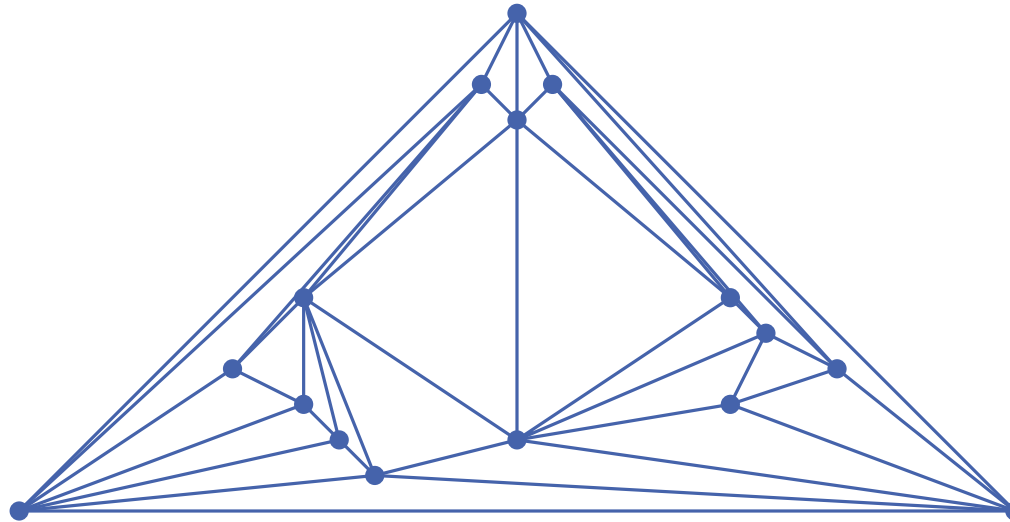


Algorithms for graph visualization

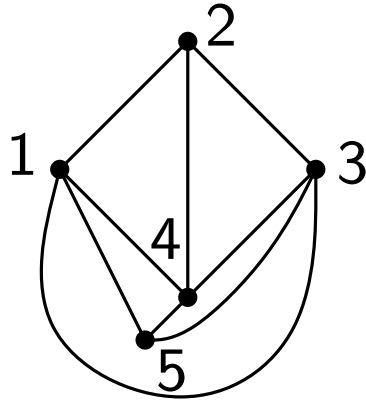
Layouts for planar graphs. Shift method.

WINTER SEMESTER 2012/2013

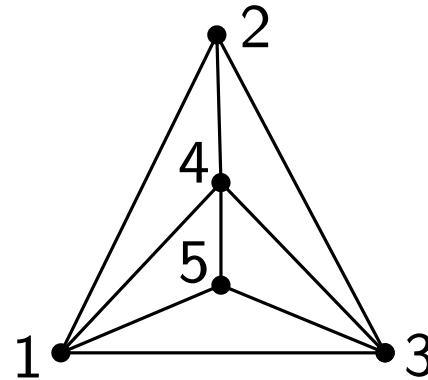
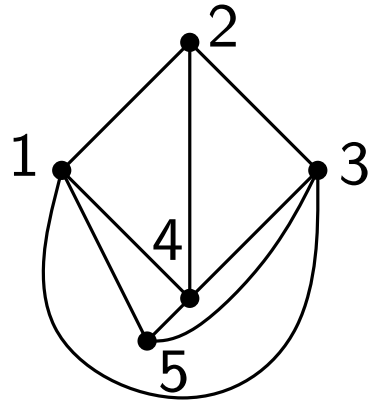
Tamara Mchedlidze – MARTIN NÖLLENBURG – IGNAZ RUTTER



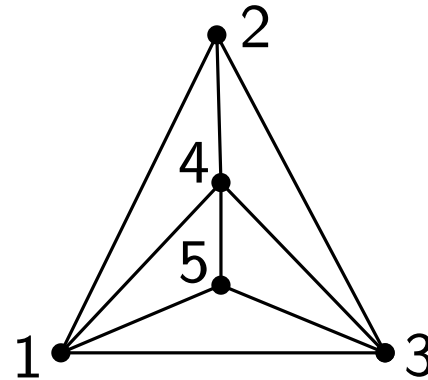
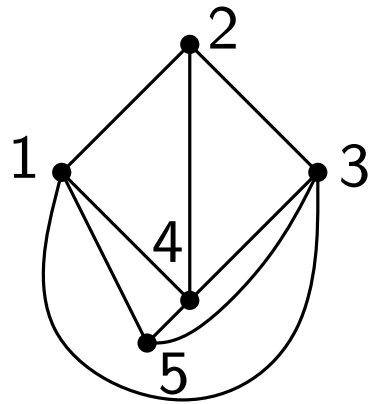
- Straight line drawing of a planar graph



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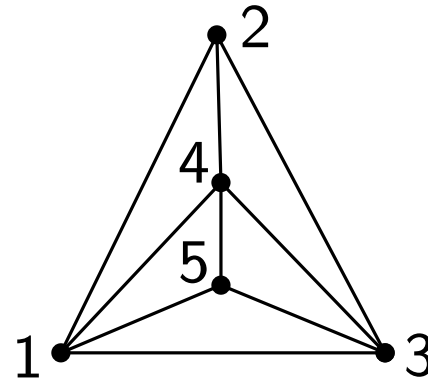
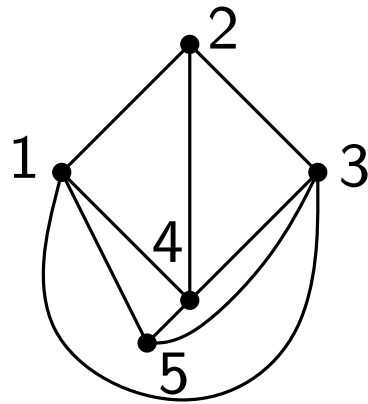
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Theorem [Wagner '36, Fary '48, Stein '51]

Every planar graph has a planar straight-line drawing.

- Straight line drawing of a planar graph



Theorem [Wagner '36, Fary '48, Stein '51]

Every planar graph has a planar straight-line drawing.

- These algorithms produce drawings with area **not bounded** by any polynomial on n .

This lecture:

Theorem [De Fraysseix, Pach, Pollack '90]

Every n -vertex planar graph has a planar straight-line drawing of a size $(2n - 4) \times (n - 2)$.

Next lecture:

Theorem [Schnyder '90]

Every n -vertex planar graph has a planar straight-line drawing of a size $(n - 2) \times (n - 2)$.

Definition: Canonical Ordering

Let $G = (V, E)$ be a triangulated planar embedded graph of $n \geq 3$ vertices. An ordering $\pi = (v_1, v_2, \dots, v_n)$ is called a **canonical ordering**, if the following conditions hold for each k , $3 \leq k \leq n$.

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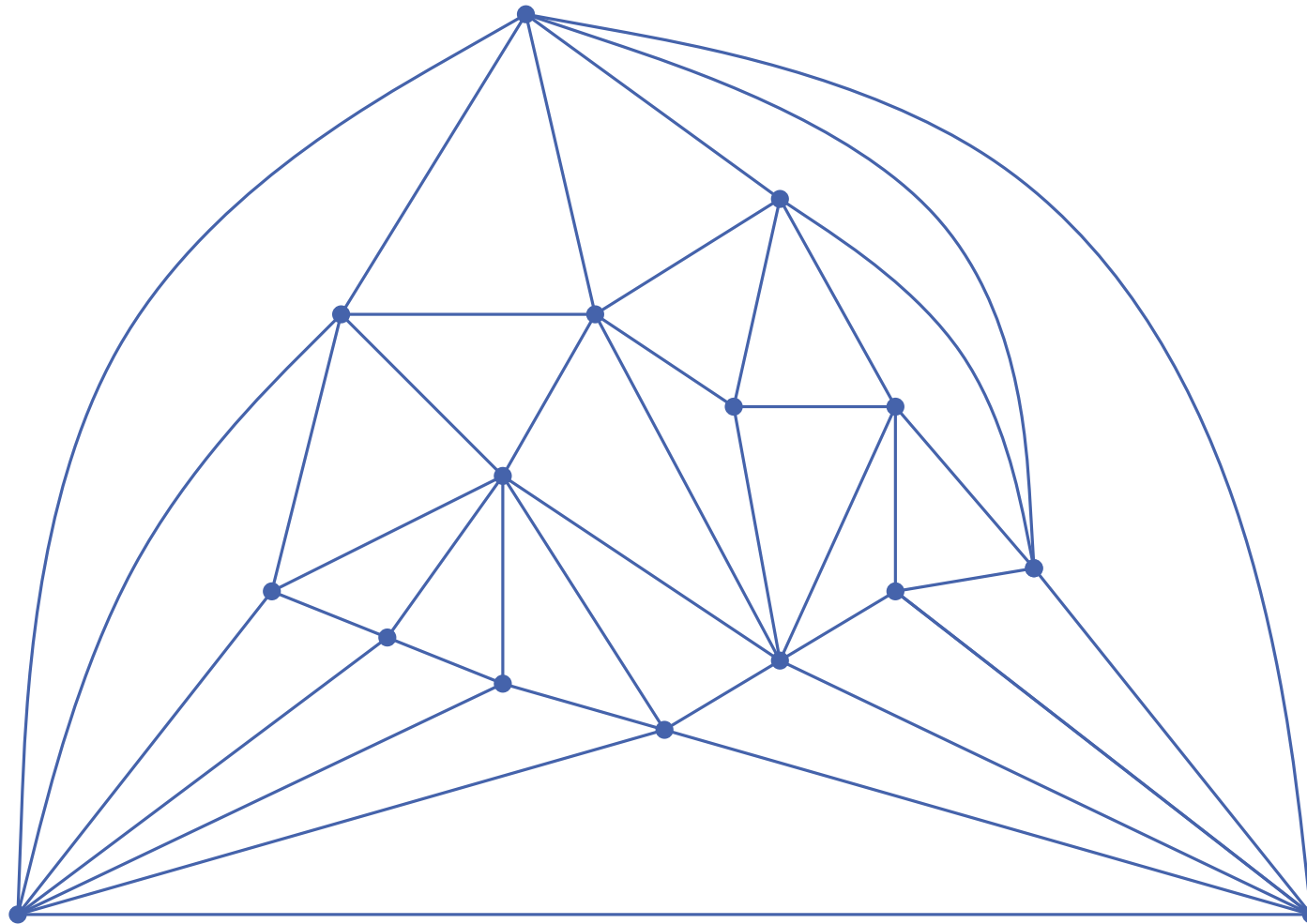
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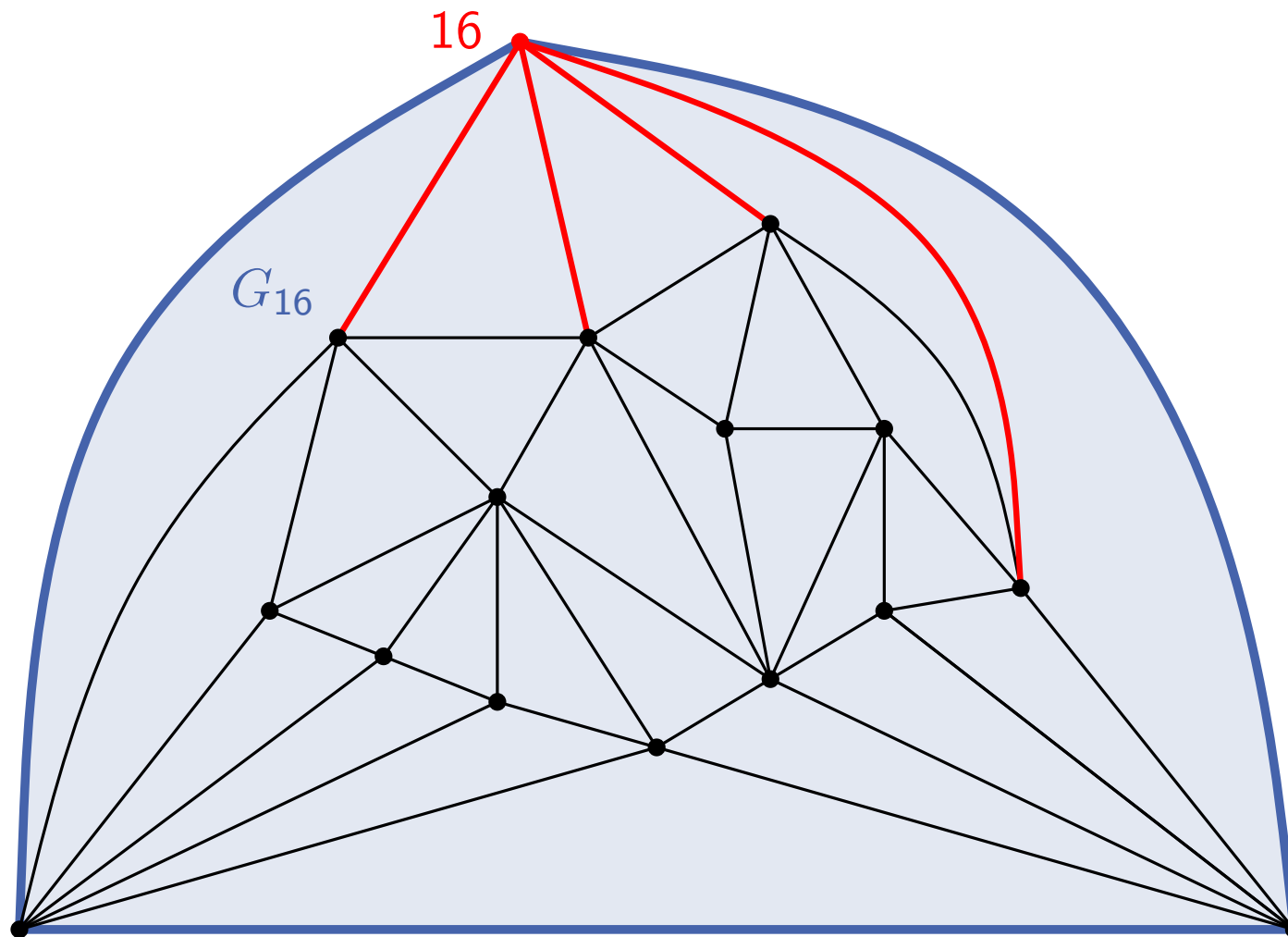
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- (C3) If $k < n$ then vertex v_{k+1} lies in the outer face of G_k , and all neighbors of v_{k+1} in G_k appear on the boundary of G_k consecutively.

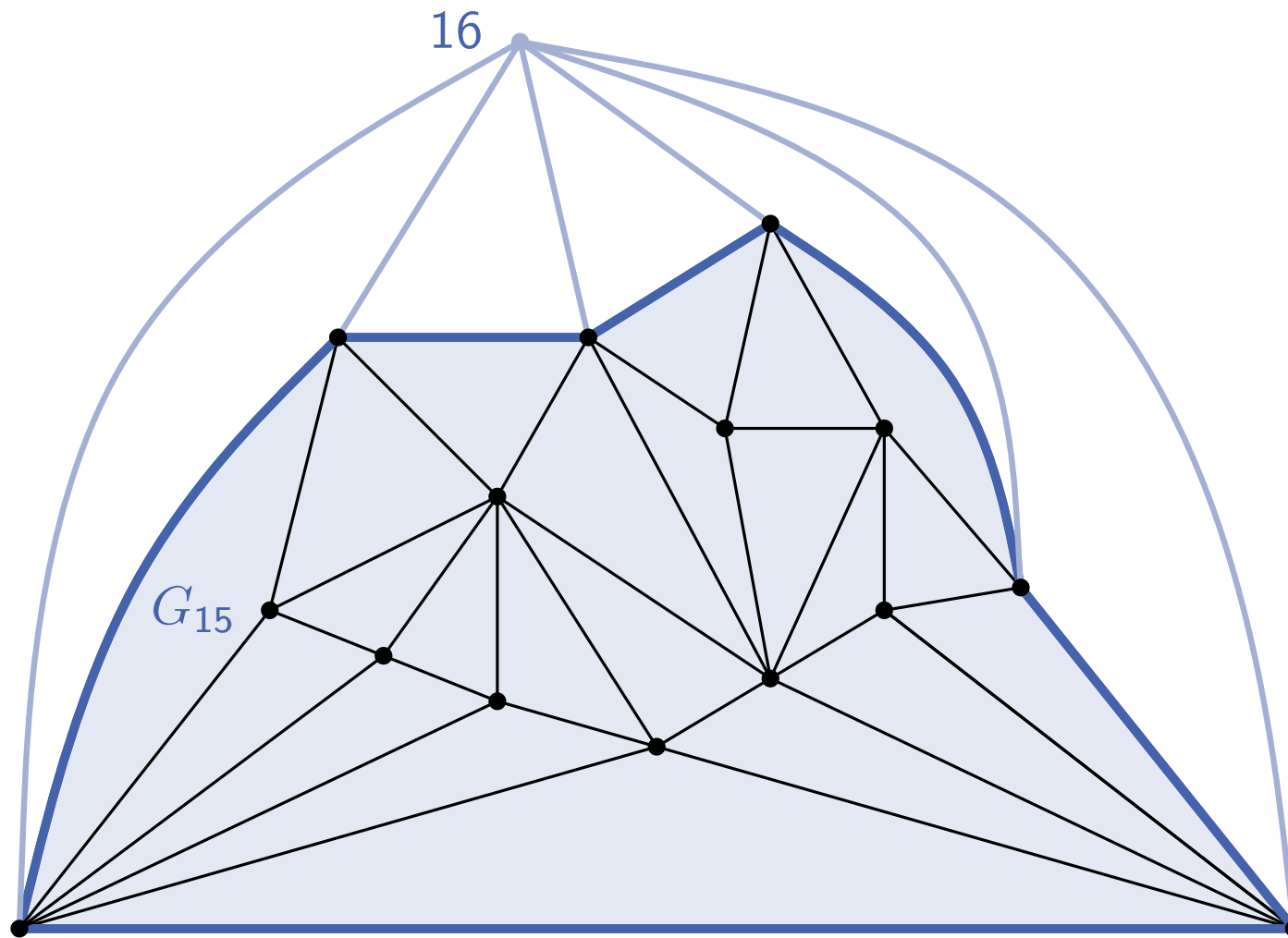
Example of Canonical Ordering



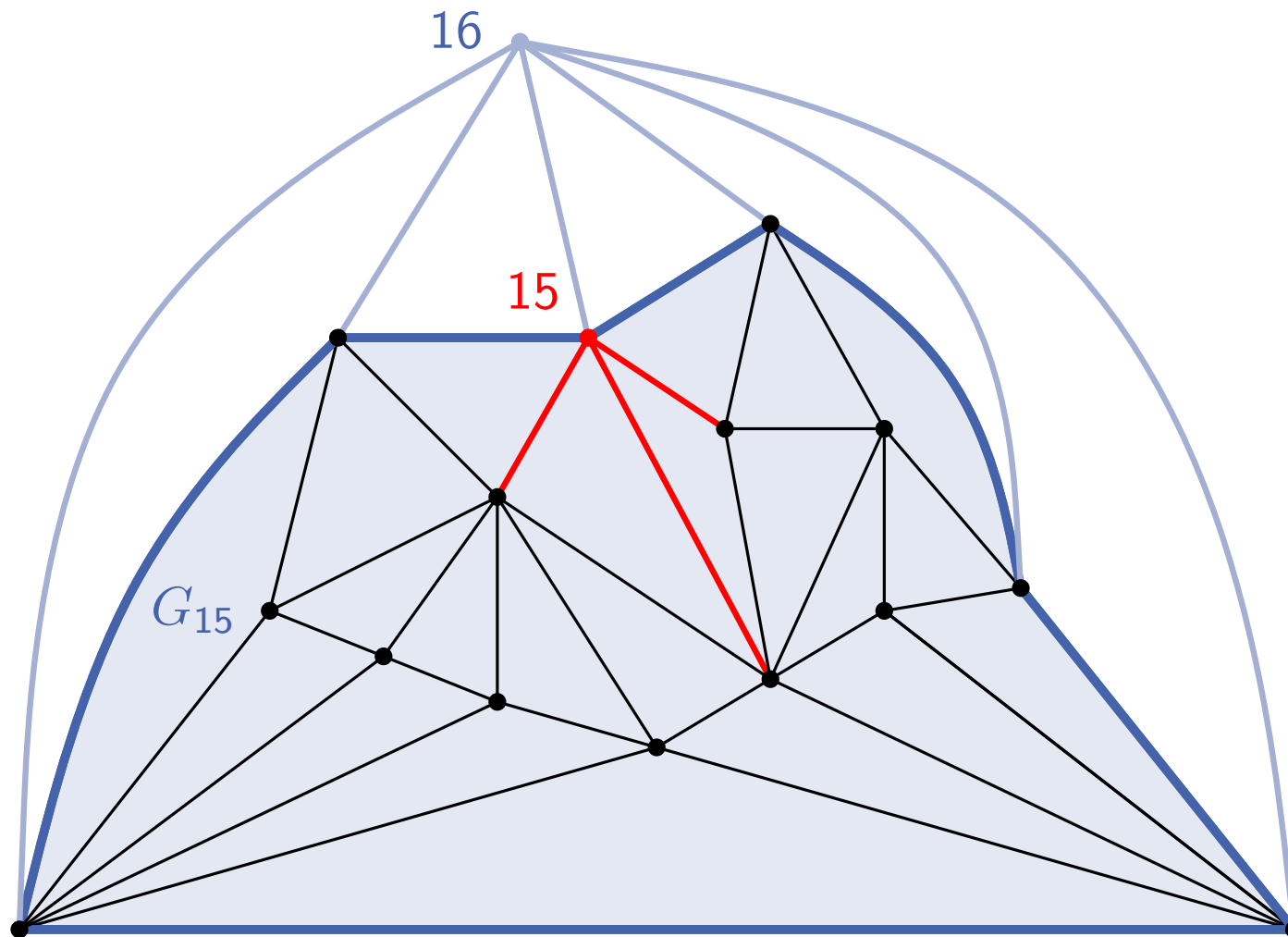
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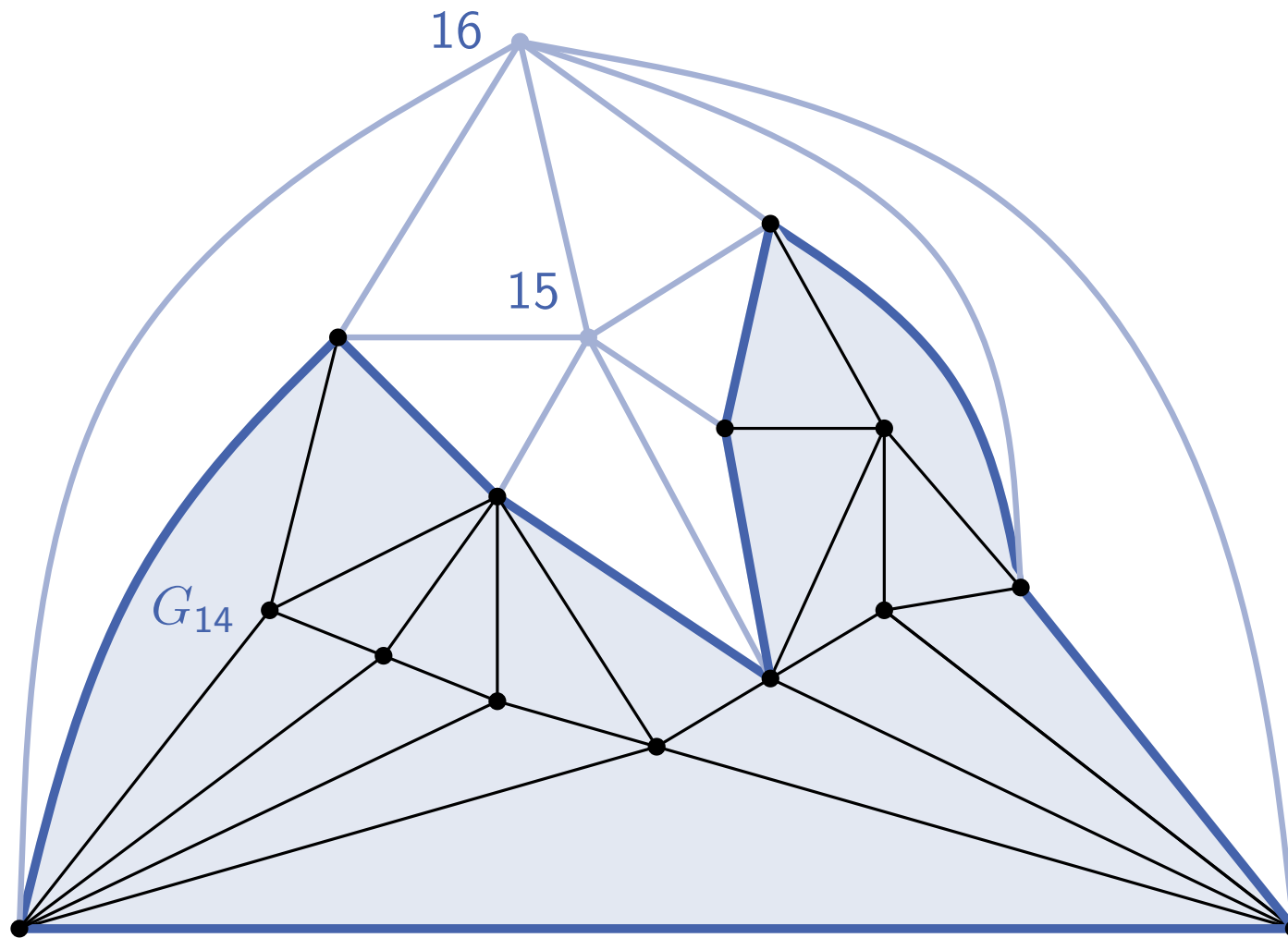
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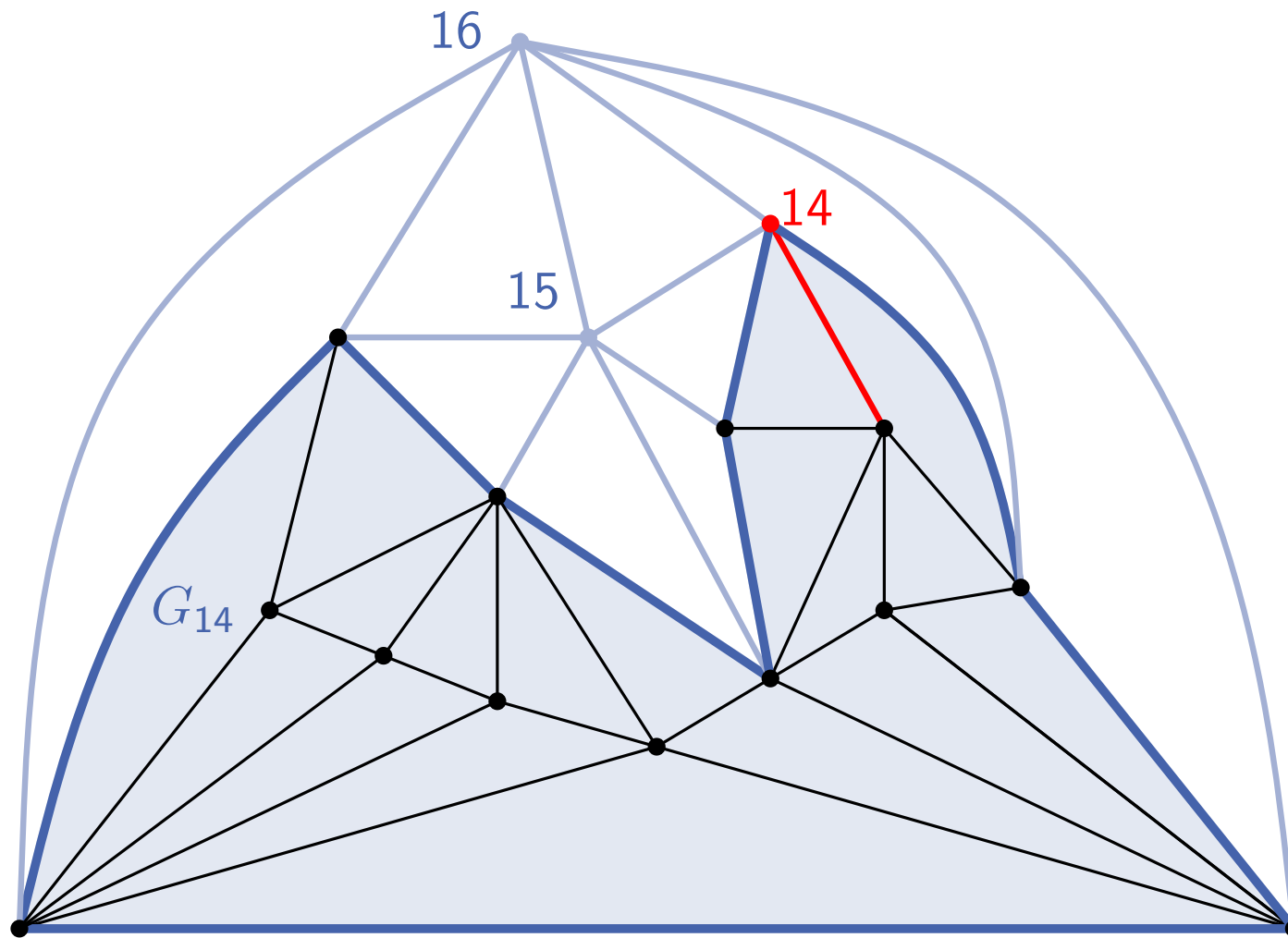
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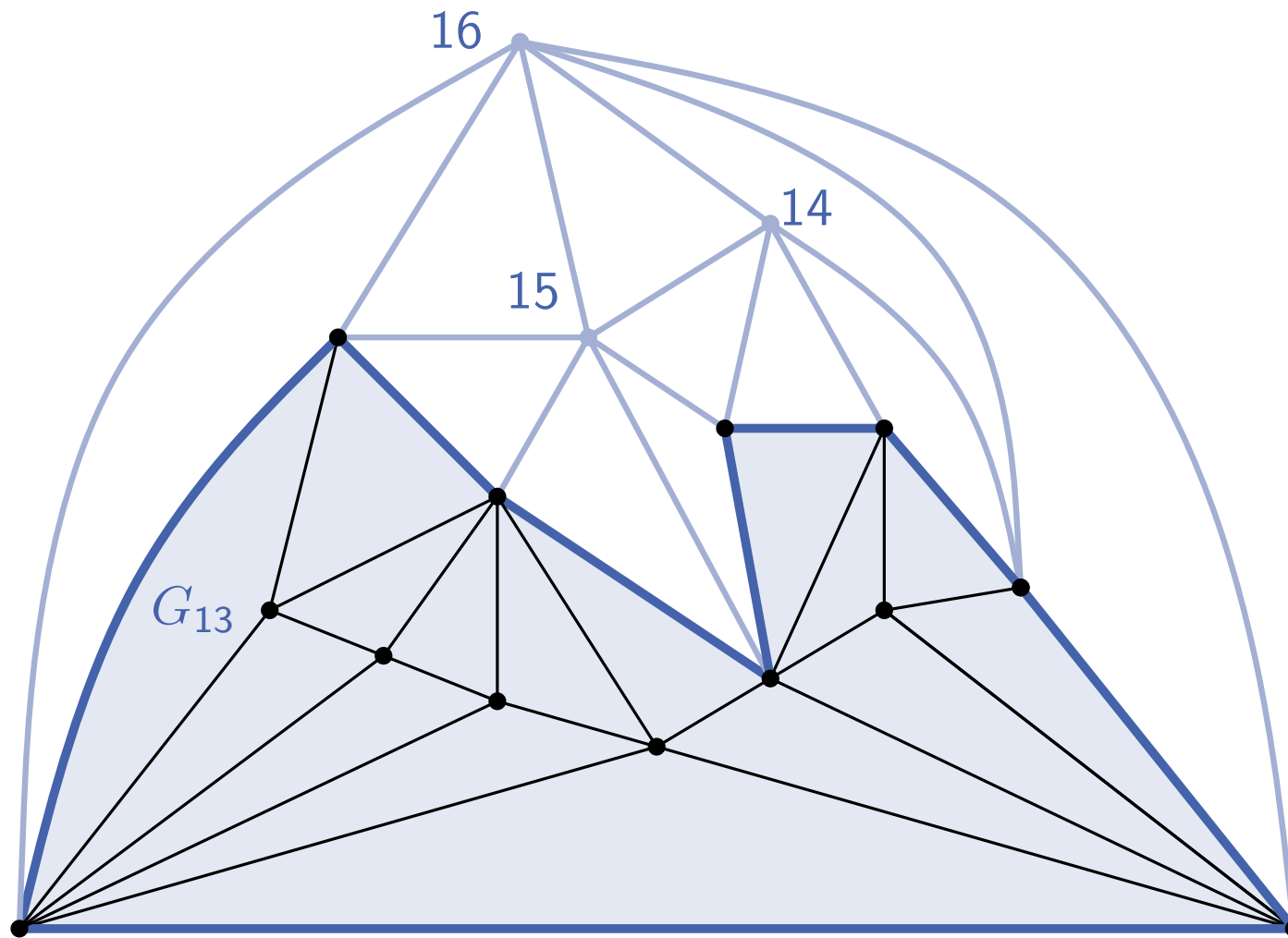
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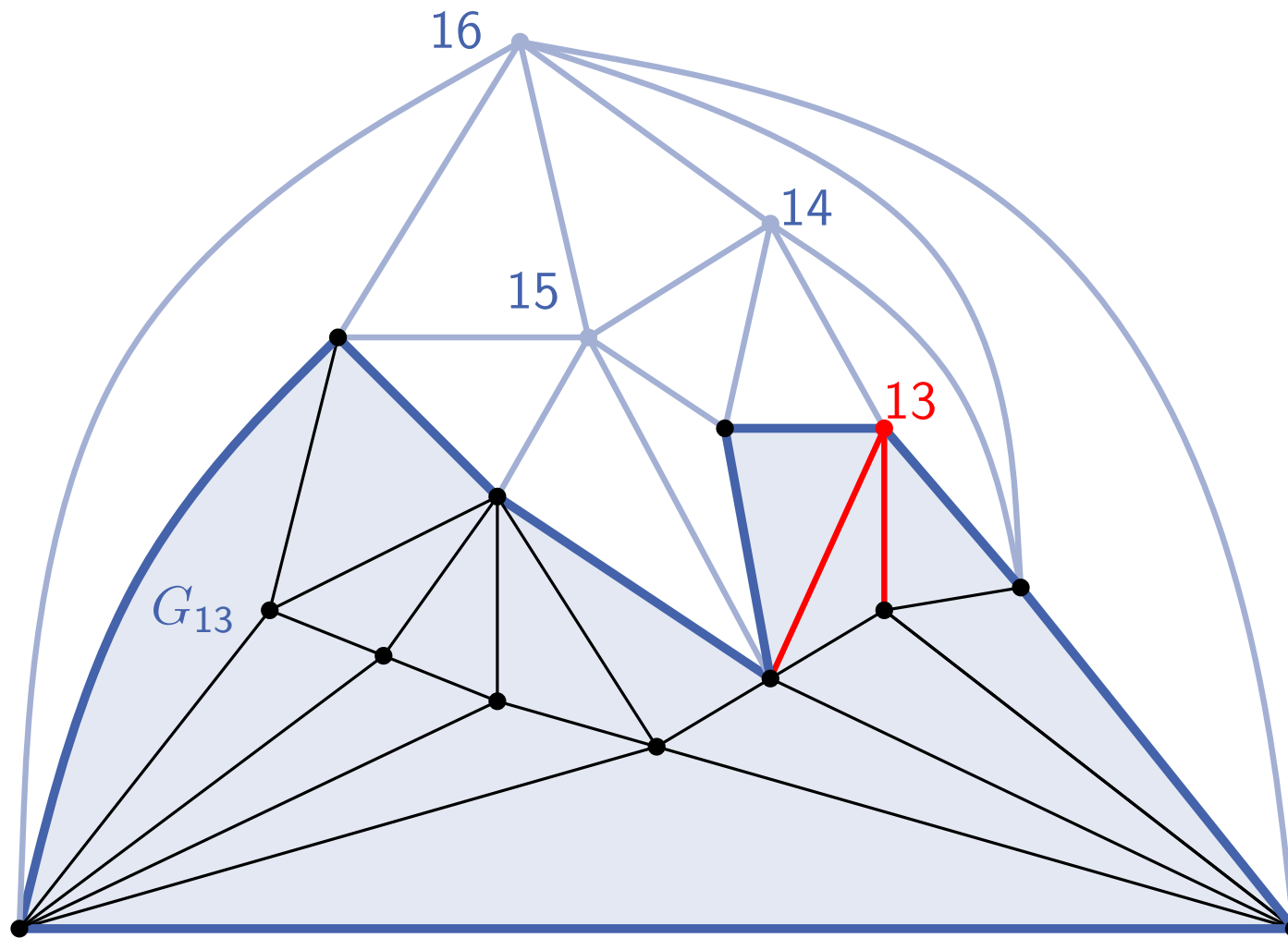
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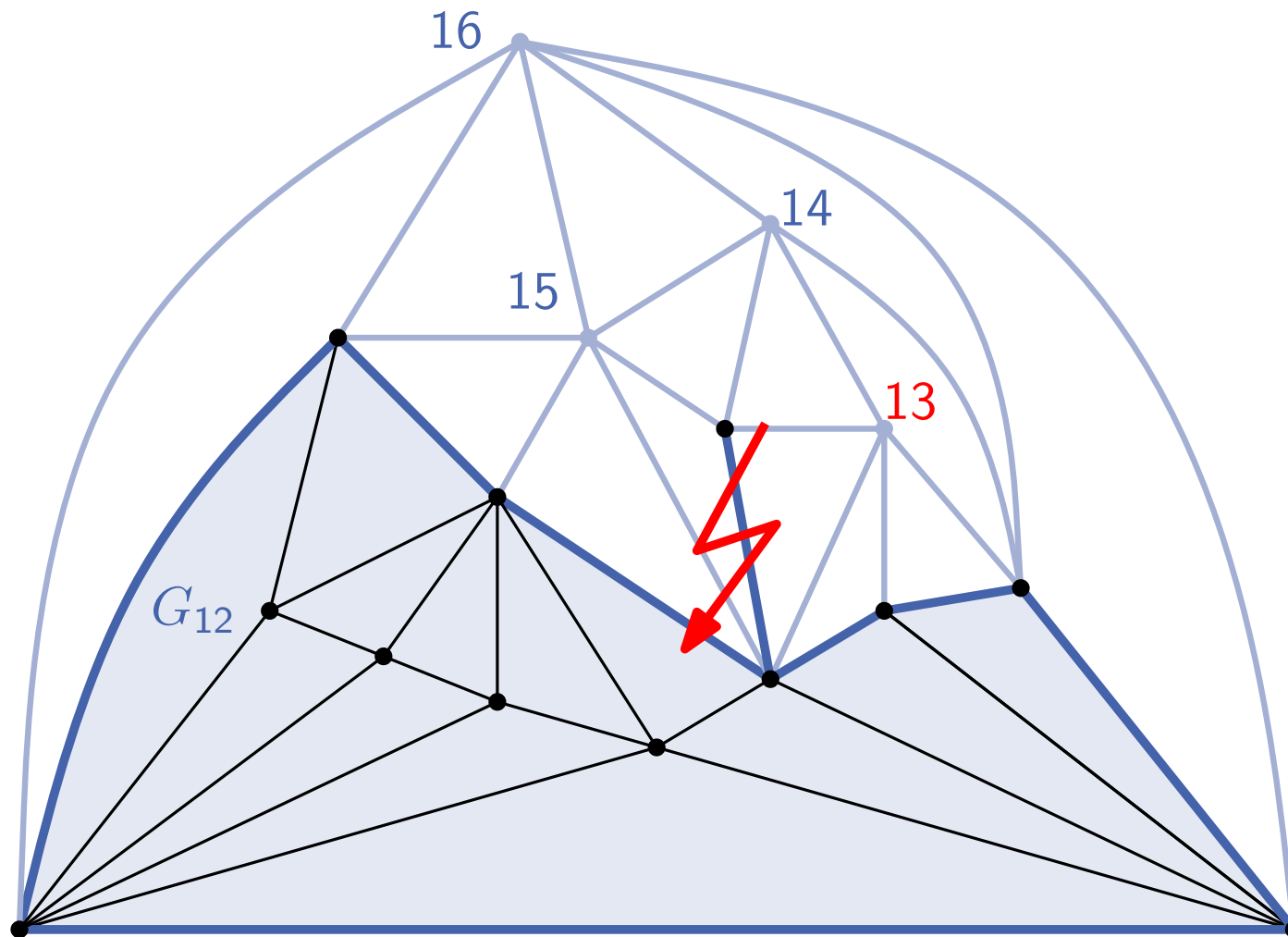
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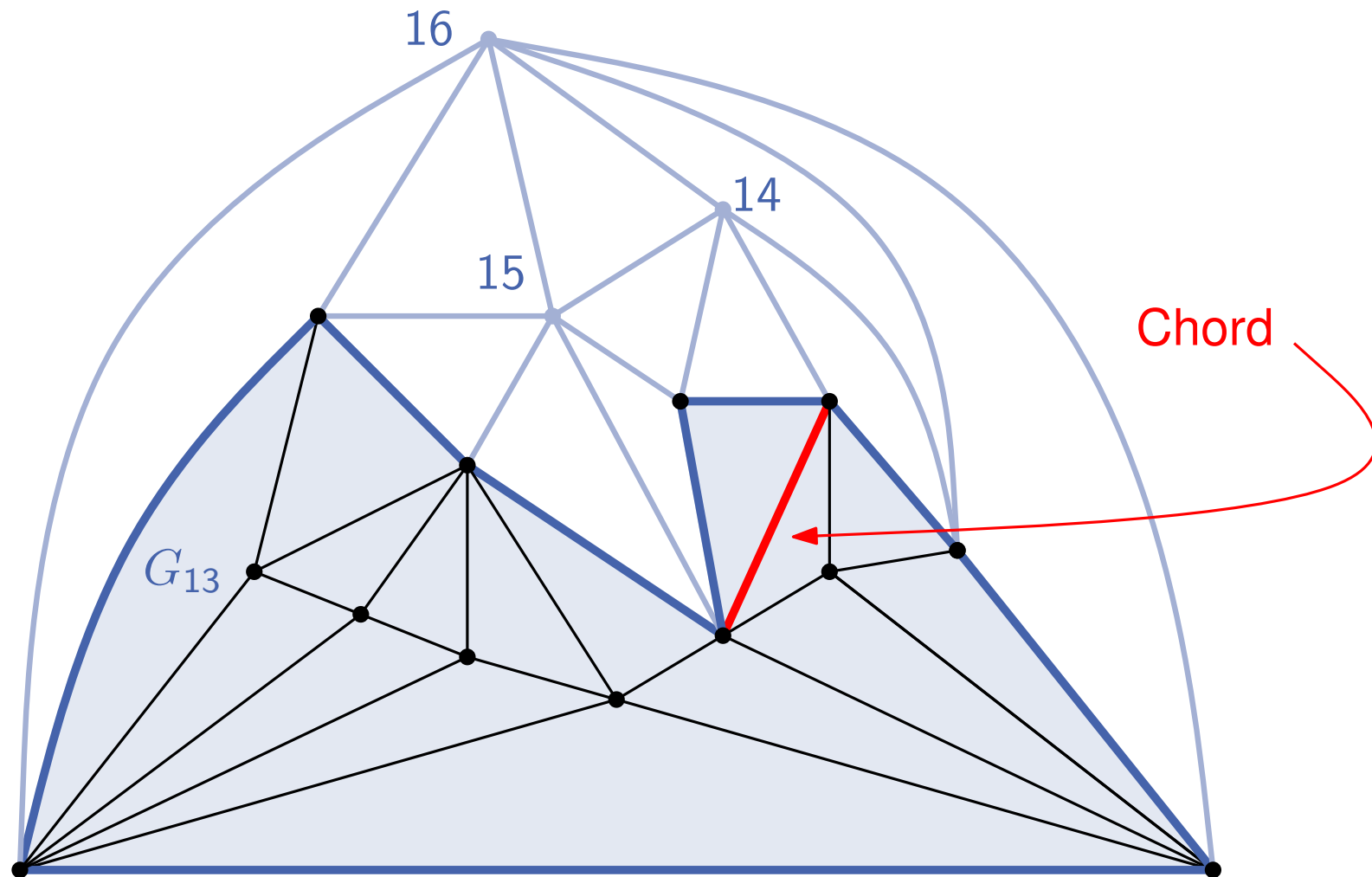
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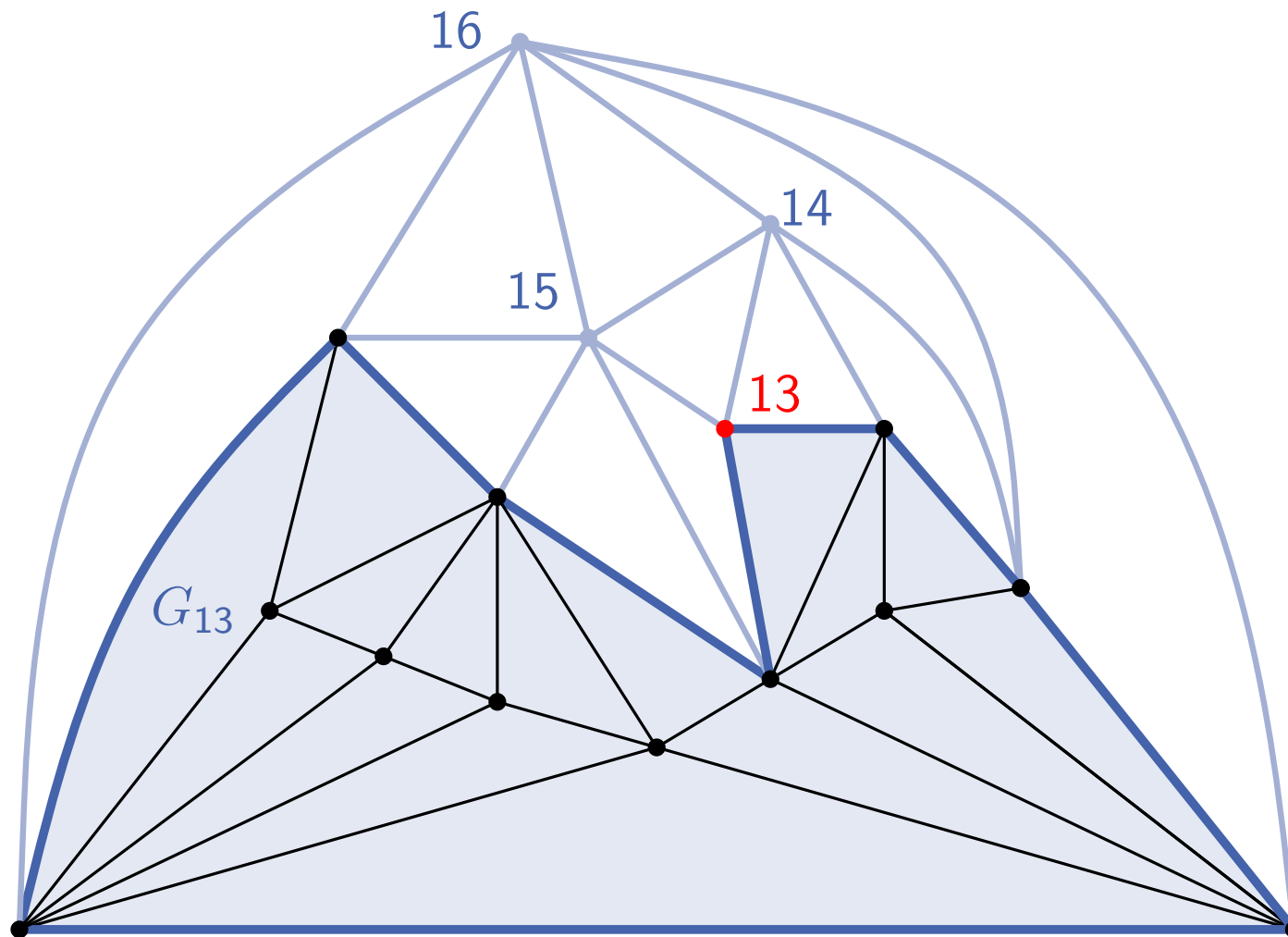
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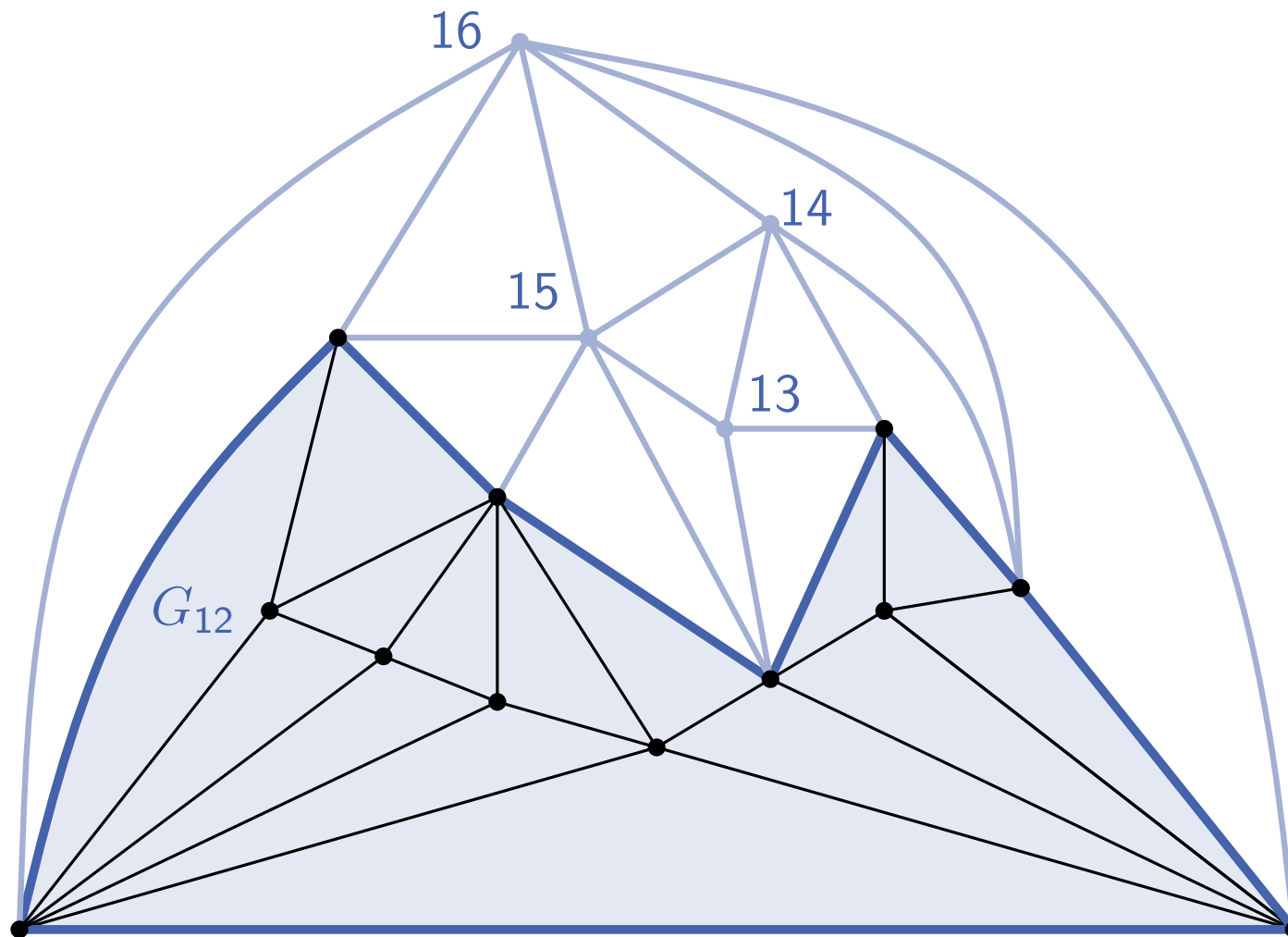
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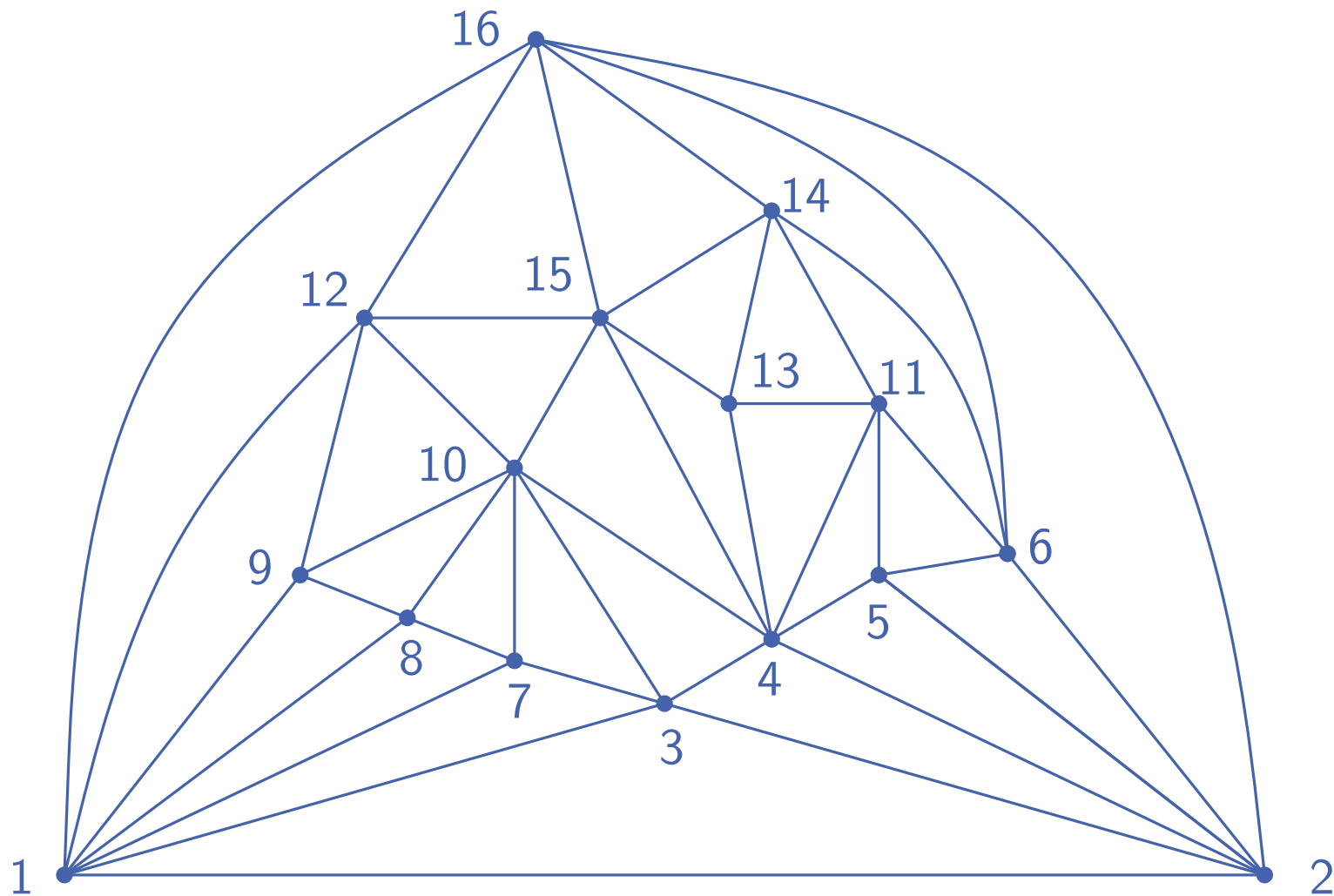
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Lemma

Every triangulated plane graph has a canonical ordering.

- Let $G_n = G$, and let v_1, v_2, v_n be the vertices of the outer face of G_n . Conditions C1-C3 hold.

Lemma

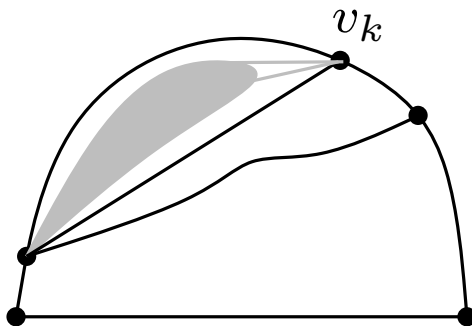
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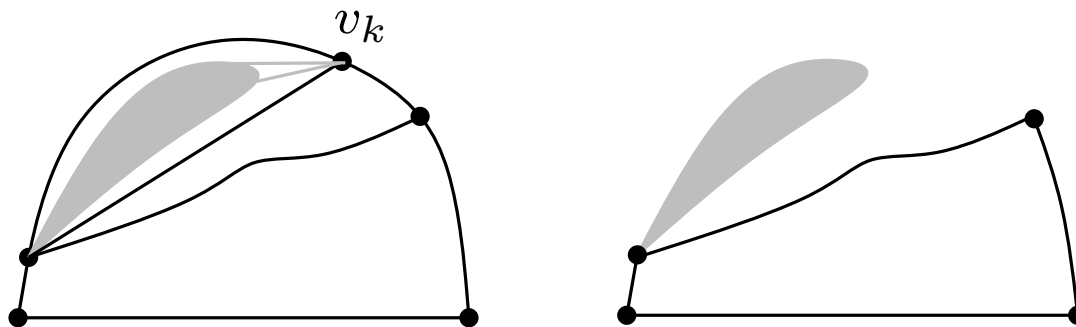
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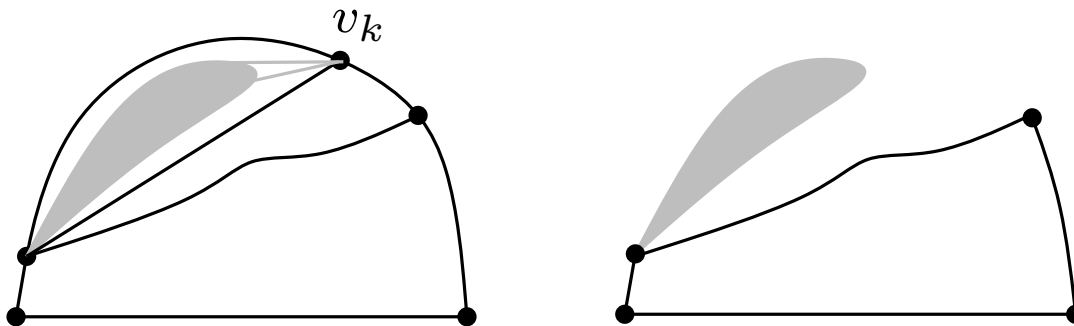
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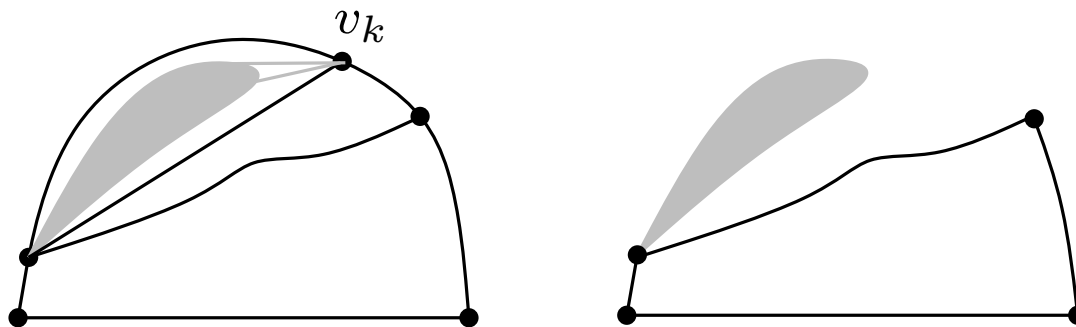
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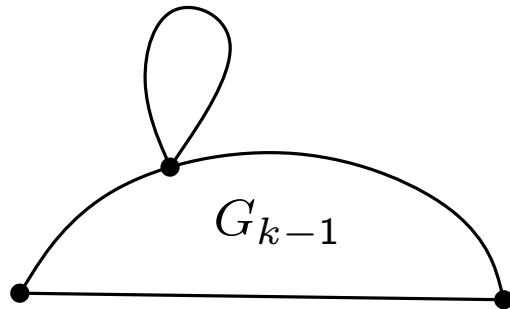
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Is it sufficient?

Canonical Ordering Existence

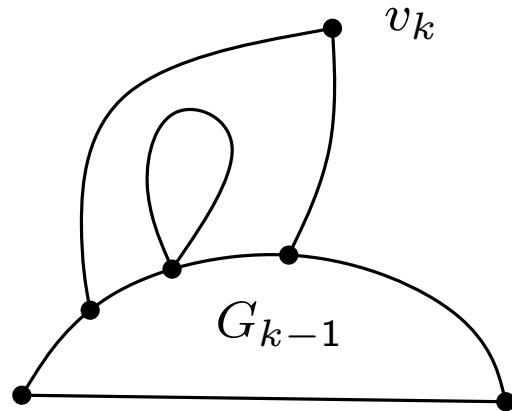
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• v_k



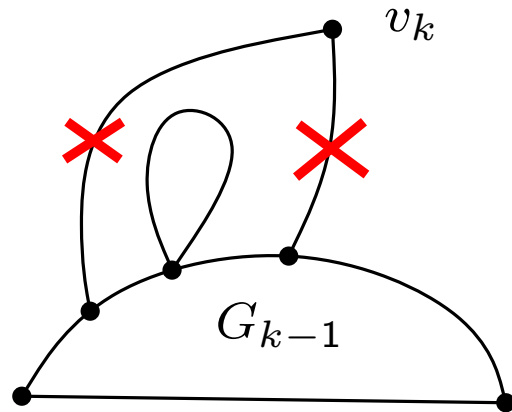
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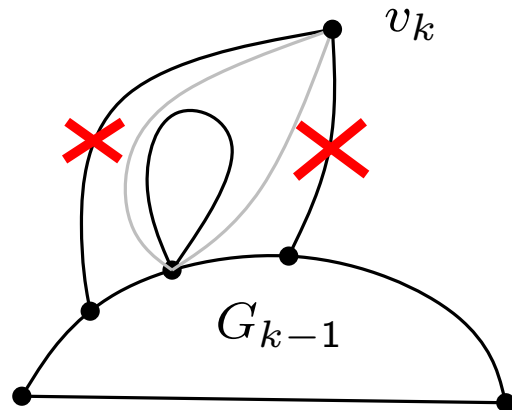
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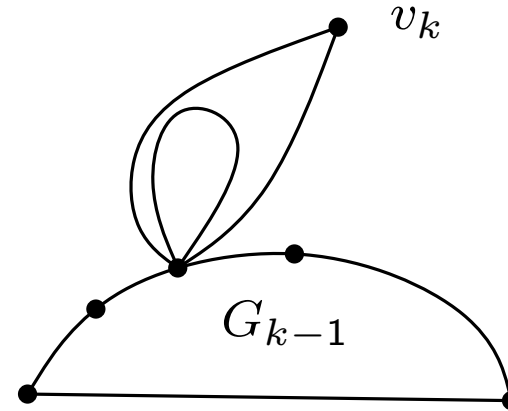
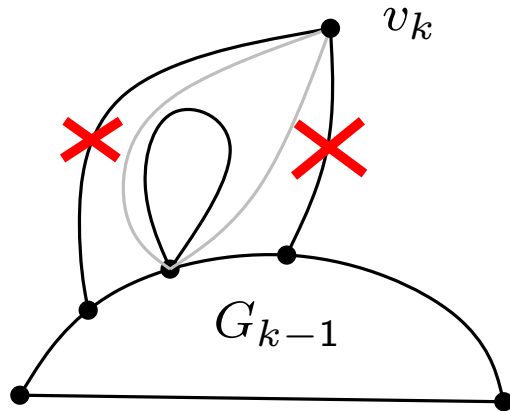
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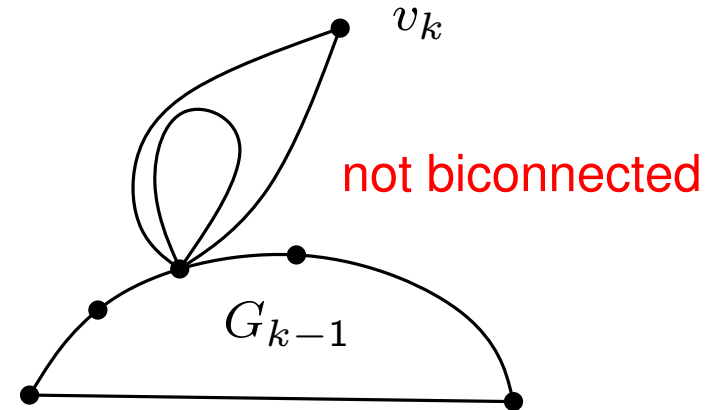
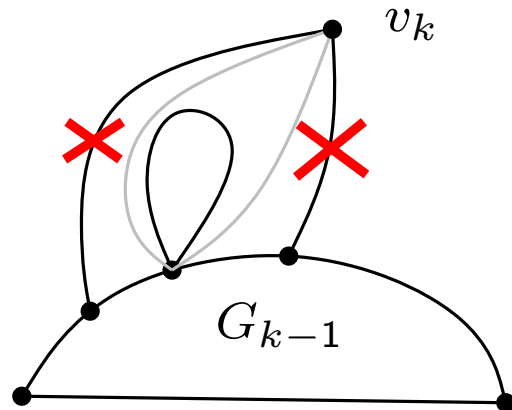
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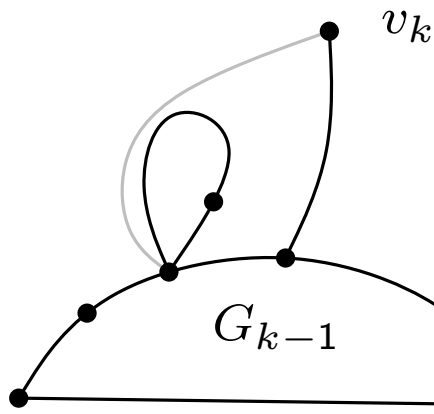
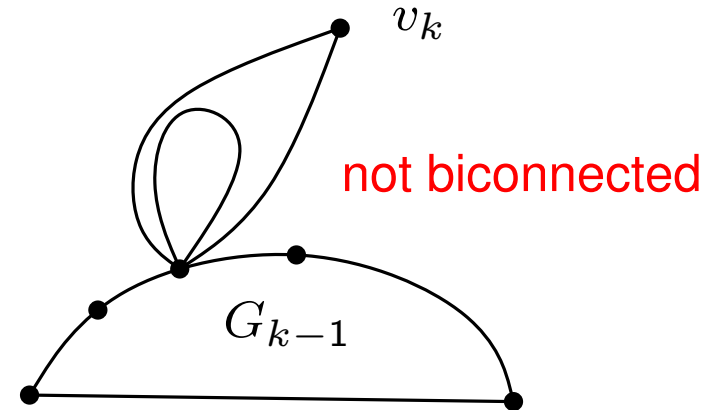
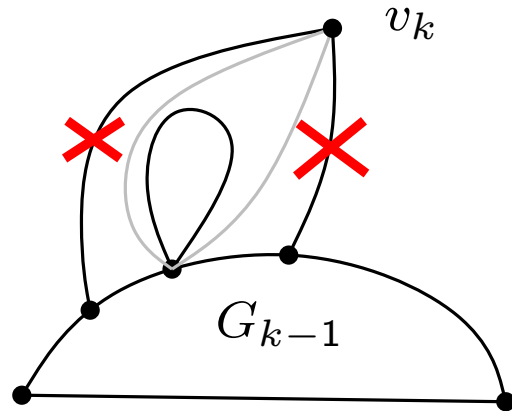
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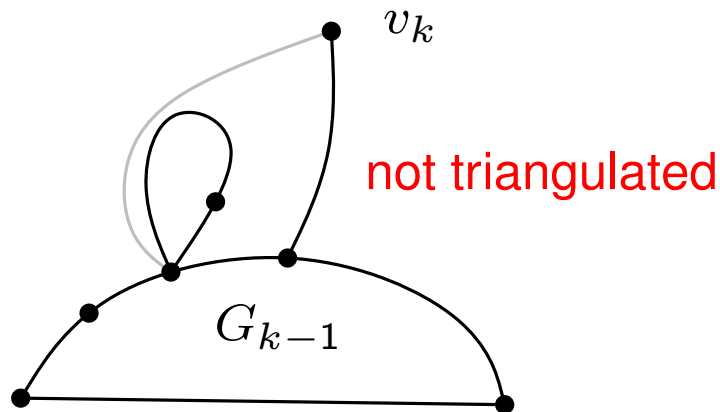
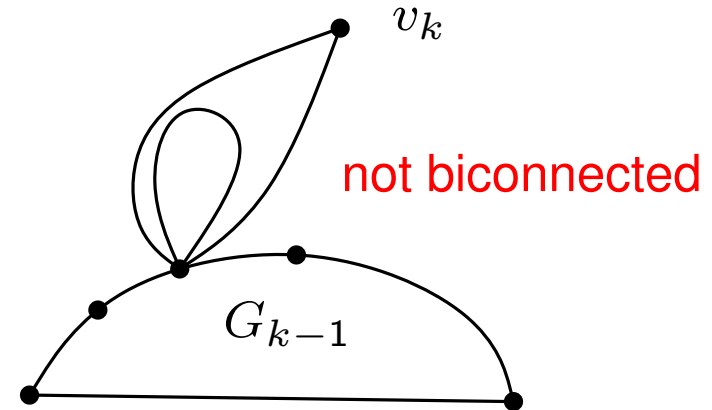
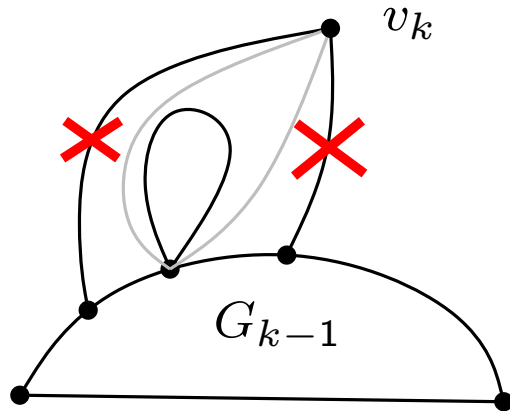
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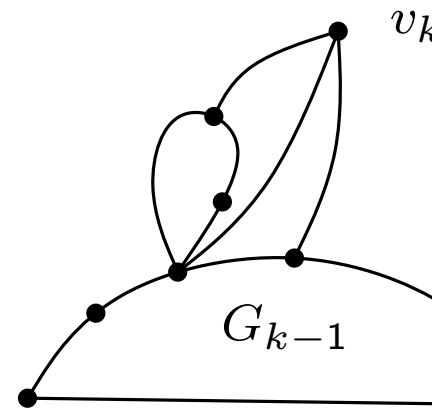
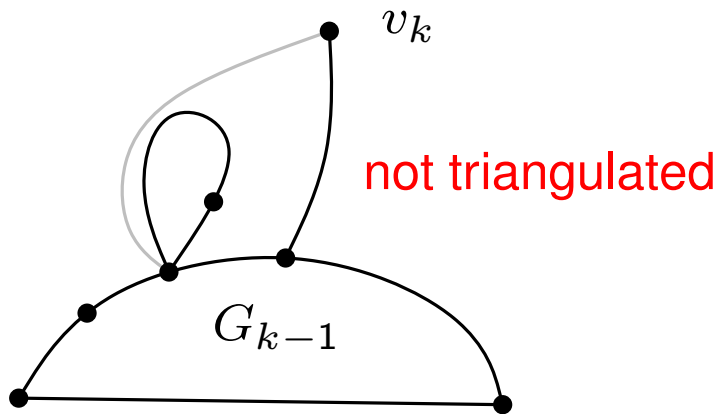
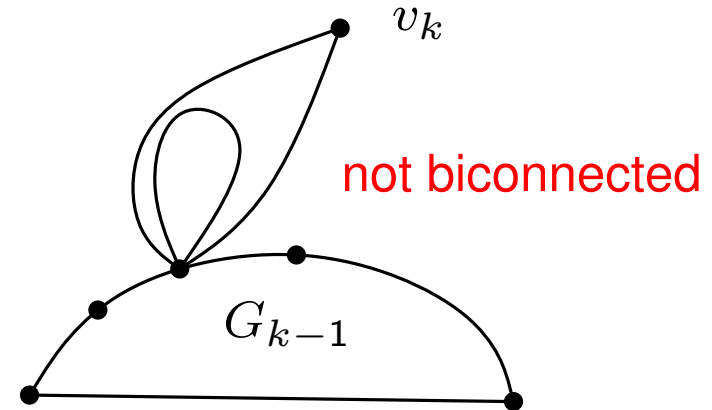
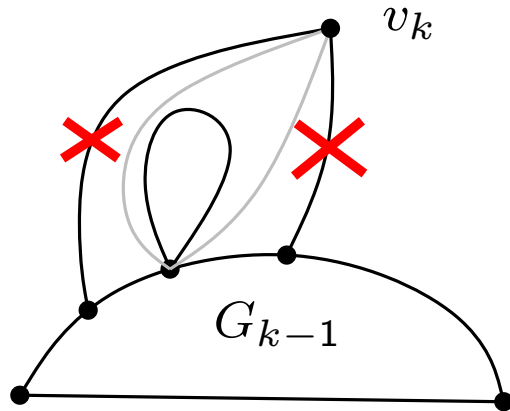
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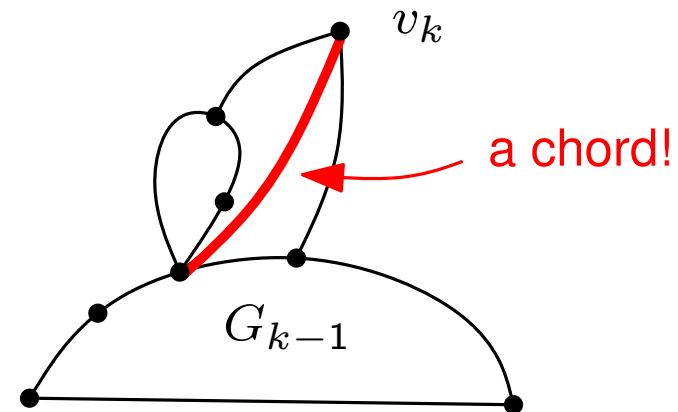
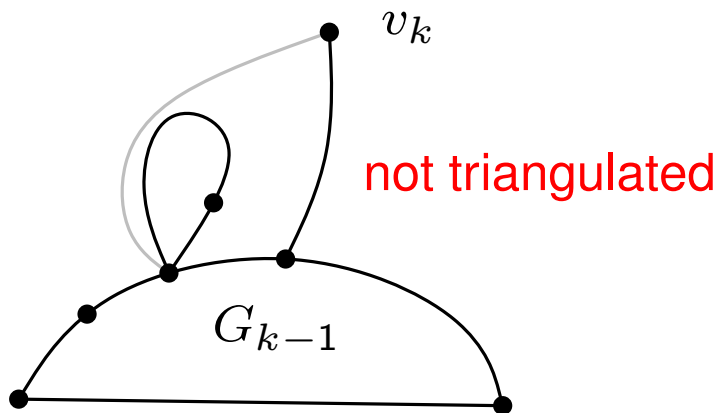
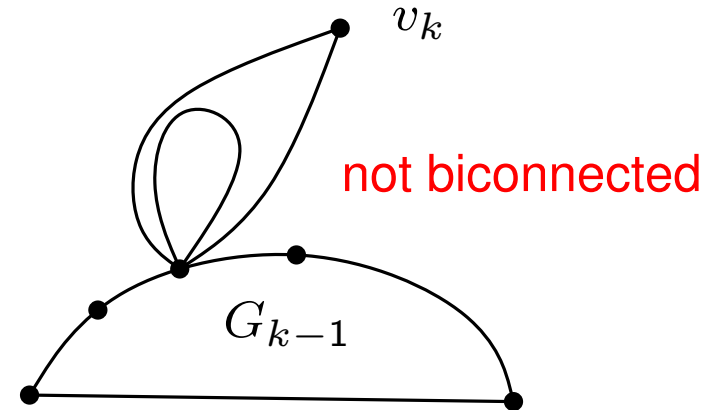
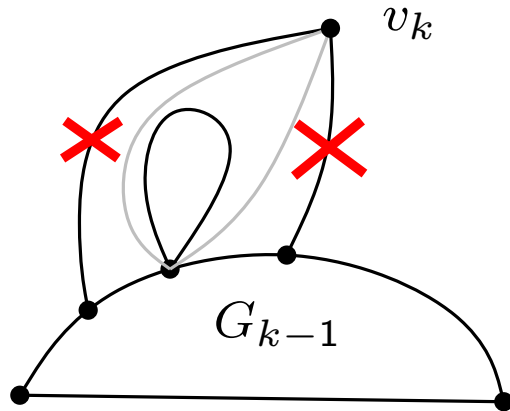
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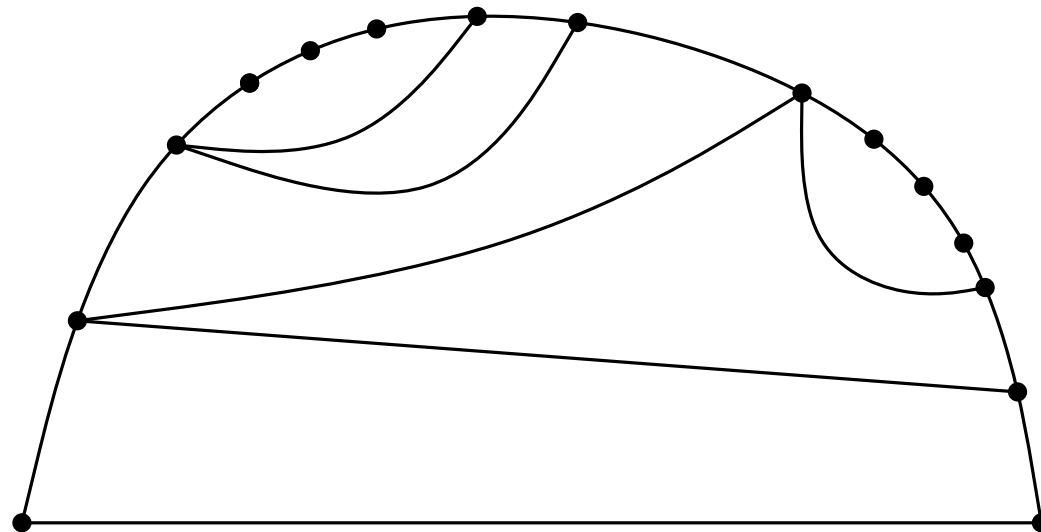
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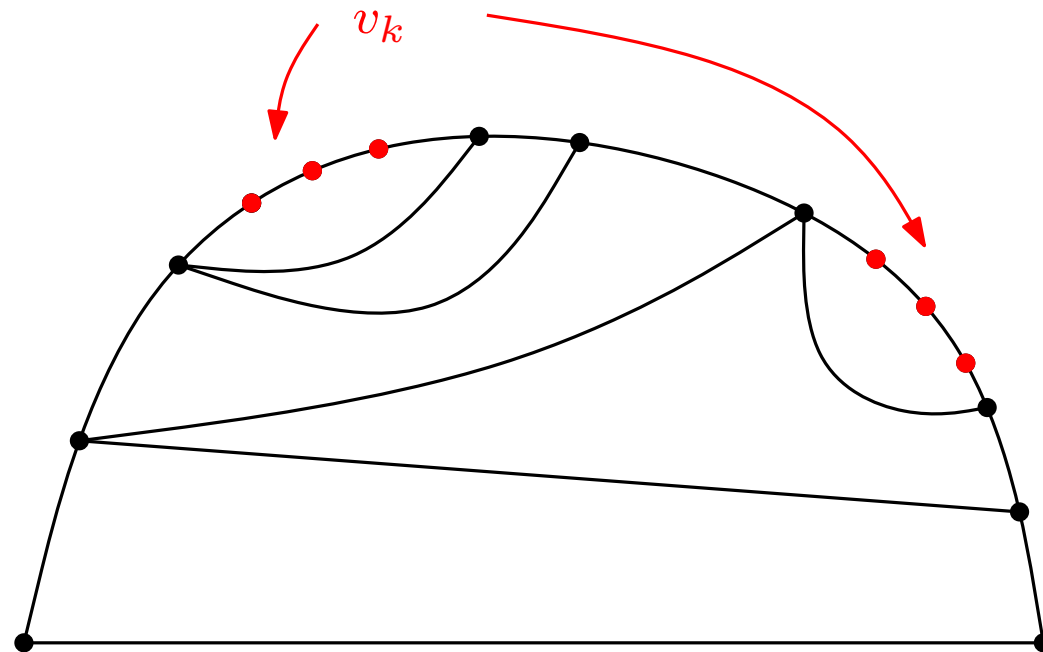
Canonical Ordering Existence

- Why a vertex not adjacent to a chord exists?



Canonical Ordering Existence

- Why a vertex not adjacent to a chord exists?



Algorithm CO

forall the $v \in V$ do

┌ chords(v) \leftarrow 0; out(v) \leftarrow false; mark(v) \leftarrow false;

out(v_1), out(v_2), out(v_n) \leftarrow true;

for $k = n$ to 3 do

┌ choose $v \neq v_1, v_2$ such that mark(v) = false, out(v) = true,
 chords(v) = 0;

$v_k \leftarrow v$; mark(v) \leftarrow true;

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and let w_p, \dots, w_q be the unmarked neighbors v_k ;

out(w_i) \leftarrow true for all $p < i < q$;

┌ update number of chords for w_i and its neighbors;

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  out( $w_i$ )  $\leftarrow$  true for all  $p < i < q$ ;  
  update number of chords for  $w_i$  and its neighbors;
```

- chord(v) - number of chords adjacent to v
- mark(v) = true iff vertex v was numbered
- out(v)=true iff v is the outer vertex of current plane graph

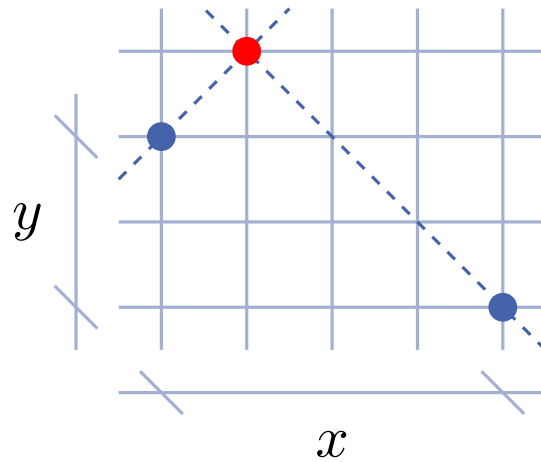
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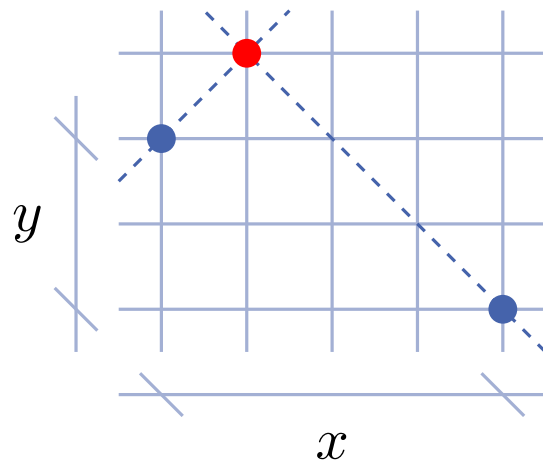
Lemma

Algorithm CO computes a canonical ordering of a graph in $O(n)$ time.

De Fraysseix Pach Pollack (Shift) Algorithm

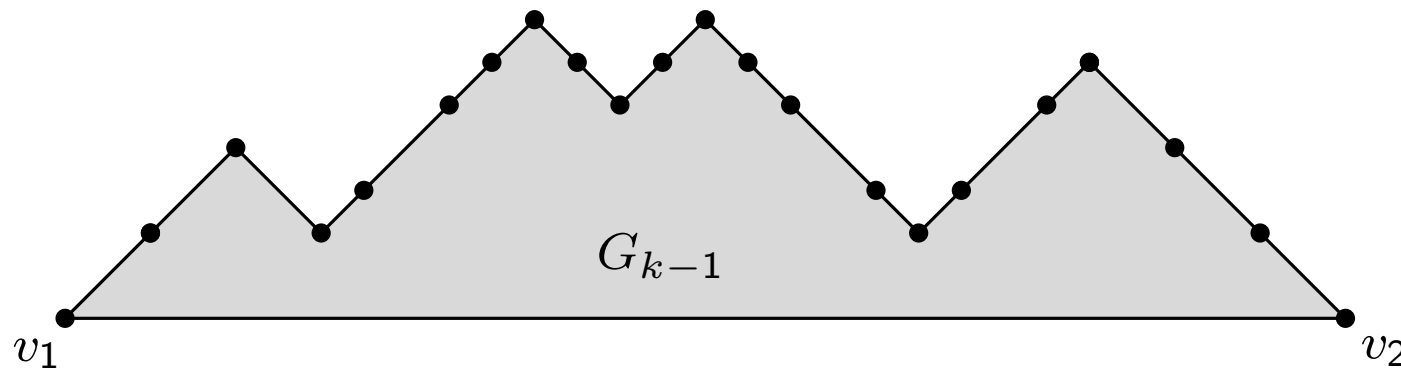


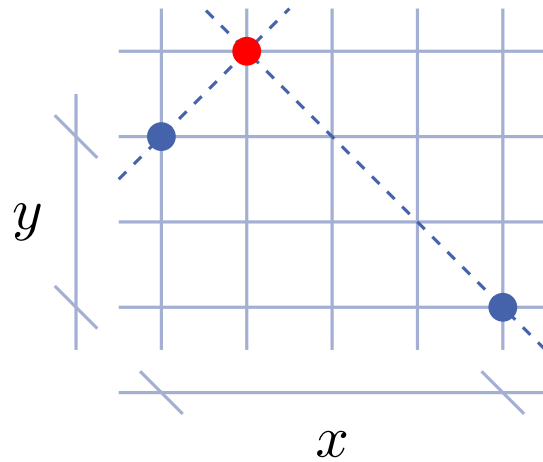
De Fraysseix Pach Pollack (Shift) Algorithm



Algorithm constraints: G_{k-1} is drawn such that

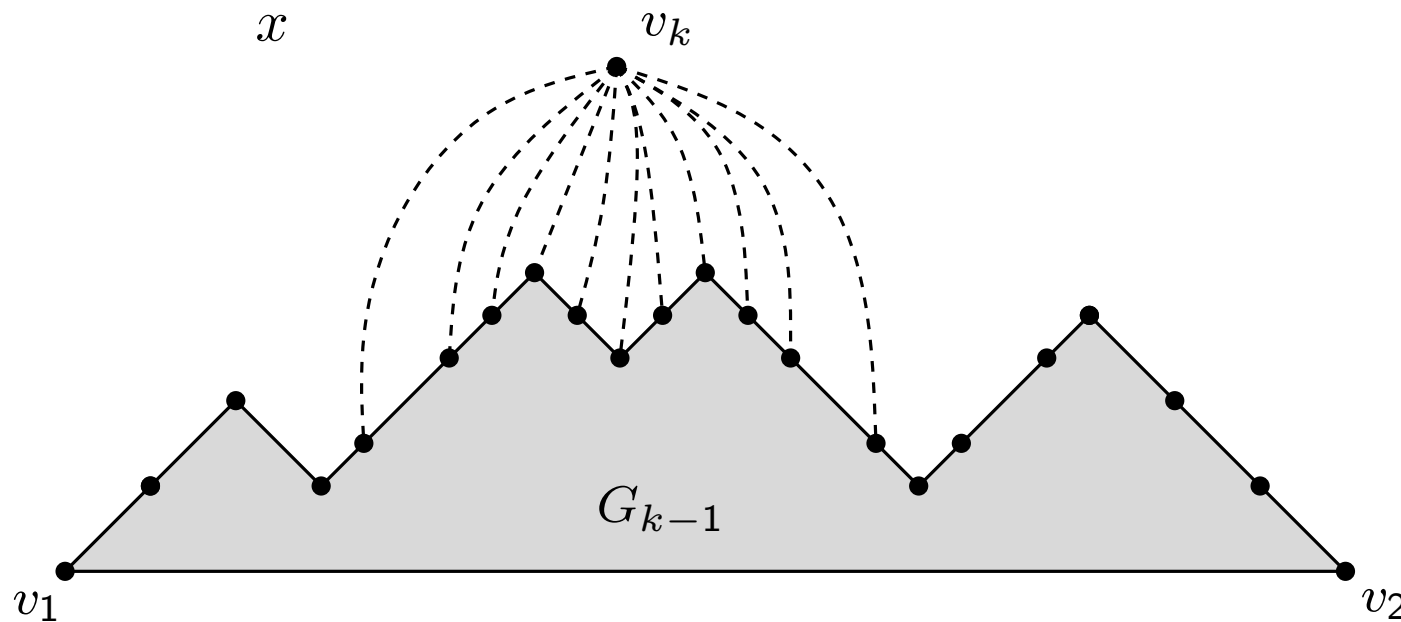
- v_1 is on $(0, 0)$, v_2 is on $(2k - 6, 0)$
- Boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone
- Each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1



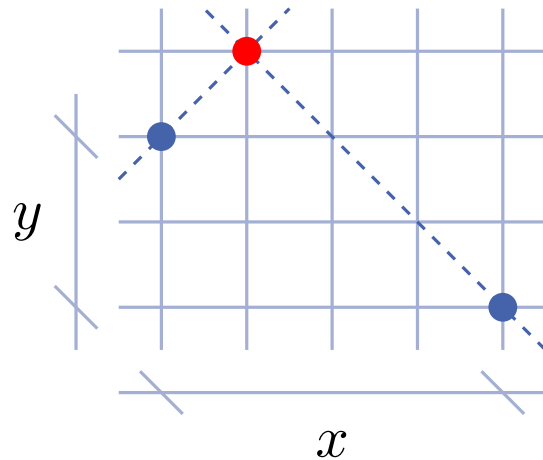


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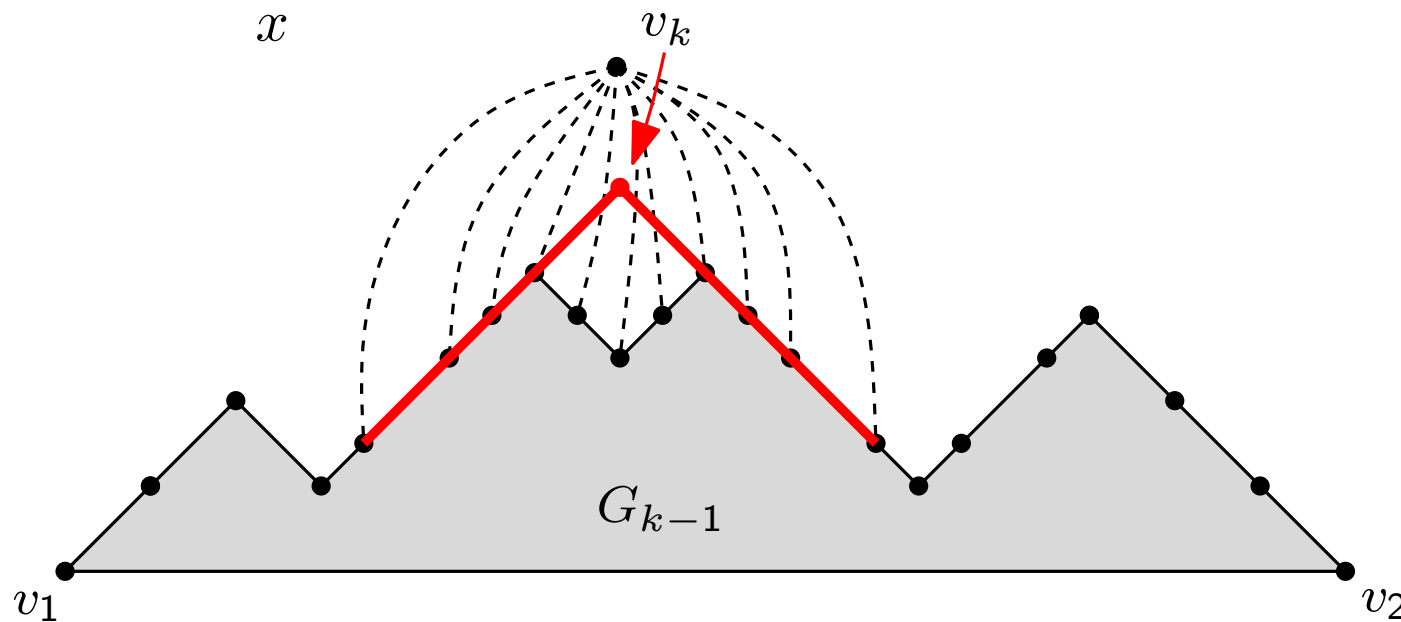


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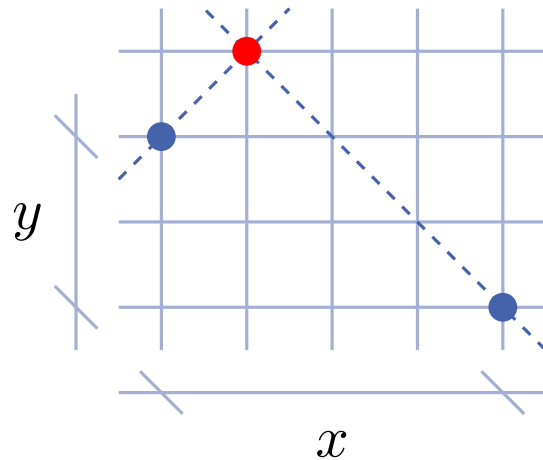


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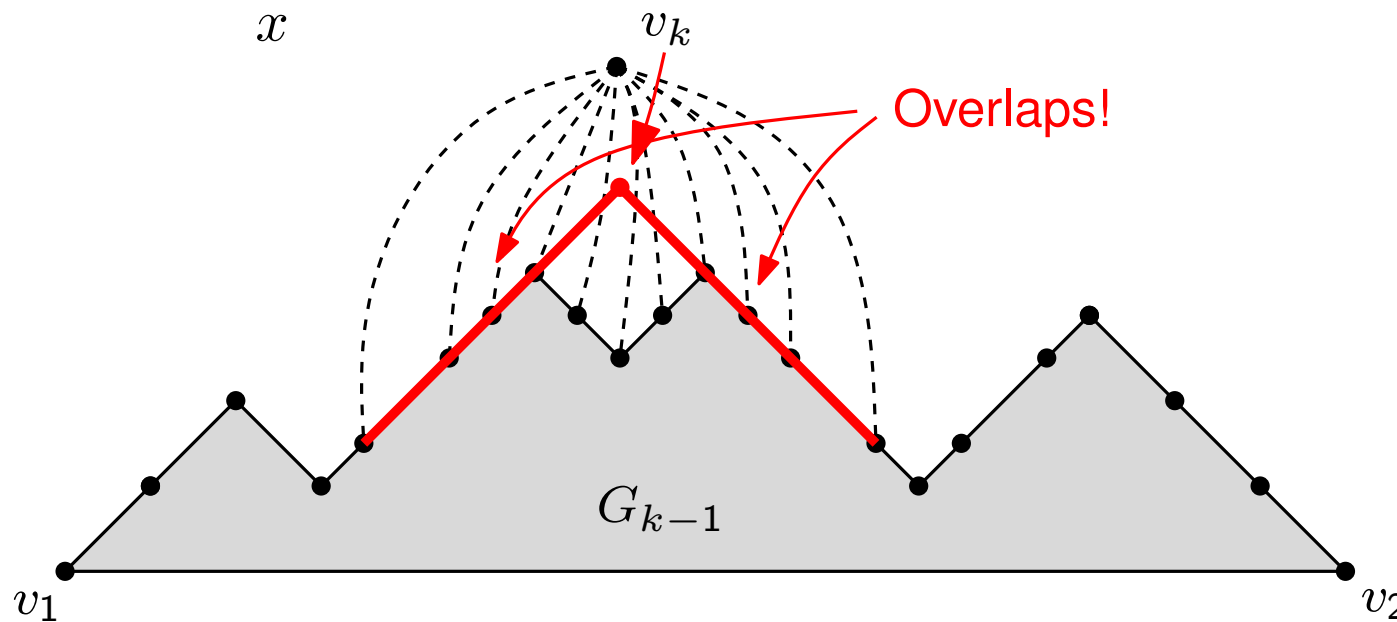


De Fraysseix Pach Pollack (Shift) Algorithm

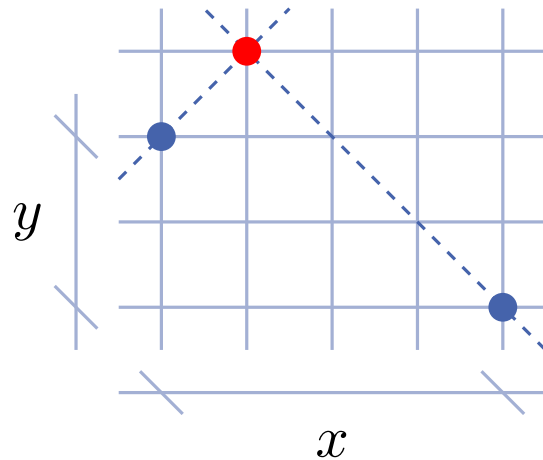


Algorithm constraints: G_{k-1} is drawn such that

- v_1 is on $(0, 0)$, v_2 is on $(2k - 6, 0)$
- Boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone
- Each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1

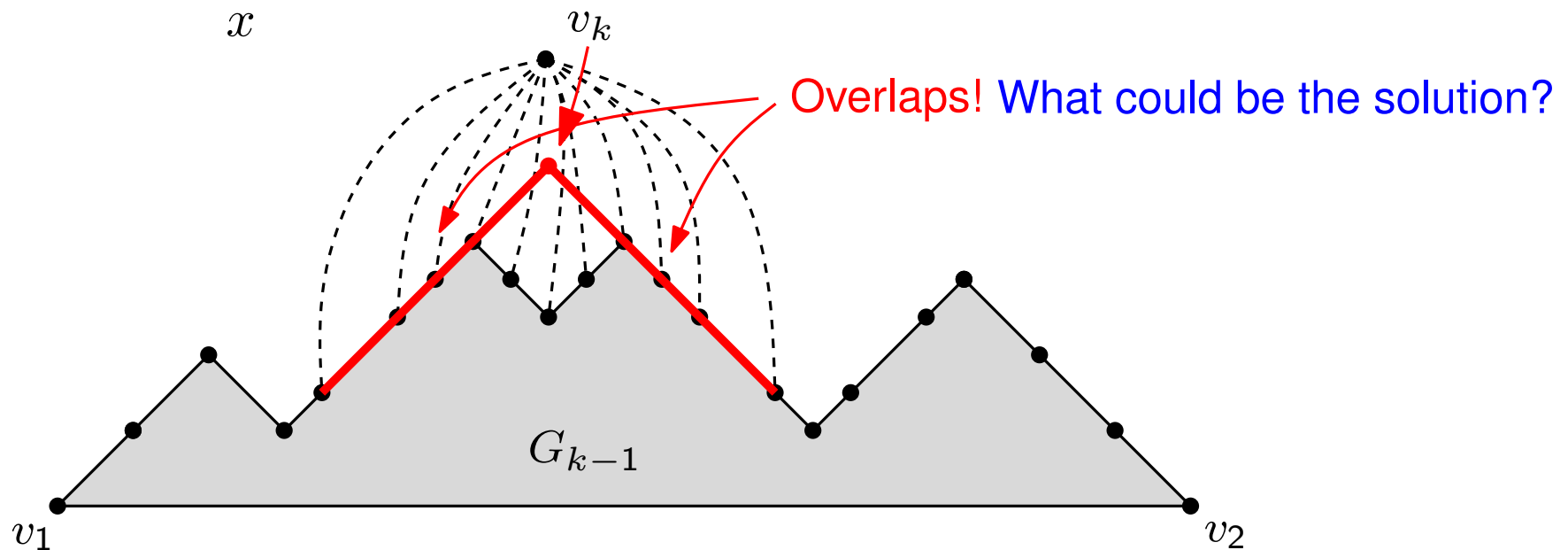


De Fraysseix Pach Pollack (Shift) Algorithm

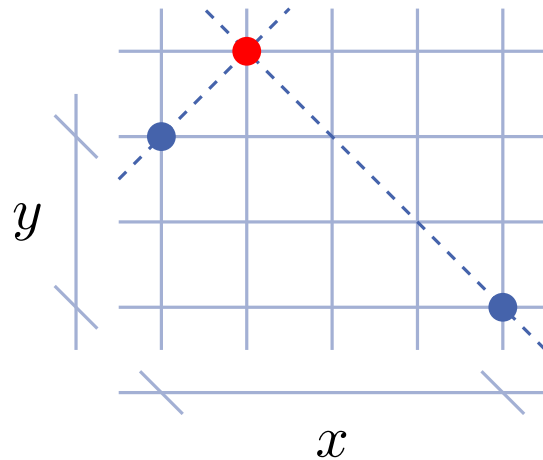


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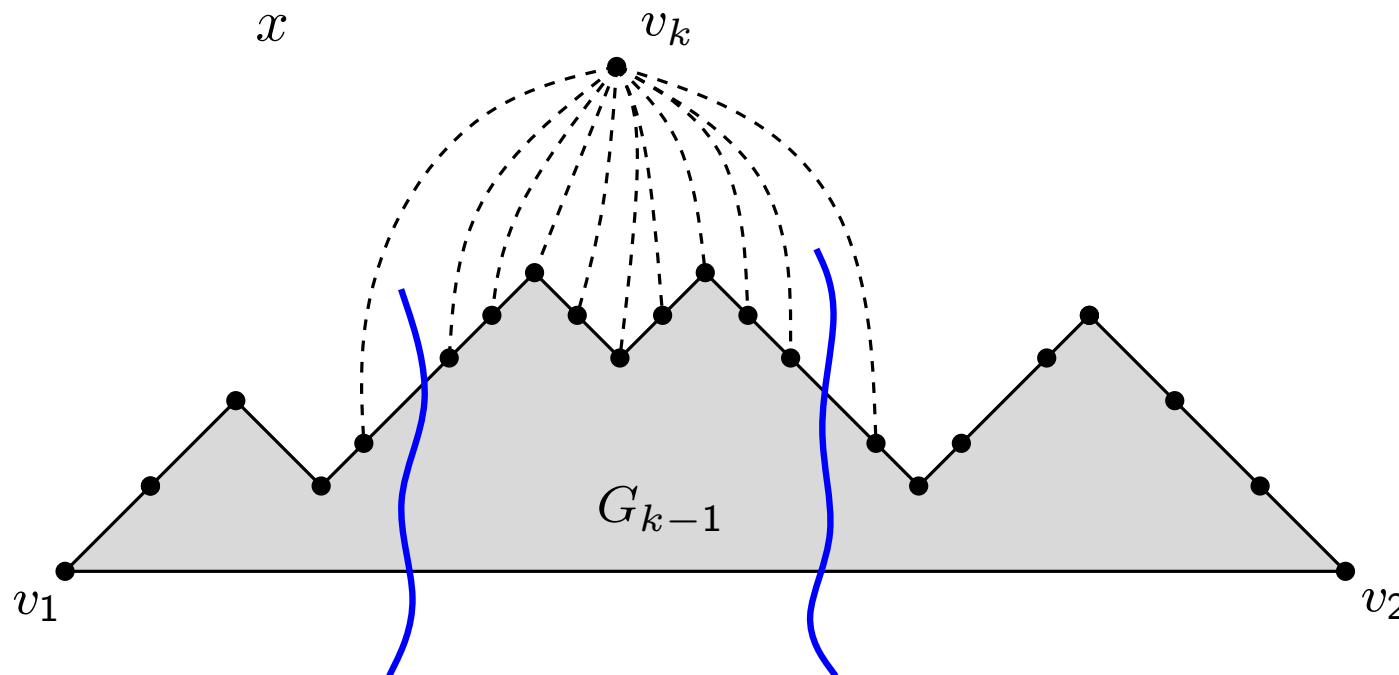


De Fraysseix Pach Pollack (Shift) Algorithm

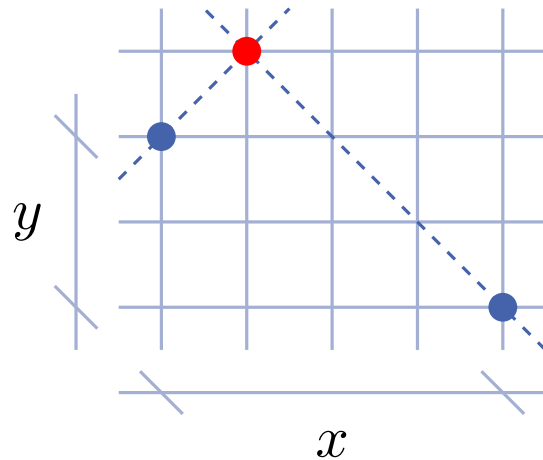


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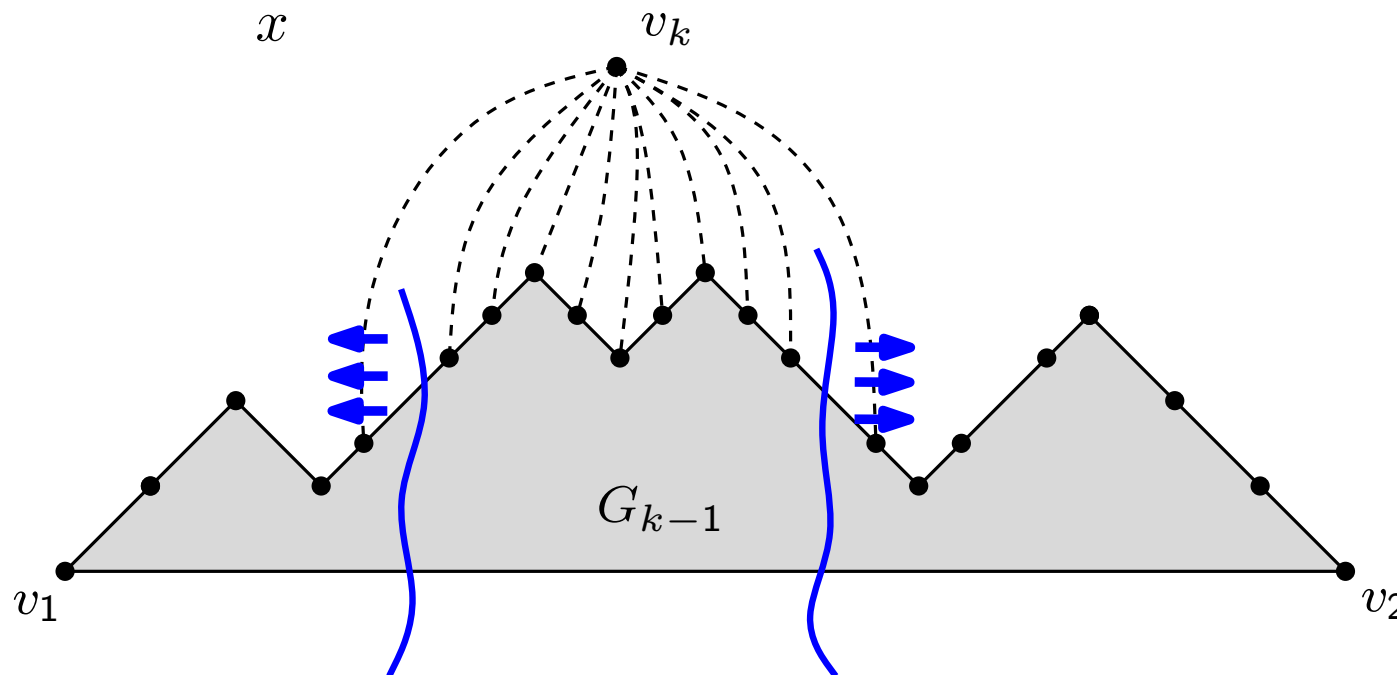


De Fraysseix Pach Pollack (Shift) Algorithm

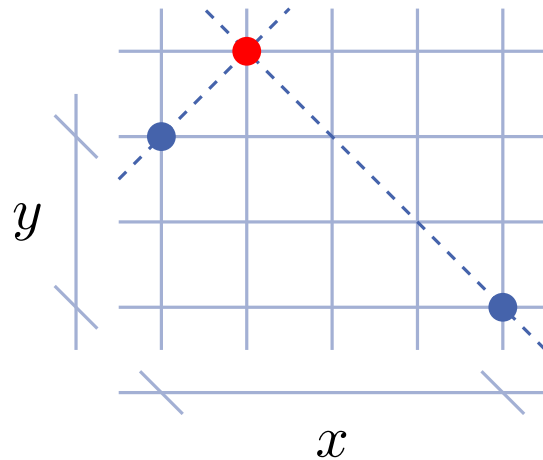


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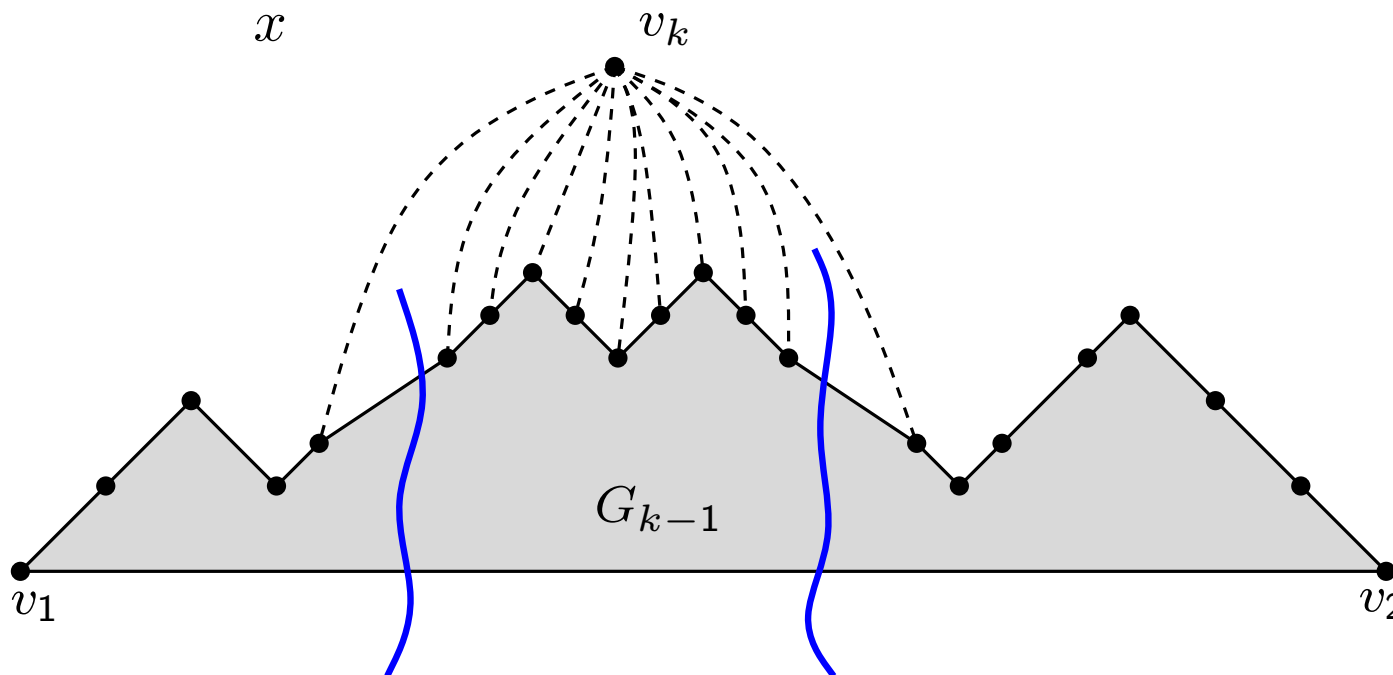


De Fraysseix Pach Pollack (Shift) Algorithm

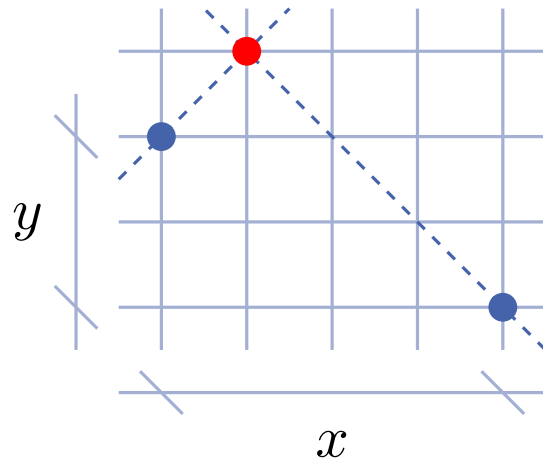


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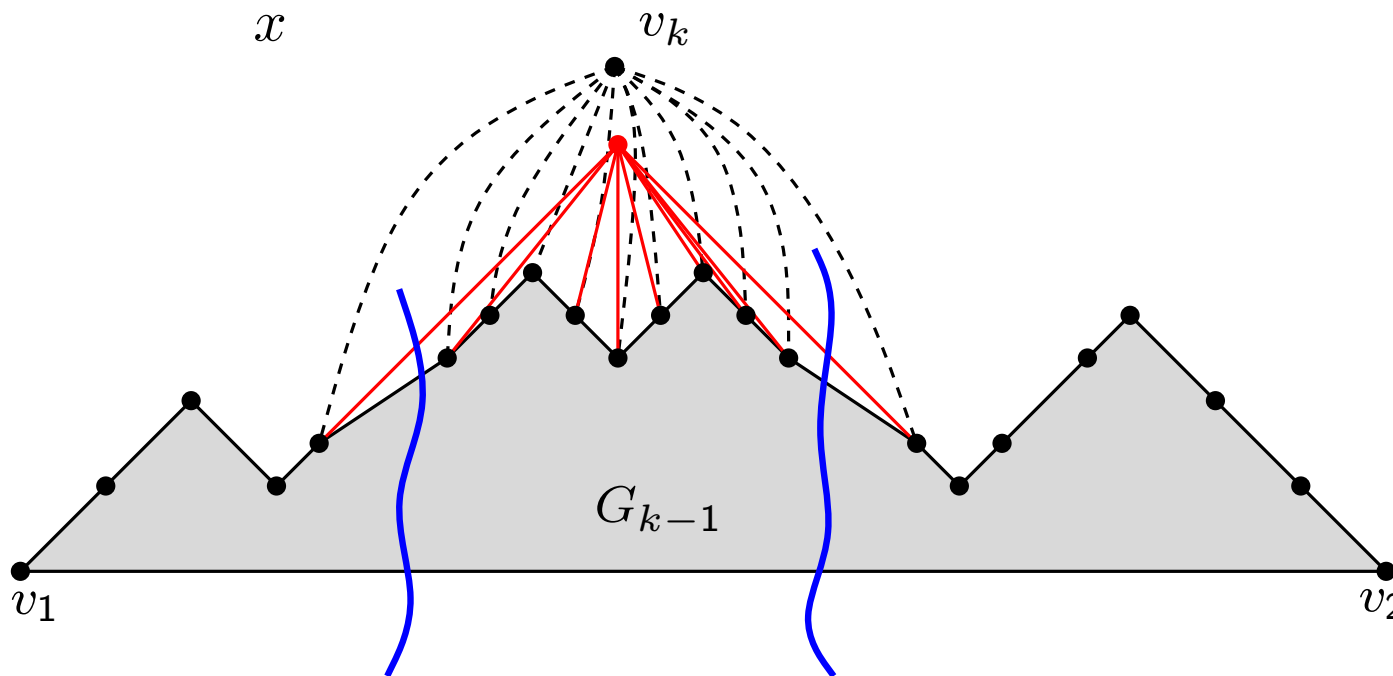


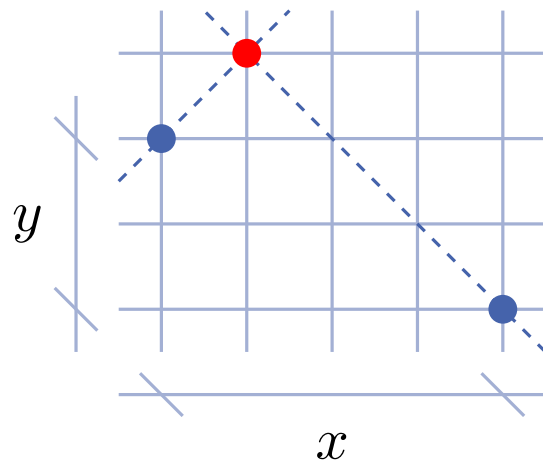
De Fraysseix Pach Pollack (Shift) Algorithm



Algorithm constraints: G_{k-1} is drawn such that

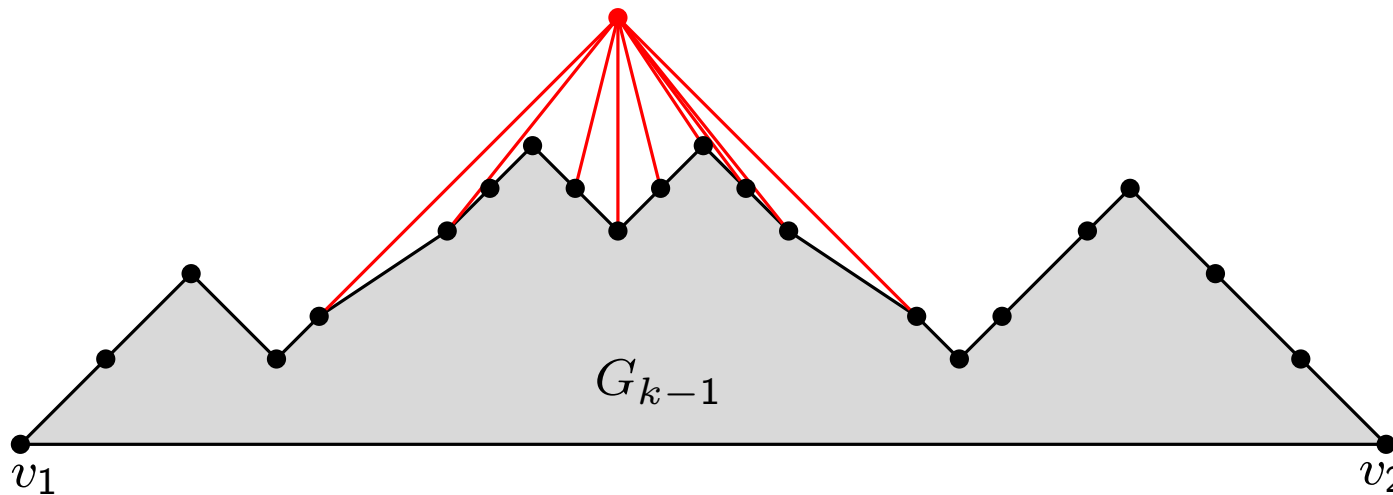
- v_1 is on $(0, 0)$, v_2 is on $(2k - 6, 0)$
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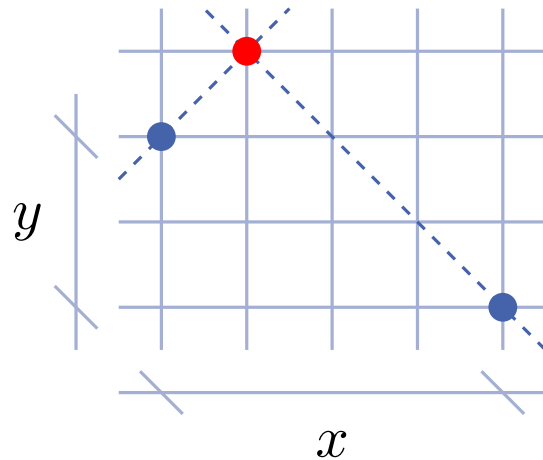


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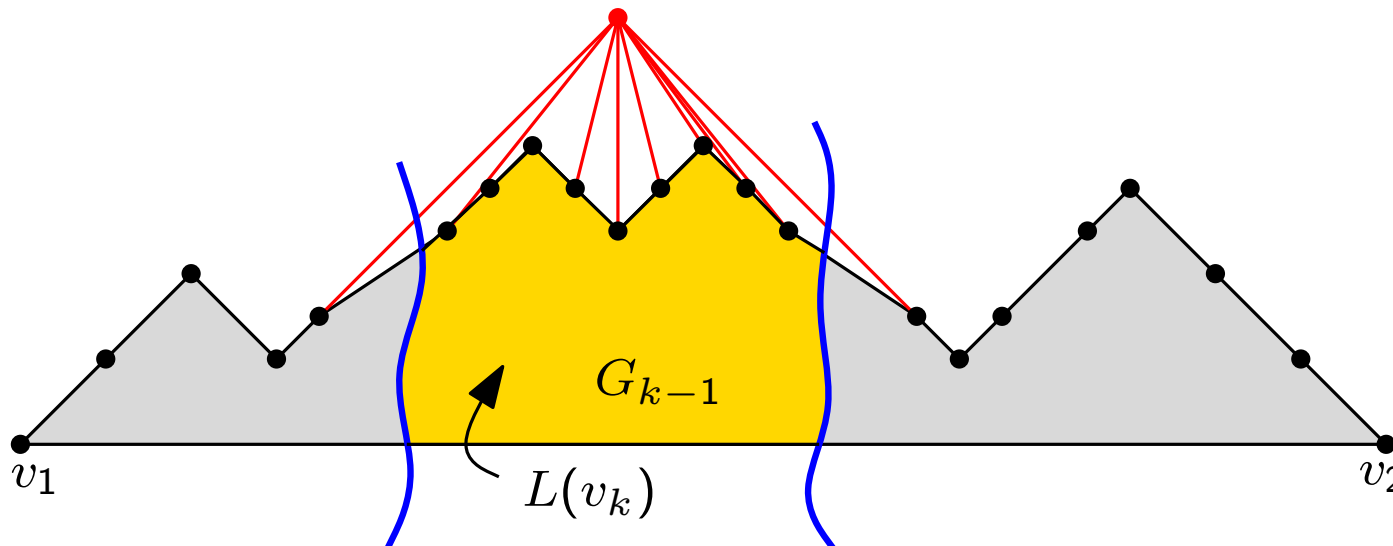


De Fraysseix Pach Pollack (Shift) Algorithm

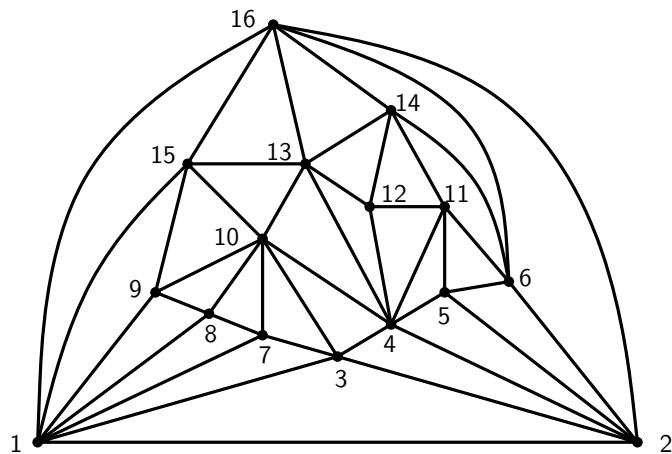
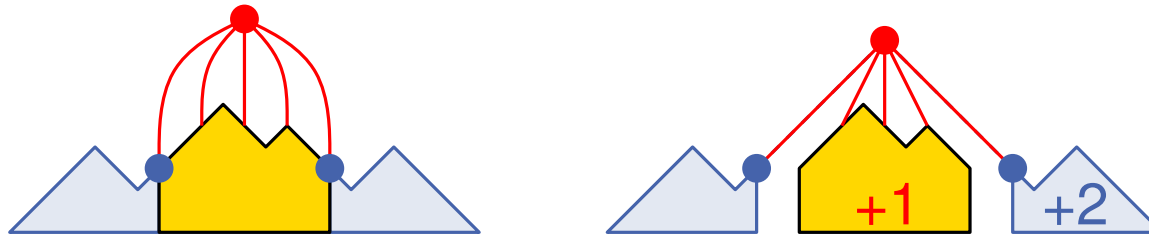


Algorithm constraints: G_{k-1} is drawn such that

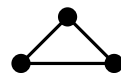
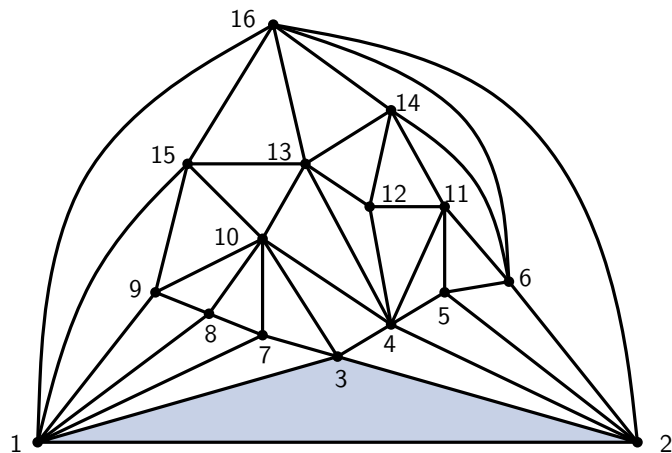
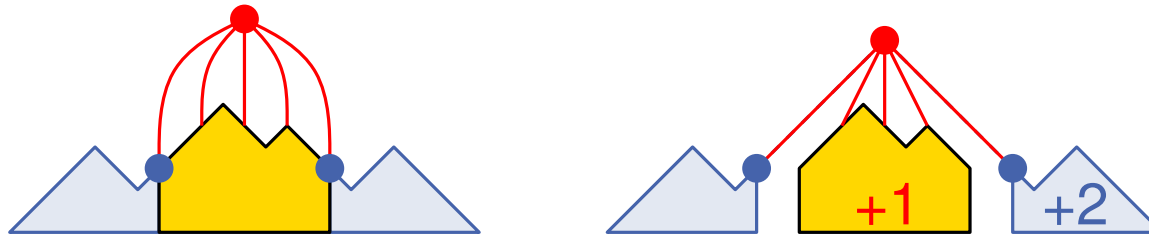
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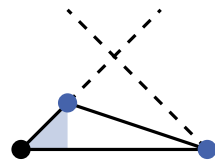
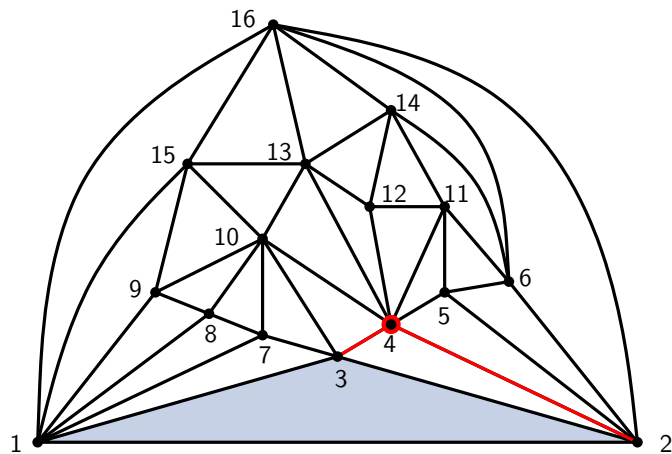
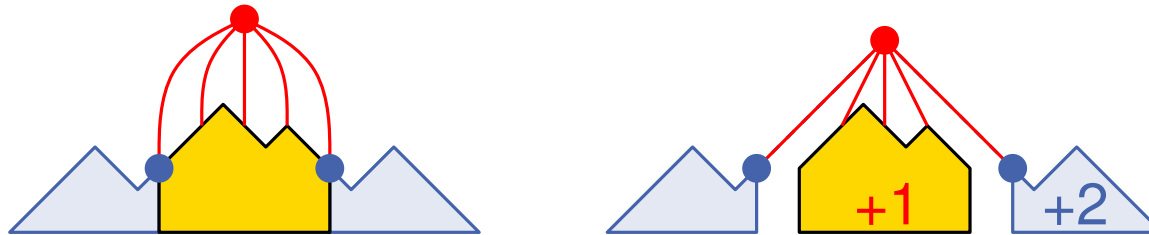
De Fraysseix Pach Pollack (Shift) Algorithm



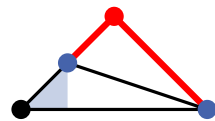
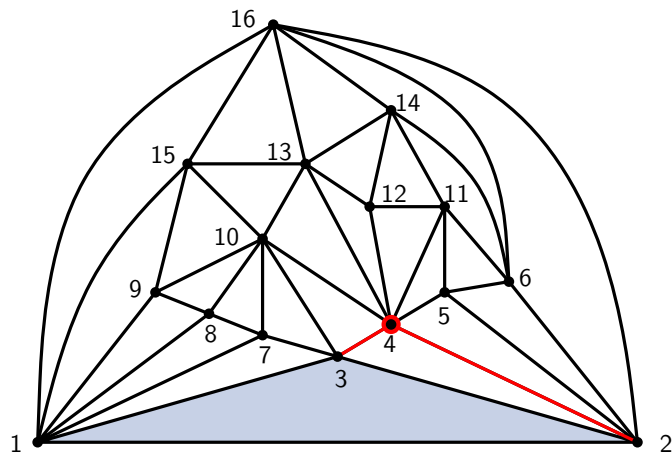
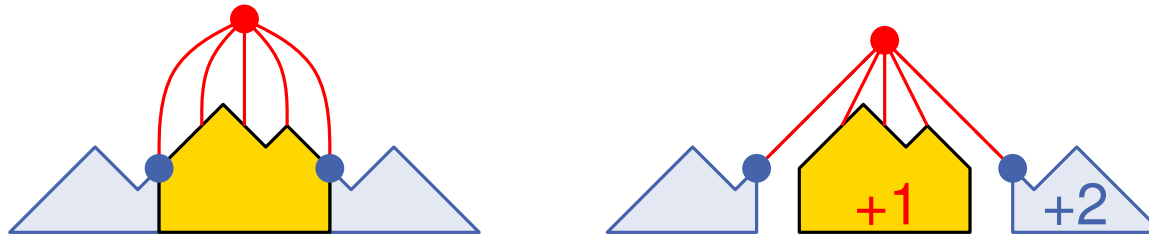
De Fraysseix Pach Pollack (Shift) Algorithm



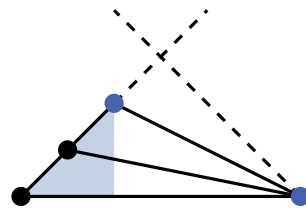
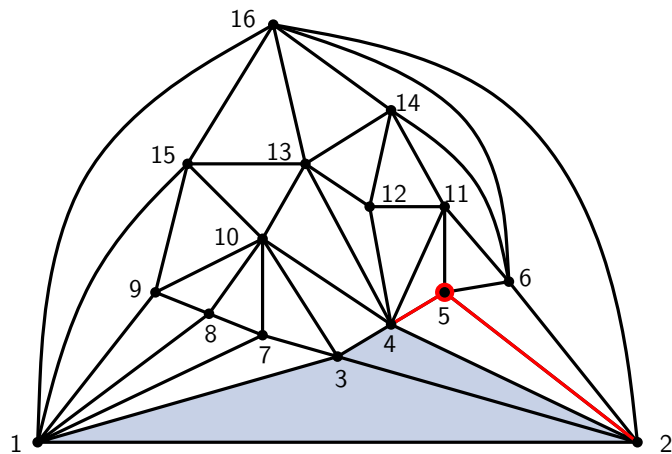
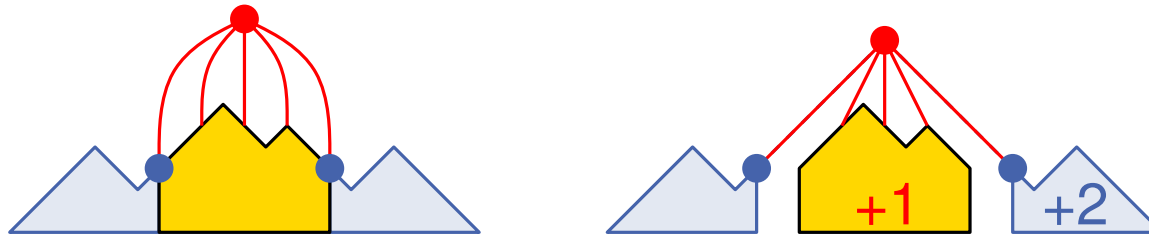
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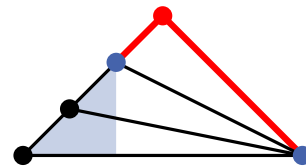
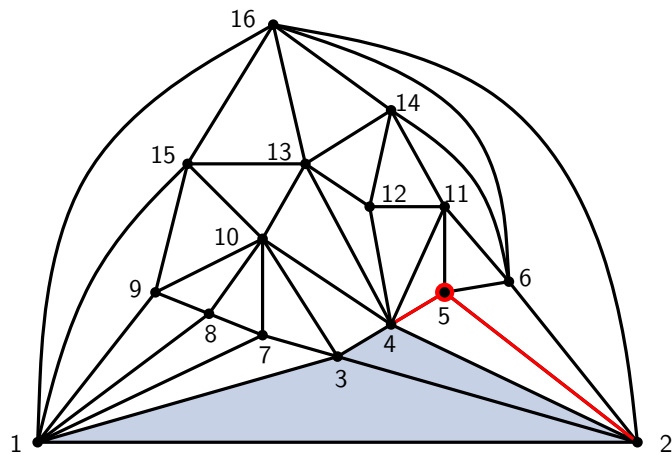
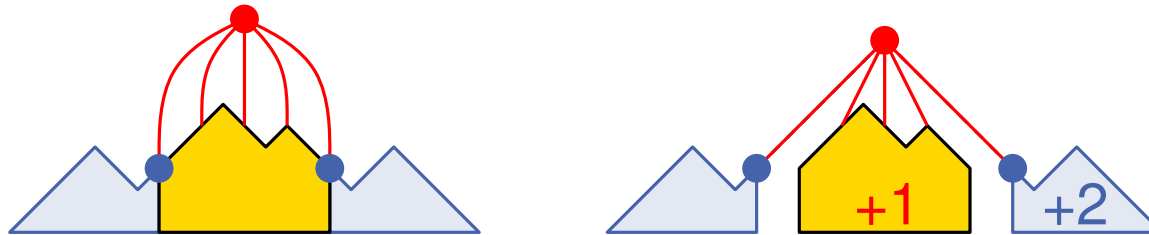
De Fraysseix Pach Pollack (Shift) Algorithm



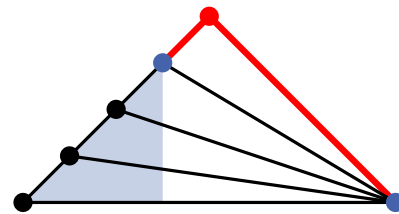
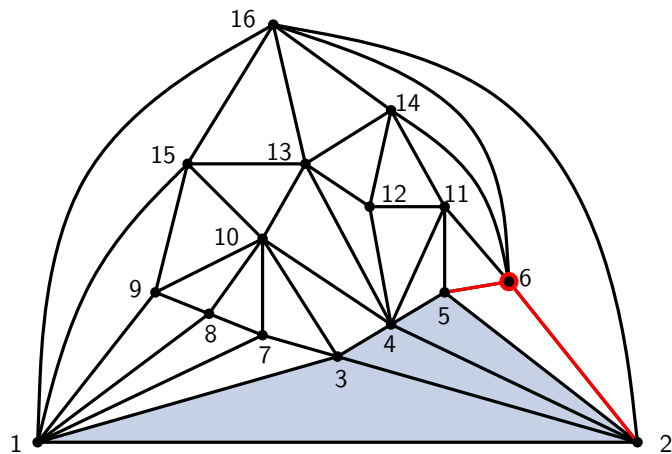
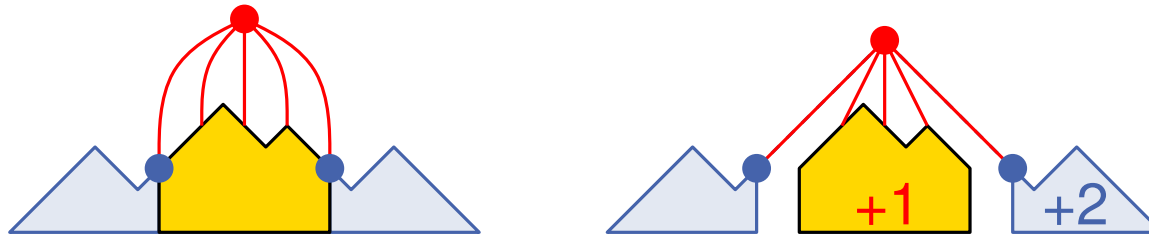
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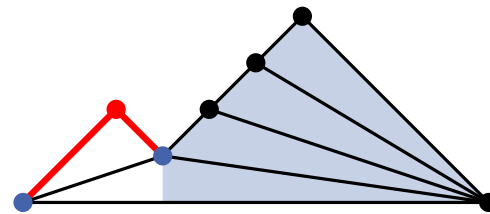
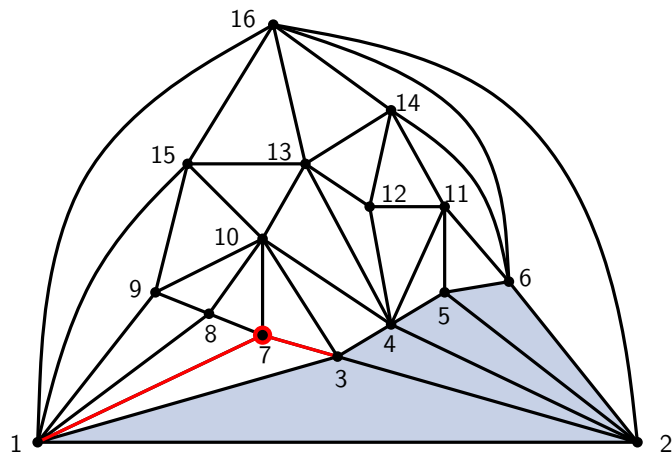
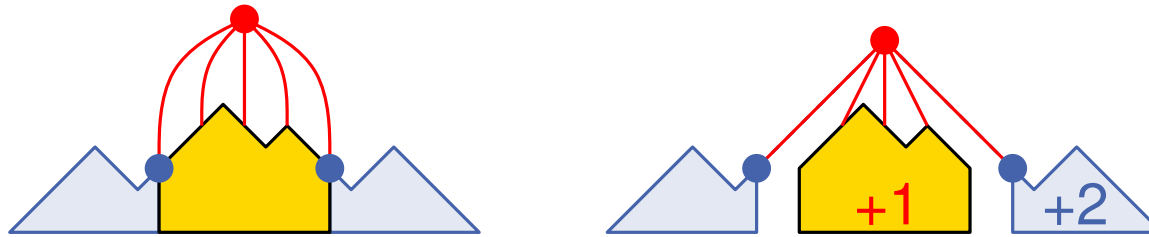
De Fraysseix Pach Pollack (Shift) Algorithm



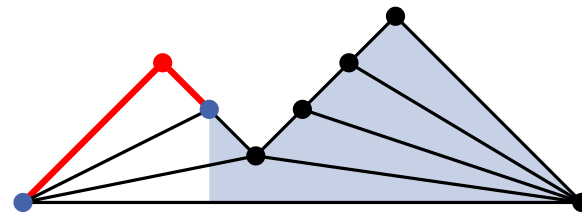
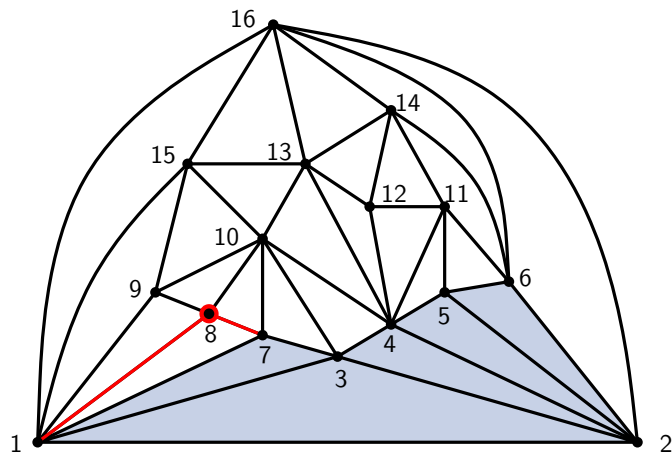
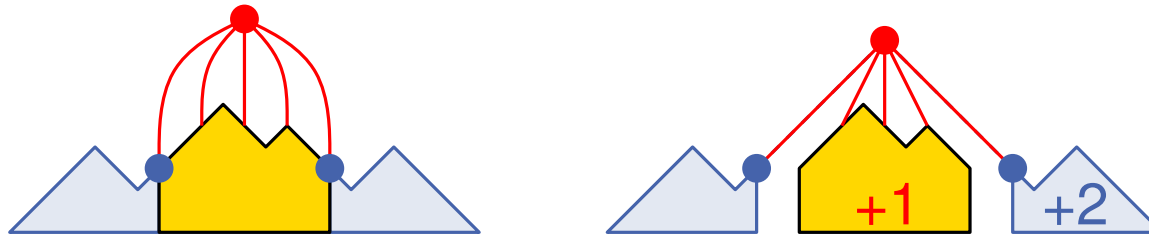
De Fraysseix Pach Pollack (Shift) Algorithm



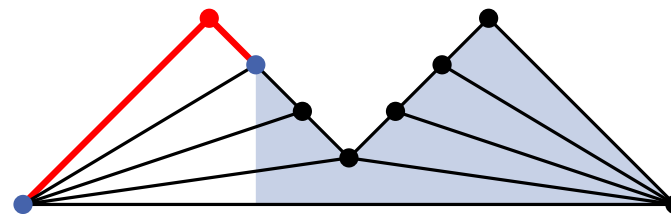
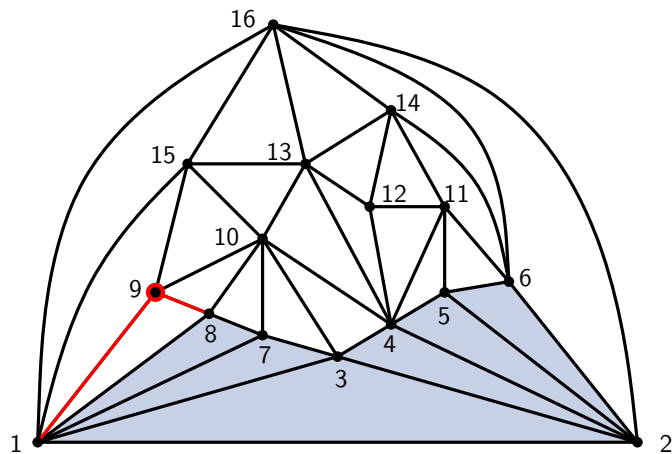
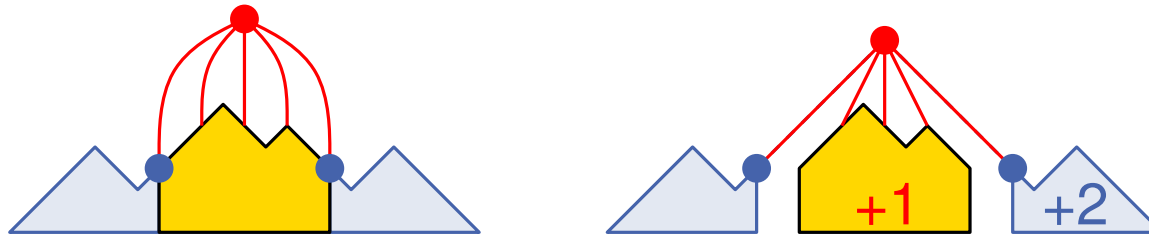
De Fraysseix Pach Pollack (Shift) Algorithm



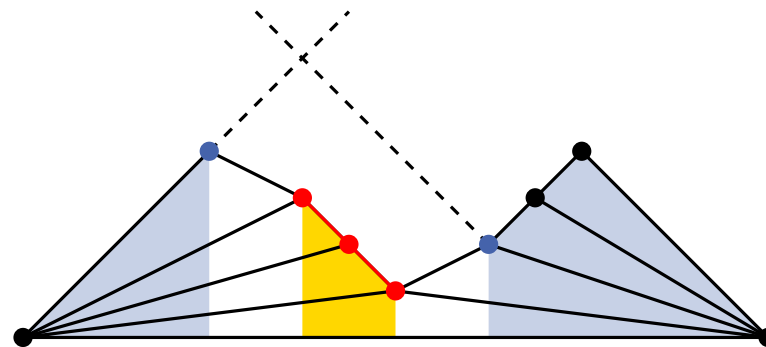
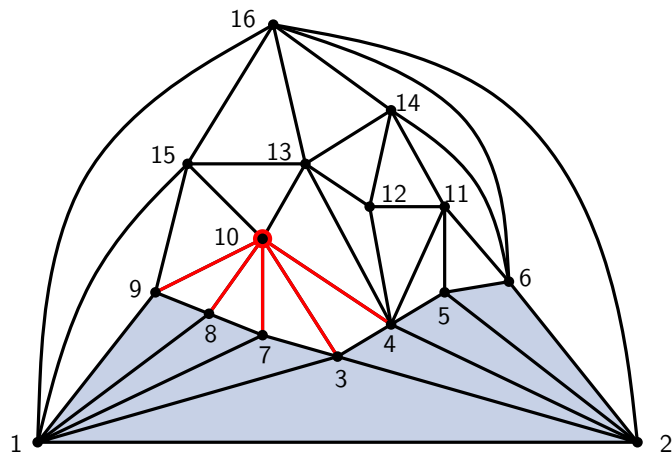
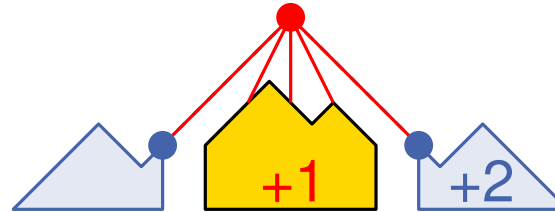
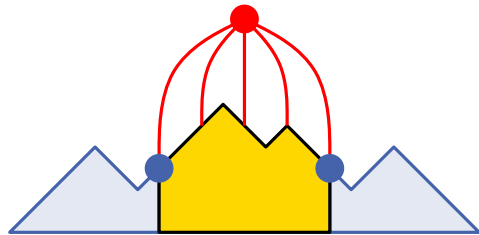
De Fraysseix Pach Pollack (Shift) Algorithm



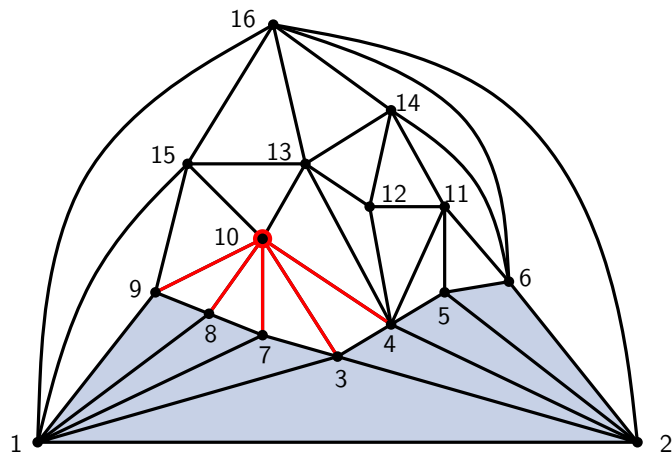
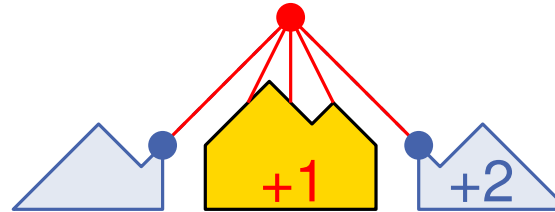
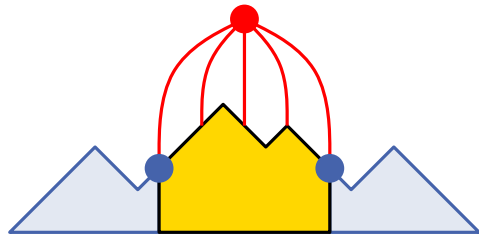
De Fraysseix Pach Pollack (Shift) Algorithm



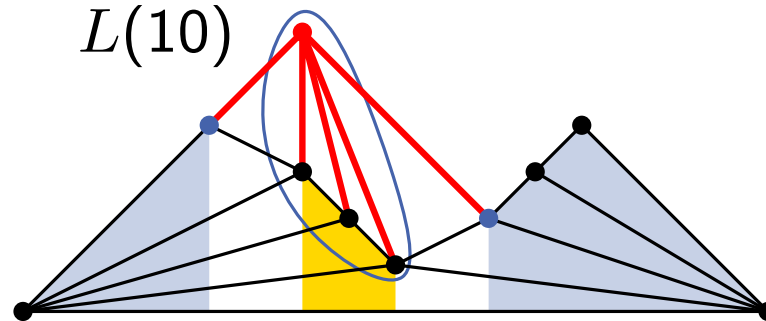
De Fraysseix Pach Pollack (Shift) Algorithm



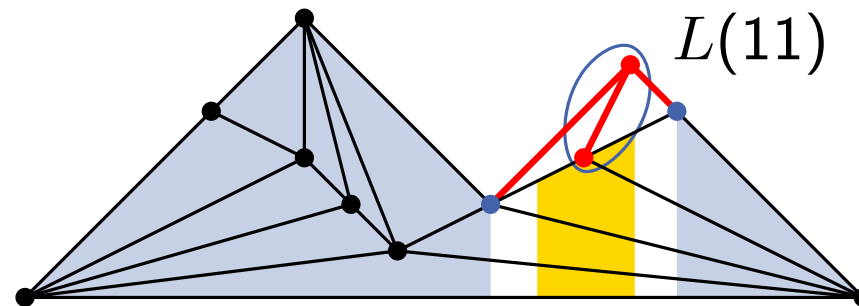
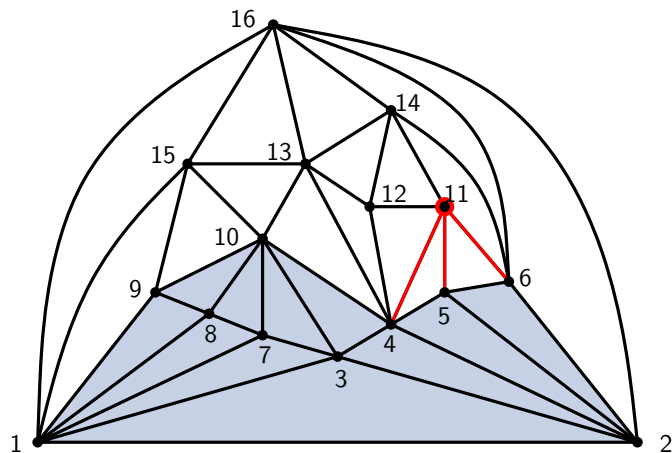
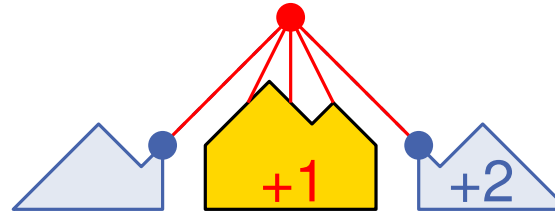
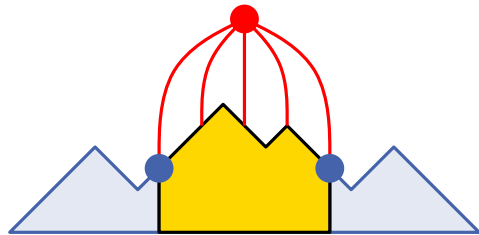
De Fraysseix Pach Pollack (Shift) Algorithm



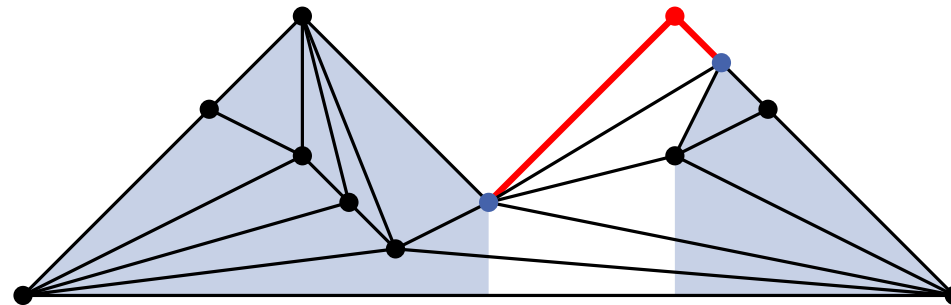
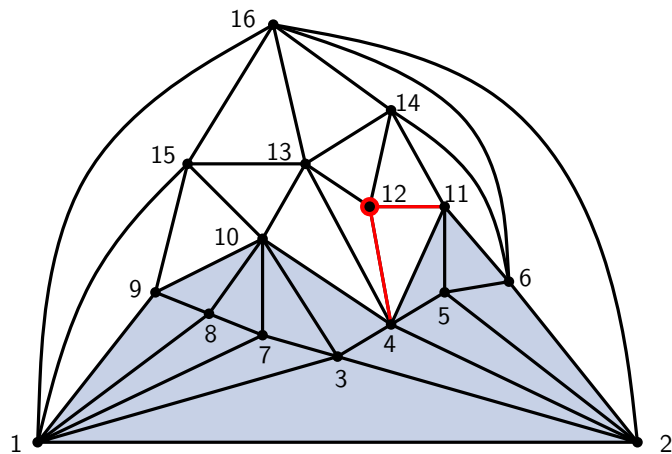
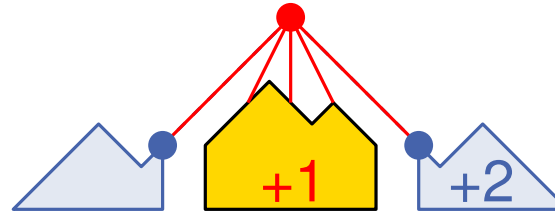
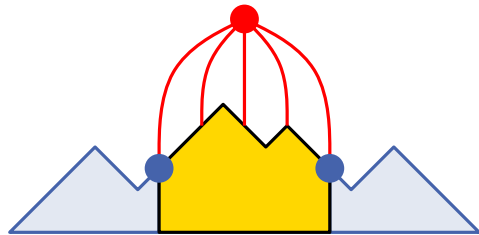
$L(10)$



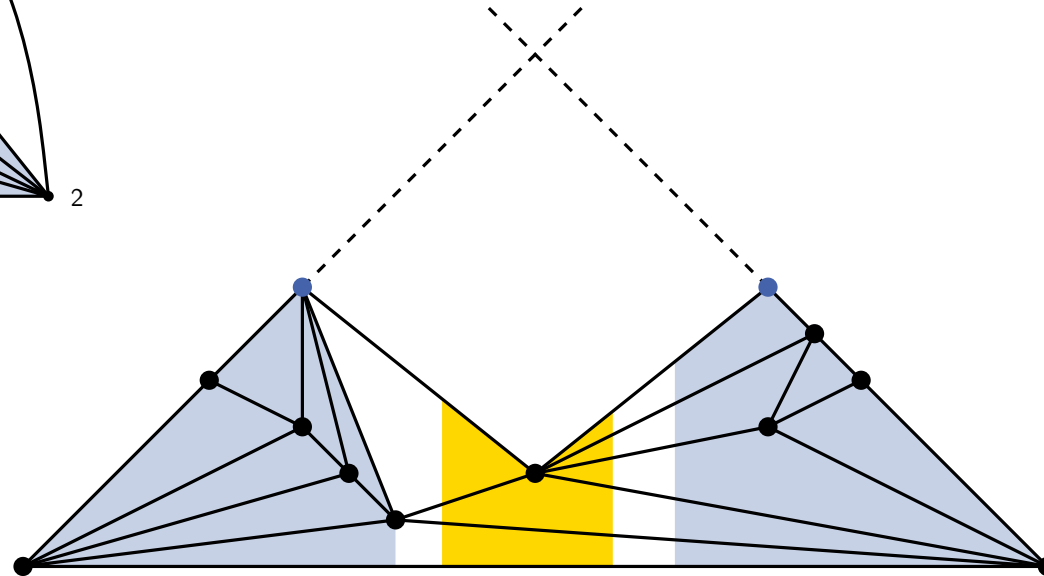
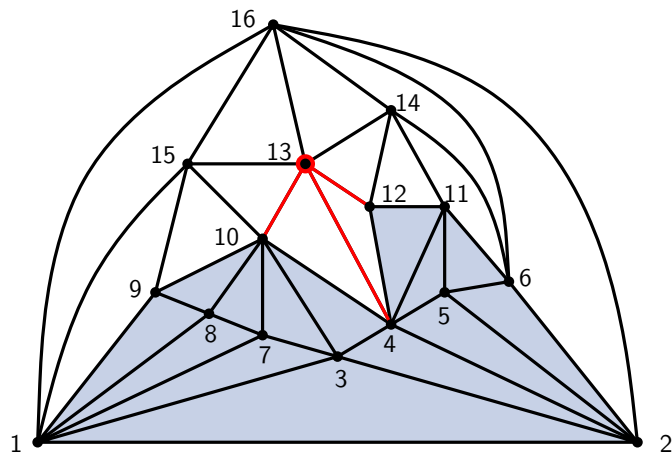
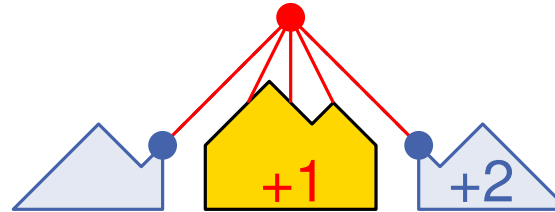
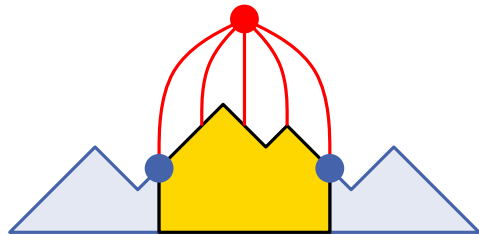
De Fraysseix Pach Pollack (Shift) Algorithm



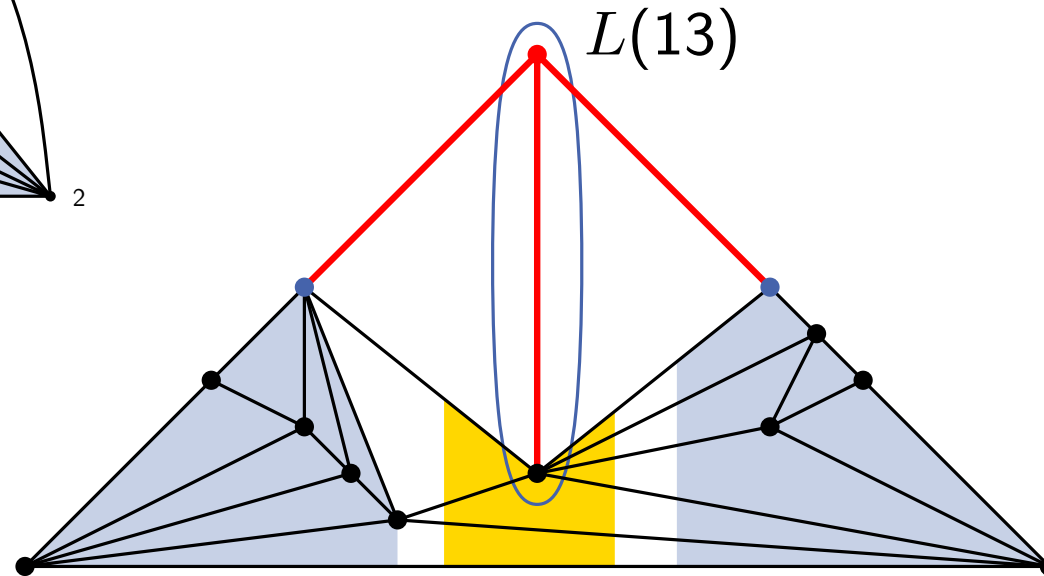
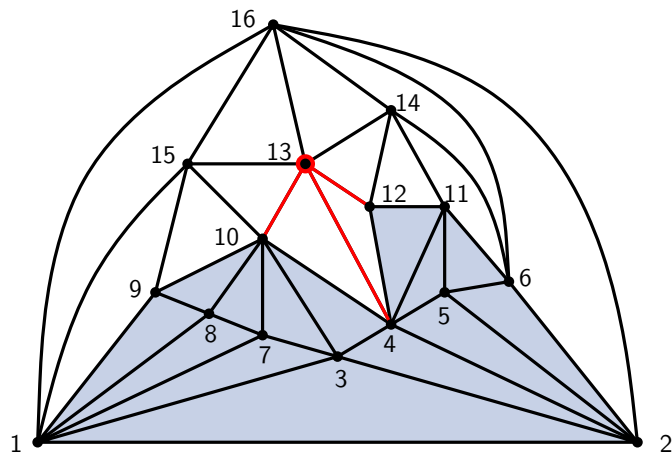
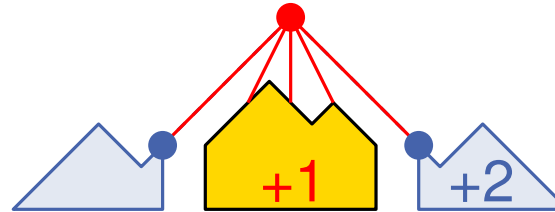
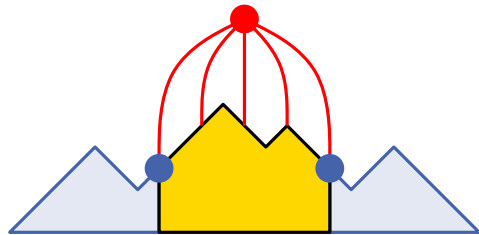
De Fraysseix Pach Pollack (Shift) Algorithm



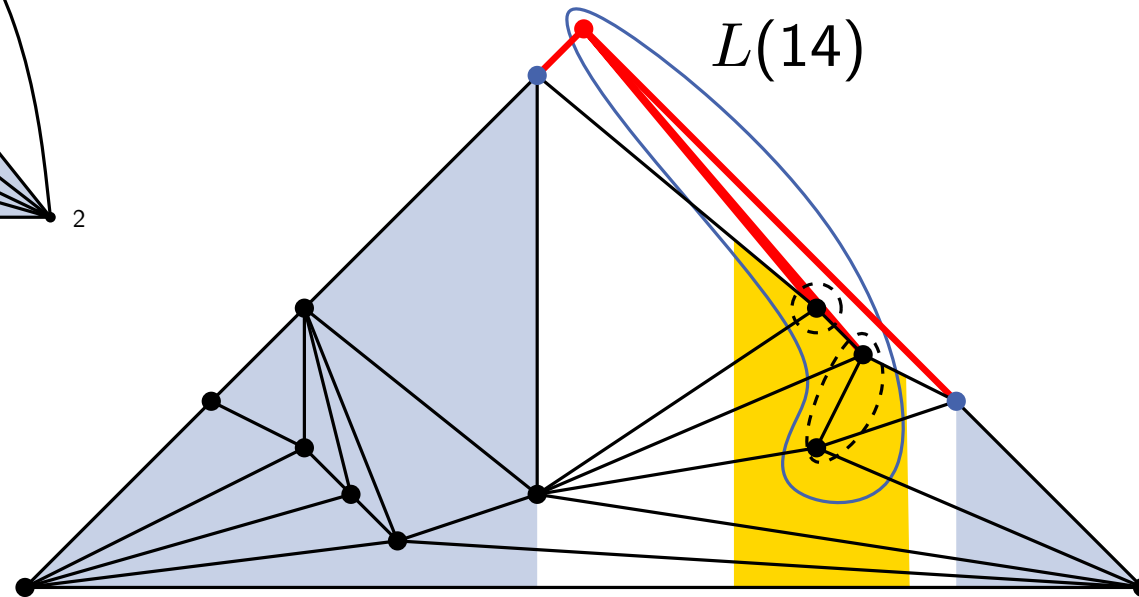
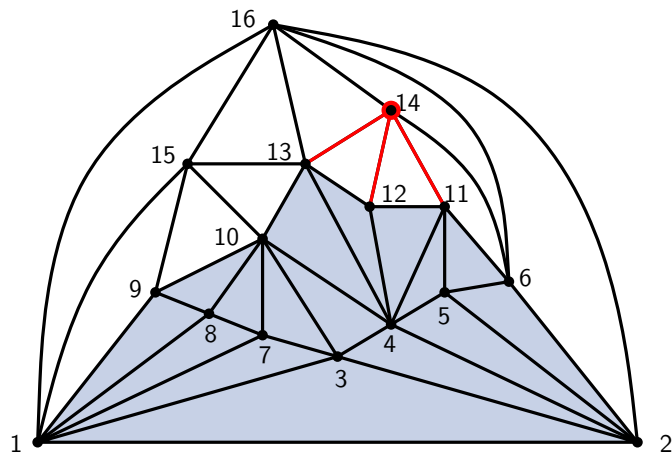
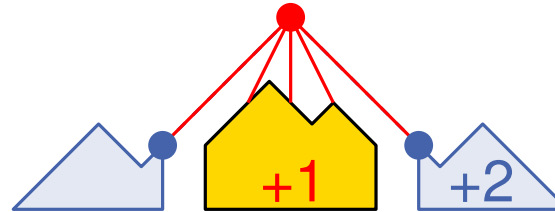
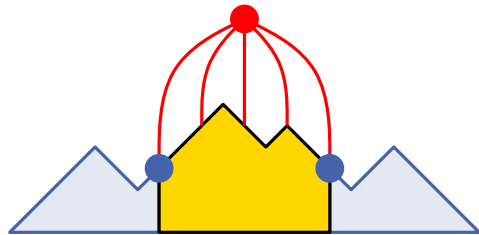
De Fraysseix Pach Pollack (Shift) Algorithm



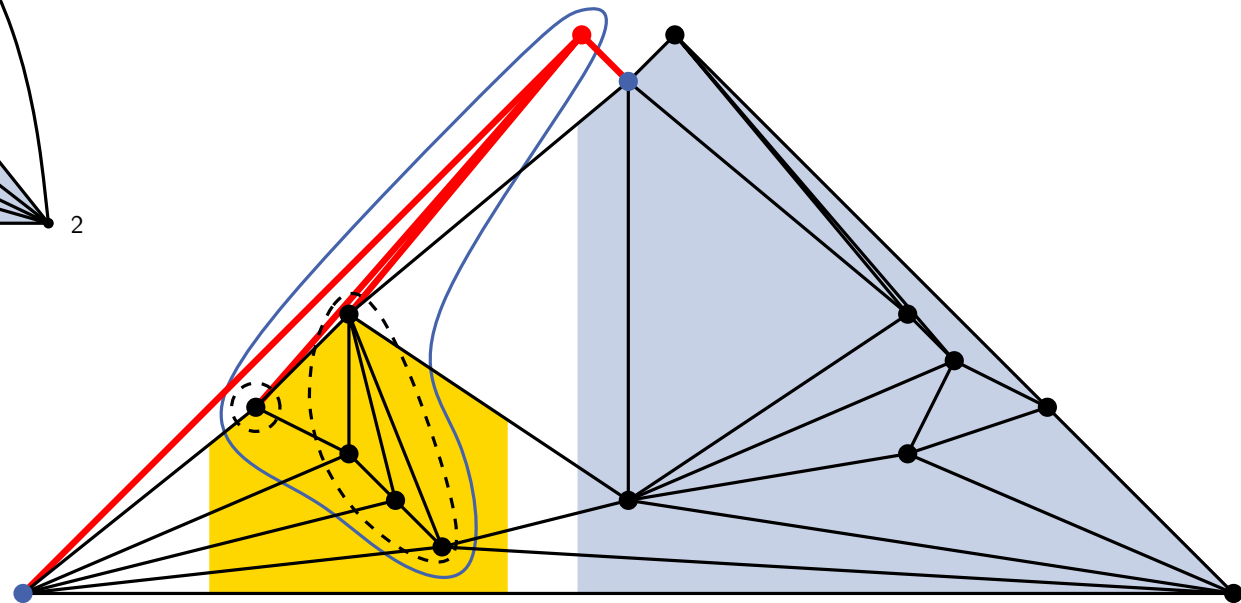
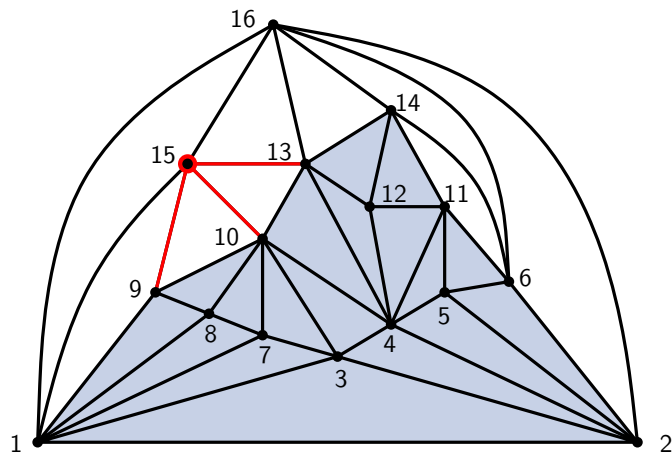
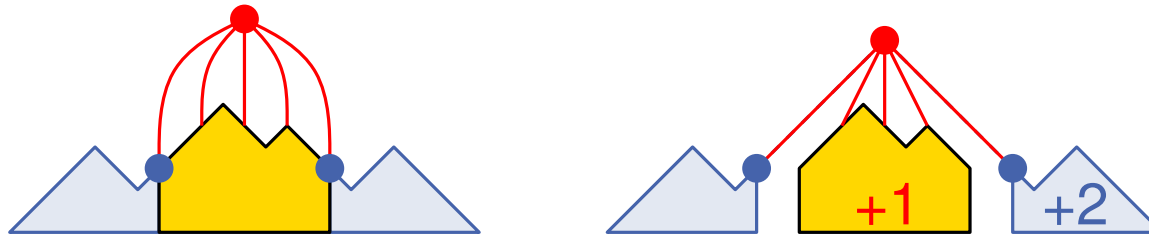
De Fraysseix Pach Pollack (Shift) Algorithm



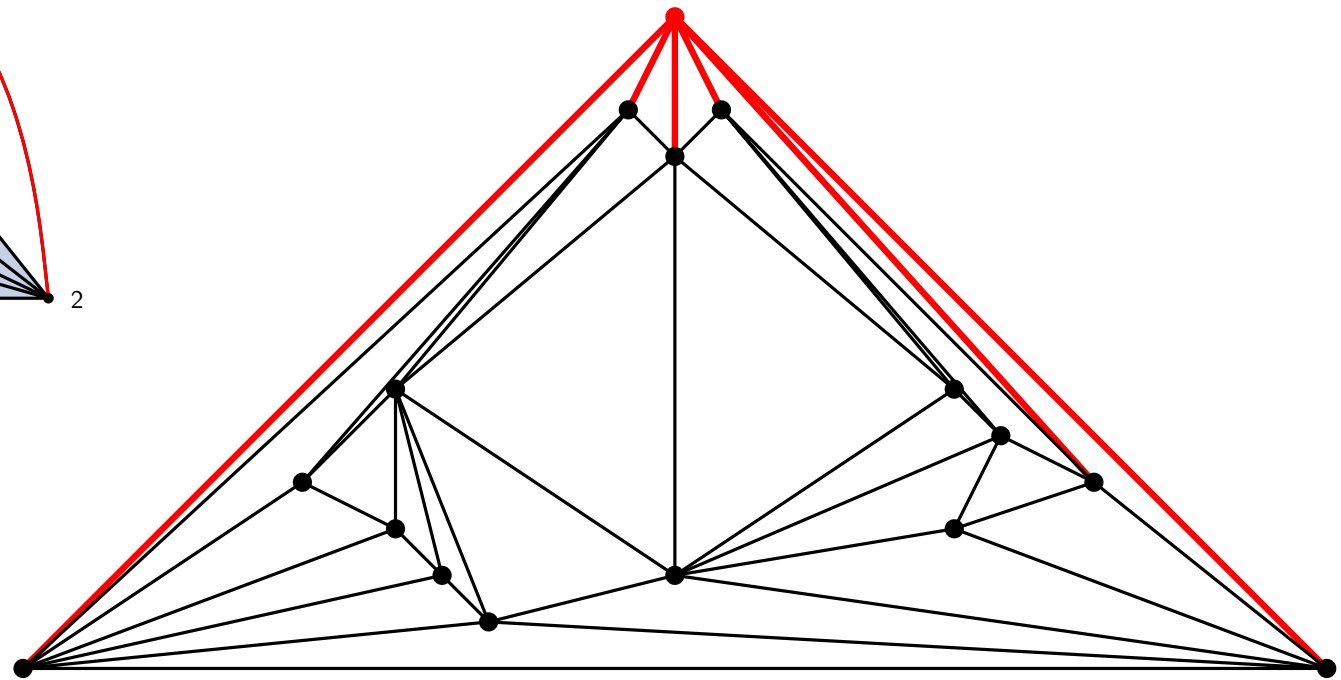
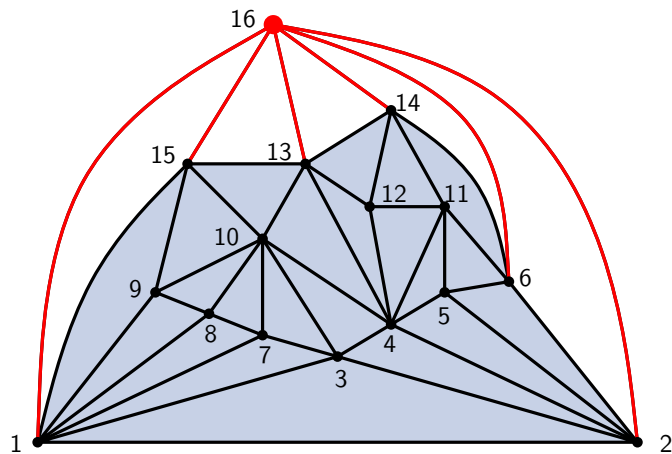
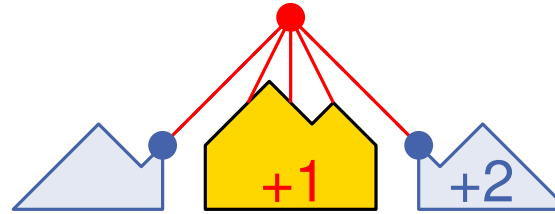
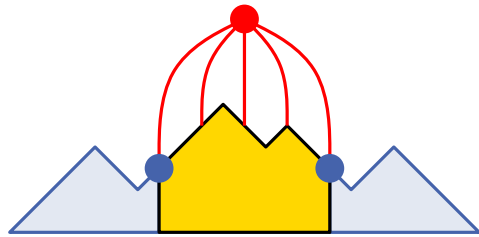
De Fraysseix Pach Pollack (Shift) Algorithm



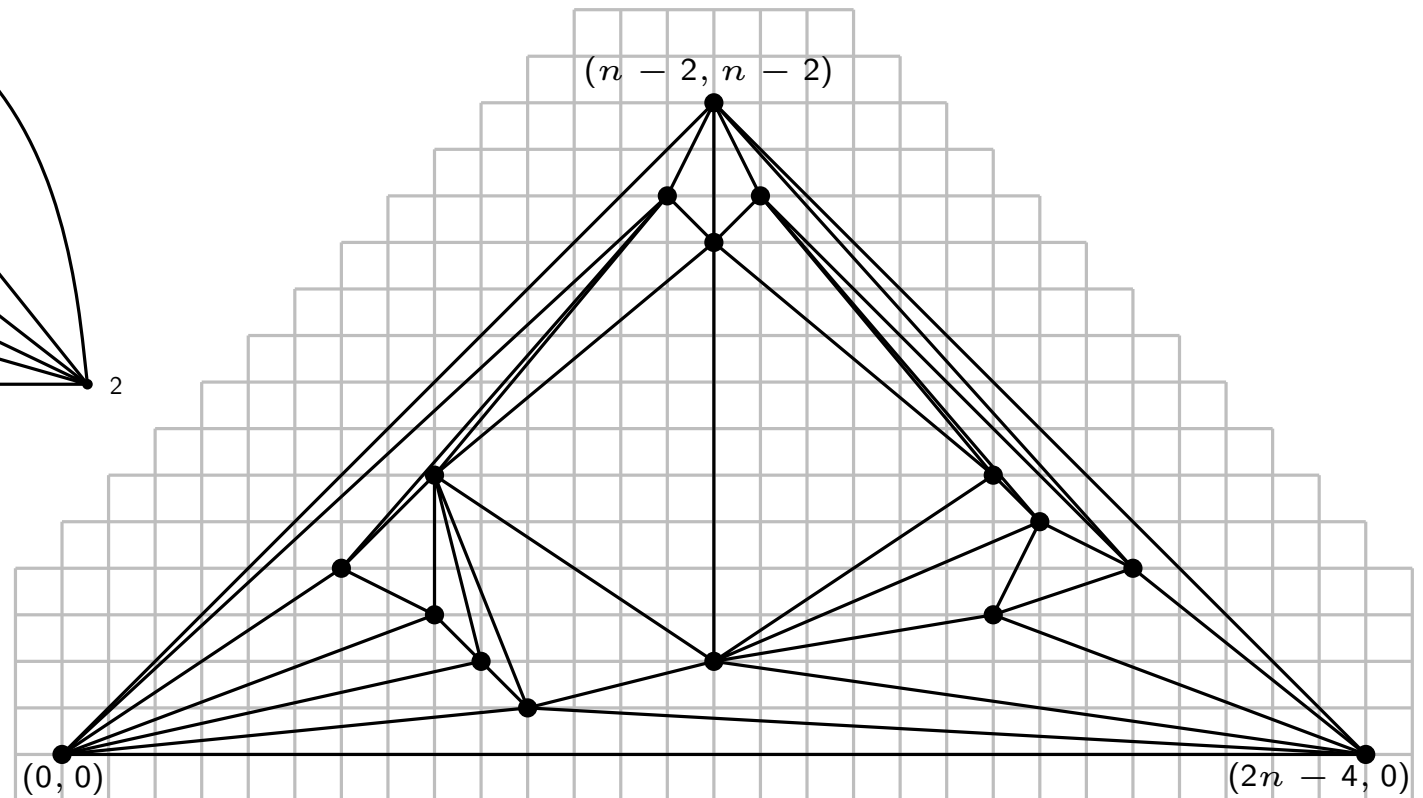
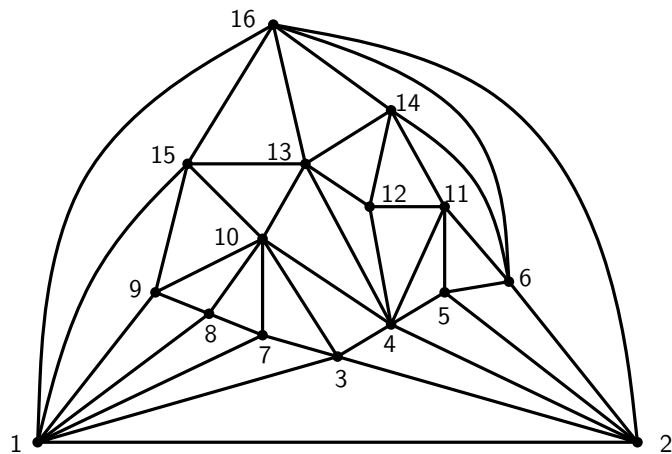
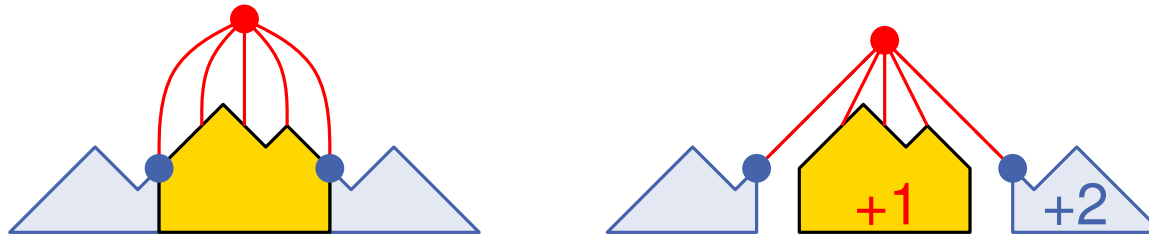
De Fraysseix Pach Pollack (Shift) Algorithm



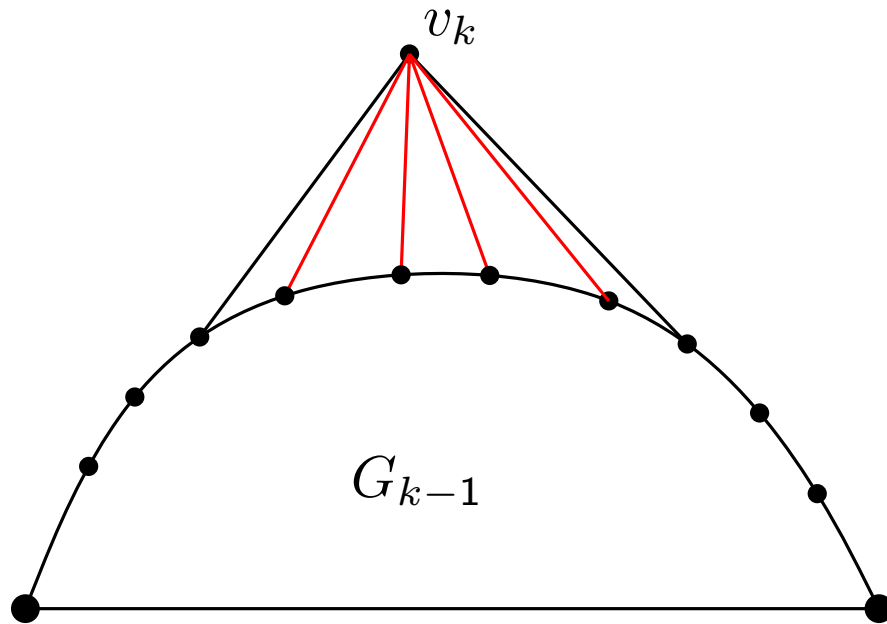
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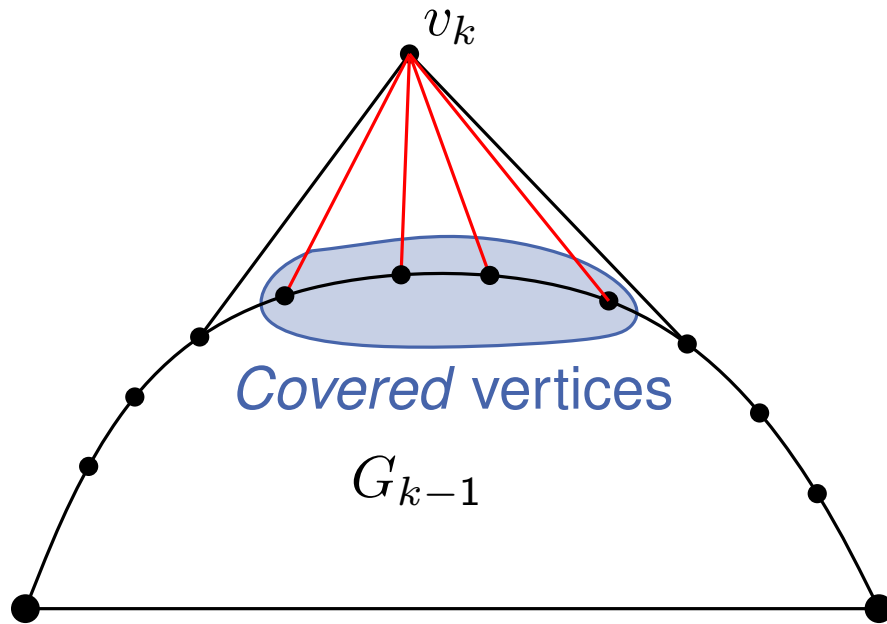
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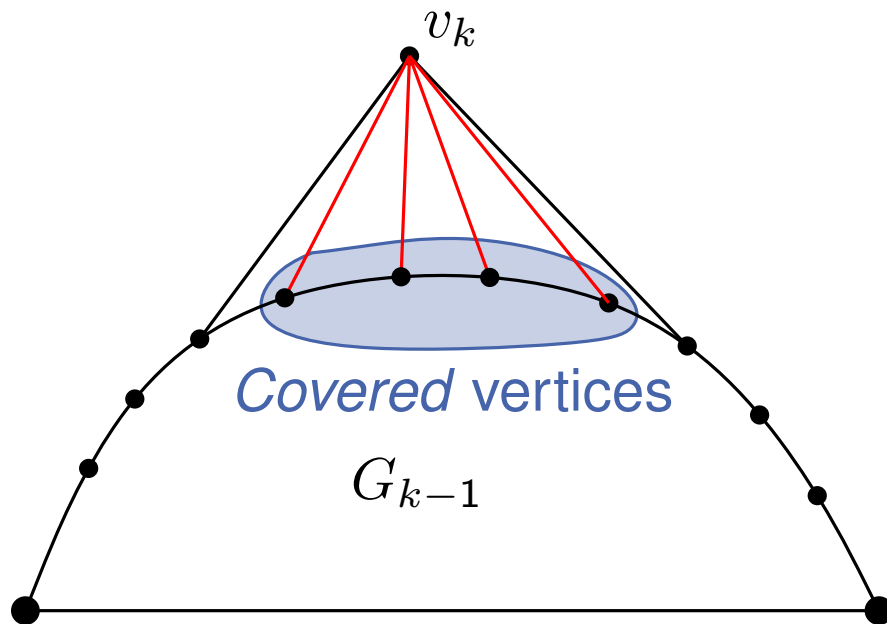


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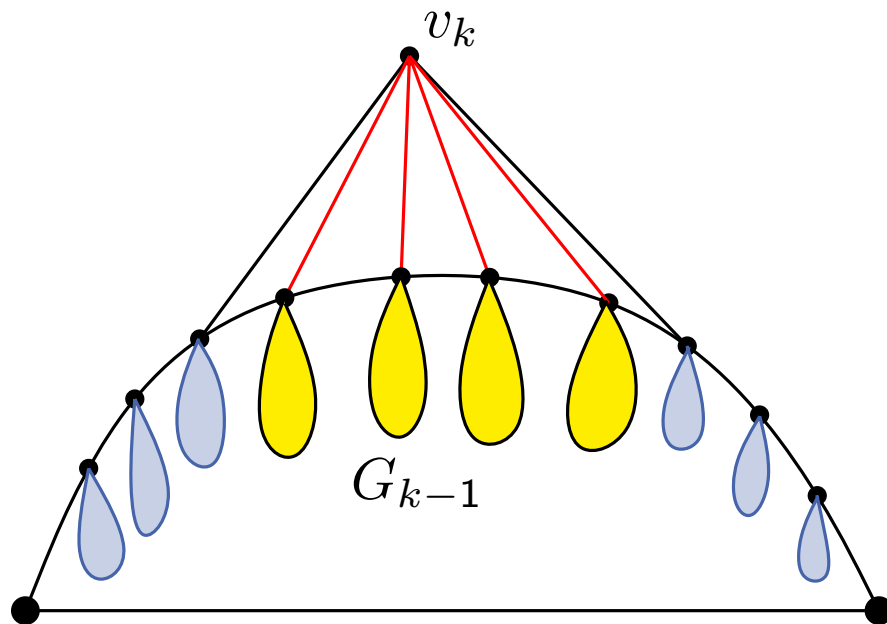


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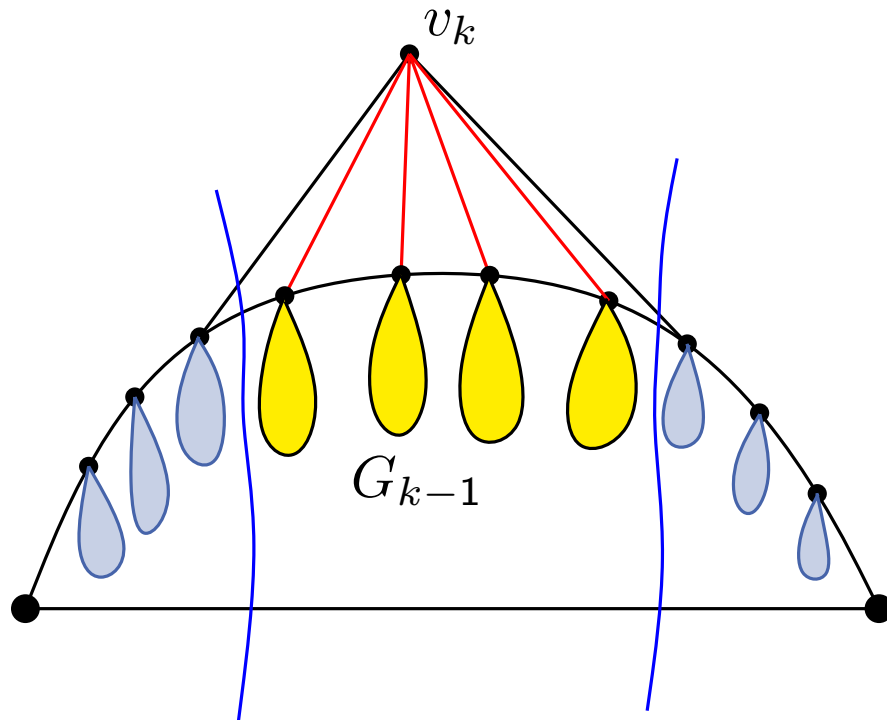




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- Coverance relation defines a tree in G
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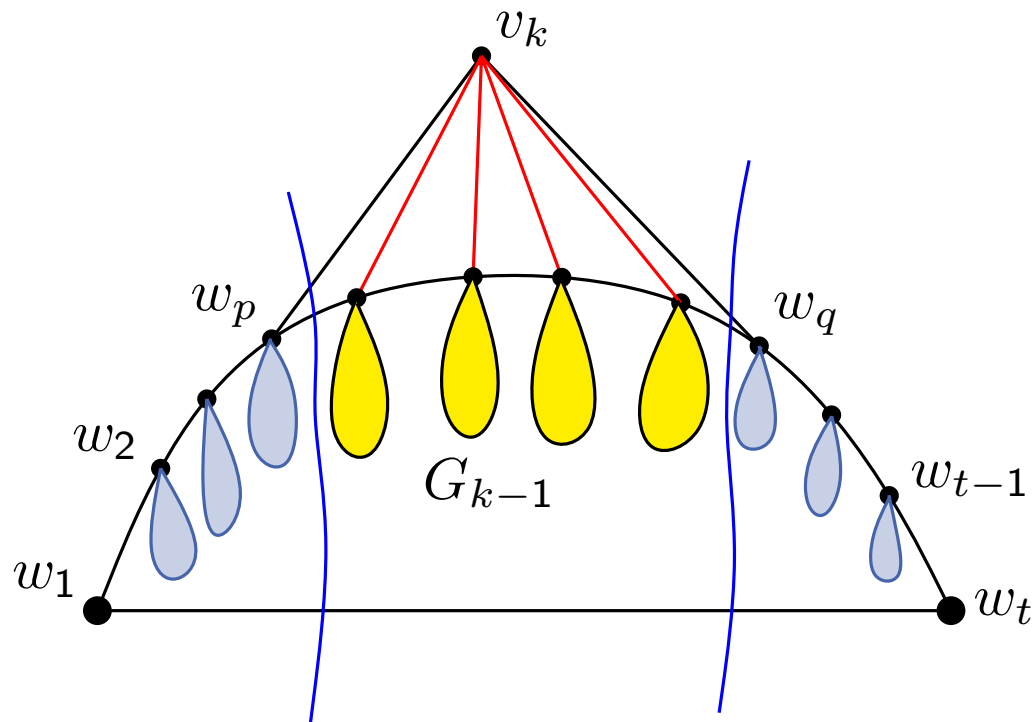


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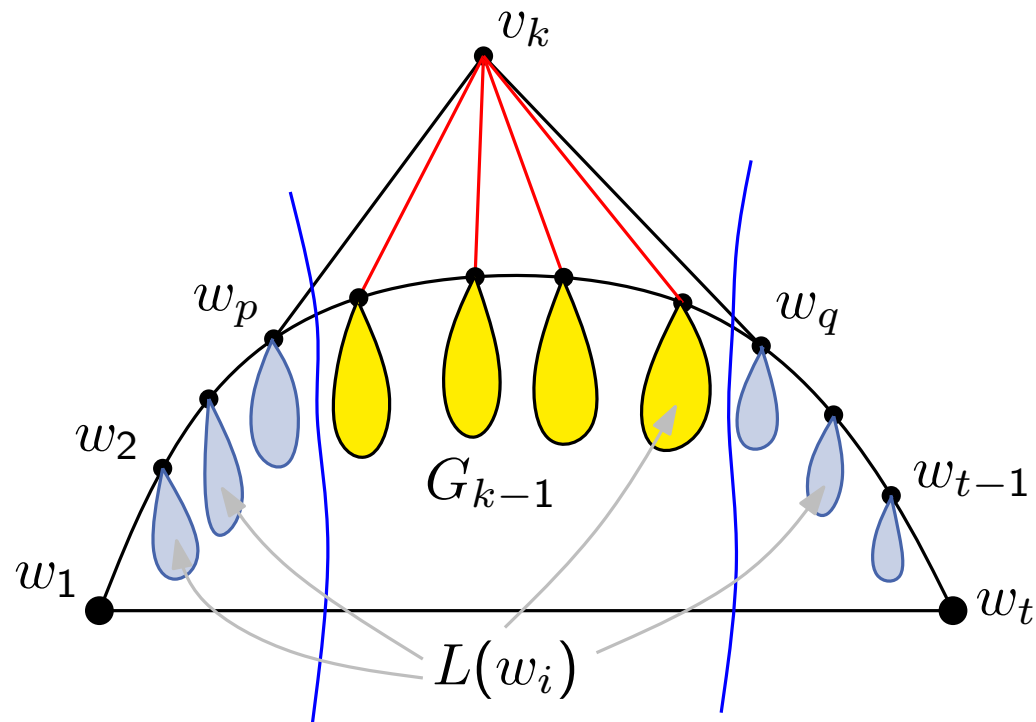
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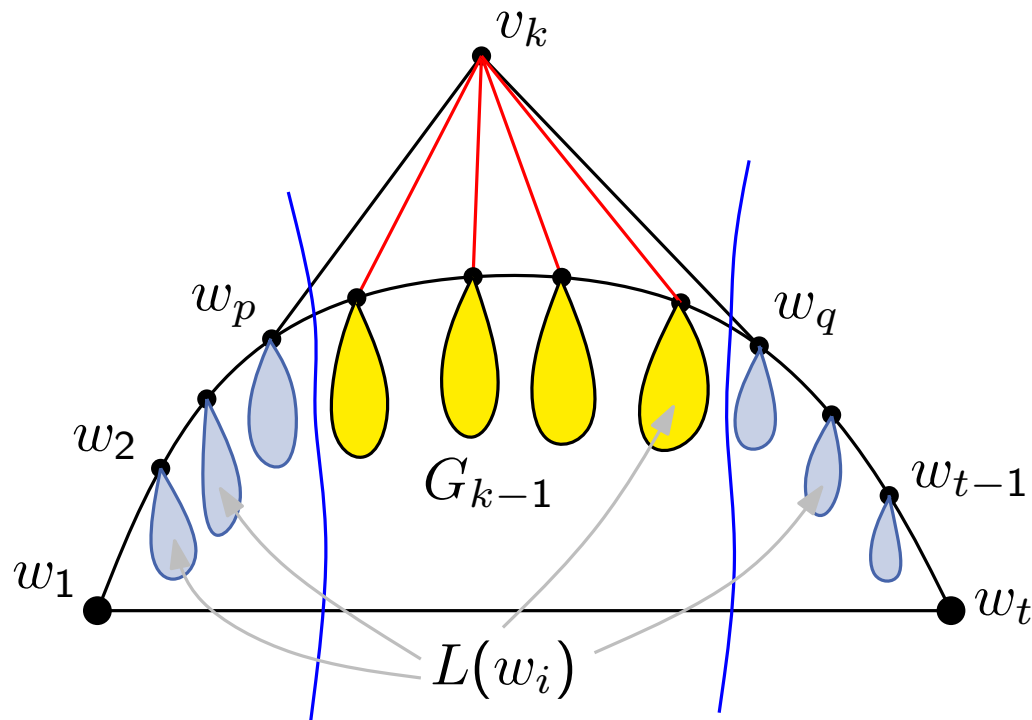


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- We can complete the drawing by placing v_k .

Algorithm Shift

Let v_1, \dots, v_n be a canonical ordering of G

for $i = 1$ **to** n **do**

└ $L(v_i) \leftarrow \{v_i\};$

$P(v_1) \leftarrow (0, 0); P(v_2) \leftarrow (2, 0); P(v_3) \leftarrow (1, 1);$

for $i = 4$ **to** n **do**

└ Let $w_1 = v_1, w_2, \dots, w_{t-1}, w_t = v_2$ denote the boundary of $G_{i-1};$
and let w_p, \dots, w_q be the neighbors $v_i;$

└ **for** $\forall v \in \cup_{j=p+1}^{q-1} L(w_j)$ **do**

└ $x(v) \leftarrow x(v) + 1;$

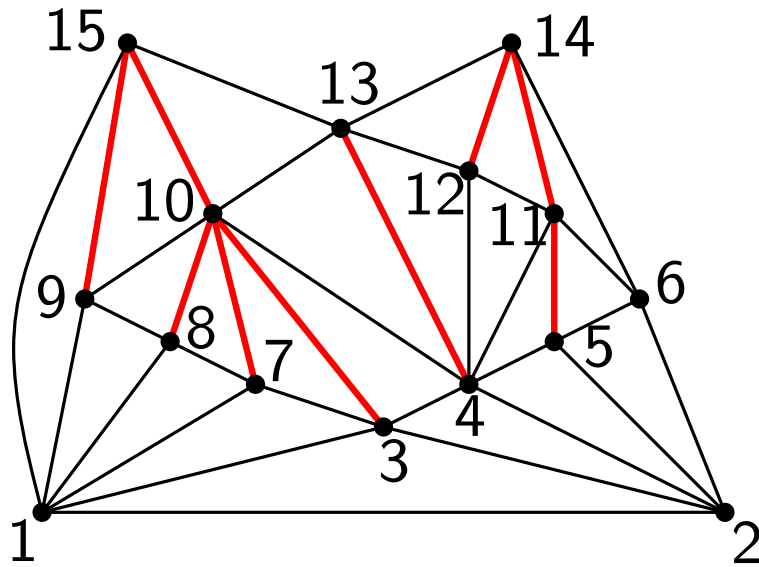
└ **for** $\forall v \in \cup_{j=q}^t L(w_j)$ **do**

└ $x(v) \leftarrow x(v) + 2;$

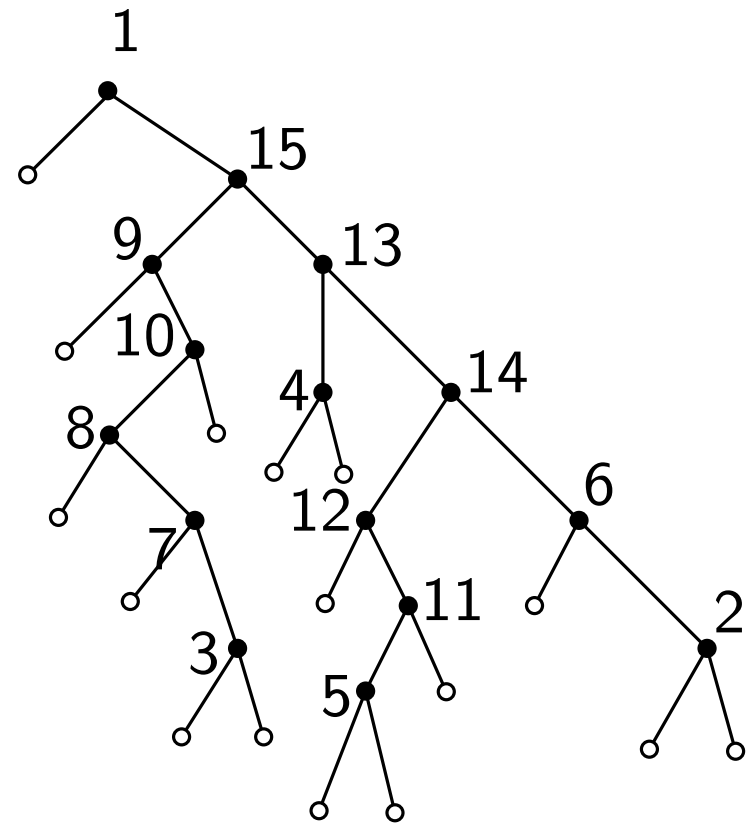
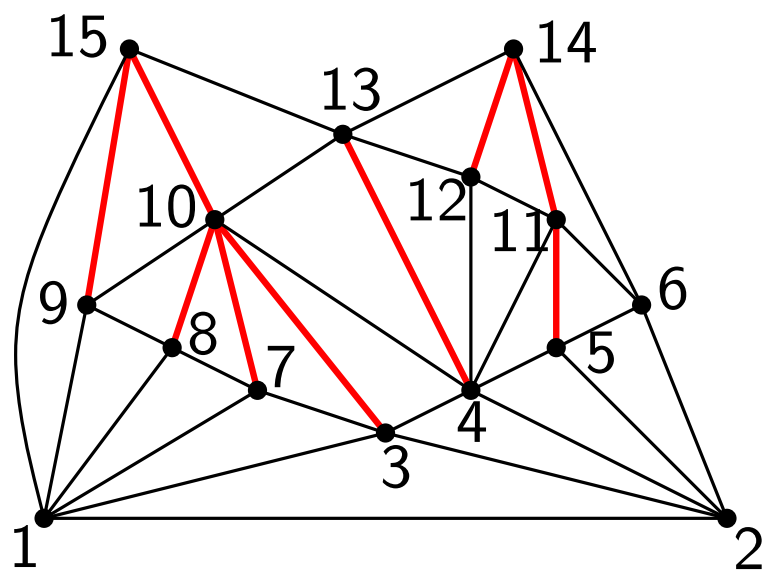
$P(v_i) \leftarrow$ intersection of $+1$ and -1 edges from $P(w_p)$ and $P(w_q);$

└ $L(v_i) = \cup_{j=p+1}^{q-1} L(w_j) \cup \{v_i\};$

Linear Time Implementation of Shift Algorithm

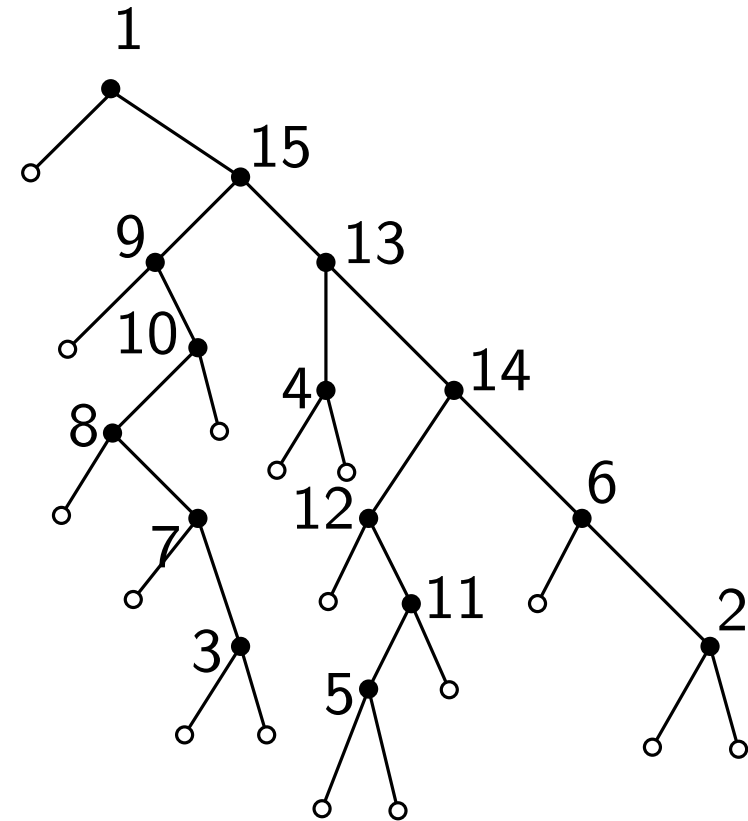
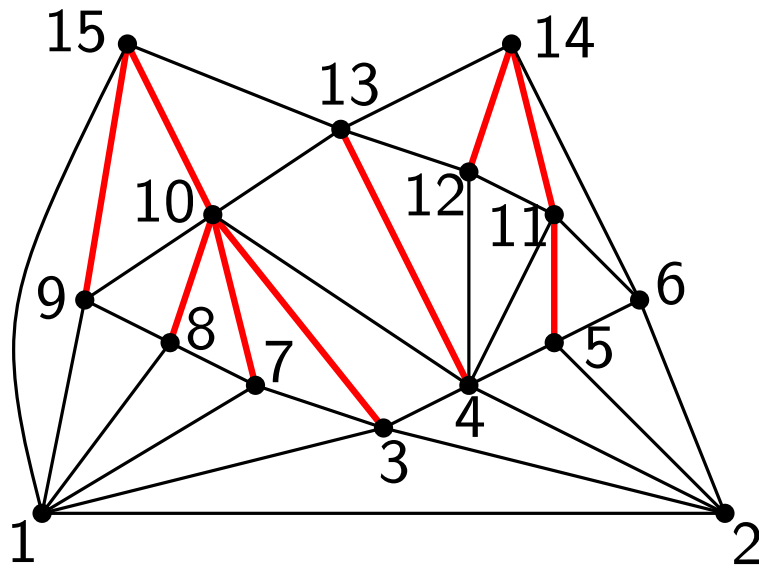


Linear Time Implementation of Shift Algorithm



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- $x(v_k) = \frac{1}{2}(x(w_q) + x(w_p) + y(w_q) - y(w_p))$ (1)

- $y(v_k) = \frac{1}{2}(x(w_q) - x(w_p) + y(w_q) + y(w_p))$ (2)

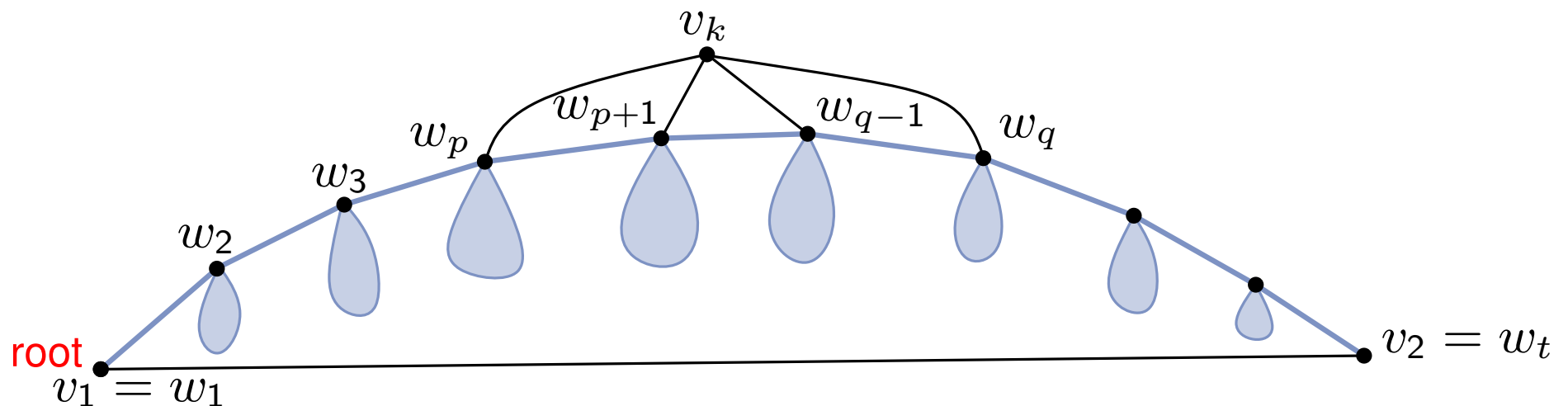
- $x(v_k) - x(w_p) = \frac{1}{2}(x(w_q) - x(w_p) + y(w_q) - y(w_p))$ (3)

- If we know the y -coordinates of w_p and w_q and the difference $x(w_p) - x(w_q)$, we can compute the relative distance of v_k and w_p .
- In the binary tree which we construct we keep the relative x -distance of each node from its parent.

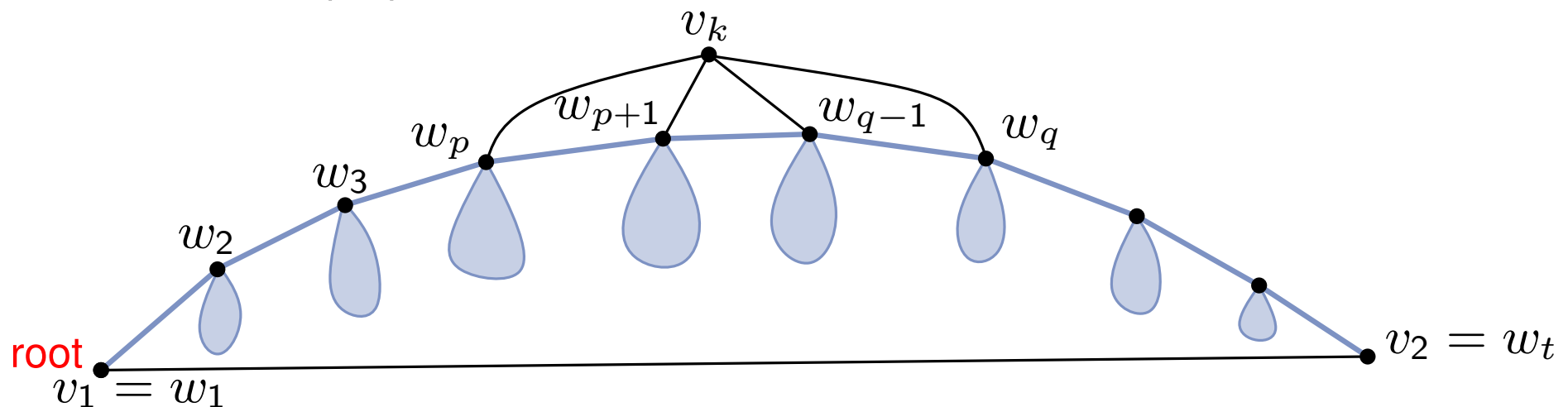
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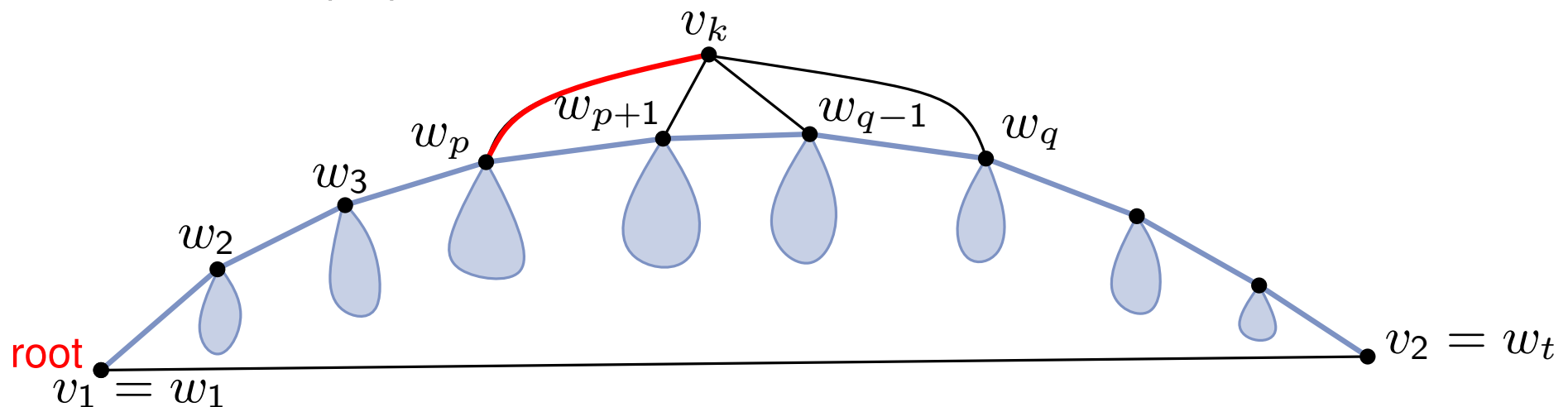
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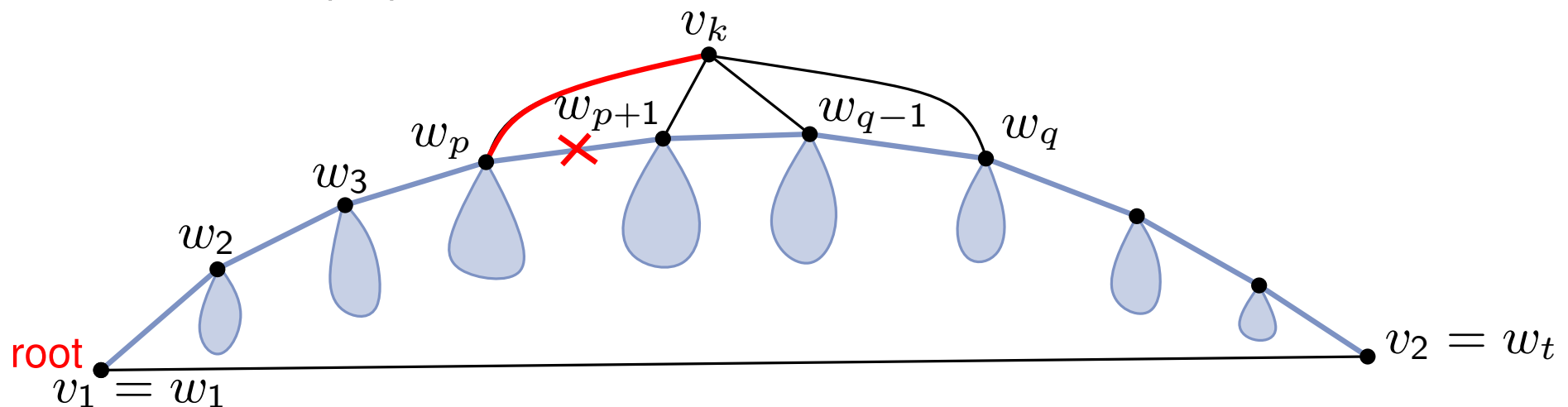


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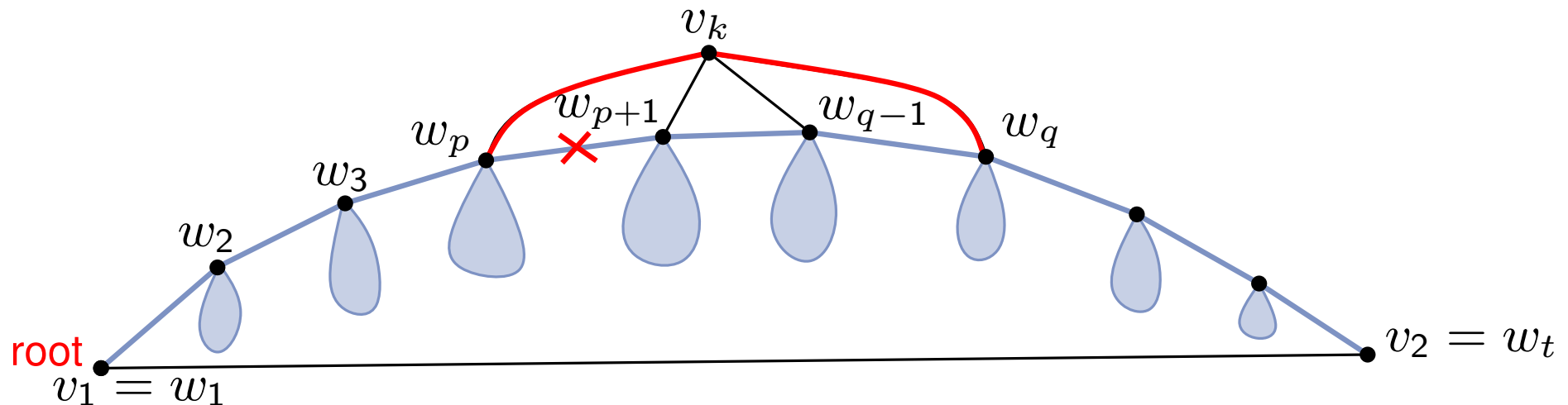


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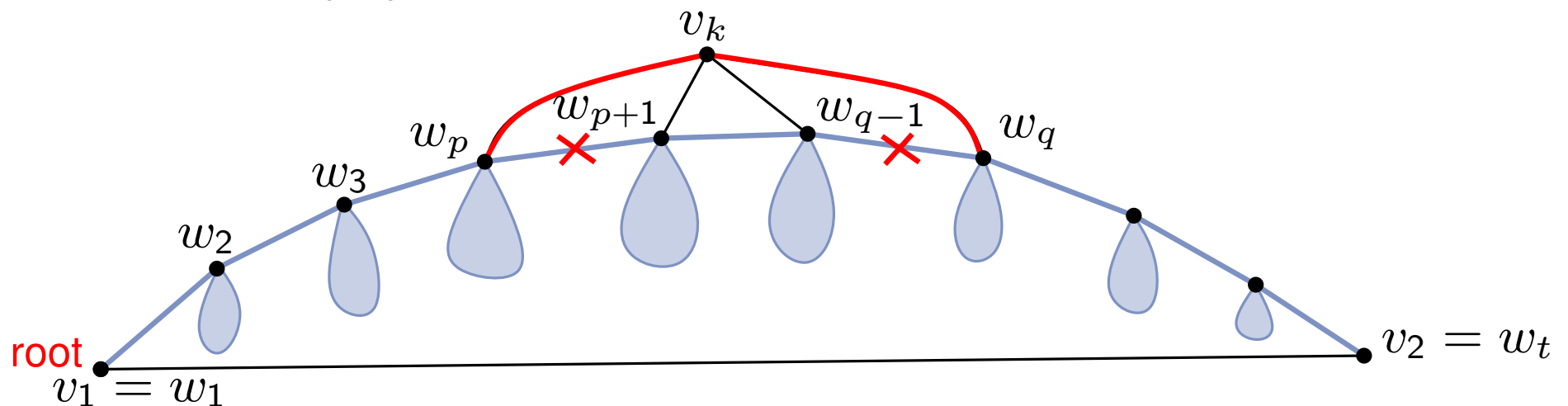
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