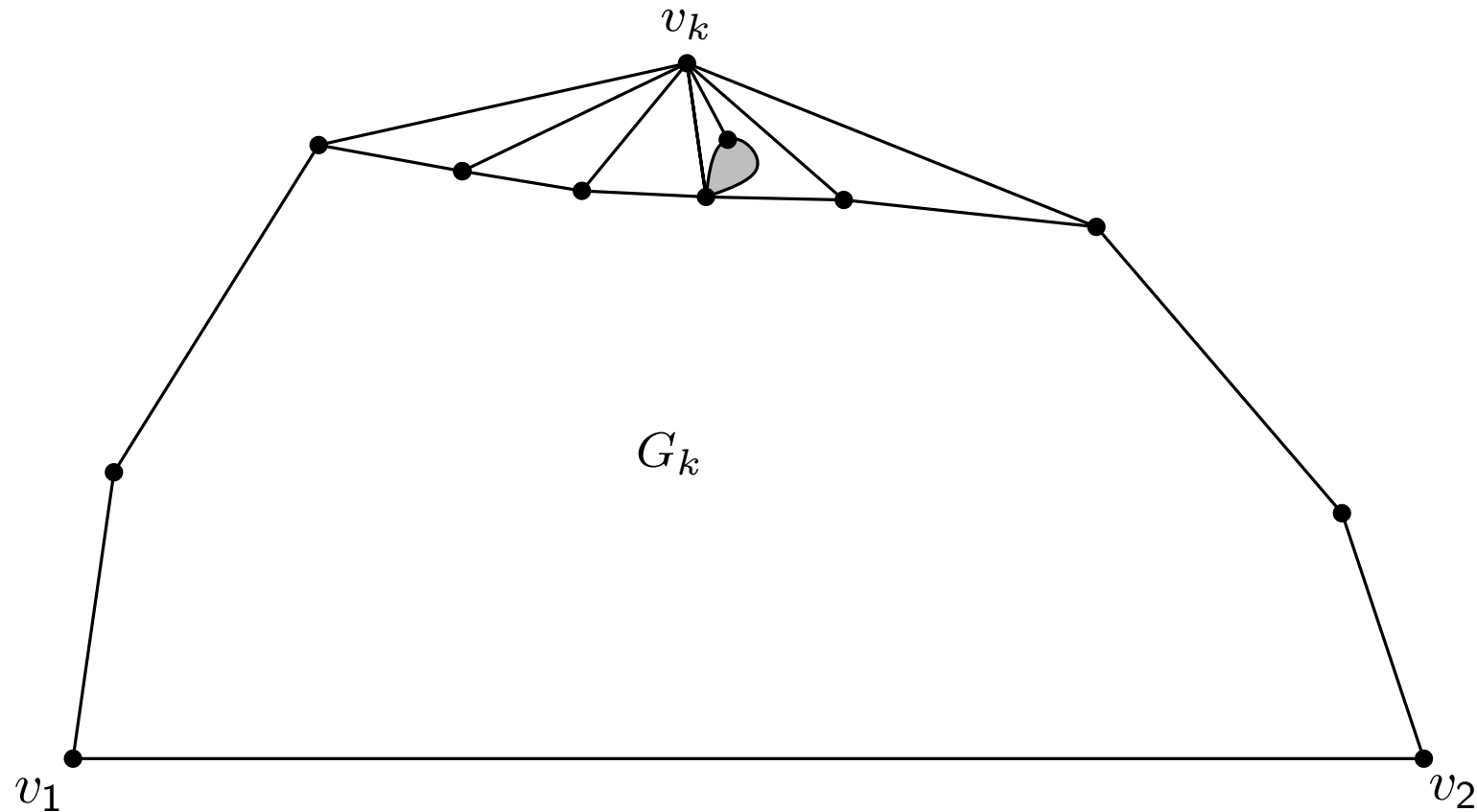
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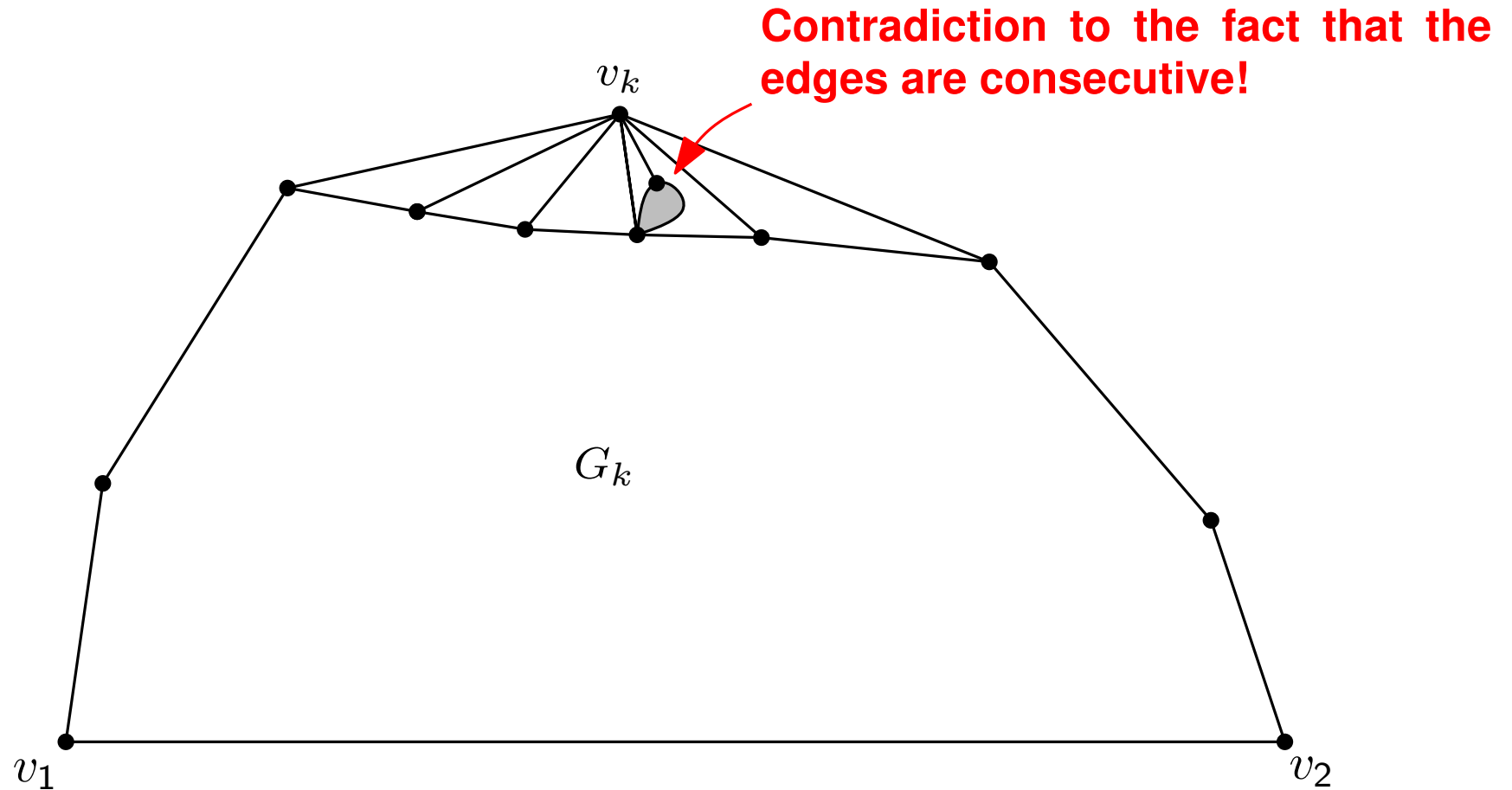
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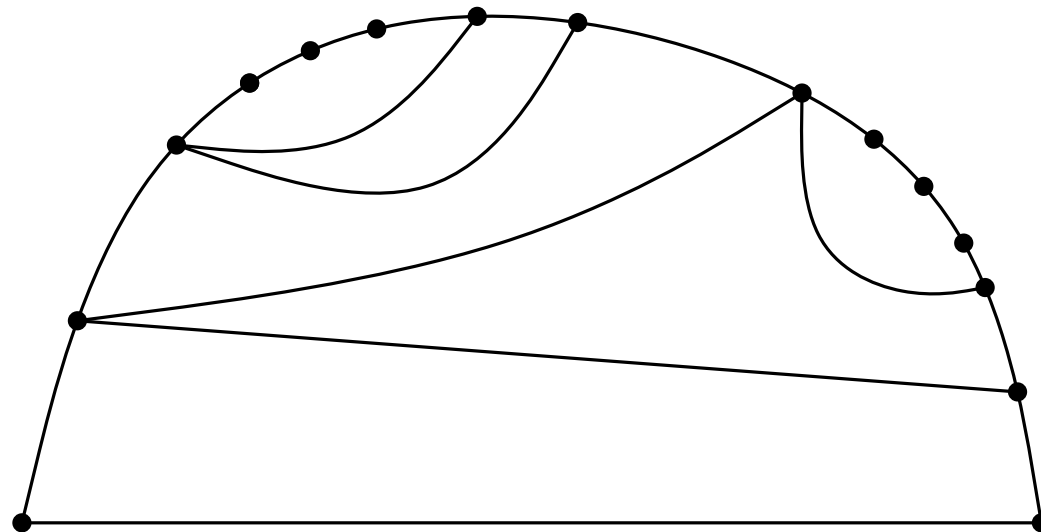
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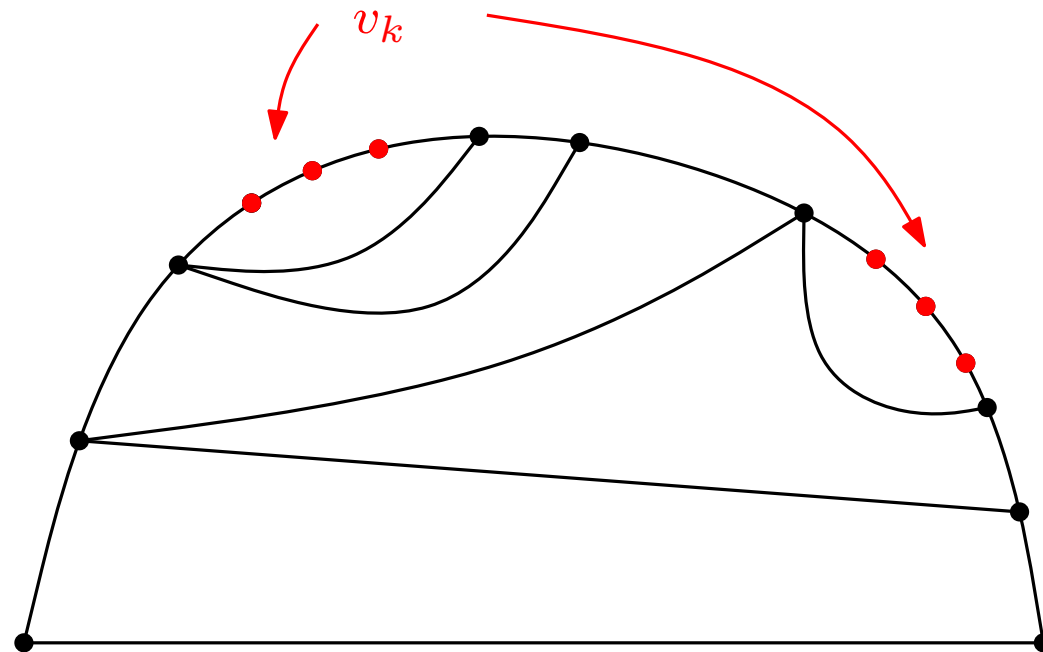
Canonical Ordering Existence

- Why a vertex not adjacent to a chord exists?



Canonical Ordering Existence

- Why a vertex not adjacent to a chord exists?



Algorithm CO

forall the $v \in V$ **do**

┌ chords(v) \leftarrow 0; out(v) \leftarrow false; mark(v) \leftarrow false;

out(v_1), out(v_2), out(v_n) \leftarrow true;

for $k = n$ **to** 3 **do**

┌ choose $v \neq v_1, v_2$ such that mark(v) = false, out(v) = true,
 chords(v) = 0;

$v_k \leftarrow v$; mark(v) \leftarrow true;

*// Let $w_1 = v_1, w_2, \dots, w_{t-1}, w_t = v_2$ denote the boundary of G_{k-1} ;
and let w_p, \dots, w_q be the unmarked neighbors v_k ;*

out(w_i) \leftarrow true for all $p < i < q$;

┌ update number of chords for w_i and its neighbors;

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   $\lfloor$  chords( $v$ )  $\leftarrow$  0; out( $v$ )  $\leftarrow$  false; mark( $v$ )  $\leftarrow$  false;  
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  update number of chords for  $w_i$  and its neighbors;
```

- chord(v) - number of chords adjacent to v
- mark(v) = true iff vertex v was numbered
- out(v)=true iff v is the outer vertex of current plane graph

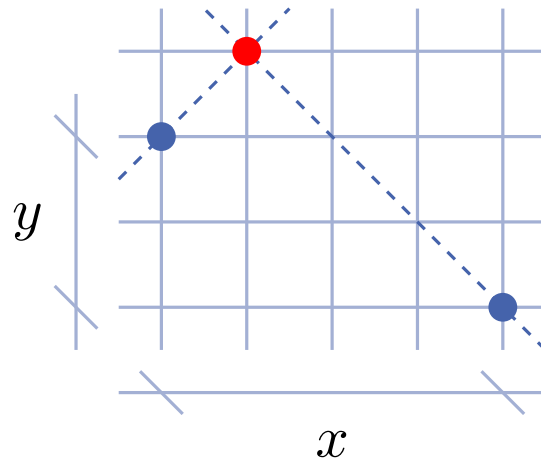
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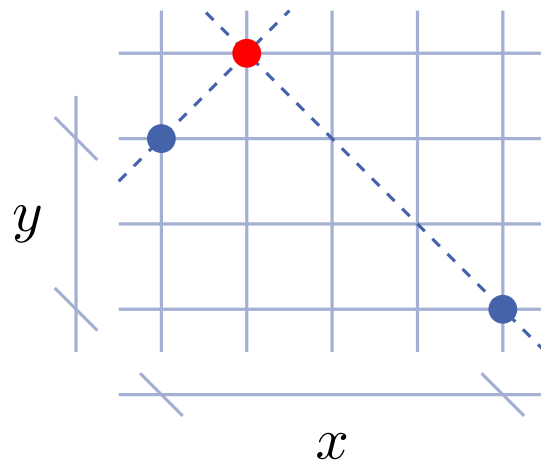
Lemma

Algorithm CO computes a canonical ordering of a graph in $O(n)$ time.

De Fraysseix Pach Pollack (Shift) Algorithm

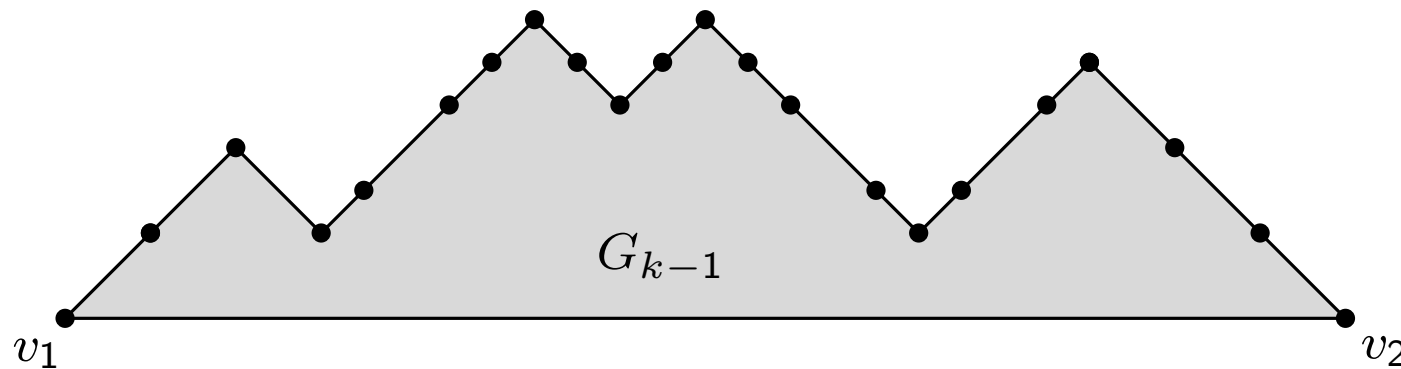


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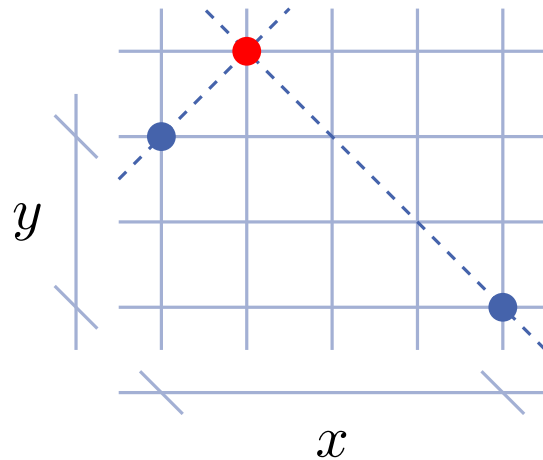


Algorithm constraints: G_{k-1} is drawn such that

- v_1 is on $(0, 0)$, v_2 is on $(2k - 6, 0)$
- Boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone
- Each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1

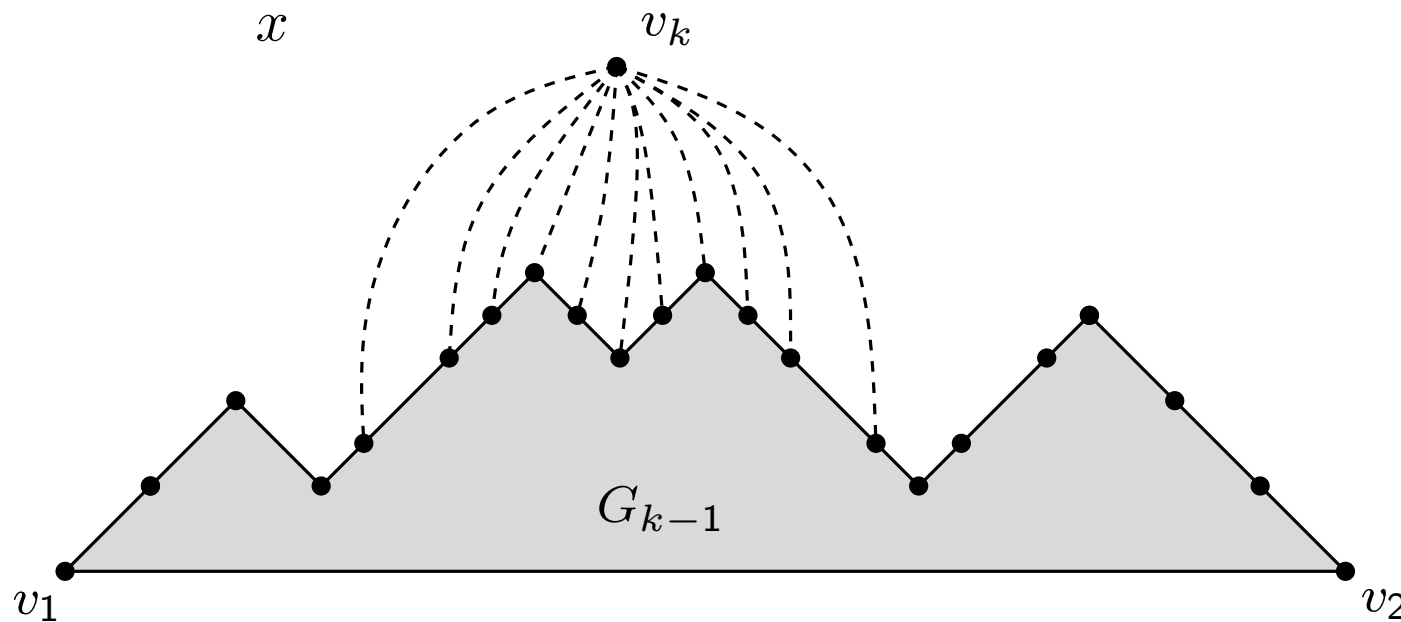


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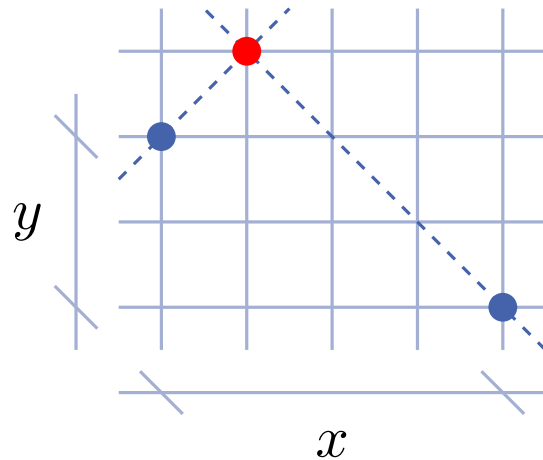


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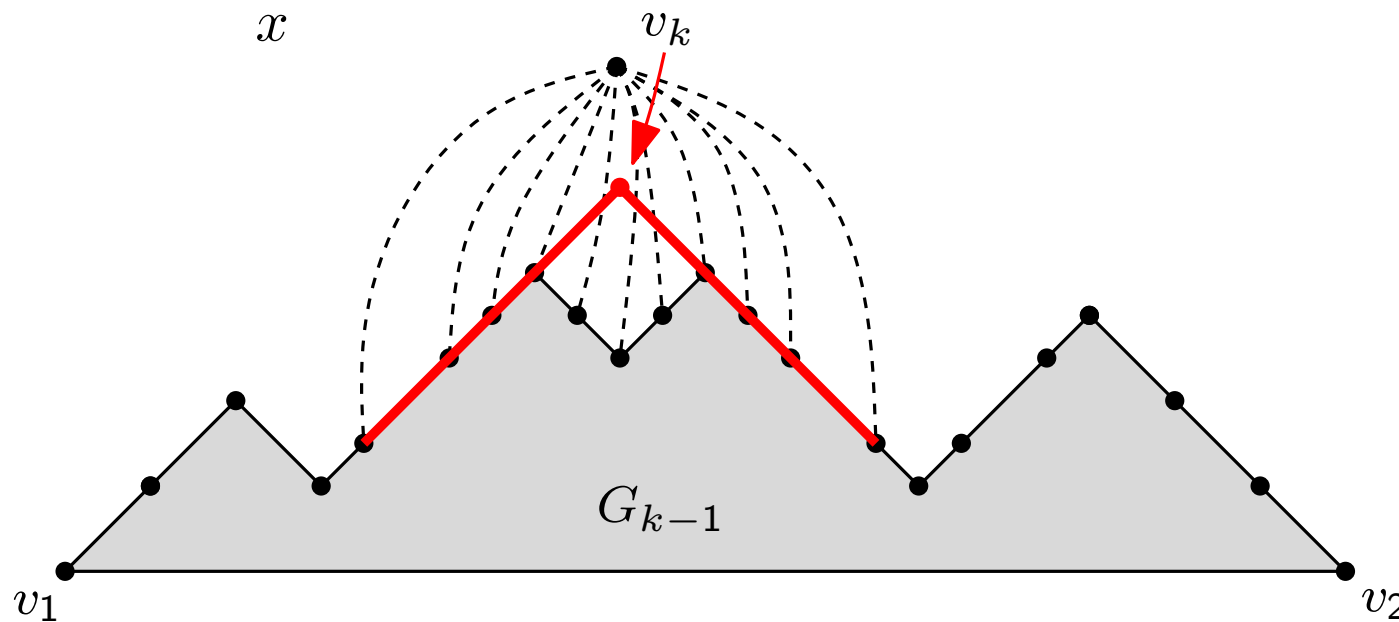


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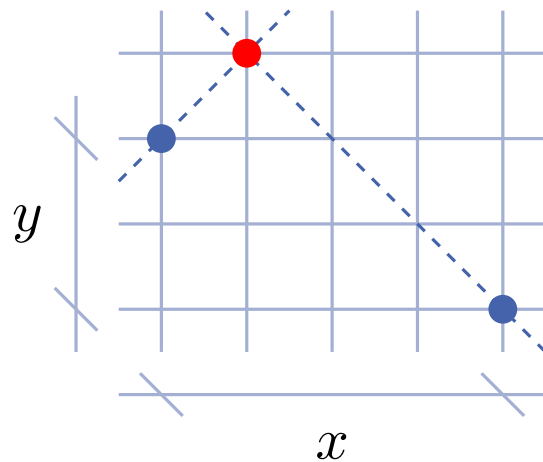


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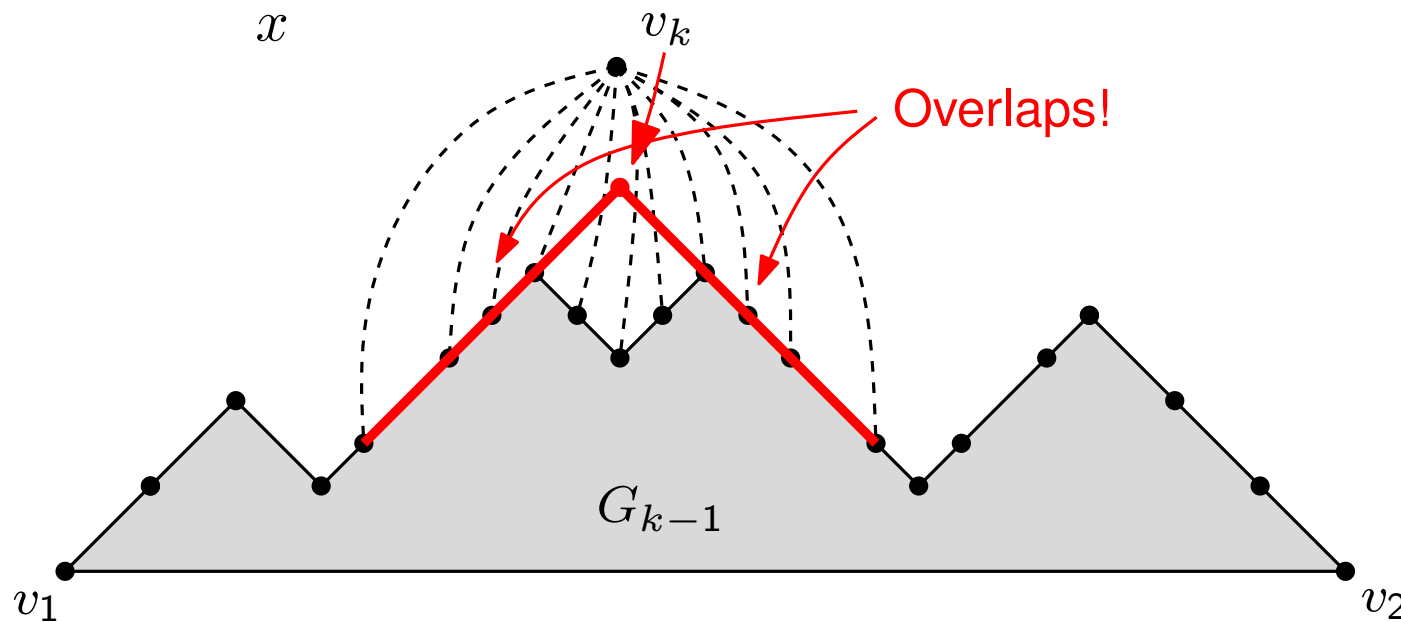


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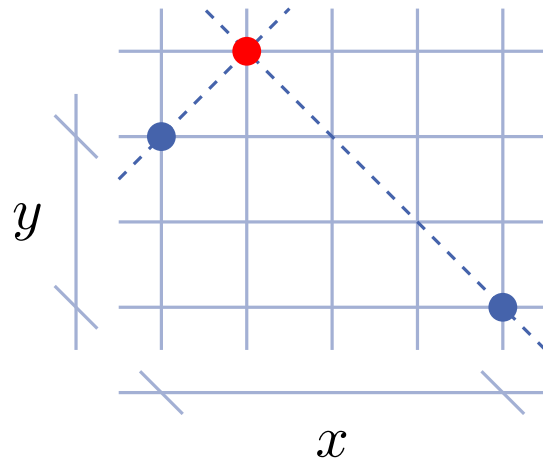


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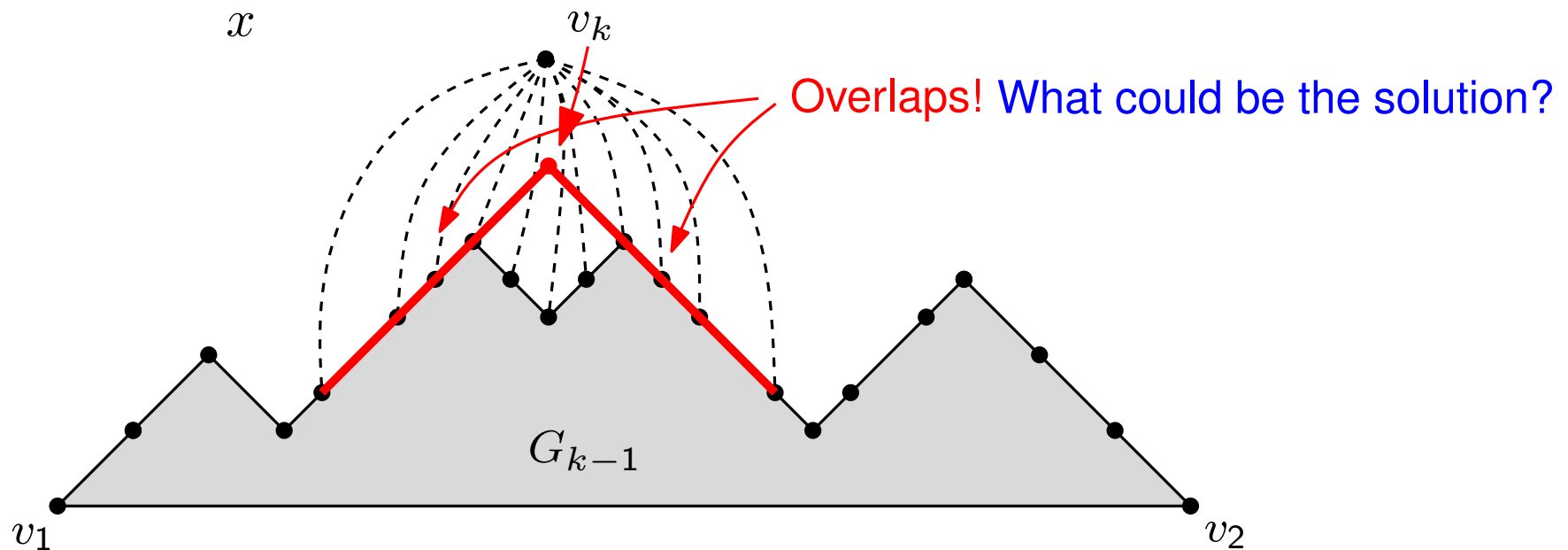


De Fraysseix Pach Pollack (Shift) Algorithm

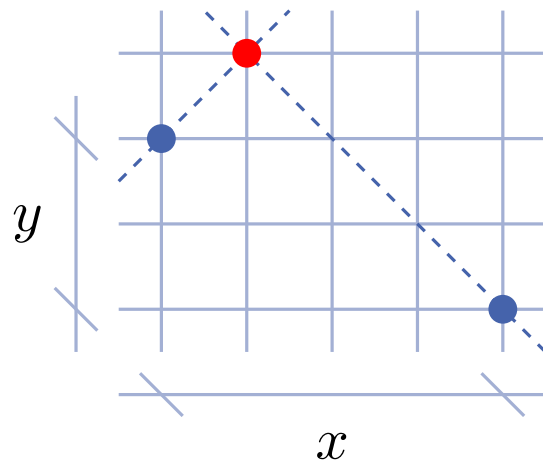


Algorithm constraints: G_{k-1} is drawn such that

- v_1 is on $(0, 0)$, v_2 is on $(2k - 6, 0)$
- Boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone
- Each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1

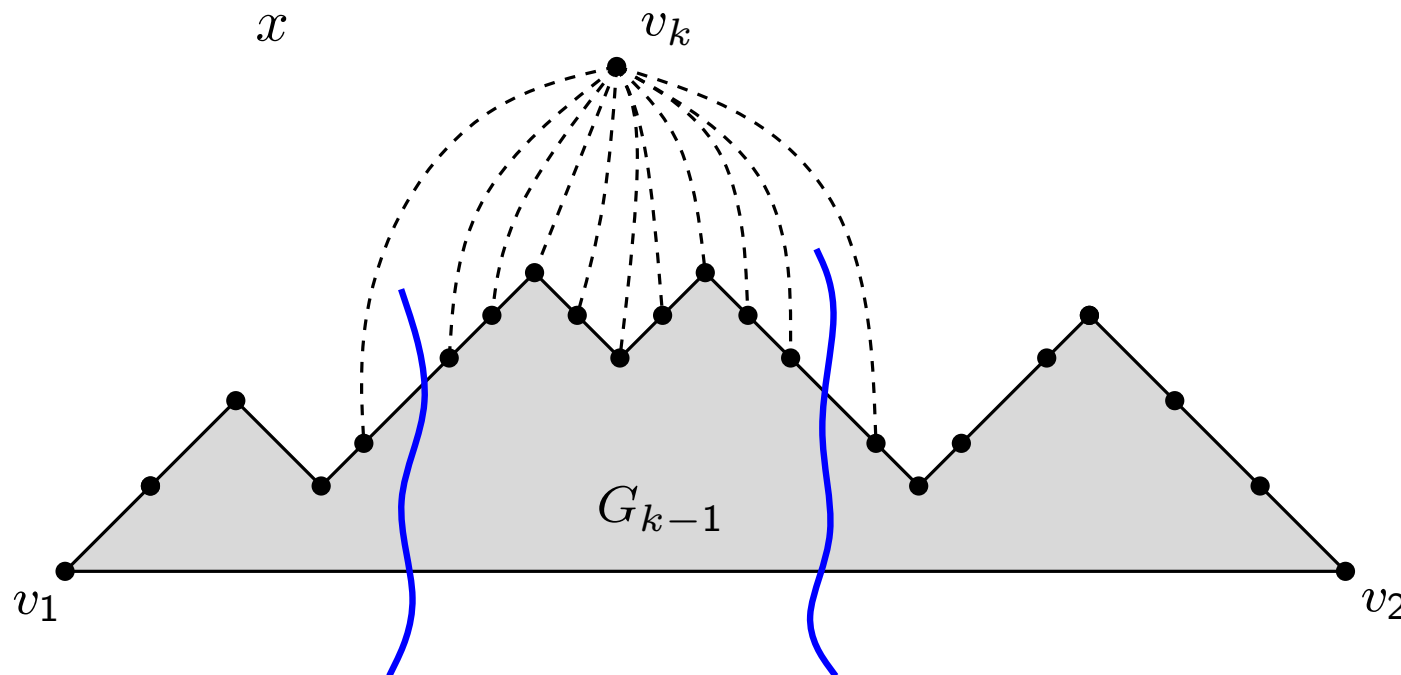


De Fraysseix Pach Pollack (Shift) Algorithm

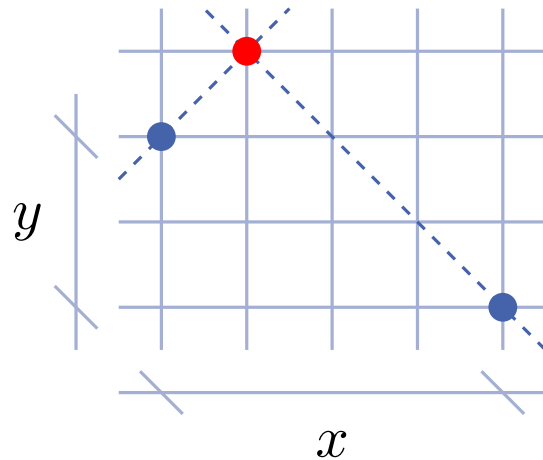


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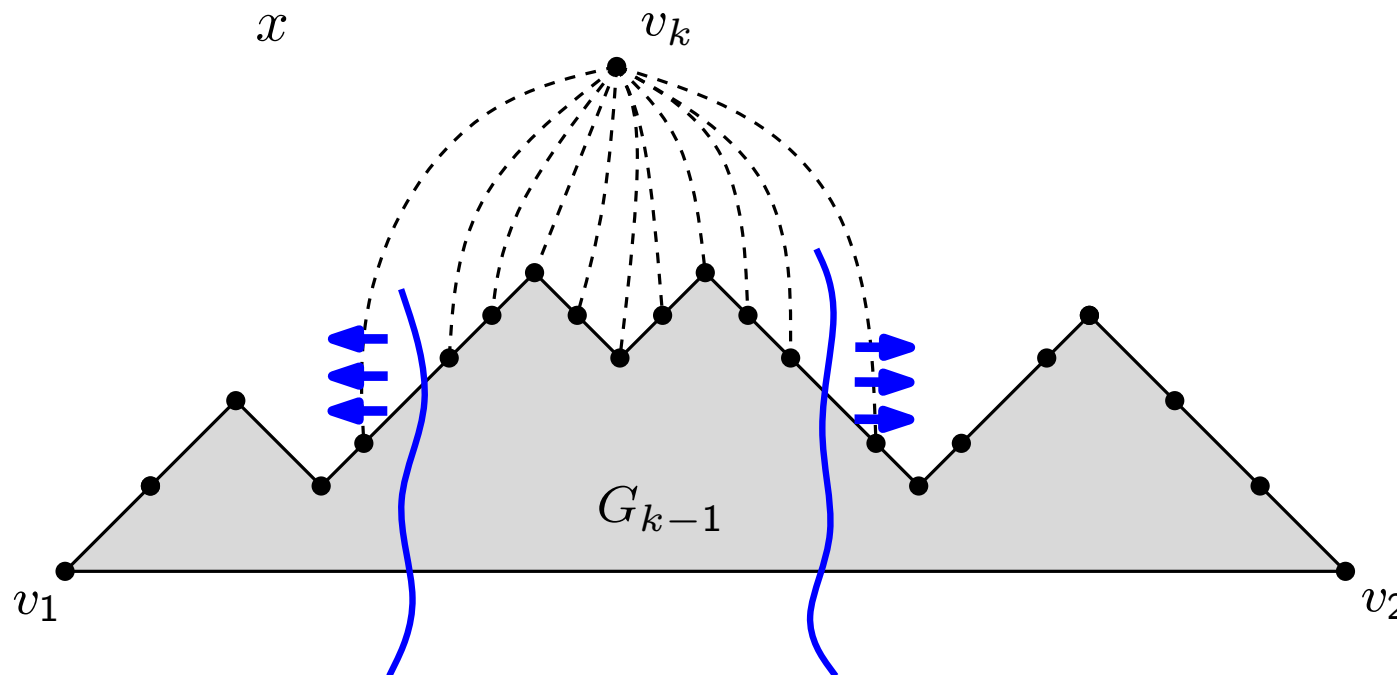


De Fraysseix Pach Pollack (Shift) Algorithm

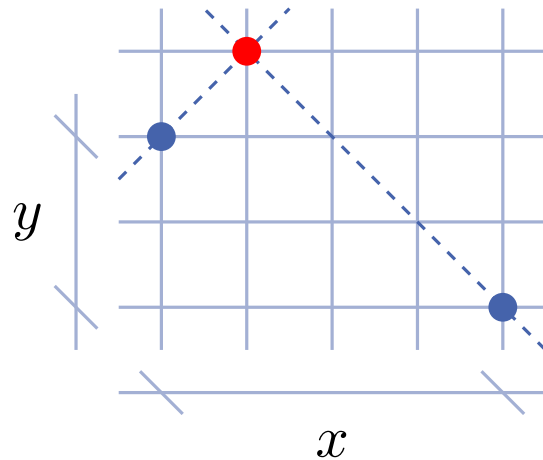


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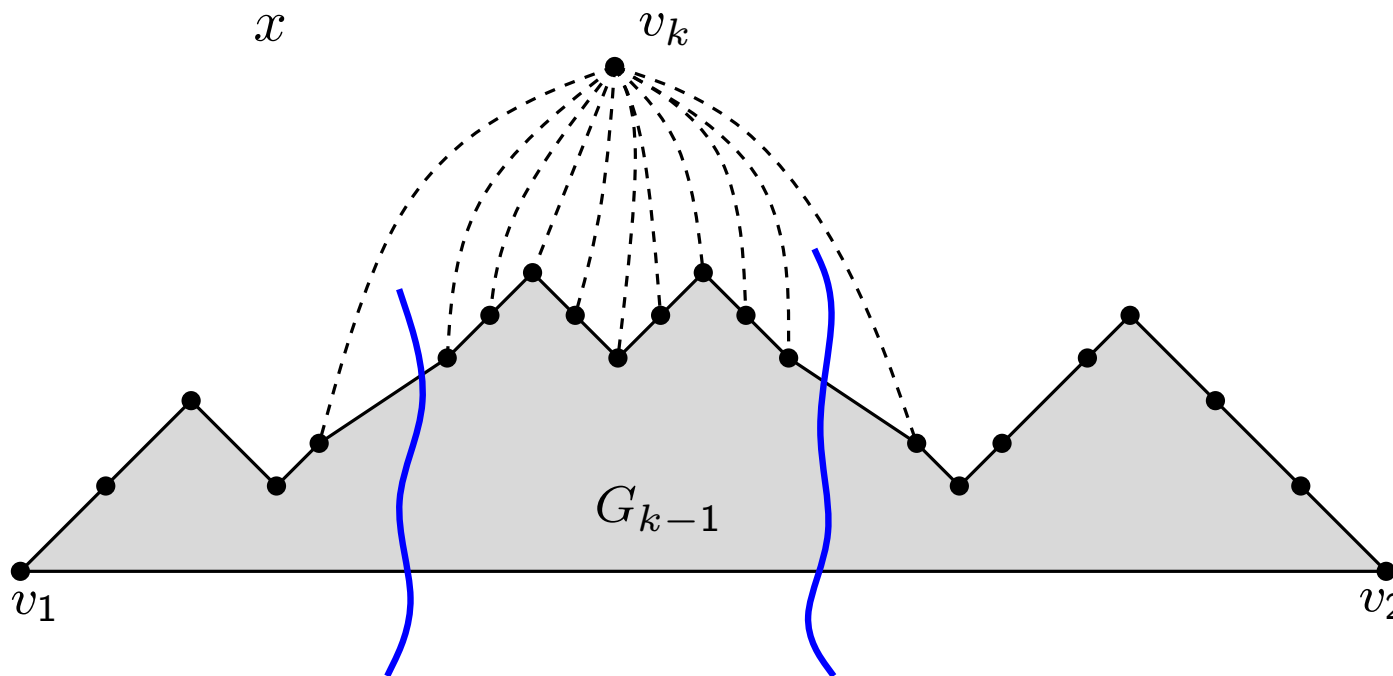


De Fraysseix Pach Pollack (Shift) Algorithm

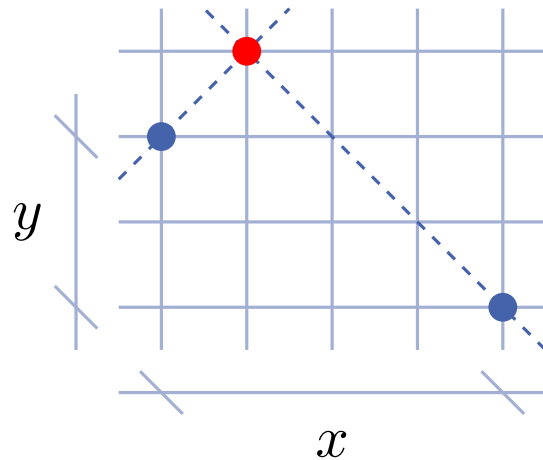


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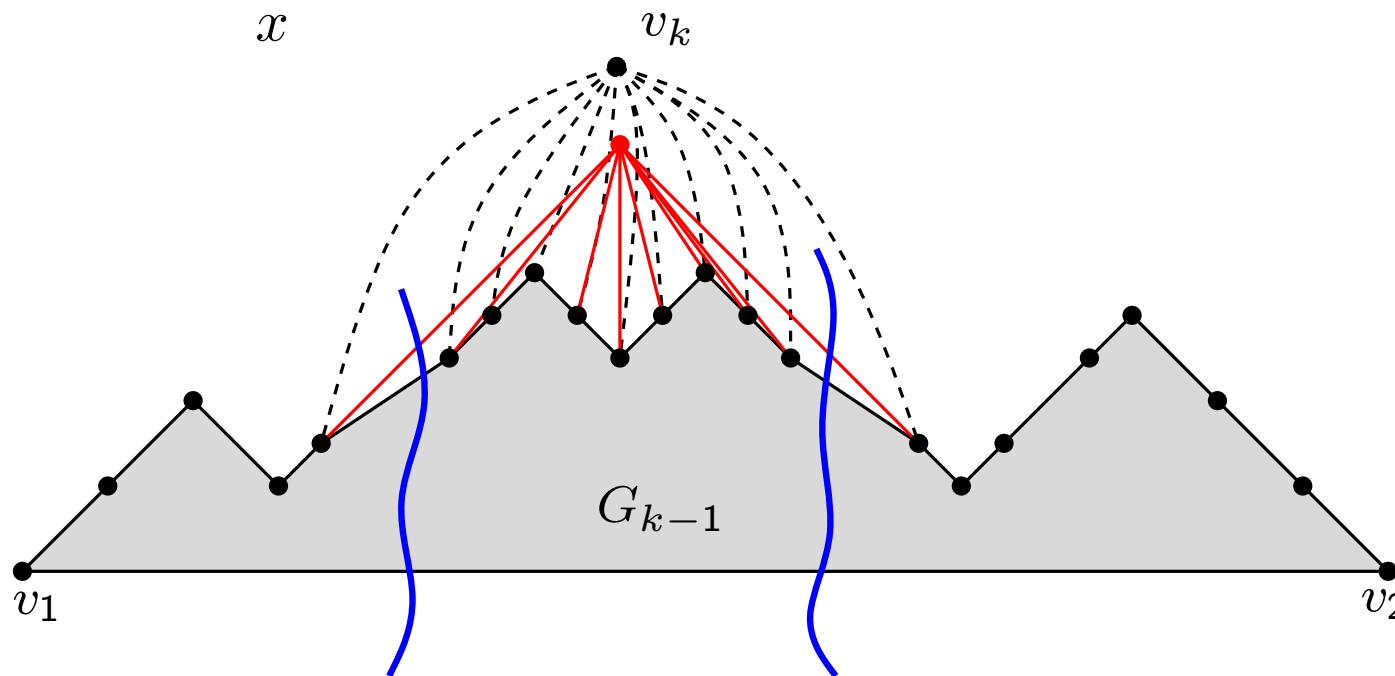


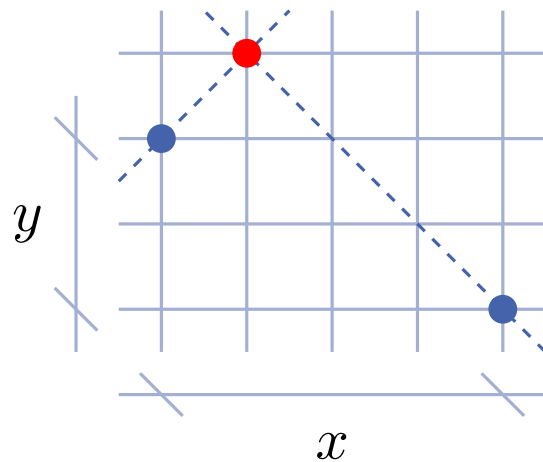
De Fraysseix Pach Pollack (Shift) Algorithm



Algorithm constraints: G_{k-1} is drawn such that

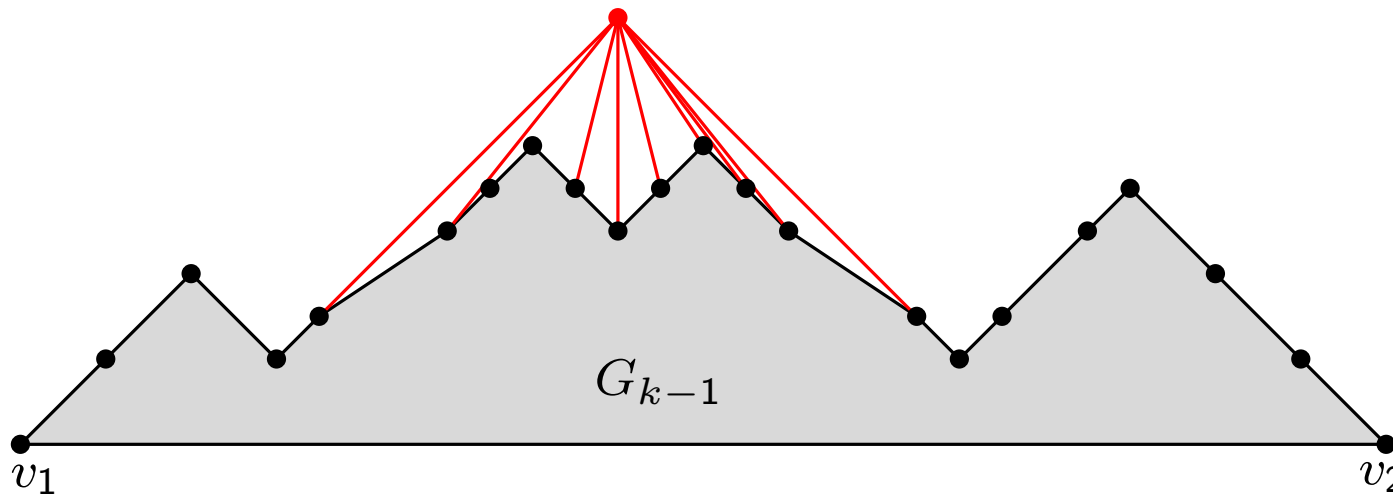
- v_1 is on $(0, 0)$, v_2 is on $(2k - 6, 0)$
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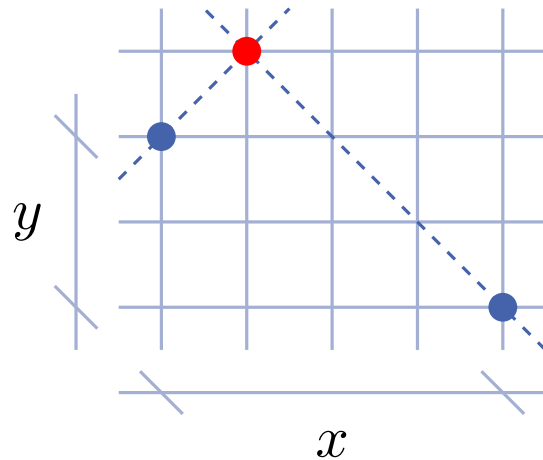


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- Each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1

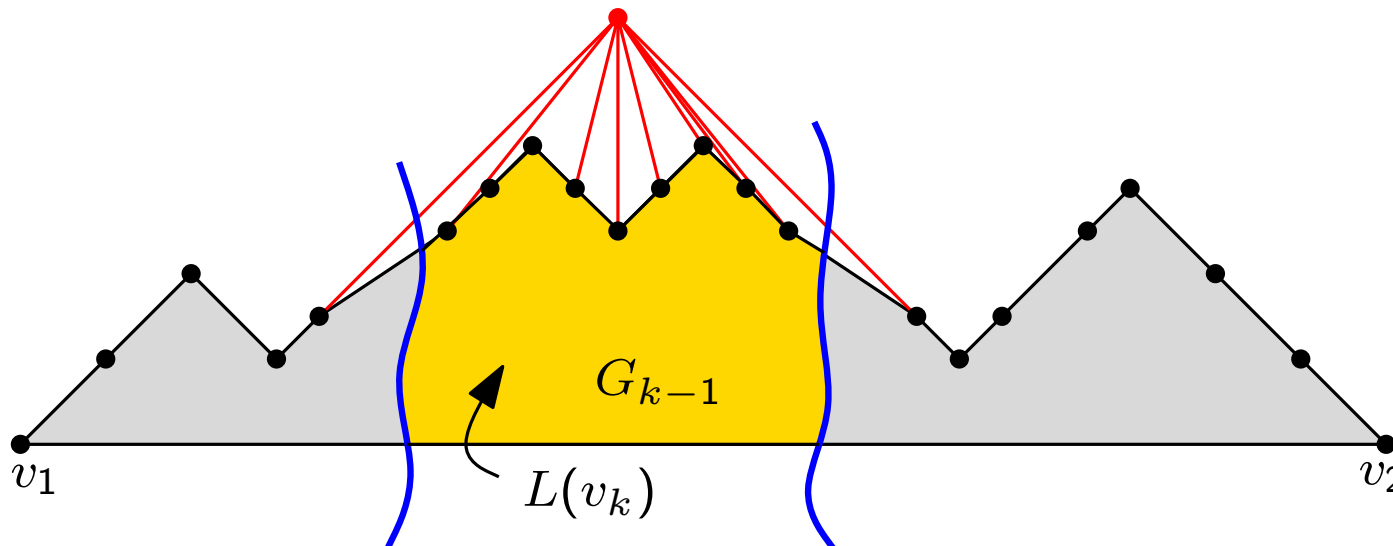


De Fraysseix Pach Pollack (Shift) Algorithm

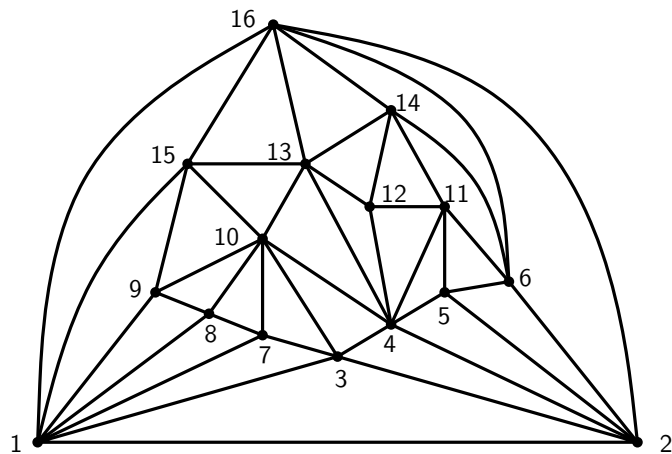
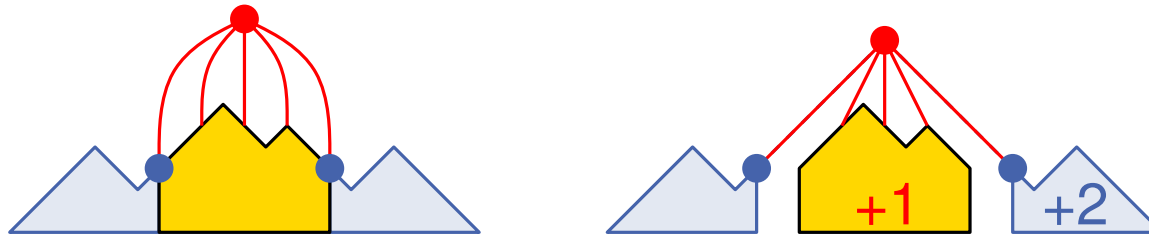


Algorithm constraints: G_{k-1} is drawn such that

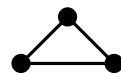
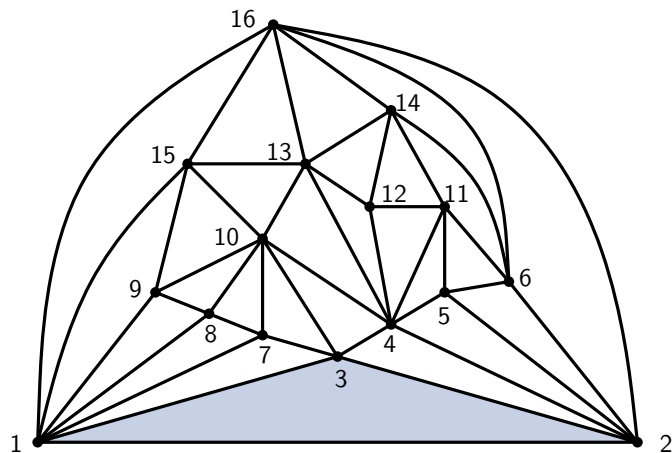
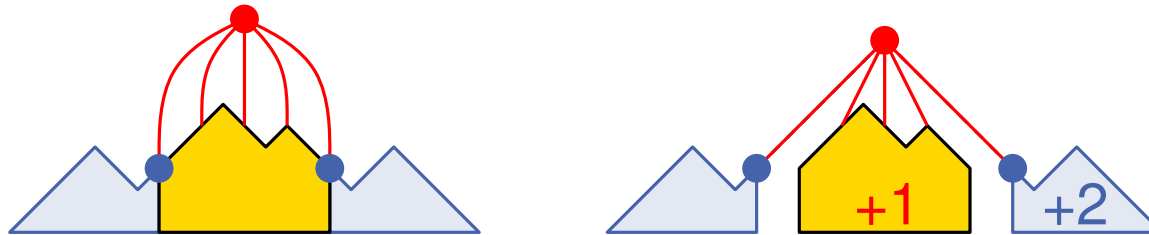
- v_1 is on $(0, 0)$, v_2 is on $(2k - 6, 0)$
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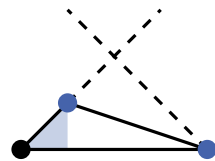
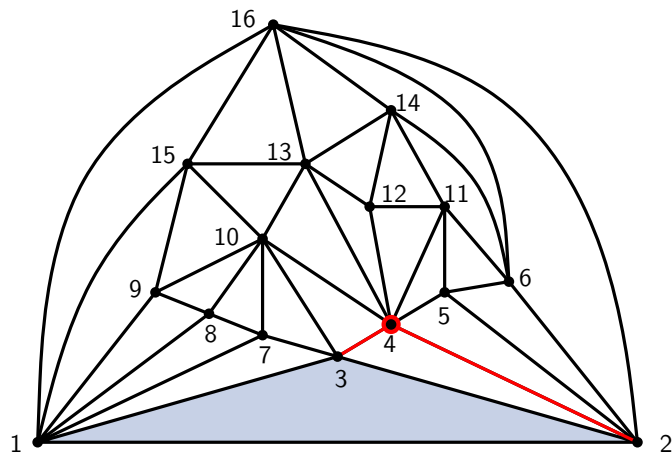
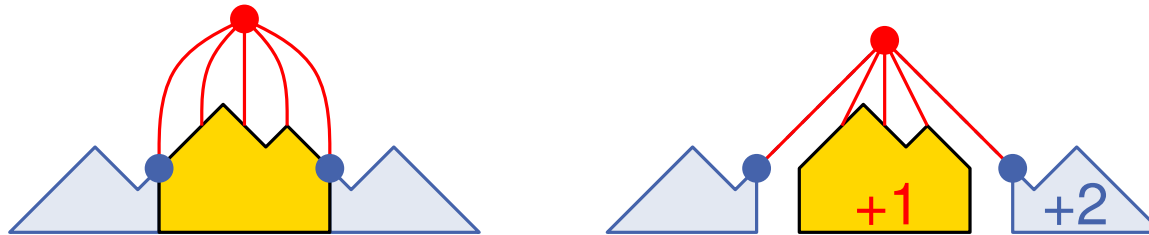
De Fraysseix Pach Pollack (Shift) Algorithm



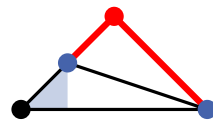
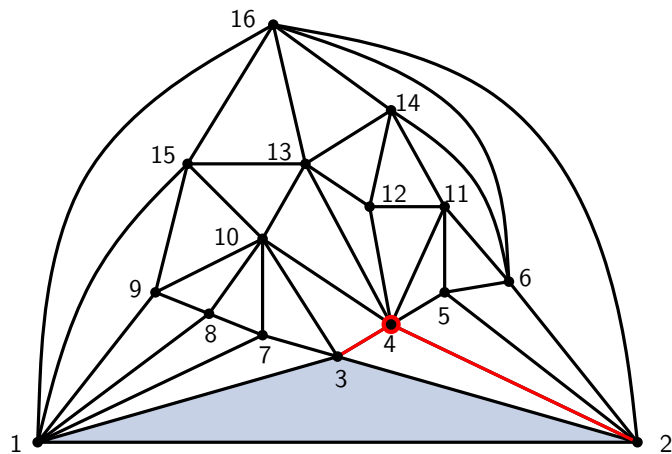
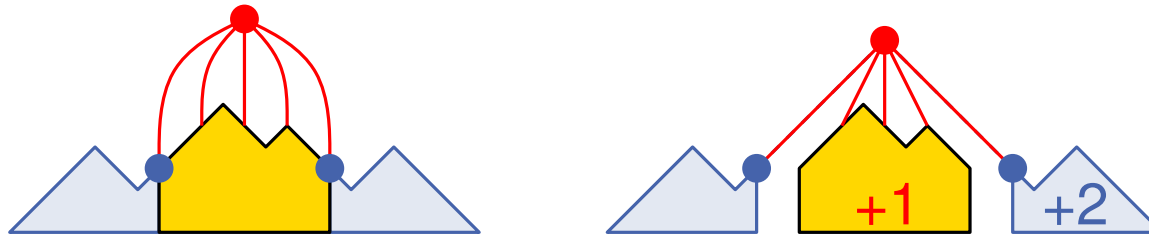
De Fraysseix Pach Pollack (Shift) Algorithm



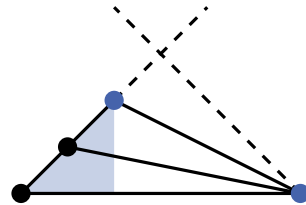
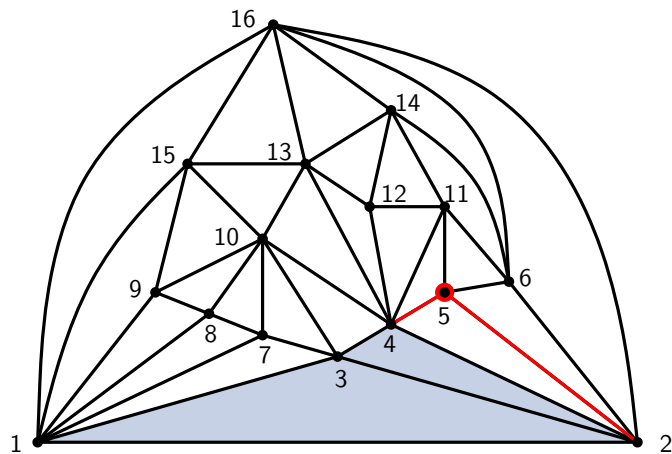
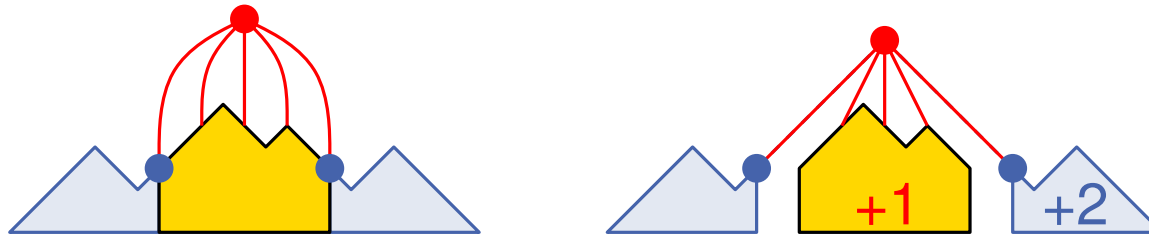
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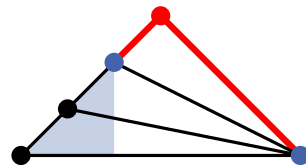
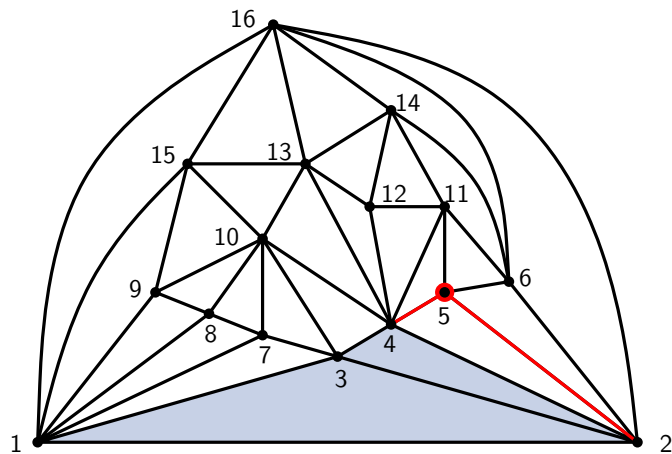
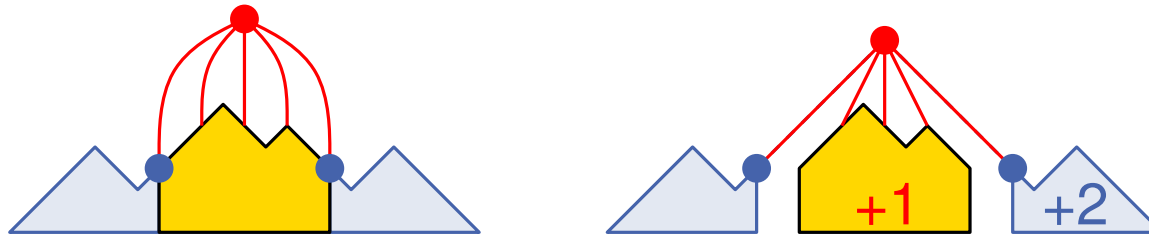
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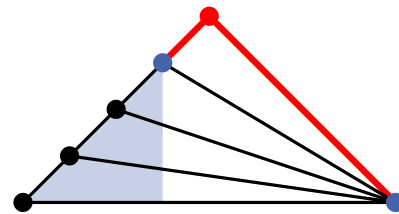
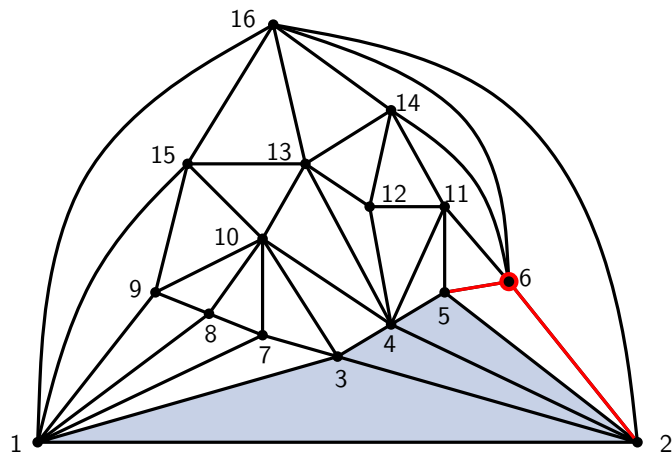
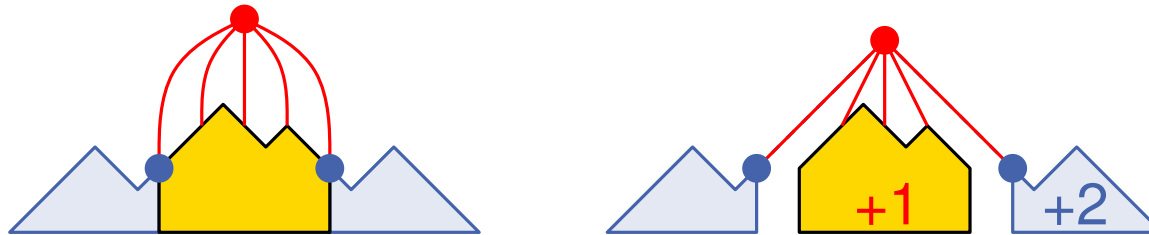
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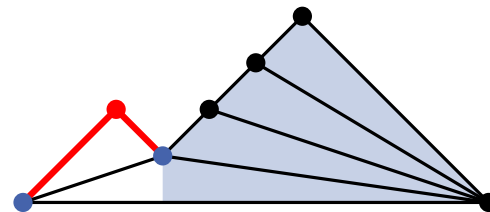
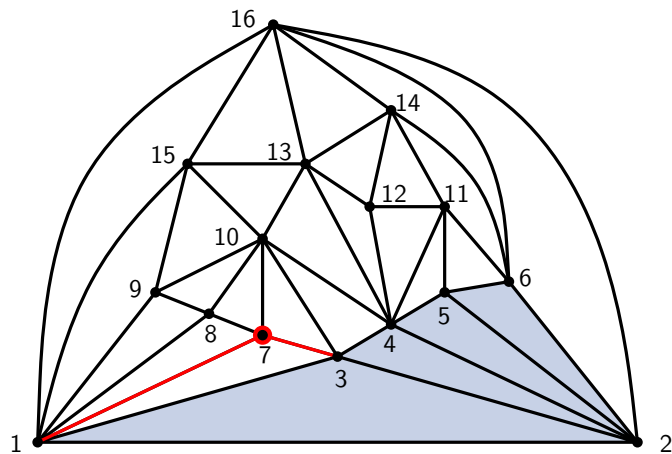
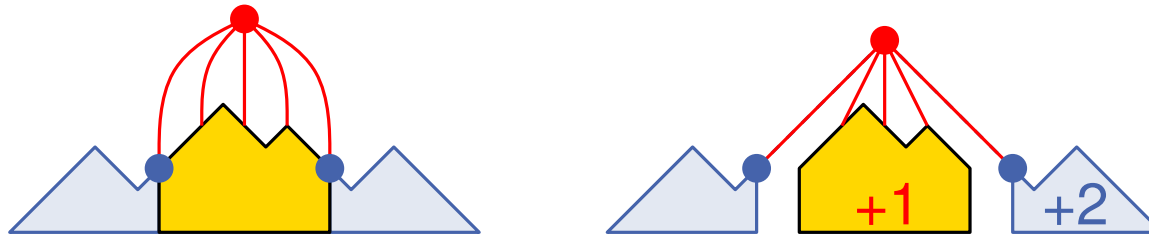
De Fraysseix Pach Pollack (Shift) Algorithm



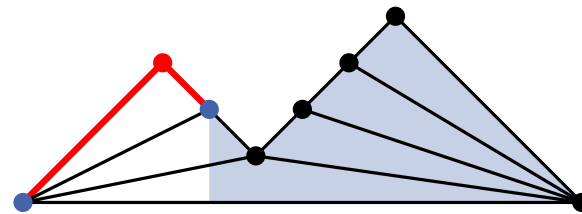
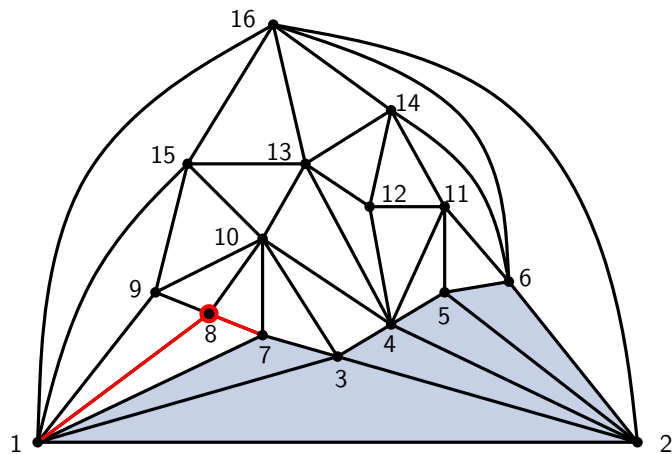
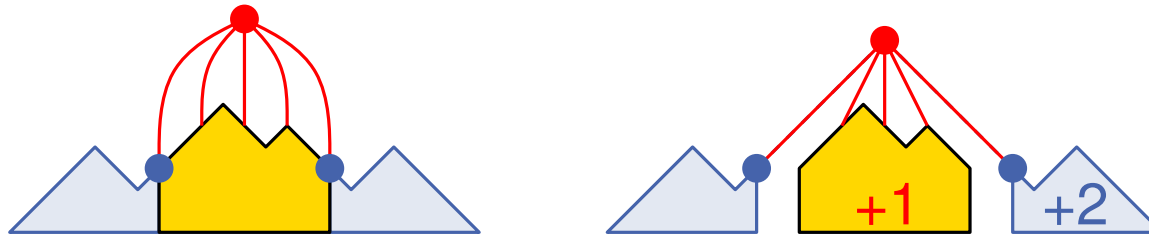
De Fraysseix Pach Pollack (Shift) Algorithm



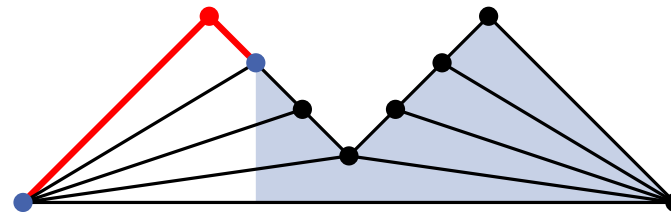
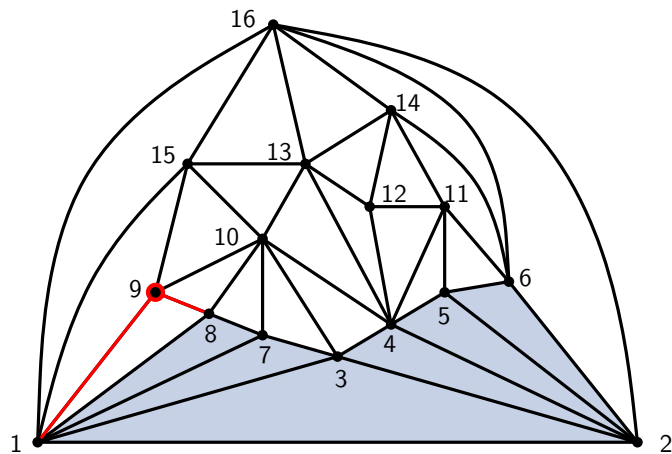
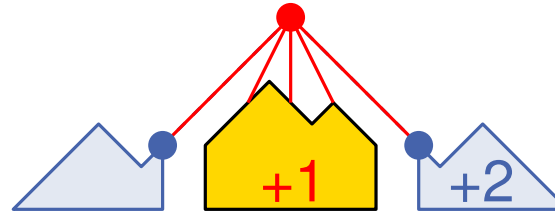
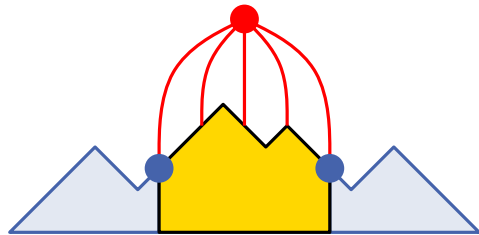
De Fraysseix Pach Pollack (Shift) Algorithm



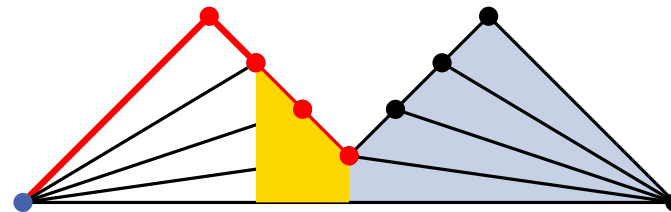
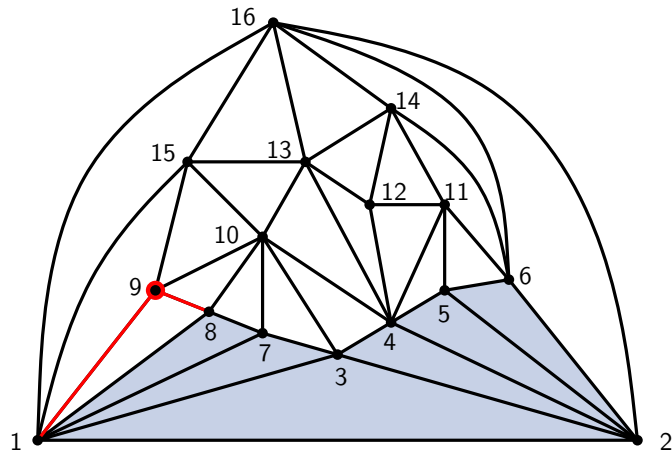
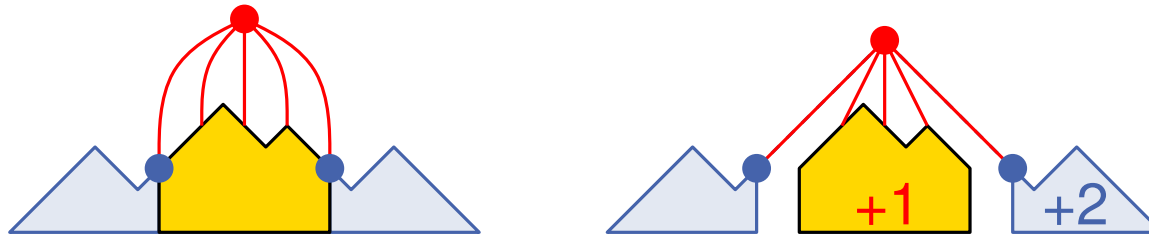
De Fraysseix Pach Pollack (Shift) Algorithm



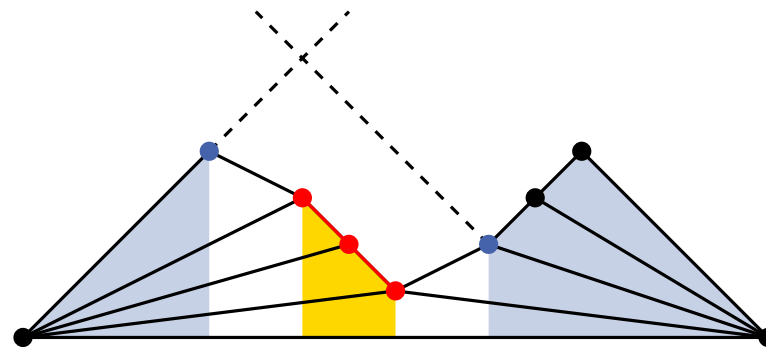
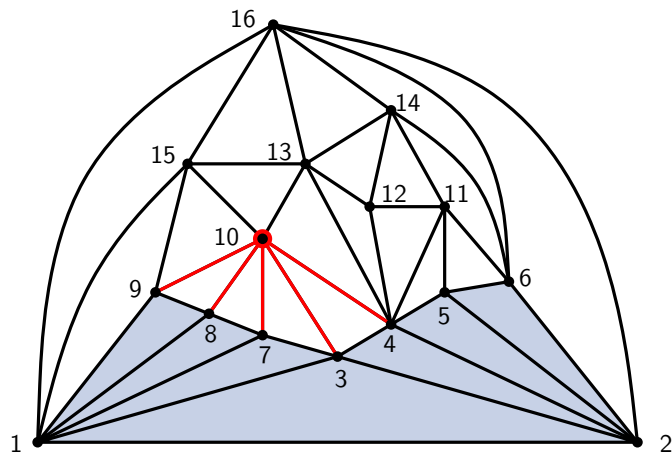
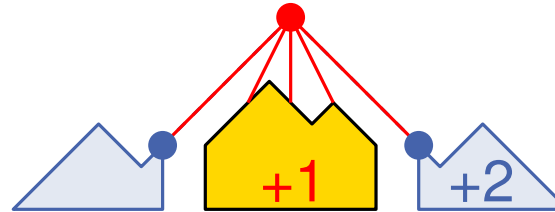
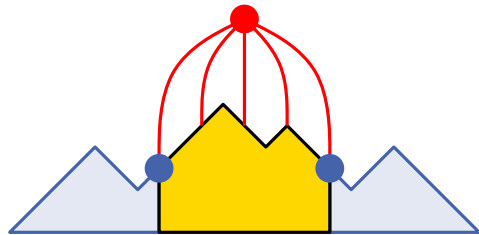
De Fraysseix Pach Pollack (Shift) Algorithm



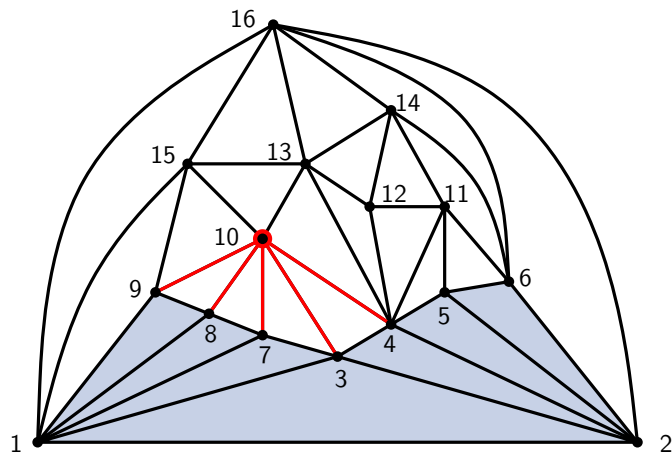
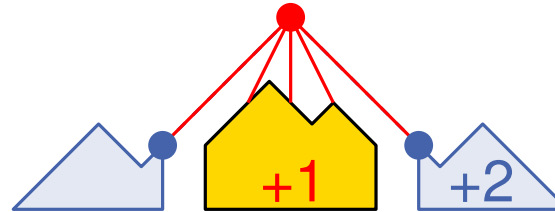
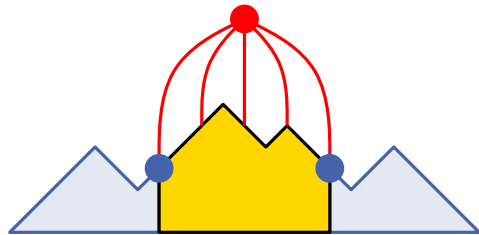
De Fraysseix Pach Pollack (Shift) Algorithm



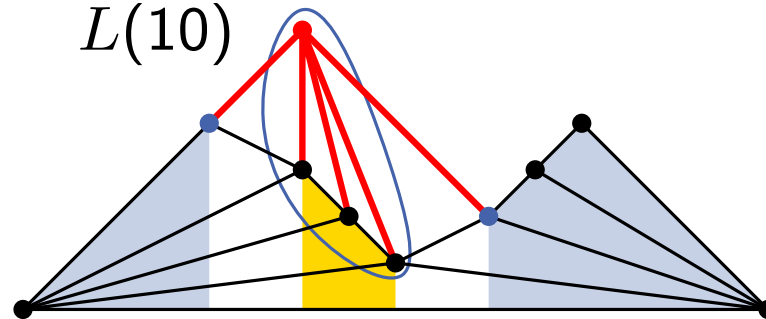
De Fraysseix Pach Pollack (Shift) Algorithm



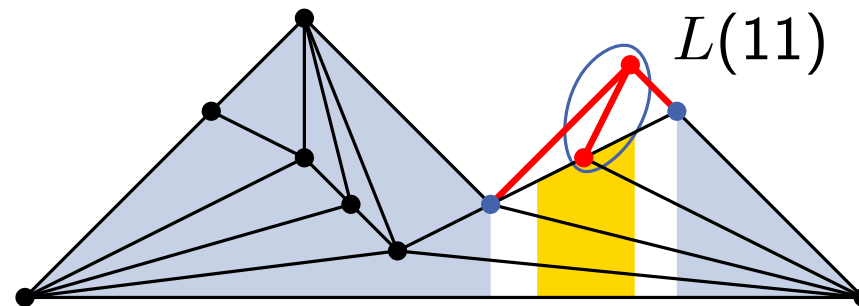
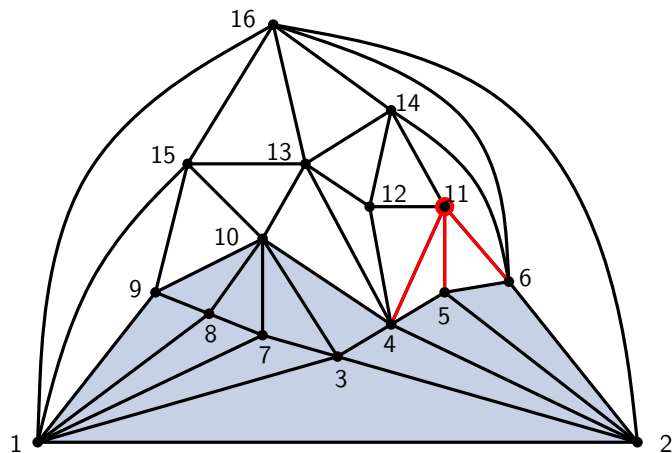
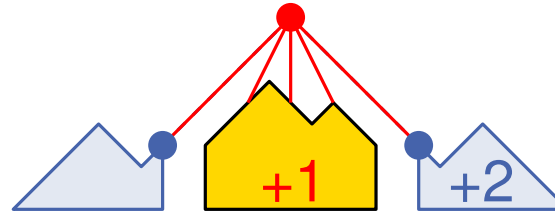
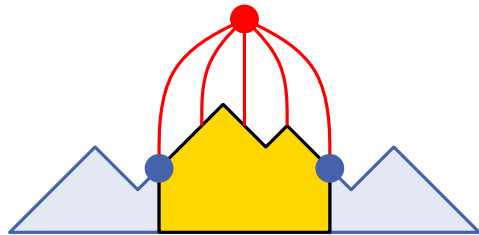
De Fraysseix Pach Pollack (Shift) Algorithm



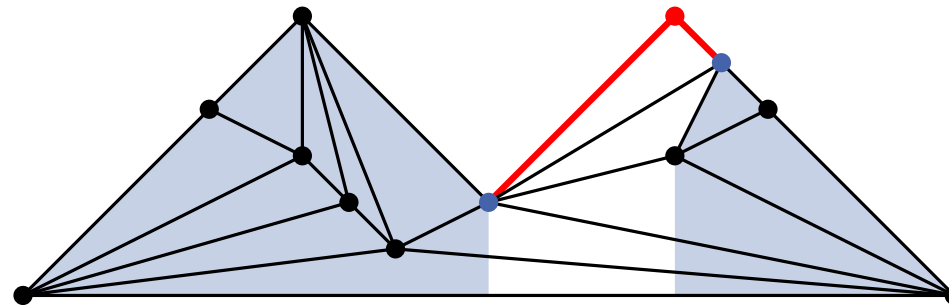
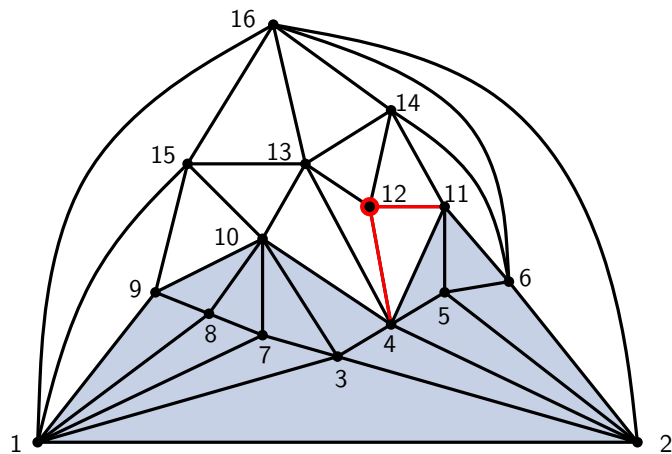
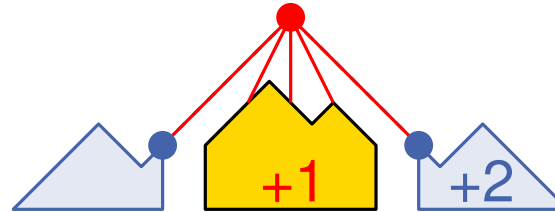
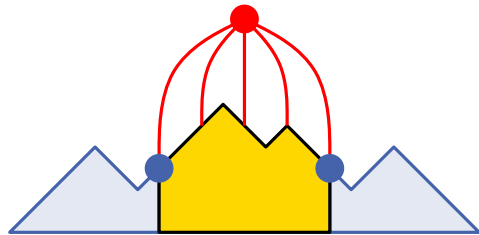
$L(10)$



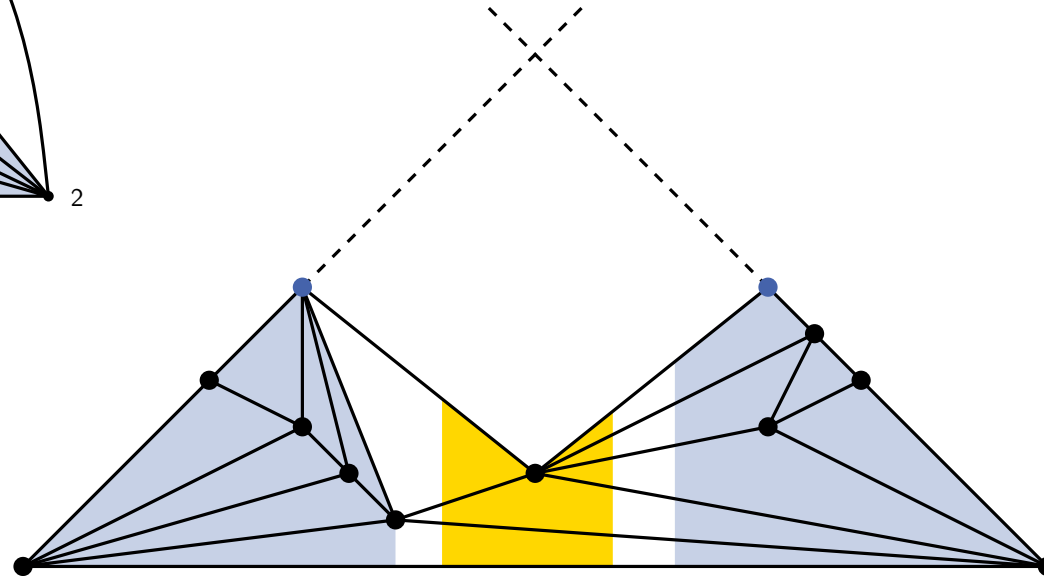
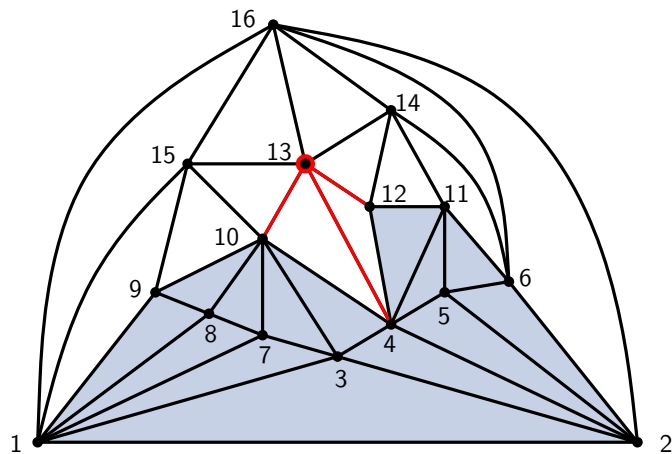
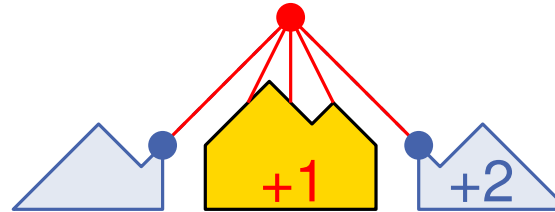
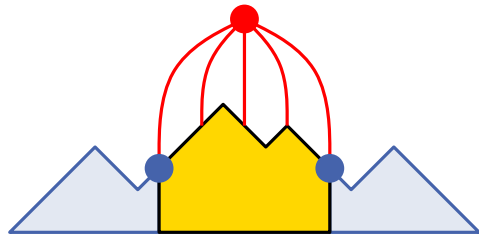
De Fraysseix Pach Pollack (Shift) Algorithm



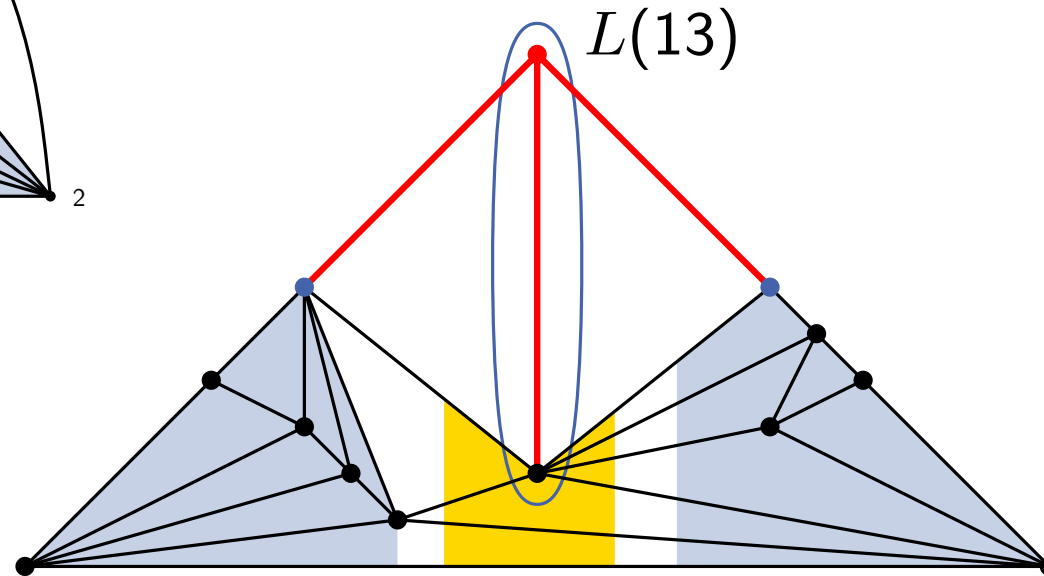
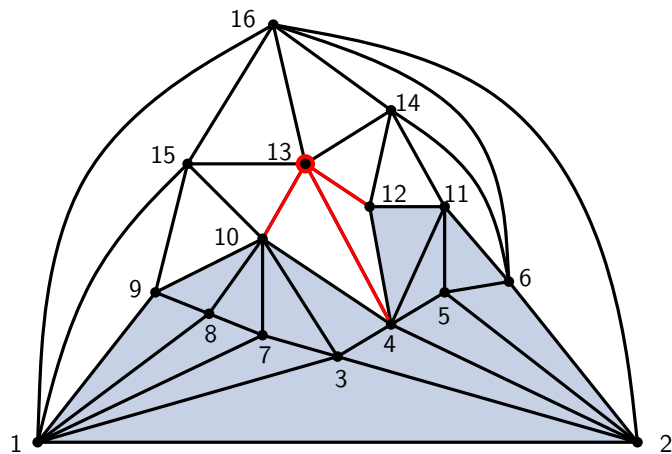
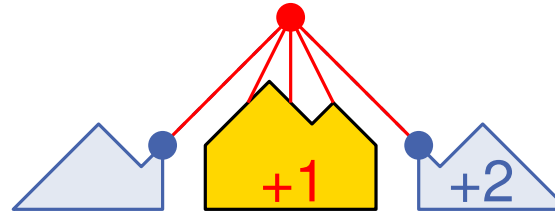
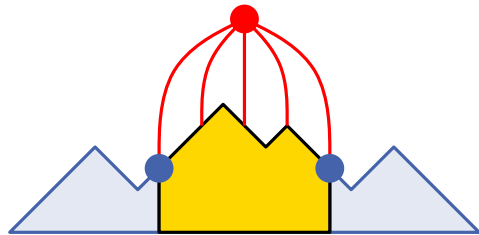
De Fraysseix Pach Pollack (Shift) Algorithm



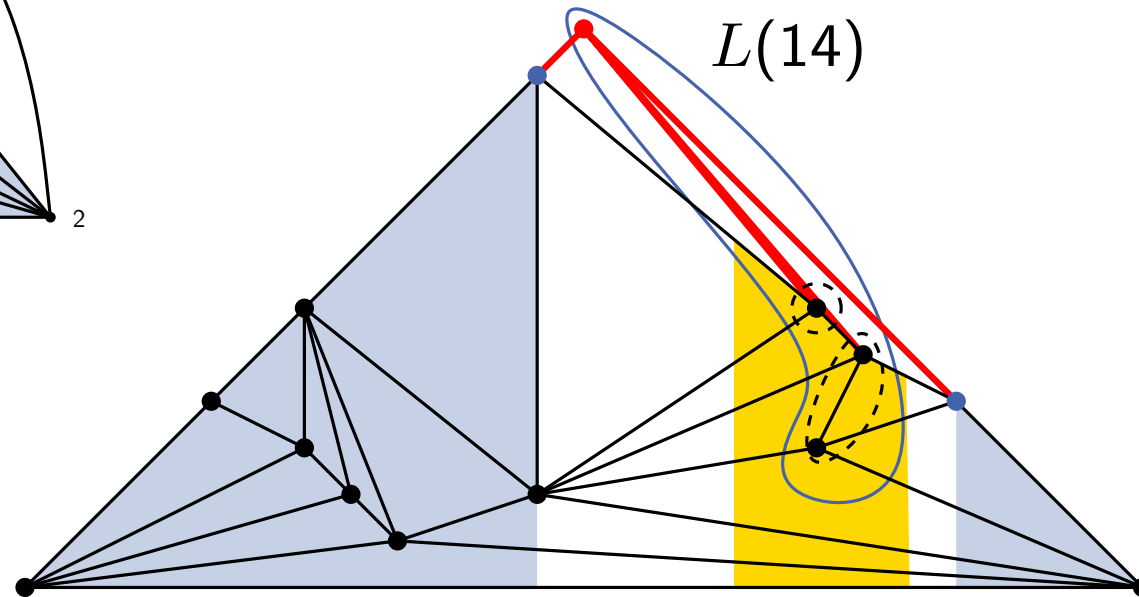
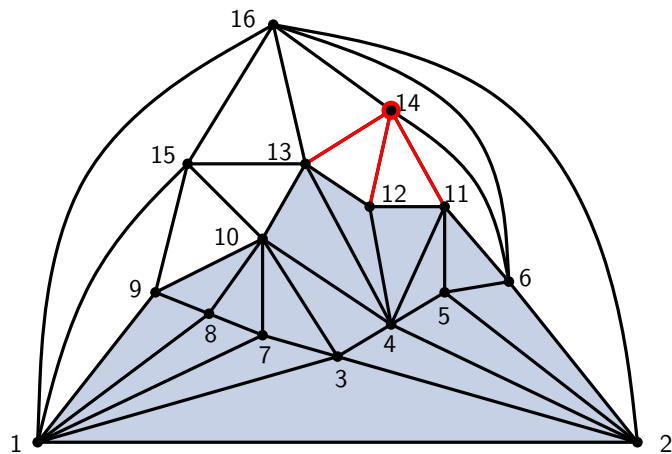
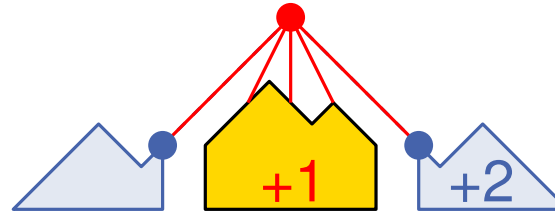
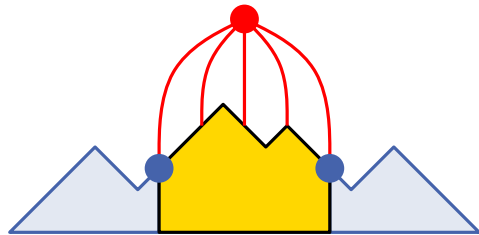
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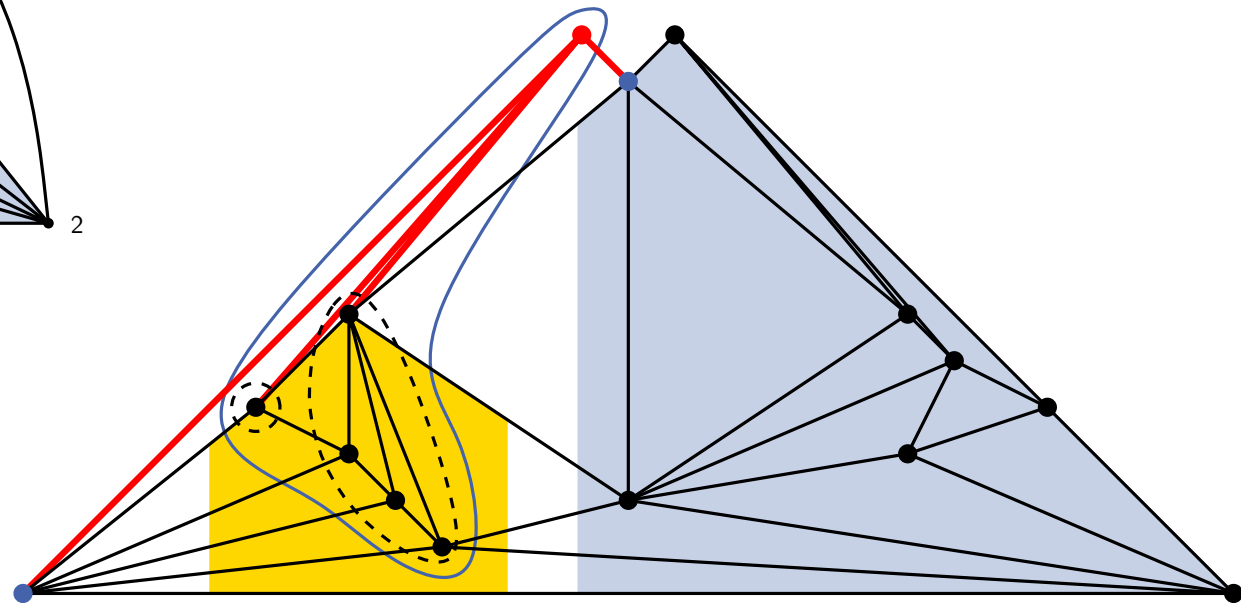
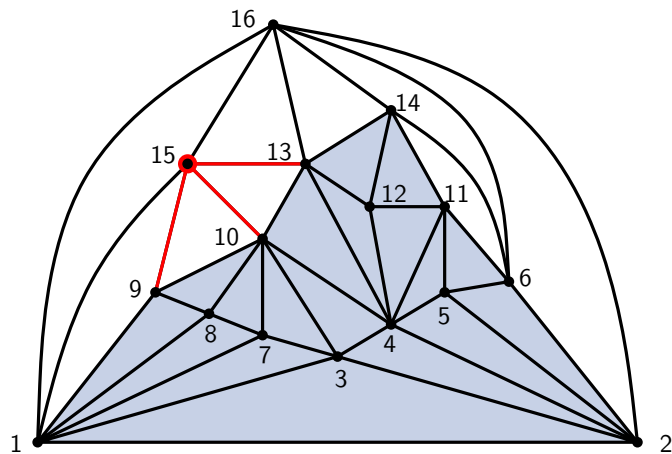
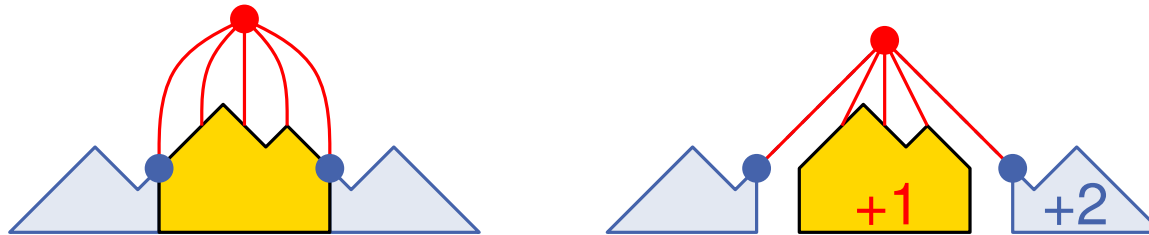
De Fraysseix Pach Pollack (Shift) Algorithm



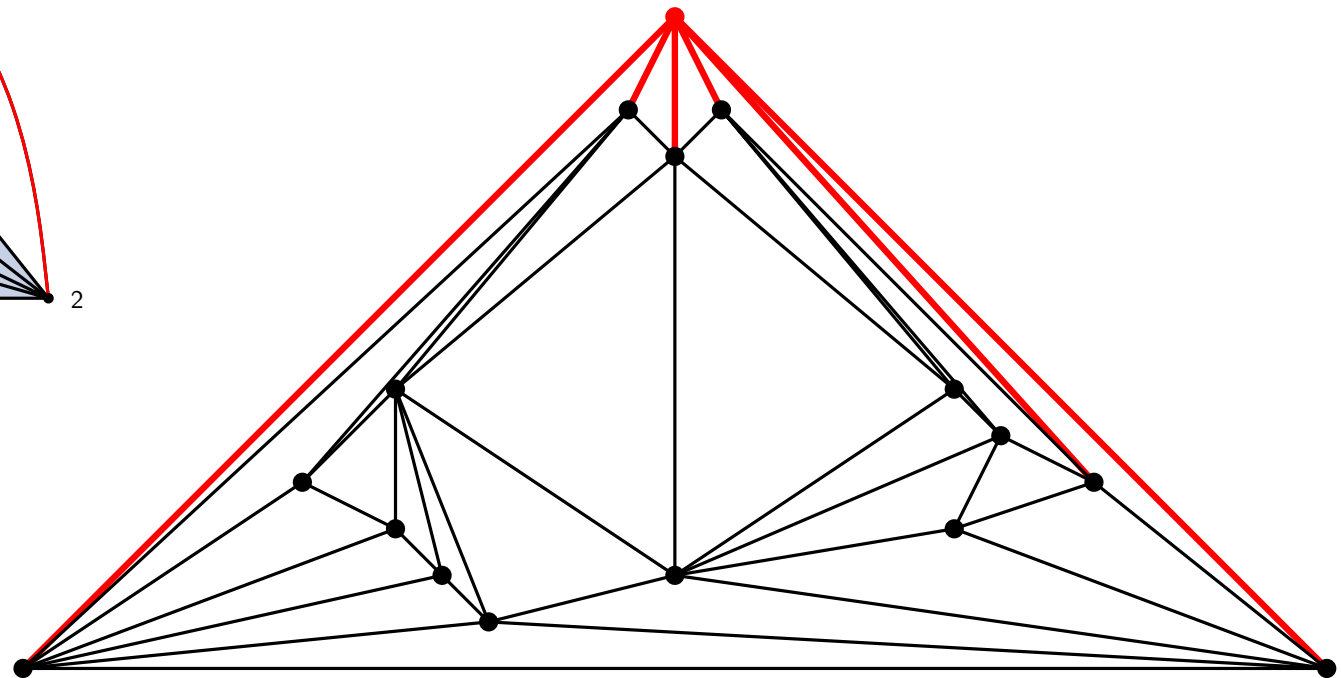
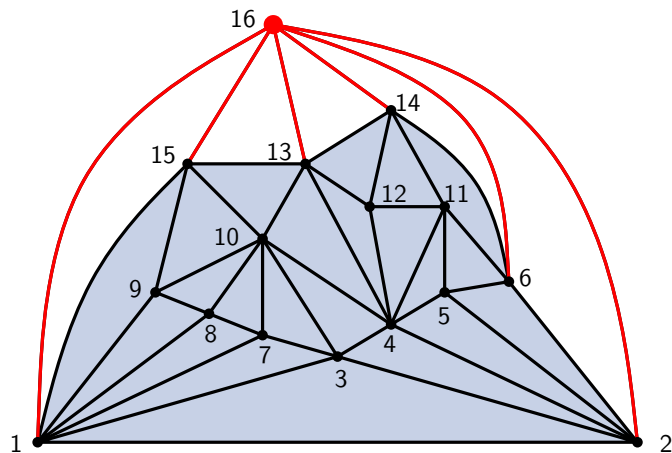
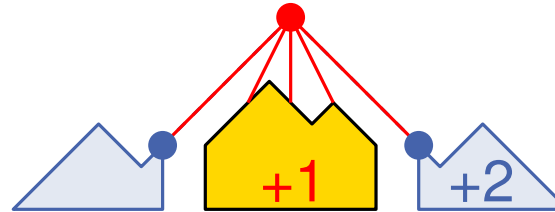
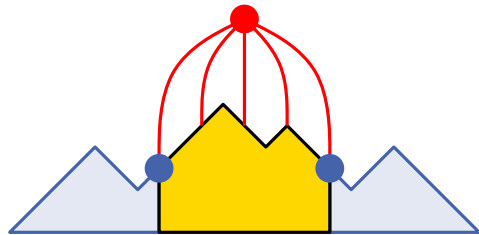
De Fraysseix Pach Pollack (Shift) Algorithm



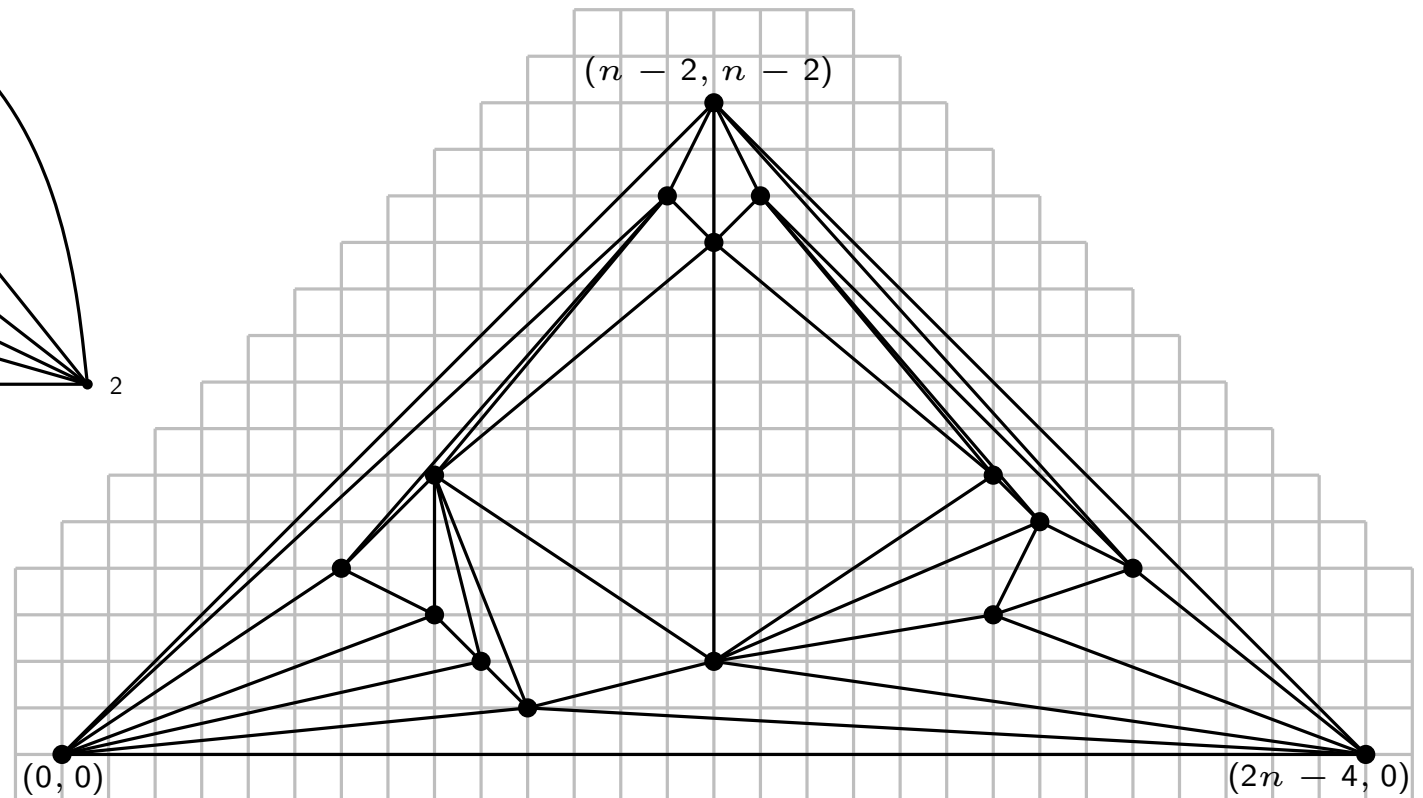
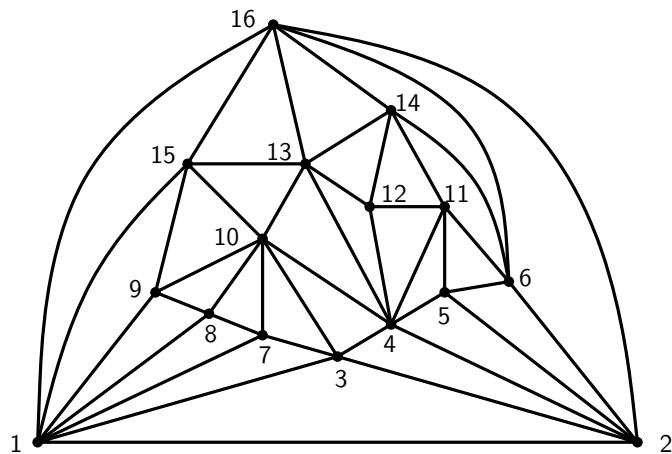
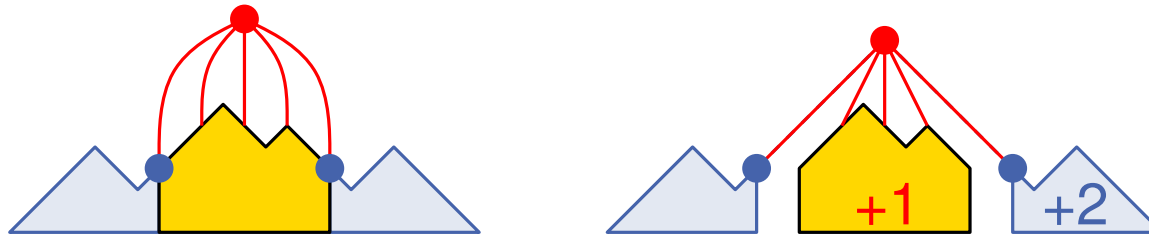
De Fraysseix Pach Pollack (Shift) Algorithm



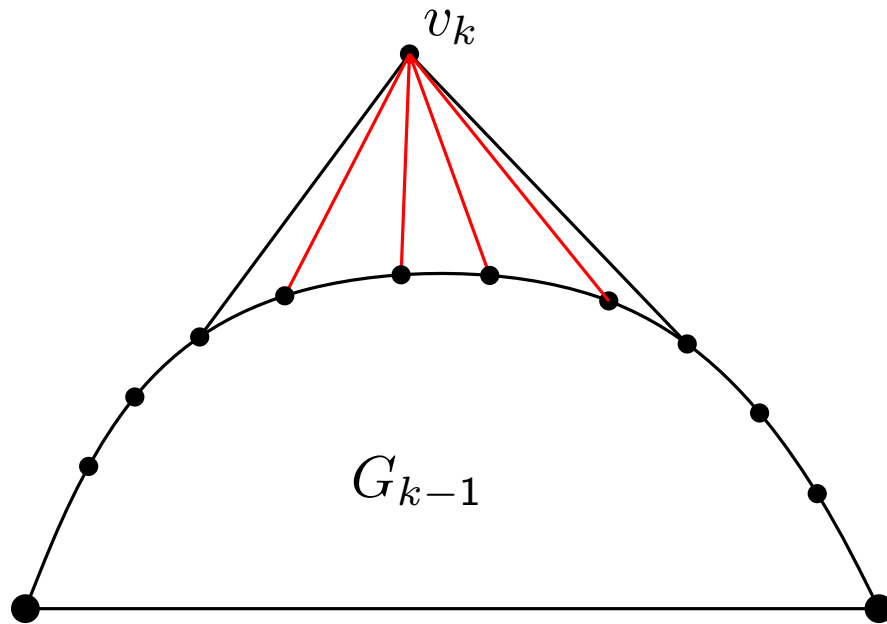
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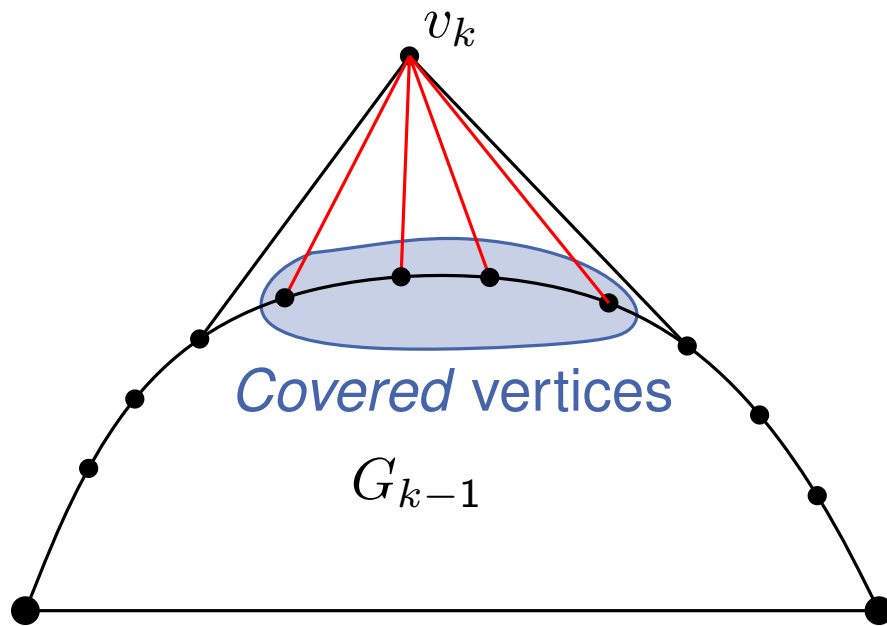
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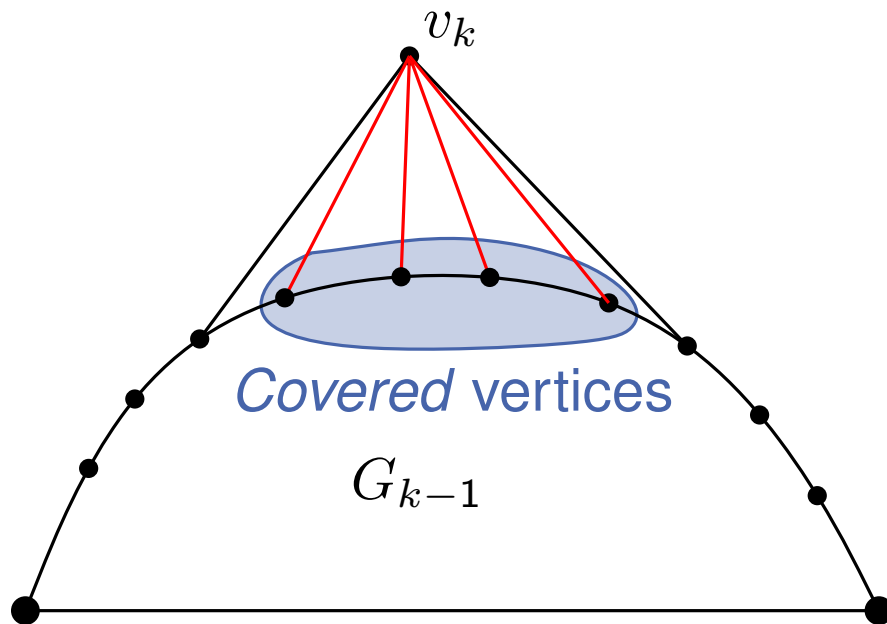


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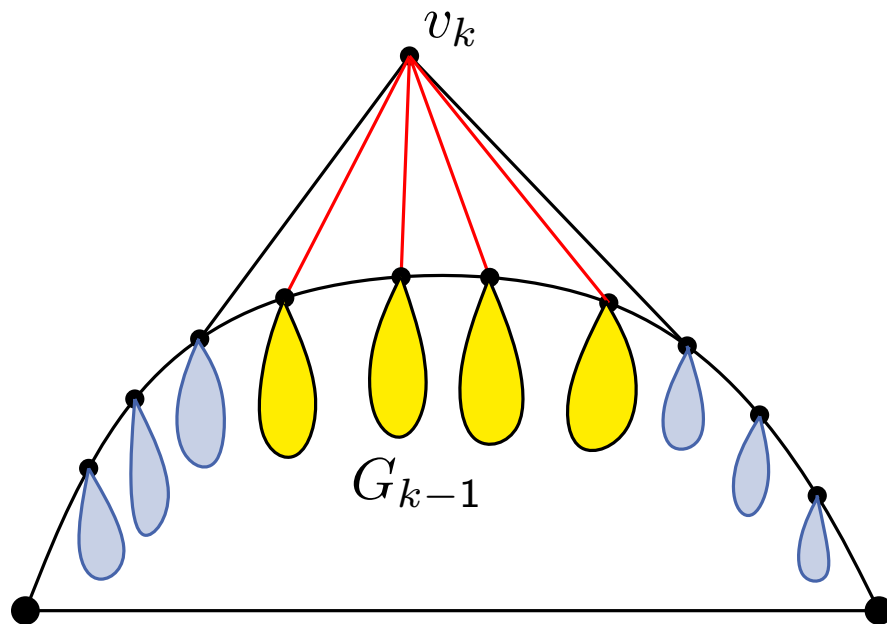


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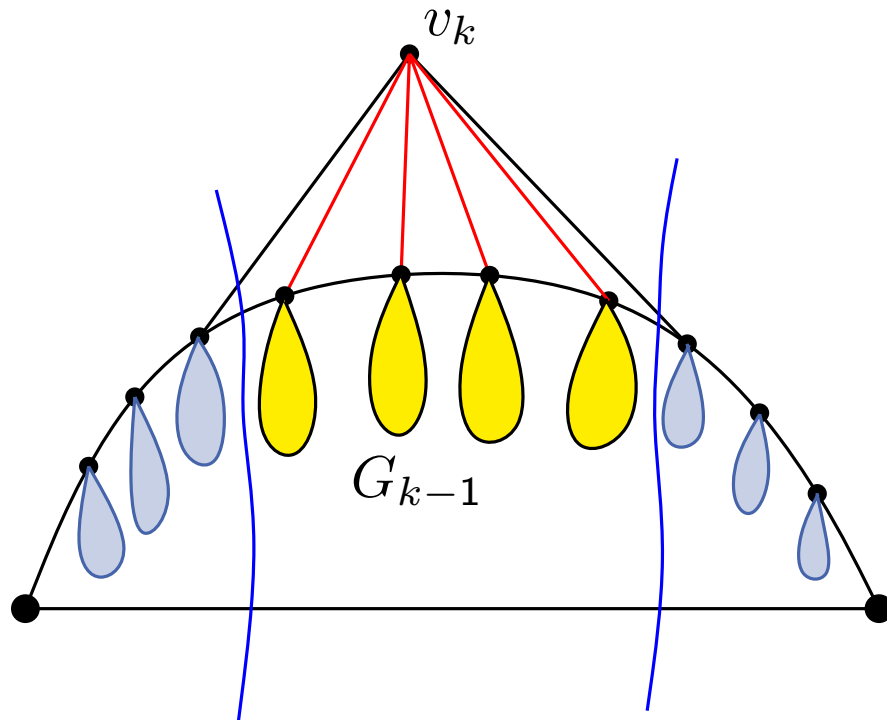




- Each internal vertex is covered exactly once
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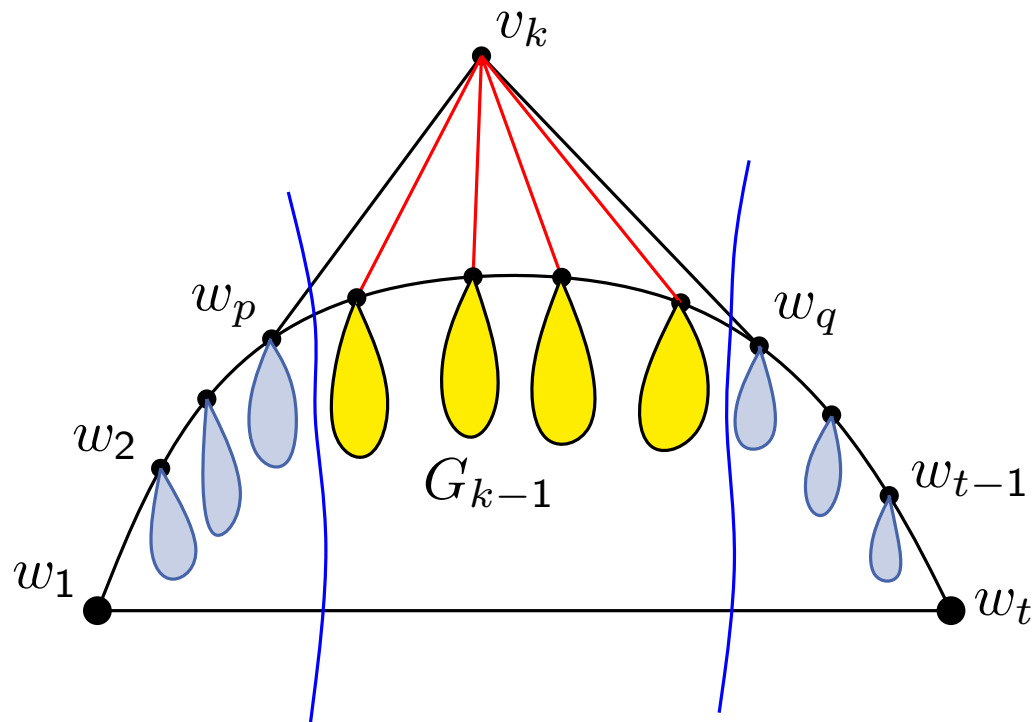


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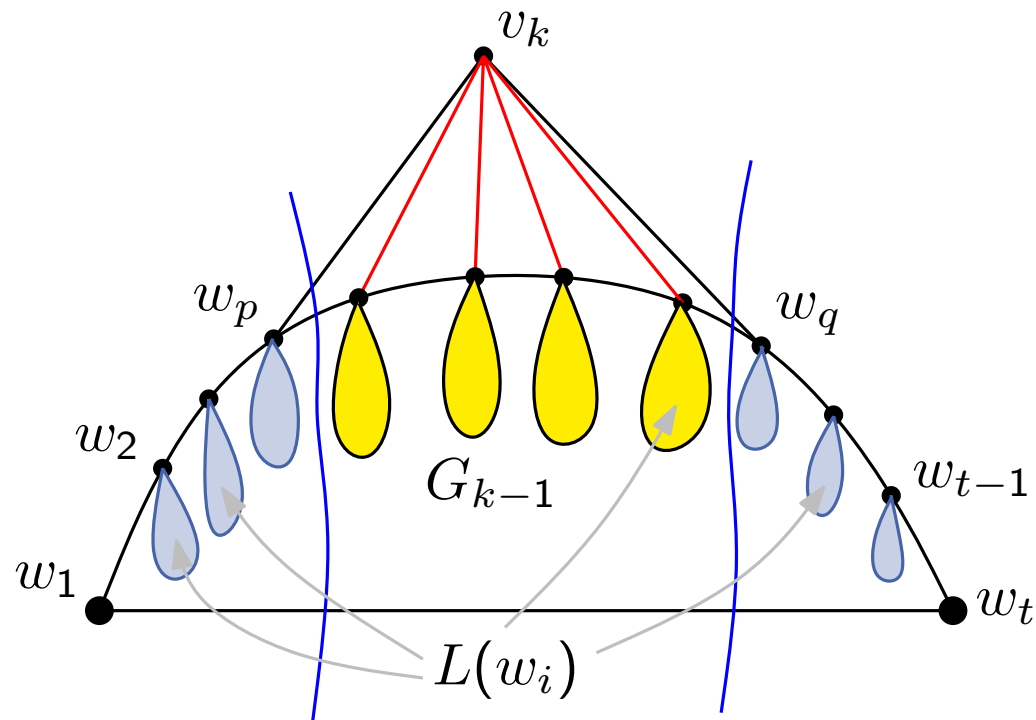
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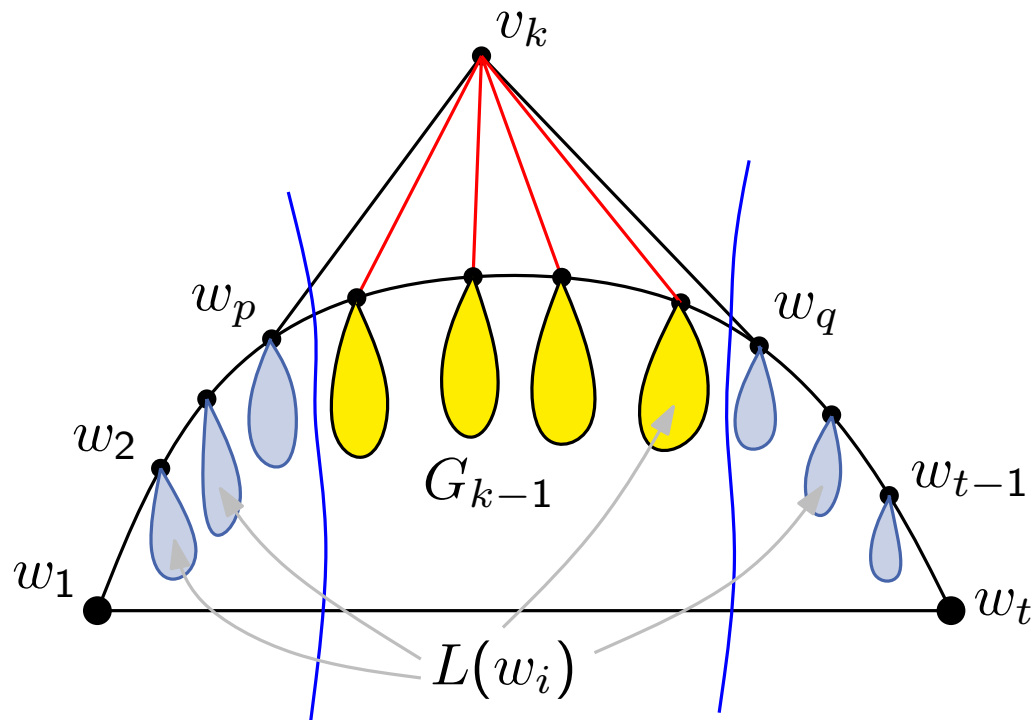


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- We set $\delta'_i = \delta_i$ for $1 \leq i \leq p$,
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- We can complete the drawing by placing v_k , v_k is moved with $L(w_{p+1}), \dots, L(w_{q-1})$ by δ .

Algorithm Shift

Let v_1, \dots, v_n be a canonical ordering of G

for $i = 1$ **to** n **do**

└ $L(v_i) \leftarrow \{v_i\};$

$P(v_1) \leftarrow (0, 0); P(v_2) \leftarrow (2, 0); P(v_3) \leftarrow (1, 1);$

for $i = 4$ **to** n **do**

└ Let $w_1 = v_1, w_2, \dots, w_{t-1}, w_t = v_2$ denote the boundary of $G_{i-1};$
and let w_p, \dots, w_q be the neighbors $v_i;$

└ **for** $\forall v \in \cup_{j=p+1}^{q-1} L(w_j)$ **do**

└ $x(v) \leftarrow x(v) + 1;$

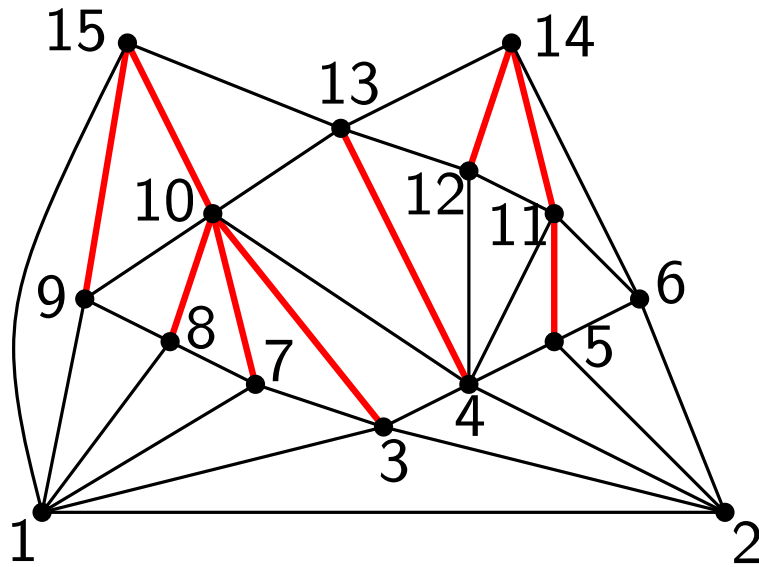
└ **for** $\forall v \in \cup_{j=q}^t L(w_j)$ **do**

└ $x(v) \leftarrow x(v) + 2;$

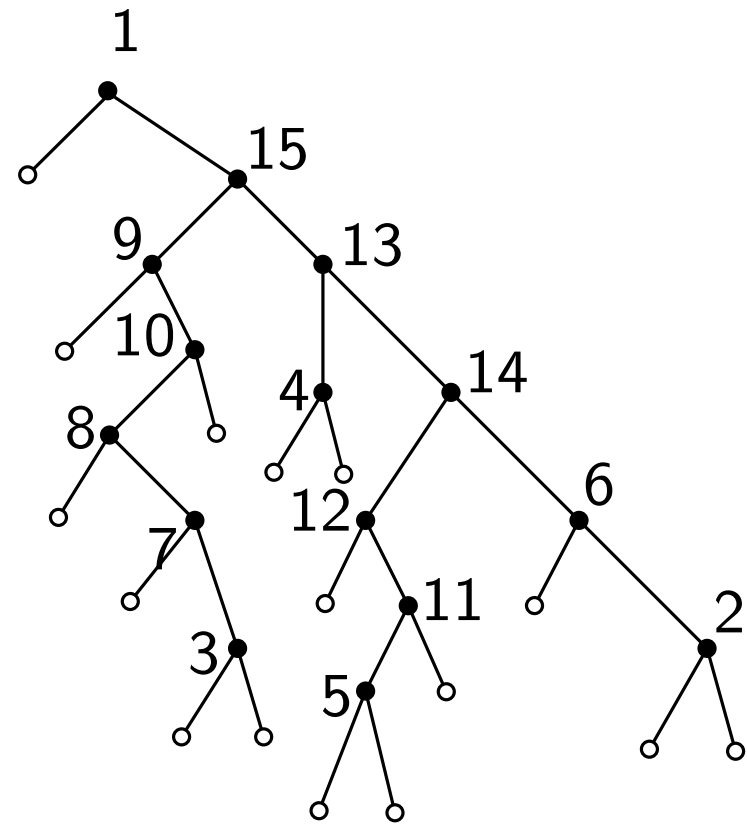
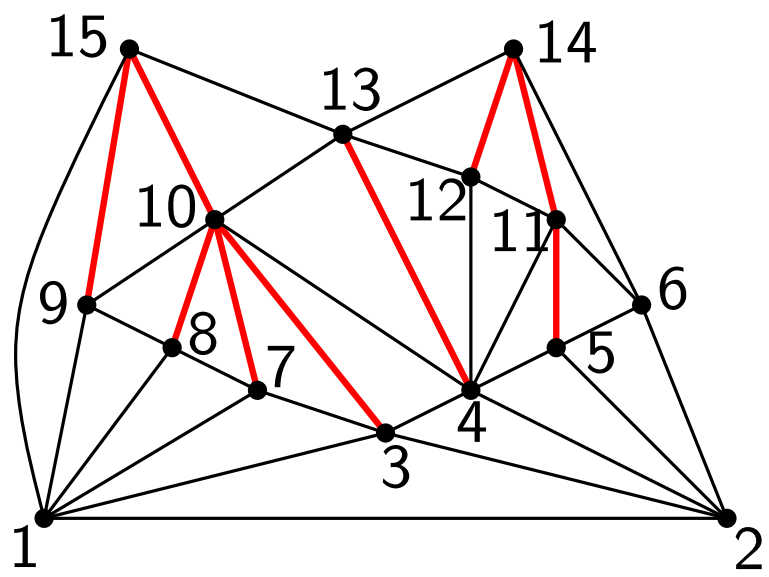
$P(v_i) \leftarrow$ intersection of $+1$ and -1 edges from $P(w_p)$ and $P(w_q);$

└ $L(v_i) = \cup_{j=p+1}^{q-1} L(w_j) \cup \{v_i\};$

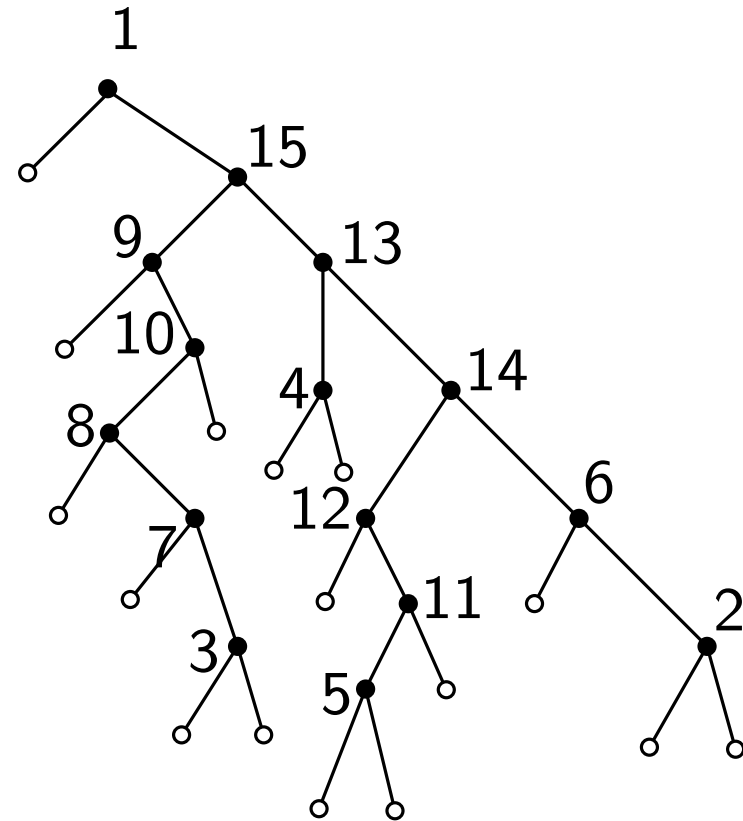
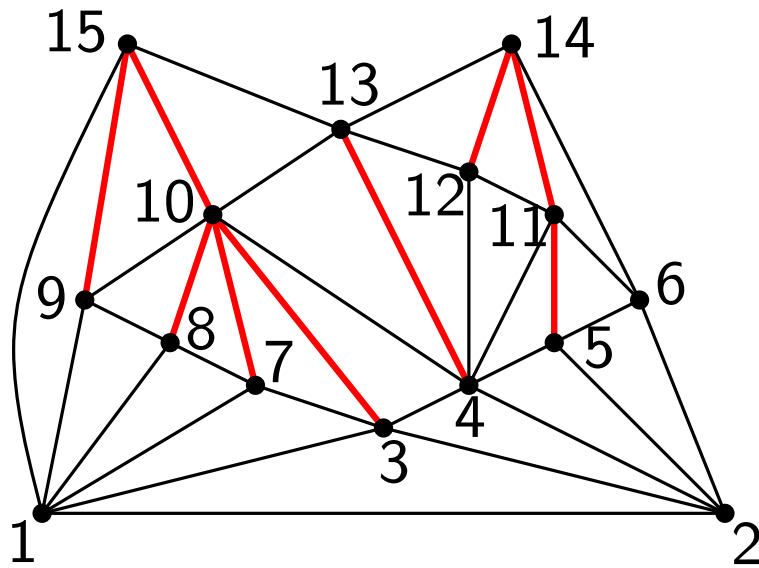
Linear Time Implementation of Shift Algorithm



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- $x(v_k) = \frac{1}{2}(x(w_q) + x(w_p) + y(w_q) - y(w_p))$ (1)

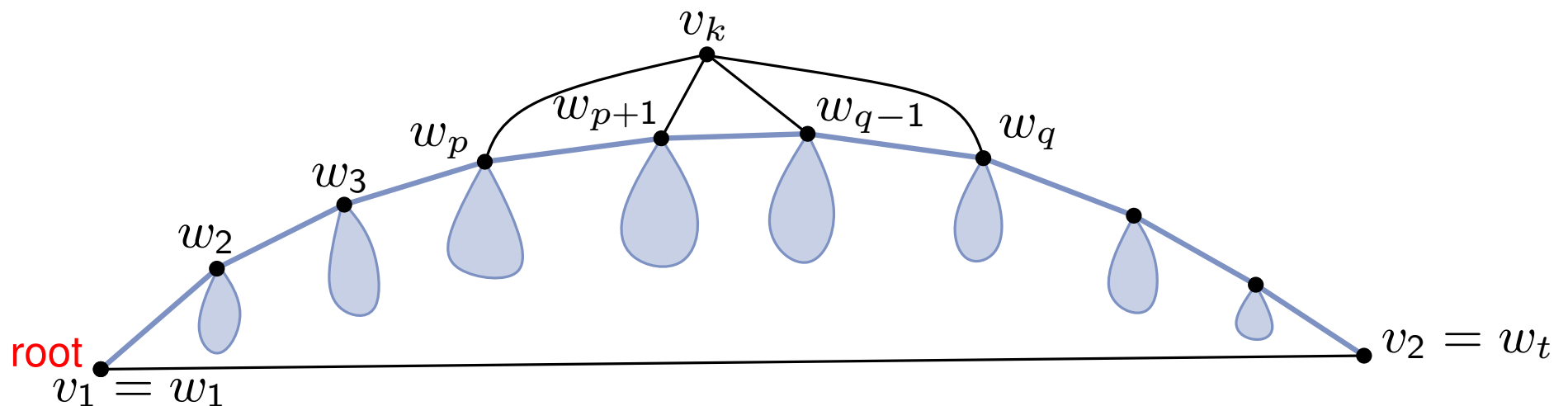
- $y(v_k) = \frac{1}{2}(x(w_q) - x(w_p) + y(w_q) + y(w_p))$ (2)

- $x(v_k) - x(w_p) = \frac{1}{2}(x(w_q) - x(w_p) + y(w_q) - y(w_p))$ (3)

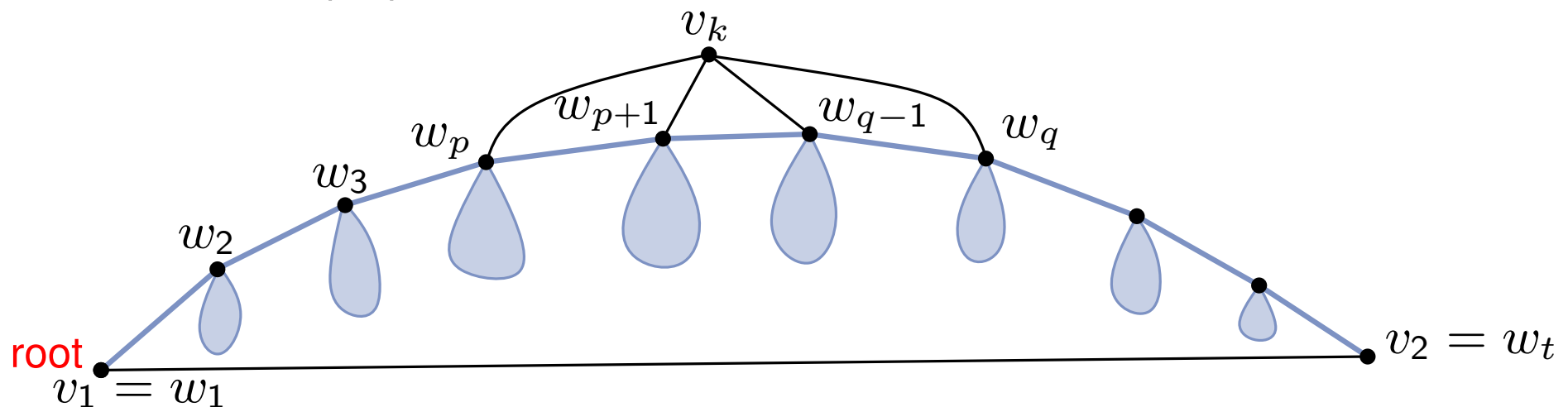
- If we know the y -coordinates of w_p and w_q and the difference $x(w_p) - x(w_q)$, we can compute the relative distance of v_k and w_p .
- In the binary tree which we construct we keep the relative x -distance of each node from its parent.

Linear Time Implementation of Shift Algorithm

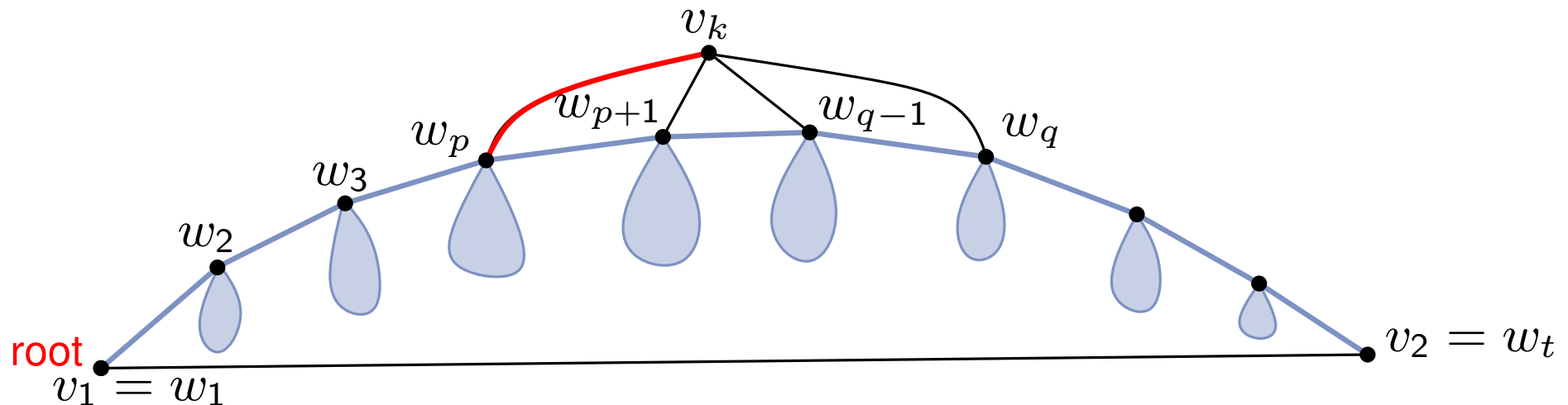
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- $\Delta_x(w_p, w_q) = \Delta_x(w_{p+1}) + \dots + \Delta_x(w_q)$
- Calculate $\Delta_x(v_k)$ by eq. (3)
- Calculate $y(v_k)$ by eq. (2)

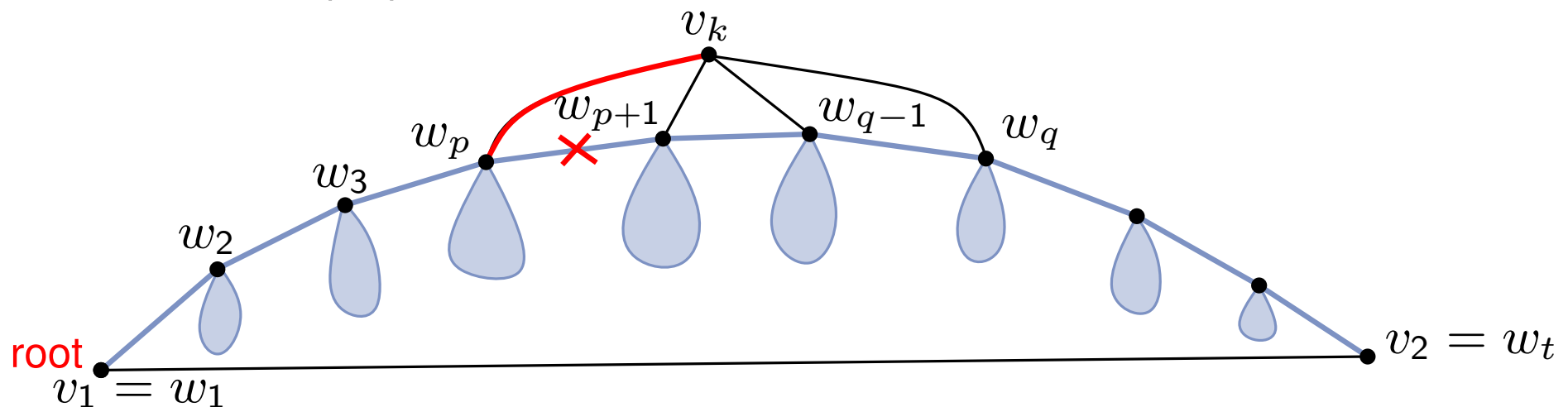


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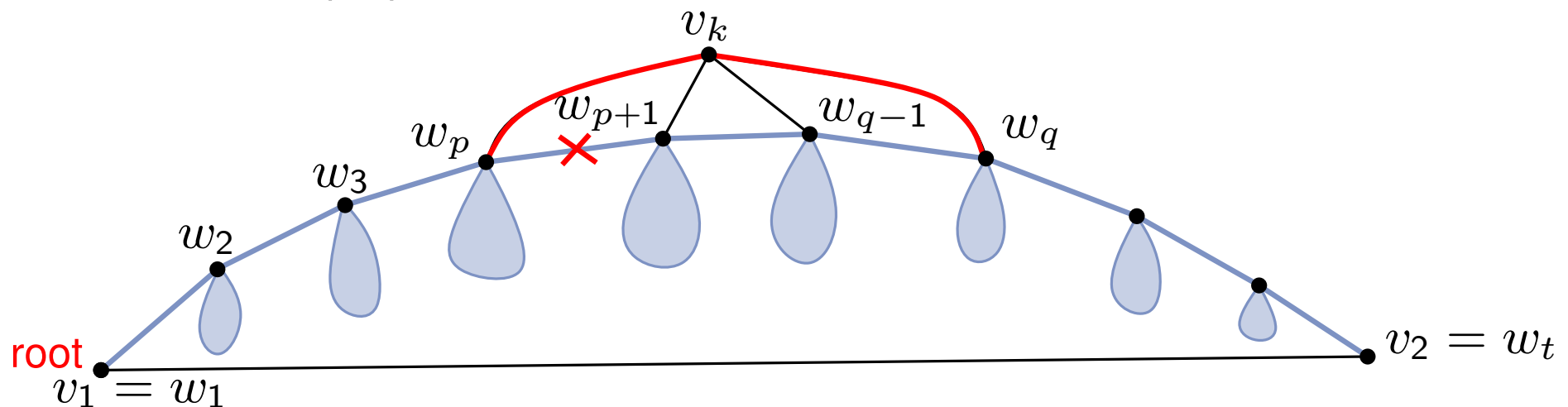


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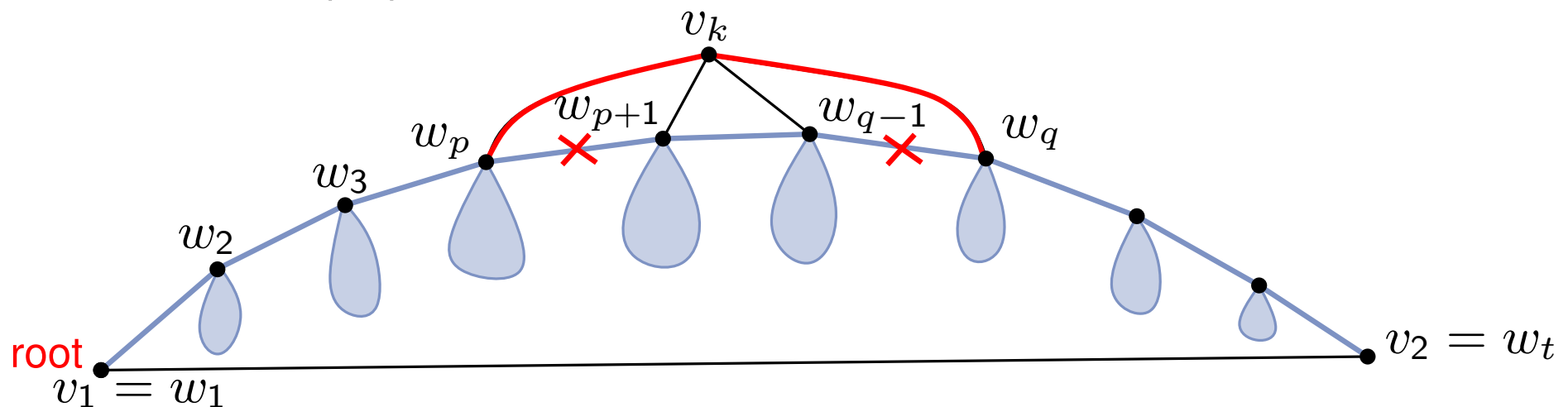
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- $\Delta_x(w_q) = \Delta_x(w_p, w_q) - \Delta_x(v_k)$
- $\Delta_x(w_{p+1}) = \Delta_x(w_{p+1}) - \Delta_x(v_k)$

